



# Release Notes

*Release 12.2*

**NVIDIA**

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## NVIDIA CUDA Toolkit Release Notes

The Release Notes for the CUDA Toolkit.

The release notes for the NVIDIA® CUDA® Toolkit can be found online at <https://docs.nvidia.com/cuda/cuda-toolkit-release-notes/index.html>.

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**Note:** The release notes have been reorganized into two major sections: the general CUDA release notes, and the CUDA libraries release notes including historical information for 12.x releases.

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# Chapter 1. CUDA Toolkit Major Component Versions

**CUDA Components** Starting with CUDA 11, the various components in the toolkit are versioned independently.

For CUDA 12.2 Update 1, the table below indicates the versions:

Table 1: CUDA 12.2 Update 1 Component Versions

Component Name		Version Information	Supported Architectures	Supported Platforms
CUDA C++ Core Compute Libraries	Thrust	2.1.0	x86_64, POWER, aarch64-jetson	Linux, Windows
	CUB	2.1.0		
	libcudpp	2.1.0		
	Cooperative Groups	12.0.0		
CUDA Compatibility		12.2.33777445	x86_64, POWER, aarch64-jetson	Linux, Windows
CUDA Runtime (cudart)		12.2.128	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
cuobjdump		12.2.128	x86_64, POWER, aarch64-jetson	Linux, Windows
CUPTI		12.2.131	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
CUDA cuxxfilt (demangler)		12.2.128	x86_64, POWER, aarch64-jetson	Linux, Windows
CUDA Demo Suite		12.2.128	x86_64	Linux, Windows
CUDA GDB		12.2.128	x86_64, POWER, aarch64-jetson	Linux, WSL
CUDA Nsight Eclipse Plugin		12.2.128	x86_64, POWER	Linux
CUDA NVCC		12.2.128	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL

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Table 1 – continued from previous page

Component Name	Version Information	Supported Architectures	Supported Platforms
CUDA nvdasm	12.2.128	x86_64, POWER, aarch64-jetson	Linux, Windows
CUDA NVML Headers	12.2.128	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
CUDA nvprof	12.2.131	x86_64, POWER	Linux, Windows
CUDA nvprune	12.2.128	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
CUDA NVRTC	12.2.128	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
NVTX	12.2.128	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
CUDA NVVP	12.2.131	x86_64, POWER	Linux, Windows
CUDA OpenCL	12.2.128	x86_64	Linux, Windows
CUDA Profiler API	12.2.128	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
CUDA Compute Sanitizer API	12.2.128	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
CUDA cuBLAS	12.2.4.5	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
CUDA cuDLA	12.2.128	aarch64-jetson	Linux
CUDA cuFFT	11.0.8.91	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
CUDA cuFile	1.7.1.12	x86_64	Linux
CUDA cuRAND	10.3.3.129	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
CUDA cuSOLVER	11.5.1.129	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
CUDA cuSPARSE	12.1.2.129	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
CUDA NPP	12.2.0.5	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
CUDA nvJitLink	12.2.128	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
CUDA nvJPEG	12.2.1.2	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL

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Table 1 – continued from previous page

Component Name	Version Information	Supported Architectures	Supported Platforms
Nsight Compute	2023.2.1.3	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL (Windows 11)
Nsight Systems	2023.2.3.1001	x86_64, POWER, aarch64-jetson	Linux, Windows, WSL
Nsight Visual Studio Edition (VSE)	2023.2.1.23188	x86_64 (Windows)	Windows
nvidia_fs <sup>1</sup>	2.17.3	x86_64, aarch64-jetson	Linux
Visual Studio Integration	12.2.128	x86_64 (Windows)	Windows
NVIDIA Linux Driver	535.86.10	x86_64, POWER, aarch64-jetson	Linux
NVIDIA Windows Driver	536.67	x86_64 (Windows)	Windows, WSL

**CUDA Driver** Running a CUDA application requires the system with at least one CUDA capable GPU and a driver that is compatible with the CUDA Toolkit. See [Table 3](#). For more information various GPU products that are CUDA capable, visit <https://developer.nvidia.com/cuda-gpus>.

Each release of the CUDA Toolkit requires a minimum version of the CUDA driver. The CUDA driver is backward compatible, meaning that applications compiled against a particular version of the CUDA will continue to work on subsequent (later) driver releases.

More information on compatibility can be found at <https://docs.nvidia.com/cuda/cuda-c-best-practices-guide/index.html#cuda-compatibility-and-upgrades>.

**Note:** Starting with CUDA 11.0, the toolkit components are individually versioned, and the toolkit itself is versioned as shown in the table below.

The minimum required driver version for CUDA minor version compatibility is shown below. CUDA minor version compatibility is described in detail in <https://docs.nvidia.com/deploy/cuda-compatibility/index.html>

<sup>1</sup> Only available on select Linux distros

Table 2: CUDA Toolkit and Minimum Required Driver Version for CUDA Minor Version Compatibility

CUDA Toolkit	Minimum Required Driver Version for CUDA Minor Version Compatibility*	
	Linux x86_64 Driver Version	Windows x86_64 Driver Version
CUDA 12.2.x	>=525.60.13	>=525.41
CUDA 12.1.x	>=525.60.13	>=527.41
CUDA 12.0.x	>=525.60.13	>=527.41
CUDA 11.8.x	>=450.80.02	>=452.39
CUDA 11.7.x	>=450.80.02	>=452.39
CUDA 11.6.x	>=450.80.02	>=452.39
CUDA 11.5.x	>=450.80.02	>=452.39
CUDA 11.4.x	>=450.80.02	>=452.39
CUDA 11.3.x	>=450.80.02	>=452.39
CUDA 11.2.x	>=450.80.02	>=452.39
CUDA 11.1 (11.1.0)	>=450.80.02	>=452.39
CUDA 11.0 (11.0.3)	>=450.36.06**	>=451.22**

\* Using a Minimum Required Version that is **different** from Toolkit Driver Version could be allowed in compatibility mode – please read the CUDA Compatibility Guide for details.

\*\* CUDA 11.0 was released with an earlier driver version, but by upgrading to Tesla Recommended Drivers 450.80.02 (Linux) / 452.39 (Windows), minor version compatibility is possible across the CUDA 11.x family of toolkits.

The version of the development NVIDIA GPU Driver packaged in each CUDA Toolkit release is shown below.

Table 3: CUDA Toolkit and Corresponding Driver Versions

CUDA Toolkit	Toolkit Driver Version	
	Linux x86_64 Driver Version	Windows x86_64 Driver Version
CUDA 12.2 Update 1	>=535.86.09	>=536.67
CUDA 12.2 GA	>=535.54.03	>=536.25
CUDA 12.1 Update 1	>=530.30.02	>=531.14
CUDA 12.1 GA	>=530.30.02	>=531.14
CUDA 12.0 Update 1	>=525.85.12	>=528.33
CUDA 12.0 GA	>=525.60.13	>=527.41
CUDA 11.8 GA	>=520.61.05	>=520.06
CUDA 11.7 Update 1	>=515.48.07	>=516.31

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Table 3 – continued from previous page

CUDA Toolkit	Toolkit Driver Version	
CUDA 11.7 GA	>=515.43.04	>=516.01
CUDA 11.6 Update 2	>=510.47.03	>=511.65
CUDA 11.6 Update 1	>=510.47.03	>=511.65
CUDA 11.6 GA	>=510.39.01	>=511.23
CUDA 11.5 Update 2	>=495.29.05	>=496.13
CUDA 11.5 Update 1	>=495.29.05	>=496.13
CUDA 11.5 GA	>=495.29.05	>=496.04
CUDA 11.4 Update 4	>=470.82.01	>=472.50
CUDA 11.4 Update 3	>=470.82.01	>=472.50
CUDA 11.4 Update 2	>=470.57.02	>=471.41
CUDA 11.4 Update 1	>=470.57.02	>=471.41
CUDA 11.4.0 GA	>=470.42.01	>=471.11
CUDA 11.3.1 Update 1	>=465.19.01	>=465.89
CUDA 11.3.0 GA	>=465.19.01	>=465.89
CUDA 11.2.2 Update 2	>=460.32.03	>=461.33
CUDA 11.2.1 Update 1	>=460.32.03	>=461.09
CUDA 11.2.0 GA	>=460.27.03	>=460.82
CUDA 11.1.1 Update 1	>=455.32	>=456.81
CUDA 11.1 GA	>=455.23	>=456.38
CUDA 11.0.3 Update 1	>= 450.51.06	>= 451.82
CUDA 11.0.2 GA	>= 450.51.05	>= 451.48
CUDA 11.0.1 RC	>= 450.36.06	>= 451.22
CUDA 10.2.89	>= 440.33	>= 441.22
CUDA 10.1 (10.1.105 general release, and updates)	>= 418.39	>= 418.96
CUDA 10.0.130	>= 410.48	>= 411.31
CUDA 9.2 (9.2.148 Update 1)	>= 396.37	>= 398.26
CUDA 9.2 (9.2.88)	>= 396.26	>= 397.44
CUDA 9.1 (9.1.85)	>= 390.46	>= 391.29
CUDA 9.0 (9.0.76)	>= 384.81	>= 385.54
CUDA 8.0 (8.0.61 GA2)	>= 375.26	>= 376.51
CUDA 8.0 (8.0.44)	>= 367.48	>= 369.30

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Table 3 – continued from previous page

<b>CUDA Toolkit</b>	<b>Toolkit Driver Version</b>	
CUDA 7.5 (7.5.16)	>= 352.31	>= 353.66
CUDA 7.0 (7.0.28)	>= 346.46	>= 347.62

For convenience, the NVIDIA driver is installed as part of the CUDA Toolkit installation. Note that this driver is for development purposes and is not recommended for use in production with Tesla GPUs.

For running CUDA applications in production with Tesla GPUs, it is recommended to download the latest driver for Tesla GPUs from the NVIDIA driver downloads site at <https://www.nvidia.com/drivers>.

During the installation of the CUDA Toolkit, the installation of the NVIDIA driver may be skipped on Windows (when using the interactive or silent installation) or on Linux (by using meta packages).

For more information on customizing the install process on Windows, see <https://docs.nvidia.com/cuda/cuda-installation-guide-microsoft-windows/index.html#install-cuda-software>.

For meta packages on Linux, see <https://docs.nvidia.com/cuda/cuda-installation-guide-linux/index.html#package-manager-metas>.

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# Chapter 2. New Features

This section lists new general CUDA and CUDA compilers features.

## 2.1. General CUDA

- ▶ This release introduces Heterogeneous Memory Management (HMM), allowing seamless sharing of data between host memory and accelerator devices. HMM is supported on Linux only and requires a recent kernel (6.1.24+ or 6.2.11+).

HMM requires the use of NVIDIA's GPU Open Kernel Modules driver.

As this is the first release of HMM, some limitations exist:

- ▶ GPU atomic operations on file-backed memory are not yet supported.
  - ▶ Arm CPUs are not yet supported.
  - ▶ HugeTLBfs pages are not yet supported on HMM (this is an uncommon scenario).
  - ▶ The `fork()` system call is not fully supported yet when attempting to share GPU-accessible memory between parent and child processes.
  - ▶ HMM is not yet fully optimized, and may perform slower than programs using `cudaMalloc()`, `cudaMallocManaged()`, or other existing CUDA memory management APIs. The performance of programs not using HMM will not be affected.
- ▶ The Lazy Loading feature (introduced in CUDA 11.7) is now enabled by default on Linux with the 535 driver. To disable this feature on Linux, set the environment variable `CUDA_MODULE_LOADING=EAGER` before launch. Default enablement for Windows will happen in a future CUDA driver release. To enable this feature on Windows, set the environment variable `CUDA_MODULE_LOADING=LAZY` before launch.
  - ▶ Host NUMA memory allocation: Allocate a CPU memory targeting a specific NUMA node using either the CUDA virtual memory management APIs or the CUDA stream-ordered memory allocator. Applications must ensure device accesses to pointer backed by HOST allocations from these APIs are performed only after they have explicitly requested accessibility for the memory on the accessing device. It is undefined behavior to access these host allocations from a device without accessibility for the address range, regardless of whether the device supports pageable memory access or not.
  - ▶ Added per-client priority mapping at runtime for CUDA Multi-Process Service (MPS). This allows multiple processes running under MPS to arbitrate priority at a coarse-grained level between multiple processes without changing the application code.

We introduce a new environment variable `CUDA_MPS_CLIENT_PRIORITY`, which accepts two values: `NORMAL` priority, 0, and `BELOW_NORMAL` priority, 1.

For example, given two clients, a potential configuration is as follows:

<pre>// Client 1's Environment export CUDA_MPS_CLIENT_PRIORITY=0 // NORMAL</pre>	<pre>// Client 2's Environment export CUDA_MPS_CLIENT_PRIORITY=1 // BELOW NORMAL</pre>
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## 2.2. CUDA Compilers

- ▶ `libNVVM` samples have been moved out of the toolkit and made publicly available on GitHub as part of the `NVIDIA/cuda-samples` project. Similarly, the `nvvmir-samples` have been moved from the `nvidia-compiler-sdk` project on GitHub to the new location of the `libNVVM` samples in the `NVIDIA/cuda-samples` project.
- ▶ For changes to PTX, refer to <https://docs.nvidia.com/cuda/parallel-thread-execution/#ptx-isa-version-8-2>.

## 2.3. CUDA Developer Tools

- ▶ For changes to `nvprof` and Visual Profiler, see the [changelog](#).
- ▶ For new features, improvements, and bug fixes in `CUPTI`, see the [changelog](#).
- ▶ For new features, improvements, and bug fixes in `Nsight Compute`, see the [changelog](#).
- ▶ For new features, improvements, and bug fixes in `Compute Sanitizer`, see the [changelog](#).
- ▶ For new features, improvements, and bug fixes in `CUDA-GDB`, see the [changelog](#).

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# Chapter 3. Resolved Issues

## 3.1. General CUDA

- ▶ Resolved potential soft lock-ups around `rm_run_nano_timer_callback()`. A Linux kernel device driver API used for timer management in the Linux kernel interface of the NVIDIA GPU driver was susceptible to a race condition under multi-GPU configurations.
- ▶ Fixed potential GSP-RM hang in `kernel_resolve_address()`.
- ▶ Removed potential GPUDirect RDMA driver crash in `nvidia_p2p_put_pages()`. The legacy non-persistent memory APIs allow third party driver to invoke `nvidia_p2p_put_pages` with a stale `page_table` pointer, which has already been freed by the RM callback as part of the process shutdown sequence. This behavior was broken when persistent memory support was added to the legacy `nvidia_p2p` APIs. We resolved the issue by providing new APIs: `nvidia_p2p_get/put_pages_persistent` for persistent memory. Thus, the original behavior of the legacy APIs for non-persistent memory is restored. This is essentially a change in the API, so although the `nvidia-peermem` is updated accordingly, external consumers of persistent memory mapping will need to be changed to use the new dedicated APIs.
- ▶ Resolved an issue in `watchcat syscall`.
- ▶ Fixed potential incorrect results in optimized code under high register pressure. NVIDIA has found that under certain rare conditions, a register spilling optimization in PTXAS could result in incorrect compilation results. This issue is fixed for offline compilation (non-JIT) in the CUDA 12.2 release and will be fixed for JIT compilation in the next enterprise driver update.

NVIDIA believes this issue to be extremely rare, and applications relying on JIT that are working successfully should not be affected.





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# Chapter 4. Deprecated or Dropped Features

Features deprecated in the current release of the CUDA software still work in the current release, but their documentation may have been removed, and they will become officially unsupported in a future release. We recommend that developers employ alternative solutions to these features in their software.

## **General CUDA**

- ▶ Ubuntu 18.04 support has reached EOL.

## **CUDA Tools**

- ▶ None.

## **CUDA Compiler**

- ▶ None.



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# Chapter 5. CUDA Libraries

This section covers CUDA Libraries release notes for 12.x releases.

- ▶ CUDA Math Libraries toolchain uses C++11 features, and a C++11-compatible standard library (libstdc++ >= 20150422) is required on the host.
- ▶ Support for the following compute capabilities is removed for all libraries:
  - ▶ sm\_35 (Kepler)
  - ▶ sm\_37 (Kepler)

## 5.1. cuBLAS Library

### 5.1.1. cuBLAS: Release 12.2

#### ▶ **Known Issues**

- ▶ cuBLAS initialization fails on Hopper architecture GPUs when MPS is in use with CUDA\_MPS\_ACTIVE\_THREAD\_PERCENTAGE set to a value less than 100%. There is currently no workaround for this issue.
- ▶ Some Hopper kernels produce incorrect results for batched matmuls with CUBLASLT\_EPILOGUE\_RELU\_BIAS or CUBLASLT\_EPILOGUE\_GELU\_BIAS and a non-zero CUBLASLT\_MATMUL\_DESC\_BIAS\_BATCH\_STRIDE. The kernels apply the first batch's bias vector to all batches. This will be fixed in a future release.

### 5.1.2. cuBLAS: Release 12.1 Update 1

#### ▶ **New Features**

- ▶ Support for FP8 on NVIDIA Ada GPUs.
- ▶ Improved performance on NVIDIA L4 Ada GPUs.
- ▶ Introduced an API that instructs the cuBLASLt library to not use some CPU instructions. This is useful in some rare cases where certain CPU instructions used by cuBLASLt heuristics negatively impact CPU performance. Refer to <https://docs.nvidia.com/cuda/cublas/index.html#disabling-cpu-instructions>.

#### ▶ **Known Issues**

- ▶ When creating a matrix layout using the `cublasLtMatrixLayoutCreate()` function, the object pointed at by `cublasLtMatrixLayout_t` is smaller than `cublasLtMatrixLayoutOpaque_t` (but enough to hold the internal structure). As a result, the object should not be dereferenced or copied explicitly, as this might lead to out of bound accesses. If one needs to serialize the layout or copy it, it is recommended to manually allocate an object of size `sizeof(cublasLtMatrixLayoutOpaque_t)` bytes, and initialize it using `cublasLtMatrixLayoutInit()` function. The same applies to `cublasLtMatmulDesc_t` and `cublasLtMatrixTransformDesc_t`. The issue will be fixed in future releases by ensuring that `cublasLtMatrixLayoutCreate()` allocates at least `sizeof(cublasLtMatrixLayoutOpaque_t)` bytes.

### 5.1.3. cuBLAS: Release 12.0 Update 1

#### ▶ **New Features**

- ▶ Improved performance on NVIDIA H100 SXM and NVIDIA H100 PCIe GPUs.

#### ▶ **Known Issues**

- ▶ For optimal performance on NVIDIA Hopper architecture, cuBLAS needs to allocate a bigger internal workspace (64 MiB) than on the previous architectures (8 MiB). In the current and previous releases, cuBLAS allocates 256 MiB. This will be addressed in a future release. A possible workaround is to set the `CUBLAS_WORKSPACE_CONFIG` environment variable to `:32768:2` when running cuBLAS on NVIDIA Hopper architecture.

#### ▶ **Resolved Issues**

- ▶ Reduced cuBLAS host-side overheads caused by not using the `cublasLt` heuristics cache. This began in the CUDA Toolkit 12.0 release.
- ▶ Added forward compatible single precision complex GEMM that does not require workspace.

### 5.1.4. cuBLAS: Release 12.0

#### ▶ **New Features**

- ▶ `cublasLtMatmul` now supports FP8 with a non-zero beta.
- ▶ Added `int64` APIs to enable larger problem sizes; refer to [64-bit integer interface](#).
- ▶ Added more Hopper-specific kernels for `cublasLtMatmul` with epilogues:
  - ▶ `CUBLASLT_EPILOGUE_BGRAD{A, B}`
  - ▶ `CUBLASLT_EPILOGUE_{RELU, GELU}_AUX`
  - ▶ `CUBLASLT_EPILOGUE_D{RELU, GELU}`
- ▶ Improved Hopper performance on `arm64-sbsa` by adding Hopper kernels that were previously supported only on the `x86_64` architecture for Windows and Linux.

#### ▶ **Known Issues**

- ▶ There are no forward compatible kernels for single precision complex gemms that do not require workspace. Support will be added in a later release.

#### ▶ **Resolved Issues**

- ▶ Fixed an issue on NVIDIA Ampere architecture and newer GPUs where `cublasLtMatmul` with epilogue `CUBLASLT_EPILOGUE_BGRAD{A, B}` and a nontrivial reduction scheme (that is, not `CUBLASLT_REDUCTION_SCHEME_NONE`) could return incorrect results for the bias gradient.
- ▶ `cublasLtMatmul` for gemv-like cases (that is, `m` or `n` equals 1) might ignore bias with the `CUBLASLT_EPILOGUE_RELU_BIAS` and `CUBLASLT_EPILOGUE_BIAS` epillogues.

### Deprecations

- ▶ Disallow including `cublas.h` and `cublas_v2.h` in the same translation unit.
- ▶ Removed:
  - ▶ `CUBLAS_MATMUL_STAGES_16x80` and `CUBLAS_MATMUL_STAGES_64x80` from `cublasLtMatmulStages_t`. No kernels utilize these stages anymore.
  - ▶ `cublasLt3mMode_t`, `CUBLASLT_MATMUL_PREF_MATH_MODE_MASK`, and `CUBLASLT_MATMUL_PREF_GAUSSIAN_MODE_MASK` from `cublasLtMatmulPreferenceAttributes_t`. Instead, use the corresponding flags from `cublasLtNumericalImplFlags_t`.
  - ▶ `CUBLASLT_MATMUL_PREF_POINTER_MODE_MASK`, `CUBLASLT_MATMUL_PREF_EPILOGUE_MASK`, and `CUBLASLT_MATMUL_PREF_SM_COUNT_TARGET` from `cublasLtMatmulPreferenceAttributes_t`. The corresponding parameters are taken directly from `cublasLtMatmulDesc_t`.
  - ▶ `CUBLASLT_POINTER_MODE_MASK_NO_FILTERING` from `cublasLtPointerModeMask_t`. This mask was only applicable to `CUBLASLT_MATMUL_PREF_MATH_MODE_MASK` which was removed.

## 5.2. cuFFT Library

### 5.2.1. cuFFT: Release 12.2

#### ▶ New Features

- ▶ `cufftSetStream` can be used in multi-GPU plans with a stream from any GPU context, instead of from the primary context of the first GPU listed in `cufftXtSetGPUs`.
- ▶ Improved performance of 1000+ of FFTs of sizes ranging from 62 to 16380. The improved performance spans hundreds of single precision and double precision cases for FFTs with contiguous data layout, across multiple GPU architectures (from Maxwell to Hopper GPUs) via PTX JIT.
- ▶ Reduced the size of the static libraries when compared to cuFFT in the 12.1 release.

#### ▶ Resolved Issues

- ▶ cuFFT no longer exhibits a race condition when threads simultaneously create and access plans with more than 1023 plans alive.
- ▶ cuFFT no longer exhibits a race condition when multiple threads call `cufftXtSetGPUs` concurrently.

## 5.2.2. cuFFT: Release 12.1 Update 1

### ▶ Known Issues

- ▶ cuFFT exhibits a race condition when one thread calls `cufftCreate` (or `cufftDestroy`) and another thread calls any API (except `cufftCreate` or `cufftDestroy`), and when the total number of plans alive exceeds 1023.
- ▶ cuFFT exhibits a race condition when multiple threads call `cufftXtSetGPUs` concurrently on different plans.

## 5.2.3. cuFFT: Release 12.1

### ▶ New Features

- ▶ Improved performance on Hopper GPUs for hundreds of FFTs of sizes ranging from 14 to 28800. The improved performance spans over 542 cases across single and double precision for FFTs with contiguous data layout.

### ▶ Known Issues

- ▶ Starting from CUDA 11.8, CUDA Graphs are no longer supported for callback routines that load data in out-of-place mode transforms. An upcoming release will update the cuFFT callback implementation, removing this limitation. cuFFT deprecated callback functionality based on separate compiled device code in cuFFT 11.4.

### ▶ Resolved Issues

- ▶ cuFFT no longer produces errors with compute-sanitizer at program exit if the CUDA context used at plan creation was destroyed prior to program exit.

## 5.2.4. cuFFT: Release 12.0 Update 1

### ▶ Resolved Issues

- ▶ Scratch space requirements for multi-GPU, single-batch, 1D FFTs were reduced.

## 5.2.5. cuFFT: Release 12.0

### ▶ New Features

- ▶ PTX JIT kernel compilation allowed the addition of many new accelerated cases for Maxwell, Pascal, Volta and Turing architectures.

### ▶ Known Issues

- ▶ cuFFT plan generation time increases due to PTX JIT compiling. Refer to [Plan Initialization Time](#).

### ▶ Resolved Issues

- ▶ cuFFT plans had an unintentional small memory overhead (of a few kB) per plan. This is resolved.

## 5.3. cuSOLVER Library

### 5.3.1. cuSOLVER: Release 12.2

#### ► New Features

- A new API to ensure deterministic results or allow non-deterministic results for improved performance. See `cusolverDnSetDeterministicMode()` and `cusolverDnGetDeterministicMode()`. Affected functions are: `cusolverDn<t>geqrf()`, `cusolverDn<t>syevd()`, `cusolverDn<t>syevdx()`, `cusolverDn<t>gesvdj()`, `cusolverDnXgeqrf()`, `cusolverDnXsyevd()`, `cusolverDnXsyevdx()`, `cusolverDnXgesvdr()`, and `cusolverDnXgesvdp()`.

#### ► Known Issues

- Concurrent executions of `cusolverDn<t>getrf()` or `cusolverDnXgetrf()` in different non-blocking CUDA streams on the same device might result in a deadlock.

## 5.4. cuSPARSE Library

### 5.4.1. cuSPARSE: Release 12.2 Update 1

#### ► New Features

- The library now provides the opportunity to dump sparse matrices to files during the creation of the descriptor for debugging purposes. See logging API <https://docs.nvidia.com/cuda/cusparsed/index.html#cusparsed-logging-api>.

#### ► Resolved Issues

- Removed `CUSPARSE_SPMM_CSR_ALG3` fallback to avoid confusion in the algorithm selection process.
- Clarified the supported operations for `cusparsedSDDMM()`.
- `cusparsedCreateConstSlicedE11()` now uses `const` pointers.
- Fixed wrong results in rare edge cases of `cusparsedCsr2CscEx2()` with base 1 indexing.
- `cusparsedSpSM_bufferSize()` could ask slightly less memory than needed.
- `cusparsedSpMV()` now checks the validity of the buffer pointer only when it is strictly needed.

#### ► Deprecations

- Several legacy APIs have been officially deprecated. A compile-time warning has been added to all of them.

## 5.4.2. cuSPARSE: Release 12.1 Update 1

### ► New Features

- Introduced Block Sparse Row (BSR) sparse matrix storage for the Generic APIs with support for SDDMM routine (`cusparseSDDMM`).
- Introduced Sliced Ellpack (SELL) sparse matrix storage format for the Generic APIs with support for sparse matrix-vector multiplication (`cusparseSpMV`) and triangular solver with a single right-hand side (`cusparseSpSV`).
- Added a new API call (`cusparseSpSV_updateMatrix`) to update matrix values and/or the matrix diagonal in the sparse triangular solver with a single right-hand side after the analysis step.

## 5.4.3. cuSPARSE: Release 12.0 Update 1

### ► New Features

- `cusparseSDDMM()` now supports mixed precision computation.
- Improved `cusparseSpMM()` alg2 mixed-precision performance on some matrices on NVIDIA Ampere architecture GPUs.
- Improved `cusparseSpMV()` performance with a new load balancing algorithm.
- `cusparseSpSV()` and `cusparseSpSM()` now support in-place computation, namely the output and input vectors/matrices have the same memory address.

### ► Resolved Issues

- `cusparseSpSM()` could produce wrong results if the leading dimension (ld) of the RHS matrix is greater than the number of columns/rows.

## 5.4.4. cuSPARSE: Release 12.0

### ► New Features

- JIT LTO functionalities (`cusparseSpMMOp()`) switched from driver to `nvJitLto` library. Starting from CUDA 12.0 the user needs to link to `libnvJitLto.so`, see [cuSPARSE documentation](#). JIT LTO performance has also been improved for `cusparseSpMMOpPlan()`.
- Introduced const descriptors for the Generic APIs, for example, `cusparseConstSpVecGet()`. Now the Generic APIs interface clearly declares when a descriptor and its data are modified by the cuSPARSE functions.
- Added two new algorithms to `cusparseSpGEMM()` with lower memory utilization. The first algorithm computes a strict bound on the number of intermediate product, while the second one allows partitioning the computation in chunks.
- Added `int8_t` support to `cusparseGather()`, `cusparseScatter()`, and `cusparseCsr2cscEx2()`.
- Improved `cusparseSpSV()` performance for both the analysis and the solving phases.
- Improved `cusparseSpSM()` performance for both the analysis and the solving phases.



- ▶ Improved `cusparseSDDMM()` performance and added support for batch computation.
- ▶ Improved `cusparseCsr2cscEx2()` performance.
- ▶ **Resolved Issues**
  - ▶ `cusparseSpSV()` and `cusparseSpSM()` could produce wrong results.
  - ▶ `cusparseDnMatGetStridedBatch()` did not accept `batchStride == 0`.
- ▶ **Deprecations**
  - ▶ Removed deprecated CUDA 11.x APIs, enumerators, and descriptors.

## 5.5. Math Library

### 5.5.1. CUDA Math: Release 12.2

- ▶ **New Features**
  - ▶ CUDA Math APIs for `__half` and `__nv_bfloat16` types received usability improvements, including host side <emulated> support for many of the arithmetic operations and conversions.
  - ▶ `__half` and `__nv_bfloat16` types have implicit conversions to/from integral types, which are now available with host compilers by default. These may cause build issues due to ambiguous overloads resolution. Users are advised to update their code to select proper overloads. To opt-out user may want to define the following macros (these macros will be removed in the future CUDA release):
    - ▶ `__CUDA_FP16_DISABLE_IMPLICIT_INTEGER_CONVERTS_FOR_HOST_COMPILERS__`
    - ▶ `__CUDA_BF16_DISABLE_IMPLICIT_INTEGER_CONVERTS_FOR_HOST_COMPILERS__`

#### Resolved Issues

- ▶ During ongoing testing, NVIDIA identified that due to an algorithm error the results of 64-bit floating-point division in default round-to-nearest-even mode could produce spurious overflow to infinity. NVIDIA recommends that all developers requiring strict IEEE754 compliance update to CUDA Toolkit 12.2 or newer. The affected algorithm was present in both offline compilation as well as just-in-time (JIT) compilation. As JIT compilation is handled by the driver, NVIDIA recommends updating to driver version greater than or equal to R535 (R536 on Windows) when IEEE754 compliance is required and when using JIT. This is a software algorithm fix and is not tied to specific hardware.
- ▶ Updated the observed worst case error bounds for single precision intrinsic functions `__expf()`, `__exp10f()` and double precision functions `asinh()`, `acosh()`.

## 5.5.2. CUDA Math: Release 12.1

### ► New Features

- Performance and accuracy improvements in `atanf`, `acosf`, `asinf`, `sinpif`, `cospif`, `powf`, `erff`, and `tgammaf`.

## 5.5.3. CUDA Math: Release 12.0

### ► New Features

- Introduced new integer/fp16/bf16 CUDA Math APIs to help expose performance benefits of new DPX instructions. Refer to <https://docs.nvidia.com/cuda/cuda-math-api/index.html>.

### Known Issues

- Double precision inputs that cause the double precision division algorithm in the default 'round to nearest even mode' produce spurious overflow: an infinite result is delivered where `DBL_MAX 0x7FEF_FFFF_FFFF_FFFF` is expected. Affected CUDA Math APIs: `__ddiv_rn()`. Affected CUDA language operation: double precision / operation in the device code.

### ► Deprecations

- All previously deprecated undocumented APIs are removed from CUDA 12.0.

## 5.6. NVIDIA Performance Primitives (NPP)

### 5.6.1. NPP: Release 12.0

#### ► Deprecations

- Deprecating non-CTX API support from next release.

#### ► Resolved Issues

- A performance issue with the NPP `ResizeSqrPixel` API is now fixed and shows improved performance.

## 5.7. nvJPEG Library

### 5.7.1. nvJPEG: Release 12.2

#### ► New Features

- Added support for JPEG Lossless decode (process 14, FO prediction).
- nvJPEG is now supported on L4T.

## 5.7.2. nvJPEG: Release 12.0

### ▶ **New Features**

- ▶ Improved the GPU Memory optimisation for the nvJPEG codec.

### ▶ **Resolved Issues**

- ▶ An issue that causes runtime failures when `nvJPEGDecMultipleInstances` was tested with a large number of threads is resolved.
- ▶ An issue with CMYK four component color conversion is now resolved.

### ▶ **Known Issues**

- ▶ Backend `NVJPEG_BACKEND_GPU_HYBRID` - Unable to handle bistreams with extra scans lengths.

### ▶ **Deprecations**

- ▶ The reuse of Huffman table in Encoder (`nvjpegEncoderParamsCopyHuffmanTables`).



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# Chapter 6. Notices

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