



Blackwell Tuning Guide

Release 13.0

NVIDIA Corporation

Nov 23, 2025

Contents

1	NVIDIA Blackwell GPU Architecture	3
2	CUDA Best Practices	5
3	Application Compatibility	7
4	NVIDIA Blackwell Tuning	9
4.1	Streaming Multiprocessor	9
4.1.1	Occupancy	9
4.1.2	Thread Block Clusters	9
4.2	Memory System	10
4.2.1	High-Bandwidth Memory HBM3 Subsystem	10
4.2.2	Increased L2 Capacity	10
4.2.3	Unified Shared Memory/L1/Texture Cache	10
4.3	Fifth-Generation NVLink	11
5	Revision History	13
6	Notices	15
6.1	Notice	15
6.2	OpenCL	16
6.3	Trademarks	16

Tuning CUDA Applications for Blackwell GPU Architecture

The programming guide for tuning CUDA Applications for GPUs based on the Blackwell GPU Architecture.

Chapter 1. NVIDIA Blackwell GPU Architecture

The NVIDIA® Blackwell GPU architecture is NVIDIA's latest architecture for CUDA® compute applications. The NVIDIA Blackwell GPU architecture retains and extends the same CUDA programming model provided by previous NVIDIA GPU architectures such as NVIDIA Ampere GPU architecture and NVIDIA Hopper. Applications that follow the best practices for those architectures should typically see speedups on the Blackwell GPUs without any code changes. This guide summarizes the ways that an application can be fine-tuned to gain additional speedups by leveraging the NVIDIA Blackwell GPU architecture's features.¹

For further details on the programming features discussed in this guide, refer to the [CUDA C++ Programming Guide](#).

¹ Throughout this guide, NVIDIA Volta refers to devices of compute capability 7.0, NVIDIA Turing refers to devices of compute capability 7.5, NVIDIA Ampere GPU Architecture refers to devices of compute capability 8.x, NVIDIA Hopper refers to devices of compute capability 9.0., and NVIDIA Blackwell refers to compute capability 10.0.

Chapter 2. CUDA Best Practices

The performance guidelines and best practices described in the [CUDA C++ Programming Guide](#) and the [CUDA C++ Best Practices Guide](#) apply to all CUDA-capable GPU architectures. Programmers must primarily focus on following those recommendations to achieve the best performance.

The high-priority recommendations from those guides are as follows:

- ▶ Find ways to parallelize sequential code.
- ▶ Minimize data transfers between the host and the device.
- ▶ Adjust kernel launch configuration to maximize device utilization.
- ▶ Ensure that global memory accesses are coalesced.
- ▶ Minimize redundant accesses to global memory whenever possible.
- ▶ Avoid long sequences of diverged execution by threads within the same warp.

Chapter 3. Application Compatibility

Before addressing specific performance tuning issues covered in this guide, refer to the [Blackwell Compatibility Guide for CUDA Applications](#) to ensure that your application is compiled in a way that is compatible with NVIDIA Blackwell.

Chapter 4. NVIDIA Blackwell Tuning

4.1. Streaming Multiprocessor

The NVIDIA Blackwell Streaming Multiprocessor (SM) provides the following improvements over the NVIDIA Hopper GPU architecture.

4.1.1. Occupancy

The maximum number of concurrent warps per SM is 64 for compute capability 10.0 and 48 for compute capability 12.0. Other [factors influencing warp occupancy](#) are:

- ▶ The register file size is 64K 32-bit registers per SM.
- ▶ The maximum number of registers per thread is 255.
- ▶ The maximum number of thread blocks per SM is 32 for devices of compute capability 10.0 and 12.0.
- ▶ For devices of compute capability 10.0 shared memory capacity per SM is 228 KB. For devices of compute capability 12.0, shared memory capacity per SM is 128KB.
- ▶ For devices of compute capability 10.0 the maximum shared memory per thread block is 227 KB. For devices of compute capability 12.0 the maximum shared memory per thread block is 99 KB.
- ▶ For applications using Thread Block Clusters, it is always recommended to compute the occupancy using `cudaOccupancyMaxActiveClusters` and launch cluster-based kernels accordingly.

Overall, developers can expect similar occupancy as on NVIDIA Hopper GPU architecture GPUs without changes to their application.

4.1.2. Thread Block Clusters

NVIDIA Hopper Architecture added a new optional level of hierarchy, Thread Block Clusters, that allows for further possibilities when parallelizing applications. Thread block clusters are supported by Blackwell GPUs as well. A thread block can read from, write to, and perform atomics in shared memory of other thread blocks within its cluster. This is known as Distributed Shared Memory. As demonstrated in the [CUDA C++ Programming Guide](#), there are applications that cannot fit required data within shared memory and must use global memory instead. Distributed shared memory can act as an intermediate step between these two options.

Distributed Shared Memory can be used by an SM simultaneously with L2 cache accesses. This can benefit applications that need to communicate data between SMs by utilizing the combined bandwidth of both distributed shared memory and L2.

In order to achieve best performance for accesses to Distributed Shared Memory, access patterns to those described in the [CUDA C++ Best Practices Guide for Global Memory](#) should be used. Specifically, accesses to Distributed Shared Memory should be coalesced and aligned to 32-byte segments, if possible. Access patterns with non-unit stride should be avoided if possible, which can be achieved by using local shared memory, similar to what is shown in the [CUDA C++ Best Practices Guide for Shared Memory](#).

The maximum portable cluster size supported is 8; however, NVIDIA Blackwell B200 GPU allows for a nonportable cluster size of 16 by opting in. Launching a kernel with a nonportable cluster size requires setting the `cudaFuncAttributeNonPortableClusterSizeAllowed` function attribute. Using larger cluster sizes may reduce the maximum number of active blocks across the GPU (refer to [Occupancy](#)).

4.2. Memory System

4.2.1. High-Bandwidth Memory HBM3 Subsystem

The NVIDIA B200 GPU has support for HBM3 and HBM3e memory, with capacity up to 180 GB.

4.2.2. Increased L2 Capacity

The NVIDIA GB200 GPU increases the L2 cache capacity to 126 MB.

The NVIDIA Blackwell architecture allows CUDA users to control the persistence of data in L2 cache similar to the NVIDIA Ampere GPU Architecture. For more information on the persistence of data in L2 cache, refer to the section on managing L2 cache in the [CUDA C++ Programming Guide](#).

4.2.3. Unified Shared Memory/L1/Texture Cache

The NVIDIA B200 GPU with compute capability 10.0 has the same the maximum capacity of the combined L1 cache, texture cache, and shared memory of 256 KB as the previous NVIDIA Hopper architecture.

In the NVIDIA Blackwell GPU architecture, the portion of the L1 cache dedicated to shared memory (known as the carveout) can be selected at runtime as in previous architectures such as NVIDIA Ampere Architecture and NVIDIA Volta, using `cudaFuncSetAttribute()` with the attribute `cudaFuncAttributePreferredSharedMemoryCarveout`. Both the NVIDIA H100 GPU and the NVIDIA B200 GPU support shared memory capacities of 0, 8, 16, 32, 64, 100, 132, 164, 196 and 228 KB per SM.

CUDA reserves 1 KB of shared memory per thread block. Hence, the B200 GPU enables a single thread block to address up to 227 KB of shared memory. To maintain architectural compatibility, static shared memory allocations remain limited to 48 KB, and an explicit opt-in is also required to enable dynamic allocations above this limit. See the [CUDA C++ Programming Guide](#) for details.

Like GPU architectures going back to NVIDIA Ampere Architecture (compute capability 8.x), the NVIDIA Blackwell GPU architecture combines the functionality of the L1 and texture caches into a unified L1/Texture cache which acts as a coalescing buffer for memory accesses, gathering up the data requested by the threads of a warp before delivery of that data to the warp. Another benefit of its union with shared memory, similar to previous architectures, is improvement in terms of both latency and bandwidth.

4.3. Fifth-Generation NVLink

The fifth generation of NVIDIA's high-speed NVLink interconnect is implemented in B200 GPUs, which significantly enhances multi-GPU scalability, performance, and reliability with more links per GPU, much faster communication bandwidth, and improved error-detection and recovery features.

NVLink operates transparently within the existing CUDA model. Transfers between NVLink-connected endpoints are automatically routed through NVLink, rather than PCIe. The `cudaDeviceEnablePeerAccess()` API call remains necessary to enable direct transfers (over either PCIe or NVLink) between GPUs. The `cudaDeviceCanAccessPeer()` can be used to determine if peer access is possible between any pair of GPUs.

Chapter 5. Revision History

Version 1.0

- ▶ Initial Public Release
- ▶ Added support for compute capability 10.0 and compute capability 12.0

Chapter 6. Notices

6.1. Notice

This document is provided for information purposes only and shall not be regarded as a warranty of a certain functionality, condition, or quality of a product. NVIDIA Corporation (“NVIDIA”) makes no representations or warranties, expressed or implied, as to the accuracy or completeness of the information contained in this document and assumes no responsibility for any errors contained herein. NVIDIA shall have no liability for the consequences or use of such information or for any infringement of patents or other rights of third parties that may result from its use. This document is not a commitment to develop, release, or deliver any Material (defined below), code, or functionality.

NVIDIA reserves the right to make corrections, modifications, enhancements, improvements, and any other changes to this document, at any time without notice.

Customer should obtain the latest relevant information before placing orders and should verify that such information is current and complete.

NVIDIA products are sold subject to the NVIDIA standard terms and conditions of sale supplied at the time of order acknowledgement, unless otherwise agreed in an individual sales agreement signed by authorized representatives of NVIDIA and customer (“Terms of Sale”). NVIDIA hereby expressly objects to applying any customer general terms and conditions with regards to the purchase of the NVIDIA product referenced in this document. No contractual obligations are formed either directly or indirectly by this document.

NVIDIA products are not designed, authorized, or warranted to be suitable for use in medical, military, aircraft, space, or life support equipment, nor in applications where failure or malfunction of the NVIDIA product can reasonably be expected to result in personal injury, death, or property or environmental damage. NVIDIA accepts no liability for inclusion and/or use of NVIDIA products in such equipment or applications and therefore such inclusion and/or use is at customer’s own risk.

NVIDIA makes no representation or warranty that products based on this document will be suitable for any specified use. Testing of all parameters of each product is not necessarily performed by NVIDIA. It is customer’s sole responsibility to evaluate and determine the applicability of any information contained in this document, ensure the product is suitable and fit for the application planned by customer, and perform the necessary testing for the application in order to avoid a default of the application or the product. Weaknesses in customer’s product designs may affect the quality and reliability of the NVIDIA product and may result in additional or different conditions and/or requirements beyond those contained in this document. NVIDIA accepts no liability related to any default, damage, costs, or problem which may be based on or attributable to: (i) the use of the NVIDIA product in any manner that is contrary to this document or (ii) customer product designs.

No license, either expressed or implied, is granted under any NVIDIA patent right, copyright, or other NVIDIA intellectual property right under this document. Information published by NVIDIA regarding third-party products or services does not constitute a license from NVIDIA to use such products or

services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property rights of the third party, or a license from NVIDIA under the patents or other intellectual property rights of NVIDIA.

Reproduction of information in this document is permissible only if approved in advance by NVIDIA in writing, reproduced without alteration and in full compliance with all applicable export laws and regulations, and accompanied by all associated conditions, limitations, and notices.

THIS DOCUMENT AND ALL NVIDIA DESIGN SPECIFICATIONS, REFERENCE BOARDS, FILES, DRAWINGS, DIAGNOSTICS, LISTS, AND OTHER DOCUMENTS (TOGETHER AND SEPARATELY, "MATERIALS") ARE BEING PROVIDED "AS IS." NVIDIA MAKES NO WARRANTIES, EXPRESSED, IMPLIED, STATUTORY, OR OTHERWISE WITH RESPECT TO THE MATERIALS, AND EXPRESSLY DISCLAIMS ALL IMPLIED WARRANTIES OF NONINFRINGEMENT, MERCHANTABILITY, AND FITNESS FOR A PARTICULAR PURPOSE. TO THE EXTENT NOT PROHIBITED BY LAW, IN NO EVENT WILL NVIDIA BE LIABLE FOR ANY DAMAGES, INCLUDING WITHOUT LIMITATION ANY DIRECT, INDIRECT, SPECIAL, INCIDENTAL, PUNITIVE, OR CONSEQUENTIAL DAMAGES, HOWEVER CAUSED AND REGARDLESS OF THE THEORY OF LIABILITY, ARISING OUT OF ANY USE OF THIS DOCUMENT, EVEN IF NVIDIA HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES. Notwithstanding any damages that customer might incur for any reason whatsoever, NVIDIA's aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the Terms of Sale for the product.

6.2. OpenCL

OpenCL is a trademark of Apple Inc. used under license to the Khronos Group Inc.

6.3. Trademarks

NVIDIA and the NVIDIA logo are trademarks or registered trademarks of NVIDIA Corporation in the U.S. and other countries. Other company and product names may be trademarks of the respective companies with which they are associated.

Copyright

©2022-2025, NVIDIA Corporation & affiliates. All rights reserved