



# DATA CENTER GPU MANAGER

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## User Guide



# TABLE OF CONTENTS

<b>Chapter 1. Overview</b> .....	<b>1</b>
1.1. What is DCGM.....	1
1.2. Focus Areas.....	2
1.3. Target Users.....	3
<b>Chapter 2. Getting Started</b> .....	<b>4</b>
2.1. Supported Platforms.....	4
2.2. Installation.....	5
2.3. Basic Components.....	7
2.4. Modes of Operation.....	7
2.4.1. Embedded Mode.....	8
2.4.2. Standalone Mode.....	9
2.5. Static Library.....	9
<b>Chapter 3. Feature Overview</b> .....	<b>10</b>
3.1. Groups.....	11
3.2. Configuration.....	13
3.3. Policy.....	15
3.3.1. Notifications.....	15
3.3.2. Actions.....	17
3.4. Job Stats.....	18
3.5. Health and Diagnostics.....	20
3.5.1. Background Health Checks.....	20
3.5.2. Active Health Checks.....	21
3.6. Topology.....	23
3.7. NVlink Counters.....	24
3.8. Field Groups.....	24
3.9. Link Status.....	25
3.10. Profiling Metrics.....	26
3.10.1. Metrics.....	27
3.10.2. Multiplexing of Profiling Counters.....	31
3.10.3. Profiling Sampling Rate.....	32
3.10.4. Concurrent Usage of NVIDIA Profiling Tools.....	33
3.10.5. CUDA Test Generator (dcgmpoftester).....	33
3.10.6. Metrics on Multi-Instance GPU.....	35
3.10.6.1. Example 1.....	35
3.10.7. Platform Support.....	39
<b>Chapter 4. Integrating with DCGM</b> .....	<b>40</b>
4.1. Integrating with DCGM Reader.....	40
4.1.1. Reading Using the Dictionary.....	40
4.1.2. Reading Using Inheritance.....	41
4.1.3. Completing the Proof of Concept.....	42

4.1.4. Additional Customization.....	42
4.2. Integrating with Prometheus and Grafana.....	43
4.2.1. Starting the Prometheus Server.....	43
4.2.2. Starting the Prometheus Client.....	44
4.2.3. Integrating with Grafana.....	45
4.2.4. Customizing the Prometheus Client.....	49
<b>Chapter 5. DCGM Diagnostics.....</b>	<b>51</b>
5.1. Overview.....	51
5.1.1. DCGM Diagnostics Goals.....	51
5.1.2. Beyond the Scope of the DCGM Diagnostics.....	52
5.1.3. Dependencies.....	52
5.1.4. Supported Products.....	52
5.2. Using DCGM Diagnostics.....	53
5.2.1. Command line options.....	53
5.2.2. Usage Examples.....	57
5.2.3. Configuration file.....	58
5.2.4. Global parameters.....	58
5.2.5. GPU parameters.....	59
5.2.6. Test Parameters.....	60
5.3. Overview of Plugins.....	61
5.3.1. Deployment Plugin.....	61
5.3.2. PCIe - GPU Bandwidth Plugin.....	62
5.3.3. Memory Bandwidth Plugin.....	68
5.3.4. SM Stress Plugin.....	69
5.3.5. Hardware Diagnostic Plugin.....	72
5.3.6. Targeted Stress Plugin.....	75
5.3.7. Power Plugin.....	78
5.4. Test Output.....	80
5.4.1. JSON Output.....	80
<b>Chapter 6. DCGM Modularity.....</b>	<b>81</b>
6.1. Module List.....	81
6.2. Blacklisting Modules.....	82



# Chapter 1.

## OVERVIEW

### 1.1. What is DCGM

The NVIDIA® Data Center GPU Manager (DCGM) simplifies administration of NVIDIA Tesla GPUs in cluster and datacenter environments. At its heart, DCGM is an intelligent, lightweight user space library/agent that performs a variety of functions on each host system:

- ▶ GPU behavior monitoring
- ▶ GPU configuration management
- ▶ GPU policy oversight
- ▶ GPU health and diagnostics
- ▶ GPU accounting and process statistics
- ▶ NVSwitch configuration and monitoring

This functionality is accessible programmatically through public APIs and interactively through CLI tools. It is designed to be run either as a standalone entity or as an embedded library within management tools.

This document is intended as an overview of DCGM's main goals and features and is intended for system administrators, ISV developers, and individual users managing groups of Tesla GPUs.

#### TERMINOLOGY

Term	Meaning
DCGM	NVIDIA's Datacenter GPU Manager
NVIDIA Host Engine	Standalone executable wrapper for DCGM shared library
Host Engine daemon	Daemon mode of operation for the NVIDIA Host Engine

Term	Meaning
Fabric Manager	A module within the Host Engine daemon that supports NVSwitch fabric on DGX-2 or HGX-2.
3rd-party DCGM Agent	Any node-level process from a 3rd-party that runs DCGM in Embedded Mode
Embedded Mode	DCGM executing as a shared library within a 3rd-party DCGM agent
Standalone Mode	DCGM executing as a standalone process via the Host Engine
System Validation	Health checks encompassing the GPU, board and surrounding environment
HW diagnostic	System validation component focusing on GPU hardware correctness
RAS event	Reliability, Availability, Serviceability event. Corresponding to both fatal and non-fatal GPU issues
NVML	NVIDIA Management Library

## 1.2. Focus Areas

DCGM's design is geared towards the following key functional areas.

*Manage GPUs as collections of related resources.* In the majority of large-scale GPU deployments there are multiple GPUs per host, and often multiple hosts per job. In most cases there is a strong desire to ensure homogeneity of behavior across these related resources, even as specific expectations may change from job to job or user to user, and even as multiple jobs may use resources on the same host simultaneously. DCGM applies a group-centric philosophy to node level GPU management.

*Configure NVSwitches.* On DGX-2 or HGX-2, all GPUs communicate by way of NVSwitch. The Fabric Manager component of DCGM configures the switches to form a single memory fabric among all participating GPUs, and monitors the NVLinks that support the fabric.

*Define and enforce GPU configuration state.* The behavior of NVIDIA GPUs can be controlled by users to match requirements of particular environments or applications. This includes performance characteristics such as clock settings, exclusivity constraints like compute mode, and environmental controls like power limits. DCGM provides enforcement and persistence mechanisms to ensure behavioral consistency across related GPUs.

*Automate GPU management policies.* NVIDIA GPUs have advanced capabilities that facilitate error containment and identify problem areas. Automated policies that define

GPU response to certain classes of events, including recovery from errors and isolation of bad hardware, ensure higher reliability and a simplified administration environment. DCGM provides policies for common situations that require notification or automated action.

*Provide robust, online health and diagnostics.* The ability to ascertain the health of a GPU and its interaction with the surrounding system is a critical management need. This need comes in various forms, from passive background monitoring to quick system validation to extensive hardware diagnostics. In all cases it is important to provide these features with minimal impact on the system and minimal additional environmental requirements. DCGM provides extensive automated and non-automated health and diagnostic capabilities.

*Enable job-level statistics and accounting.* Understanding GPU usage is important for schedulers and resource managers. Tying this information together with RAS events, performance information and other telemetry, especially at the boundaries of a workload, is very useful in explaining job behavior and root-causing potential performance or execution issues. DCGM provides mechanism to gather, group and analyze data at the job level.

## 1.3. Target Users

DCGM is targeted at the following users:

- ▶ OEMs and ISVs wishing to improve GPU integration within their software.
- ▶ Datacenter admins managing their own GPU enabled infrastructure.
- ▶ Individual users and FAEs needing better insight into GPU behavior, especially during problem analysis.
- ▶ All DGX-2 and HGX-2 users will use the Fabric Manager to configure and monitor the NVSwitch fabric.

DCGM provides different interfaces to serve different consumers and use cases. Programmatic access via C and Python is geared towards integration with 3rd-party software. Python interfaces are also geared towards admin-centric scripting environments. CLI-based tools are present to provide an interactive out-of-the-box experience for end users. Each interface provides roughly equivalent functionality.

# Chapter 2.

## GETTING STARTED

### 2.1. Supported Platforms

DCGM currently supports the following products and environments:

- ▶ All K80 and newer Tesla GPUs
- ▶ NVSwitch on DGX A100, HGX A100. Note that for DGX-2 and HGX-2 systems, while a minimum version of DCGM 1.7 is required, DCGM 2.0 is recommended.
- ▶ All Maxwell and newer non-Tesla GPUs



Starting with v1.3, limited DCGM functionality is available on non-Tesla GPUs. More details are available in the section [Feature Overview](#).

- ▶ CUDA 7.5+ and NVIDIA Driver R418+

NVIDIA Driver R450 and later is required on systems using NVSwitch, such as DGX A100 or HGX A100. Starting with DCGM 2.0, Fabric Manager (FM) for NVSwitch systems is no longer bundled with DCGM packages. FM is a separate artifact that can be installed using the CUDA network repository. For more information, see the [Fabric Manager User Guide](#).

- ▶ Bare metal and virtualized (full passthrough only)
- ▶ Supported Linux distributions and architectures are shown in the table below:

Table 1 Linux Distributions and Architectures

Linux Distribution	x86 (x86_64)	Arm (aarch64)	POWER (ppc64le)
RHEL 8.y	X	X	X
RHEL/CentOS 7.y	X		
SLES 15	X	X	
Ubuntu 20.04 LTS	X	X	
Ubuntu 18.04 LTS	X	X	




Linux Distribution	x86 (x86_64)	Arm (aarch64)	POWER (ppc64le)
Ubuntu 16.04 LTS	X		

## 2.2. Installation

To run DCGM the target system must include the following NVIDIA components, listed in dependency order:

1. Supported [NVIDIA Datacenter Driver](#)
2. Supported CUDA Toolkit
3. DCGM Runtime and SDK
4. DCGM Python bindings (if desired)

All of the core components are available as RPMs/DEBs from NVIDIA's website. The Python bindings are available in the `/usr/src/dcgm/bindings` directory after installation. The user must be root or have sudo privileges for installation, as for any such packaging operations.

 DCGM is tested and designed to run with NVIDIA Datacenter Drivers. Attempting to run on other drivers, such as a developer driver, could result in missing functionality.

To remove the previous installation (if any), perform the following steps (e.g. on an RPM-based system).

1. Make sure that the `nv-hostengine` is not running. You can stop it using the following command

```
# sudo nv-hostengine -t
```

2. Remove the previous installation.

```
# sudo yum remove datacenter-gpu-manager
```

It is recommended to install DCGM via Linux package managers from the CUDA network repository.

### ► Install DCGM on Ubuntu

1. Install repository meta-data. Note substitute `<architecture>` as **x86\_64**, **sbsa** or **ppc64le** as appropriate.

```
$ distribution=$(cat /etc/os-release;echo $ID$VERSION_ID | sed -e 's/\./g')
```

```
$ echo "deb http://developer.download.nvidia.com/compute/cuda/repos/$distribution/<architecture>/" | sudo tee /etc/apt/sources.list.d/cuda.list
```

2. Trust the CUDA public GPG key

When installing on Ubuntu 20.04/18.04:

```
$ sudo apt-key adv --fetch-keys https://developer.download.nvidia.com/compute/cuda/repos/$distribution/<architecture>/7fa2af80.pub
```

When installing on Ubuntu 16.04:

```
$ sudo apt-key adv --fetch-keys http://developer.download.nvidia.com/compute/cuda/repos/$distribution/<architecture>/7fa2af80.pub
```

Pin file to prioritize CUDA repository:

```
$ wget https://developer.download.nvidia.com/compute/cuda/repos/$distribution/<architecture>/cuda-$distribution.pin
```

```
$ sudo mv cuda-$distribution.pin /etc/apt/preferences.d/cuda-repository-pin-600
```

3. Update the Apt repository cache

```
$ sudo apt-get update
```

4. Install DCGM

```
$ sudo apt-get install -y datacenter-gpu-manager
```

5. Enable DCGM systemd service (on reboot) and start it now

```
$ sudo systemctl --now enable nvidia-dcgm
```

#### ► Install DCGM on RHEL

1. Install repository meta-data and GPG key. Note substitute <architecture> as **x86\_64**, **sbsa** or **ppc64le** as appropriate.

```
$ distribution=$(. /etc/os-release;echo $ID`rpm -E "%{?rhel}%{?fedora}"`)
```

```
$ sudo dnf config-manager --add-repo http://developer.download.nvidia.com/compute/cuda/repos/$distribution<architecture>/cuda-rhel8.repo
```

2. Update metadata

```
$ sudo dnf clean expire-cache
```

3. Install DCGM

```
$ sudo dnf install -y datacenter-gpu-manager
```

4. Enable DCGM systemd service (on reboot) and start it now

```
$ sudo systemctl --now enable nvidia-dcgm
```

Note that the default **nvidia-dcgm.service** files included in the installation package use the systemd format. If DCGM is being installed on OS distributions that use the **init.d** format, then these files may need to be modified.

To verify installation, start the standalone host engine and use **dcgmi** to query the system. You should see a listing of all supported GPUs:

```
# nv-hostengine
Starting host engine using port number : 5555

# dcgmi discovery -l
2 GPUs found.
+-----+-----+-----+-----+-----+-----+-----+-----+-----+-----+
| GPU ID | Device Information |
+-----+-----+-----+-----+-----+-----+-----+-----+-----+-----+
| 0      | Name: Tesla K80   |
```

```

|          | PCI Bus ID: 0000:07:00.0          |
|          | Device UUID: GPU-0000000000000000000000000000000000000000000000000000000000000000 |
+-----+-----+
| 1       | Name: Tesla K80                  |
|          | PCI Bus ID: 0000:08:00.0          |
|          | Device UUID: GPU-111111111111111111111111111111111111111111111111115 |
+-----+-----+

# nv-hostengine -t
Host engine successfully terminated.

```

## 2.3. Basic Components

### DCGM shared library

The user space shared library, `libdcgm.so`, is the core component of DCGM. This library implements the major underlying functionality and exposes this as a set of C-based APIs. It sits on top of the NVIDIA driver, NVML, and the CUDA Toolkit.

### NVIDIA Host Engine

The NVIDIA host engine, `nv-hostengine`, is a thin wrapper around the DCGM shared library. Its main job is to instantiate the DCGM library as a persistent standalone process, including appropriate management of the monitoring and management activities.



- ▶ DCGM can run as root or non-root. Some DCGM functionality, such as configuration management, are not allowed to be run as non-root.
- ▶ On DGX-2 or HGX-2, `nv-hostengine` must run as root to enable the Fabric Manager.

### DCGM CLI Tool

The command line interface to DCGM, `dcgmi`, is a network-capable interface into the NVIDIA host engine. It exposes much of the DCGM functionality in a simple, interactive format. It is intended for users and admins who want to control DCGM, or gather relevant data, without needing to build against the programmatic interfaces. It is not intended for scripting.

### Python Bindings

The Python bindings are included with the DCGM package and installed in `/usr/src/dcgm/bindings`.

### Software Development Kit

The DCGM SDK includes examples of how to leverage major DCGM features, alongside API documentation and headers. The SDK includes coverage for both C and Python based APIs, and include examples for using DCGM in both standalone and embedded modes.

These are installed in `/usr/src/dcgm/sdk_samples`.

## 2.4. Modes of Operation

The core DCGM library can be run as a standalone process or be loaded by an agent as a shared library. In both cases it provides roughly the same class of functionality and has

the same overall behavior. The choice of mode depends on how it best fits within the user's existing environment.



In both modes the DCGM library should be run as root. Many features will not work without privileged access to the GPU, including various configuration settings and diagnostics.

## 2.4.1. Embedded Mode

In this mode the agent is loaded as a shared library. This mode is provided for the following situations:

- ▶ A 3rd-party agent already exists on the node, and
- ▶ Extra jitter associated with an additional autonomous agent needs to be managed

By loading DCGM as a shared library and managing the timing of its activity, 3rd-party agents can control exactly when DCGM is actively using CPU and GPU resources.

In this mode the 3rd-party agent should generally load the shared library at system initialization and manage the DCGM infrastructure over the lifetime of the host. Since DCGM is stateful, it is important that the library is maintained over the life of the 3rd-party agent, not invoked in a one-off fashion. In this mode all data gathering loops, management activities, etc. can be explicitly invoked and controlled via library interfaces. A 3rd-party agent may choose, for example, to synchronize DCGM activities across an entire multi-node job in this way.



**Caution** In this mode it is important that the various DCGM management interfaces be executed by the 3rd-party within the designated frequency ranges, as described in the API definitions. Running too frequently will waste resources with no noticeable gain. Running too infrequently will allow for gaps in monitoring and management coverage.

Working in this mode requires a sequence of setup steps and a management thread within the 3rd-party agent that periodically triggers all necessary DCGM background work. The logic is roughly as follows:

- ▶ On Agent Startup

```
dcgmInit()

System or job-level setup, e.g.
call dcgmGroupCreate() to set up GPU groups
call dcgmWatchFields() to manage watched metrics
call dcgmPolicySet() to set policy
```

- ▶ Periodic Background Tasks (managed)

```
Trigger system management behavior, i.e.
call dcgmUpdateAllFields() to manage metrics
call dcgmPolicyTrigger() to manage policies

Gather system data, e.g.
call dcgmHealthCheck() to check health
call dcgmGetLatestValues() to get metric updates
```

- ▶ On Agent Shutdown

```
dcgmShutdown()
```



For a more complete example see the Embedded Mode example in the DCGM SDK

## 2.4.2. Standalone Mode

In this mode the DCGM agent is embedded in a simple daemon provided by NVIDIA, the NVIDIA Host Engine. This mode is provided for the following situations:

- ▶ DCGM clients prefer to interact with a daemon rather than manage a shared library resource themselves
- ▶ Multiple clients wish to interact with DCGM, rather than a single node agent
- ▶ Users wish to leverage the NVIDIA CLI tool, DCGMI
- ▶ Users of DGX-2 or HGX-2 systems will need to run the Host Engine daemon to configure and monitor the NVSwitches

Generally, NVIDIA prefers this mode of operation, as it provides the most flexibility and lowest maintenance cost to users. In this mode the DCGM library management routines are invoked transparently at default frequencies and with default behaviors, in contrast to the user control provided by the Embedded Mode. Users can either leverage DCGMI tool to interact with the daemon process or load the DCGM library with daemon's IP address during initialization for programmatic interaction.

The daemon leverages a socket-based interface to speak with external processes, e.g. DCGMI. Users are responsible for configuring the system initialization behavior, post DCGM install, to ensure the daemon is properly executed on startup.



- ▶ Helper installation scripts for daemon setup will be included in the next Release Candidate package.
- ▶ On DGX-2 or HGX-2 systems, `nv-hostengine` is automatically started at system boot time, so that the Fabric Manager can configure and monitor the NVSwitches.

## 2.5. Static Library

A statically-linked stub version of the DCGM library has been included for the purposes of being able to remove an explicit dependency on the DCGM shared library. This library provides wrappers to the DCGM symbols and uses `dlopen()` to dynamically access `libdcgm.so`. If the shared library is not installed, or cannot be found in the `LD_LIBRARY_PATH`, an error code is returned. When linking against this library `libdl` must be included in the compile line which is typically done using:

```
# gcc foo.c -o foo -ldcgm_stub -ldl
```

# Chapter 3.

## FEATURE OVERVIEW

The following sections review key DCGM features, along with examples of input and output using the DCGMI tool. Common usage scenarios and suggested best practices are included as well. Starting with v1.3, DCGM is supported on non-Tesla GPUs. The following table lists the features available on different GPU products.

Feature Group	Support Status			
	Tesla	Titan	Quadro	GeForce
Field Value Watches (GPU metrics)	X	X	X	X
Configuration Management	X	X	X	X
Active Health Checks (GPU subsystems)	X	X	X	X
Job Statistics	X	X	X	X
Topology	X	X	X	X
Introspection	X	X	X	X
Policy Notification	X			
GPU Diagnostics (Diagnostic Levels - 1, 2, 3)	All Levels	Level 1	Level 1	Level 1



While DCGM interfaces are shown, all functionality below is accessible via the C and Python APIs as well.

## 3.1. Groups

Almost all DCGM operations take place on groups. Users can create, destroy and modify collections of GPUs on the local node, using these constructs to control all subsequent DCGM activities.

Groups are intended to help the user manage collections of GPUs as a single abstract resource, usually correlated to the scheduler's notion of a node-level job. By working in this way clients can ask question about the entire job, such as job-level health, without needing to track the individual resources.



**# Note:** Today DCGM does not enforce group behavior beyond itself, e.g. through OS isolation mechanisms like cgroups. It is expected that clients do this externally. The ability for clients to opt-in to DCGM enforcement of this state is likely in the future.

In machines with only one GPU the group concept can be ignored altogether, as all DCGM operations that require a group can use one containing that sole GPU. For convenience, at init, DCGM creates a default group representing all supported GPUs in the system.

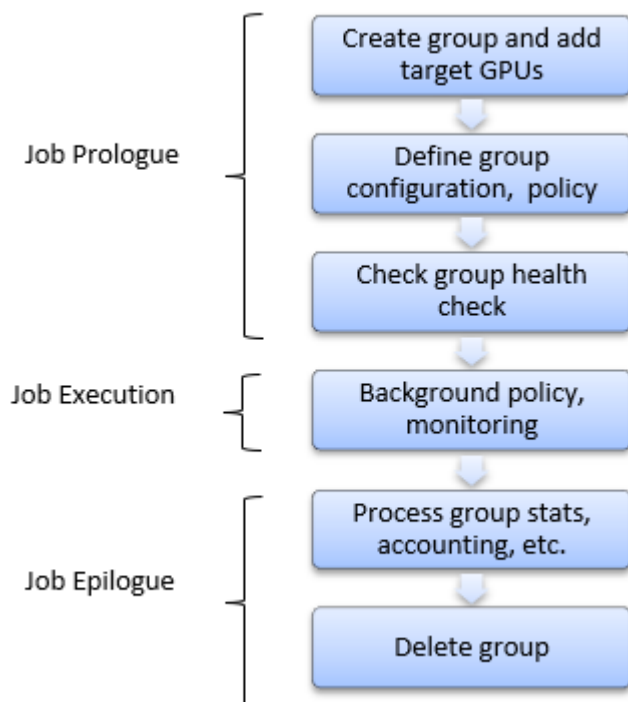
Groups in DCGM need not be disjoint. In many cases it may make sense to maintain overlapping groups for different needs. Global groups, consisting of all GPUs in the system, are useful for node-level concepts such as global configuration or global health. Partitioned groups, consisting of only a subset of GPUs, are useful for job-level concepts such as job stats and health.



**Tip** It is recommended that the client maintain one long-lived global group for node-level activities. For systems with multiple transient concurrent workloads it is recommended that additional partitioned groups be maintained on a per-job basis.

For example, a group created to manage the GPUs associated with a single job might have the following lifecycle. During prologue operations the group is created, configured, and used to verify the GPUs are ready for work. During epilogue operations the groups is used to extract target information. And while the job is running, DCGM works in the background to handle the requested behaviors.

Managing groups is very simple. Using the `dcgmi group` subcommand, the following example shows how to create, list and delete a group.



```
# dcgmi group -c GPU_Group
Successfully created group "GPU_Group" with a group ID of 1
```

```
# dcgmi group -l
1 group found.
```

```
+-----+
| GROUPS                                     |
+-----+-----+
| Group ID   | 1                                     |
| Group Name | GPU_Group                             |
| GPU ID(s)  | None                                   |
+-----+-----+
```

```
# dcgmi group -d 1
Successfully removed group 1
```

To add GPUs to a group it is first necessary to identify them. This can be done by first asking DCGM for all supported GPUs in the system.

```
# dcgmi discovery -l
2 GPUs found.
```

```
+-----+-----+
| GPU ID | Device Information                       |
+-----+-----+
| 0      | Name: Tesla K80                         |
|        | PCI Bus ID: 0000:07:00.0                 |
|        | Device UUID: GPU-00000000000000000000000000000000 |
+-----+-----+
| 1      | Name: Tesla K80                         |
|        | PCI Bus ID: 0000:08:00.0                 |
|        | Device UUID: GPU-11111111111111111111111111111111 |
+-----+-----+
```

```
# dcgmi group -g 1 -a 0,1
Add to group operation successful.
```



```
# dcgmi group -g 1 -i
+-----+
| GROUPS                                     |
+-----+-----+
| Group ID      | 1                                     |
| Group Name    | GPU_Group                             |
| GPU ID(s)    | 0, 1                                   |
+-----+-----+
```

## 3.2. Configuration

An important aspect of managing GPUs, especially in multi-node environments, is ensuring consistent configuration across workloads and across devices. In this context the term *configuration* refers to the set of administrative parameters exposed by NVIDIA to tune GPU behavior. DCGM makes it easier for clients to define target configurations and ensure those configurations are maintained over time.

It is important to note that different GPU properties have different levels of persistence. There are two broad categories:

- ▶ Device InfoROM lifetime
  - ▶ Non-volatile memory on each board, holding certain configurable firmware settings.
  - ▶ Persists indefinitely, though firmware can be flashed.
- ▶ GPU initialization lifetime
  - ▶ Driver level data structures, holding volatile GPU runtime information.
  - ▶ Persists until the GPU is de-initialized by the kernel mode driver.

DCGM is primarily focused on maintaining configuration settings that fall into the second category. These settings are normally volatile, potentially resetting each time a GPU becomes idle or is reset. By using DCGM a client can ensure that these settings persist over the desired lifetime.

In most common situations the client should be expected to define a configuration for all GPUs in the system (global group) at system initialization, or define individual partitioned group settings on a per-job basis. Once a configuration has been defined DCGM will enforce that configuration, for example across driver restarts, GPU resets or at job start.

DCGM currently supports the follows configuration settings:

Setting	Description	Defaults
Sync Boost	Coordinate Auto Boost across GPUs in the group	None
Target Clocks	Attempt to maintain fixed clocks at the target values	None
ECC Mode	Enable ECC protection throughout the GPU's memory	Usually On

Setting	Description	Defaults
Power Limit	Set the maximum allowed power consumption	Varies
Compute Mode	Limit concurrent process access to the GPU	No restrictions

To define a target configuration for a group, use the `dcgmi config` subcommand. Using the group created in the section above, the following example shows how to set a compute mode target and then list the current configuration state.

```
# dcgmi config -g 1 --set -c 2
Configuration successfully set.
#dcgmi config -g 1 --get
```

GPU_Group	TARGET CONFIGURATION	CURRENT CONFIGURATION
Group of 2 GPUs		
Sync Boost	Not Specified	Disabled
SM Application Clock	Not Specified	****
Memory Application Clock	Not Specified	****
ECC Mode	Not Specified	****
Power Limit	Not Specified	****
Compute Mode	E. Process	E. Process

```
**** Non-homogenous settings across group. Use with -v flag to see details.

#dcgmi config -g 1 --get --verbose
```

GPU ID: 0	TARGET CONFIGURATION	CURRENT CONFIGURATION
Tesla K20c		
Sync Boost	Not Specified	Disabled
SM Application Clock	Not Specified	705
Memory Application Clock	Not Specified	2600
ECC Mode	Not Specified	Disabled
Power Limit	Not Specified	225
Compute Mode	E. Process	E. Process

GPU ID: 1	TARGET CONFIGURATION	CURRENT CONFIGURATION
GeForce GT 430		
Sync Boost	Not Specified	Disabled
SM Application Clock	Not Specified	562
Memory Application Clock	Not Specified	2505
ECC Mode	Not Specified	Enabled
Power Limit	Not Specified	200
Compute Mode	E. Process	E. Process

Once a configuration is set, DCGM maintains the notion of Target and Current state. Target tracks the user's request for configuration state while Current tracks the actual state of the GPU and group. These are generally maintained such that they are equivalent with DCGM restoring current state to target in situations where that state is lost or changed. This is common in situations where DCGM has executed some invasive policy like a health check or GPU reset.

## 3.3. Policy

DCGM provides a way for clients to configure automatic GPU behaviors in response to various conditions. This is useful for event->action situations, such as GPU recovery in the face of serious errors. It's also useful for event->notification situations, such as when a client wants to be warned if a RAS event occurs. In both scenarios the client must define a condition on which to trigger further behavior. These conditions are specified from a predefined set of possible metrics. In some cases the client must also provide a threshold above/below which the metric condition is triggered. Generally, conditions are fatal and non-fatal RAS events, or performance-oriented warnings. These include the following examples:

Condition	Type	Threshold	Description
PCIe/NVLINK Errors	Fatal	Hardcoded	Uncorrected, or corrected above SDC threshold
ECC Errors	Fatal	Hardcoded	Single DBE, multiple co-located SBEs
Page Retirement Limit	Non-Fatal	Settable	Lifetime limit for ECC errors, or above RMA rate
Power Excursions	Performance	Settable	Excursions above specified board power threshold
Thermal Excursions	Performance	Settable	Excursions above specified GPU thermal threshold
XIDs	All	Hardcoded	XIDs represent several kinds of events within the NVIDIA driver such as pending page retirements or GPUs falling off the bus. See <a href="http://docs.nvidia.com/deploy/xid-errors/index.html">http://docs.nvidia.com/deploy/xid-errors/index.html</a> for details.

### 3.3.1. Notifications

The simplest form of a policy is to instruct DCGM to notify a client when the target condition is met. No further action is performed beyond this. This is primarily interesting as a callback mechanism within the programmatic interfaces, as a way to avoid polling.

When running DCGM in embedded mode such callbacks are invoked automatically by DCGM each time a registered condition is hit, at which point the client can deal with that event as desired. The client must register through the appropriate API calls to

receive these callbacks. Doing so transparently instructs DCGM to track the conditions that trigger those results.



Once a callback has been received for a particular condition, that notification registration is terminated. If the client wants repeated notifications for a condition it should re-register after processing each callback.

The `dcgmi policy` subcommand does allow access to some of this functionality from the command line via setting of conditions and via a blocking notification mechanism. This can be useful when watching for a particular problem, e.g. during a debugging session.

As an example, the following shows setting a notification policy for PCIe fatal and non-fatal events:

```
# dcgmi policy -g 2 --set 0,0 -p
Policy successfully set.

#dcgmi policy -g 2 --get
Policy information
+-----+-----+
| GPU_Group | Policy Information |
+-----+-----+
| Violation conditions | PCI errors and replays |
| Isolation mode | Manual |
| Action on violation | None |
| Validation after action | None |
| Validation failure action | None |
+-----+-----+
**** Non-homogenous settings across group. Use with -v flag to see details.

#dcgmi policy -g 2 --get --verbose
Policy information
+-----+-----+
| GPU ID: 0 | Policy Information |
+-----+-----+
| Violation conditions | PCI errors and replays |
| Isolation mode | Manual |
| Action on violation | None |
| Validation after action | None |
| Validation failure action | None |
+-----+-----+
| GPU ID: 1 | Policy Information |
+-----+-----+
| Violation conditions | PCI errors and replays |
| Isolation mode | Manual |
| Action on violation | None |
| Validation after action | None |
| Validation failure action | None |
+-----+-----+
```

Once such a policy is set the client will receive notifications accordingly. While this is primarily interesting for programmatic use cases, `dcgmi policy` can be invoked to wait for policy notifications:

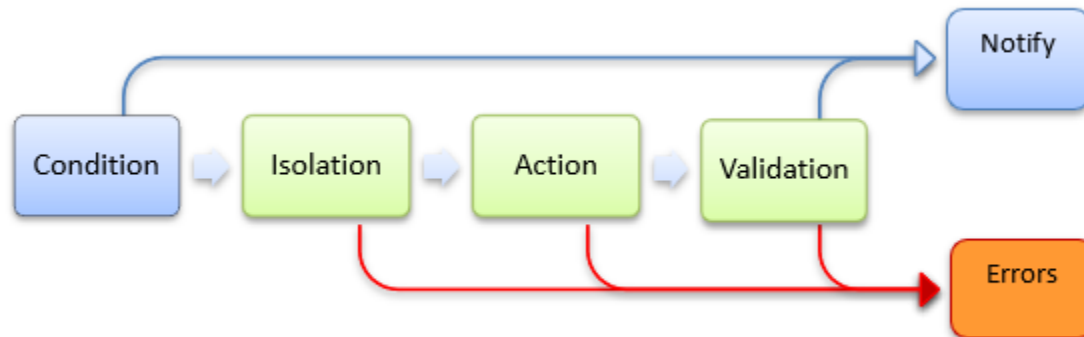
```
# dcgmi policy -g 2 --reg
Listening for violations
...
A PCIe error has violated policy manager values.
...
```

### 3.3.2. Actions

Action policies are a superset of the notification policies above.

Some clients may find it useful to tie a condition to an action that DCGM performs automatically as soon as the condition is met. This is most pertinent when the condition is a RAS event that prevents the GPU from otherwise operating normally.

Policies that are defined as actions include three additional components:



1. *Isolation mode* – whether DCGM grabs exclusive access to the GPU before performing the subsequent policy steps.
2. *Action* – The DCGM invasive behavior to perform.
3. *Validation* – Any follow-up validation of GPU state, post action.

A common action based policy is to configure DCGM to automatically retire a memory page after an ECC DBE has occurred. By retiring the page and re-initializing the GPU, DCGM can isolate the hardware fault and prepare the GPU for the next job. Since this operation involves resetting the GPU, a quick system validation is a follow-up step to ensure the GPU is healthy.

Clients setting action policies receive two notifications each time the policy is run.

1. Notification callback when condition is hit and policy enacted.
2. Notification callback when action completes, i.e. after validation step.

Using the `dcgmi policy` subcommand, this kind of action-based policy can be configured as follows:

```

# dcgmi policy -g 1 --set 1,1 -e
Policy successfully set.

# dcgmi policy -g 1 --get
Policy information for group 1
+-----+-----+
| GPU ID: 0          | Policy Information |
+-----+-----+
| Violation Conditions | Double-bit ECC errors |
| Isolation mode      | Manual              |
| Action on violation  | Reset GPU           |
| Validation after action | NVVS (Short)        |
| Validation failure action | None                 |
+-----+-----+
  
```

```
+-----+
...

```

As shown in the previous section, `dcgmi policy` can also be used to watch for notifications associated with this policy.

## 3.4. Job Stats

DCGM provides background data gathering and analysis capabilities, including the ability to aggregate data across the lifetime of a target workload and across the GPUs involved. This makes it easy for clients to gather job level data, such as accounting, in a single request.

To request this functionality a client must first enable stats recording for the target group. This tells DCGM that all relevant metrics must be periodically watched for those GPUs, along with process activity on the devices. This need only be done once at initialization for each job-level group.

```
# dcgmi stats -g 1 --enable
Successfully started process watches on group 1.
```

Stats recording must be enabled prior to the start of the target workload(s) for reliable information to be available.

Once a job has completed DCGM can be queried for information about that job, both at the summary level of a group and, if needed, broken down individually between the GPUs within that group. The suggested behavior is that clients perform this query in epilogue scripts as part of job cleanup.

An example of group-level data provided by `dcgmi stats`:

```
dcgmi stats --pid 1234 -v
Successfully retrieved process info for pid: 1234. Process ran on 1 GPUs.
+-----+
| GPU ID: 0 |
+-----+
+-----+
|----- Execution Stats -----|
| Start Time * | Tue Nov 3 17:36:43 2015 |
| End Time * | Tue Nov 3 17:38:33 2015 |
| Total Execution Time (sec) * | 110.33 |
| No. of Conflicting Processes * | 0 |
+----- Performance Stats -----+
| Energy Consumed (Joules) | 15758 |
| Power Usage (Watts) | Avg: 150, Max: 250, Min: 100 |
| Max GPU Memory Used (bytes) * | 213254144 |
| SM Clock (MHz) | Avg: 837, Max: 875, Min: 679 |
| Memory Clock (MHz) | Avg: 2505, Max: 2505, Min: 2505 |
| SM Utilization (%) | Avg: 99, Max: 100, Min: 99 |
| Memory Utilization (%) | Avg: 2, Max: 3, Min: 0 |
| PCIe Rx Bandwidth (megabytes) | Avg: N/A, Max: N/A, Min: N/A |
| PCIe Tx Bandwidth (megabytes) | Avg: N/A, Max: N/A, Min: N/A |
+----- Event Stats -----+
| Single Bit ECC Errors | 0 |
| Double Bit ECC Errors | 0 |
| PCIe Replay Warnings | 0 |
| Critical XID Errors | 0 |
+----- Slowdown Stats -----+
| Due to - Power (%) | 0 |
| - Thermal (%) | 0 |
```

```

| - Reliability (%)           | 0 |
| - Board Limit (%)         | 0 |
| - Low Utilization (%)     | 0 |
| - Sync Boost (%)         | Not Supported |
+-----+-----+
(*) Represents a process statistic. Otherwise device statistic during process
lifetime listed.

```

For certain frameworks the processes and their PIDs cannot be associated with a job directly, and the process associated with a job may spawn many children. In order to get job-level stats for such a scenario, DCGM must be notified when a job starts and stops. It is required that the client notifies DCGM with the user defined job id and the corresponding GPU group at job prologue, and notifies with the job id at the job epilogue. The user can query the job stats using the job id and get aggregated stats across all the pids during the window of interest.

An example of notifying DCGM at the beginning and end of the job using dcgmi:

```

# dcgmi stats -g 1 -s <user-provided-jobid>
Successfully started recording stats for <user-provided-jobid>
# dcgmi stats -x <user-provided-jobid>
Successfully stopped recording stats for <user-provided-jobid>

```

The stats corresponding to the job id already watched can be retrieved using dcgmi:

```

# dcgmi stats -j <user-provided-jobid>
Successfully retrieved statistics for <user-provided-jobid>
+-----+-----+
| GPU ID: 0 |
+-----+-----+
|----- Execution Stats -----|
| Start Time           | Tue Nov 3 17:36:43 2015 |
| End Time             | Tue Nov 3 17:38:33 2015 |
| Total Execution Time (sec) | 110.33 |
| No. of Processes     | 0 |
+----- Performance Stats -----+
| Energy Consumed (Joules) | 15758 |
| Power Usage (Watts)     | Avg: 150, Max: 250, Min 100 |
| Max GPU Memory Used (bytes) | 213254144 |
| SM Clock (MHz)         | Avg: 837, Max: 875, Min: 679 |
| Memory Clock (MHz)     | Avg: 2505, Max: 2505, Min: 2505 |
| SM Utilization (%)     | Avg: 99, Max: 100, Min: 99 |
| Memory Utilization (%) | Avg: 2, Max: 3, Min: 0 |
| PCIe Rx Bandwidth (megabytes) | Avg: N/A, Max: N/A, Min: N/A |
| PCIe Tx Bandwidth (megabytes) | Avg: N/A, Max: N/A, Min: N/A |
+----- Event Stats -----+
| Single Bit ECC Errors | 0 |
| Double Bit ECC Errors | 0 |
| PCIe Replay Warnings  | 0 |
| Critical XID Errors   | 0 |
+----- Slowdown Stats -----+
| Due to - Power (%)   | 0 |
| - Thermal (%)        | 0 |
| - Reliability (%)    | 0 |
| - Board Limit (%)    | 0 |
| - Low Utilization (%) | 0 |
| - Sync Boost (%)     | Not Supported |
+-----+-----+

```

## 3.5. Health and Diagnostics

DCGM provides several mechanisms for understanding GPU health, each targeted at different needs. By leveraging each of these interfaces it is easy for clients to determine overall GPU health non-invasively -- while workloads are running, and actively -- when the GPU(s) can run dedicated tests. A new major feature of DCGM is the ability to run online hardware diagnostics.

More detailed targeted use cases are as follows:

- ▶ *Background health checks.*

These are non-invasive monitoring operations that occur while jobs are running, and can be queried at any time. There is no impact on application behavior or performance.

- ▶ *Prologue health checks.*

Quick, invasive health checks that take a few seconds and are designed to verify that a GPU is ready for work prior to job submission.

- ▶ *Epilogue health checks.*

Medium duration invasive health checks, taking a few minutes, that can be run when a job has failed or a GPU's health is otherwise suspect

- ▶ *Full system validation.*

Long duration invasive health checks, taking tens of minutes, that can be run when a system is being active investigated for hardware problems or other serious issues.



**Caution** All of these are online diagnostics, meaning they run within the current environment. There is potential for factors beyond the GPU to influence behavior in negative ways. While these tools try to identify those situations, full offline diagnostics delivered via a different NVIDIA tool are required for complete hardware validation, and are required for RMA.



### 3.5.1. Background Health Checks

This form of health check is based on passive, background monitoring of various hardware and software components. The objective is to identify problems in key areas without impact on application behavior or performance. These kinds of checks can catch serious problems, such as unresponsive GPUs, corrupted firmware, thermal escapes, etc.

When such issues are identified they are reported by DCGM as warnings or errors. Each situation can require different client responses, but the following guidelines are usually true:



- ▶ *Warning* – an issue has been detected that won't prevent current work from completing, but the issue should be examined and potentially addressed in the future.
- ▶ *Error* – a critical issue has been detected and the current work is likely compromised or interrupted. These situations typically correspond to fatal RAS events and usually indicate the need for job termination and GPU health analysis.

Background health checks can be set and watched via simple DCGM interfaces. Using `dcgmi health` as the interface, the following code sets several health checks for a group and then verifies that those checks are currently enabled:

```
# dcgmi health -g 1 -s mpi
Health monitor systems set successfully.
```

To view the current status of all GPUs in the group the client can simply query for the overall group health. The result is an overall health score for the group as well as individual results for each impacted GPU, identifying key problems.

For example, DCGM would show the following when excessive PCIe replay events or InfoROM issues are detected:

```
# dcgmi health -g 1 -c
Health Monitor Report
+-----+-----+
| Group 1          | Overall Health: Warning |
+-----+-----+
| GPU ID: 0        | Warning                 |
|                  | PCIe system: Warning - Detected more than 8 PCIe |
|                  | replays per minute for GPU 0: 13 |
+-----+-----+
| GPU ID: 1        | Warning                 |
|                  | InfoROM system: Warning - A corrupt InfoROM has been |
|                  | detected in GPU 1.     |
+-----+-----+
```



The `dcgmi` interfaces above only report current health status. The underlying data, exposed via other interfaces, captures more information about the timeframe of the events and their connections to executing processes on the GPU.

### 3.5.2. Active Health Checks

This form of health check is invasive, requiring exclusive access to the target GPUs. By running real workloads and analyzing the results, DCGM is able to identify common problems of a variety of types. These include:

- ▶ *Deployment and Software Issues*
  - ▶ NVIDIA library access and versioning
  - ▶ 3rd-party software conflicts
- ▶ *Integration Issues*
  - ▶ Correctable/uncorrectable issues on PCIe/NVLINK busses
  - ▶ Topological limitations
  - ▶ OS-level device restrictions, cgroups checks
  - ▶ Basic power and thermal constraint checks

- ▶ *Stress Checks*
  - ▶ Power and thermal stress
  - ▶ PCIe/NVLINK throughput stress
  - ▶ Constant relative system performance
  - ▶ Maximum relative system performance
- ▶ *Hardware Issues and Diagnostics*
  - ▶ GPU hardware and SRAMs
  - ▶ Computational robustness
  - ▶ Memory
  - ▶ PCIe/NVLINK busses

DCGM exposes these health checks through its diagnostic and policy interfaces. DCGM provides three levels of diagnostic capability (see `dcgmi diag help` on the command line). DCGM runs more in-depth tests to verify the health of the GPU at each level. The test names and tests run at each level are provided in the table below:

Test Suite Name	Run Level	Test Duration	Test Classes			
			Software	Hardware	Integration	Stress
Quick	1	~ seconds	Deployment	--	--	--
Medium	2	~ 2 minutes	Deployment	Memory Test	PCIe/NVLink	--
Long	3	~15 minutes	Deployment	Memory Test Memory Bandwidth HW Diagnostic Tests	PCIe/NVLink	SM Stress Targeted Stress Targeted Power

While simple tests of runtime libraries and configuration are possible on non-Tesla GPUs (Run Level 1), DCGM is also able to perform hardware diagnostics, connectivity diagnostics, and a suite of stress tests on Tesla GPUs to help validate health and isolate problems. The actions in each test type are further described in the section [GPU Parameters](#).

For example, running the full system validation (long test):

```
# dcgmi diag -g 1 -r 3
Successfully ran diagnostic for group 1.
+-----+-----+
| Diagnostic | Result |
+-----+-----+
+----- Deployment -----+
| Blacklist | Pass |
| NVML Library | Pass |
| CUDA Main Library | Pass |
| CUDA Toolkit Libraries | Pass |
| Permissions and OS Blocks | Pass |
| Persistence Mode | Pass |
| Environment Variables | Pass |
| Page Retirement | Pass |
| Graphics Processes | Pass |
+----- Hardware -----+
```

GPU Memory	Pass - All	
Diagnostic	Pass - All	
+----- Integration -----+		
PCIe	Pass - All	
+----- Performance -----+		
SM Stress	Pass - All	
Targeted Stress	Pass - All	
Targeted Power	Pass - All	
Memory Bandwidth	Pass - All	
+-----+		



Diagnostic configuration options, as well as verbose output with a description of failures/actions will be included in the next Release Candidate package.

The diagnostic tests can also be run as part of the validation phase of action-based policies. A common scenario, for example, would be to run the short version of the test as a validation to a DBE page retirement action.

DCGM will store logs from these tests on the host file system. Two types of logs exist:

- ▶ Hardware diagnostics include an encrypted binary log, only viewable by NVIDIA.
- ▶ System validation and stress checks provide additional time series data via JSON text files. These can be viewed in numerous programs to see much more detailed information about GPU behavior during each test.

For complete details about the active health checks, including descriptions of the plugins and their various failure conditions, please read chapter 5.

## 3.6. Topology

DCGM provides several mechanisms for understanding GPU topology both at a verbose device-level view and non-verbose group-level view. These views are designed to give a user information about connectivity to other GPUs in the system as well as NUMA/affinity information.

For the device-level view:

```
# dcgmi topo --gpuid 0
+-----+
| GPU ID: 0          | Topology Information |
+-----+
| CPU Core Affinity | 0 - 11              |
+-----+
| To GPU 1          | Connected via an on-board PCIe switch |
| To GPU 2          | Connected via a PCIe host bridge      |
+-----+
```

And for the group-level view:

```
# dcgmi topo -g 1
+-----+
| MyGroup           | Topology Information |
+-----+
| CPU Core Affinity | 0 - 11              |
+-----+
| NUMA Optimal      | True                 |
+-----+
| Worst Path        | Connected via a PCIe host bridge      |
+-----+
```

```
+-----+
.....
```

## 3.7. NVlink Counters

DCGM provides a way to check the nvlink error counters for various links in the system. This makes it easy for clients to catch abnormalities and watch the health of the communication over nvlink. There are multiple types of nvlink errors that are accounted for by DCGM as follows:

1. CRC FLIT Error: Data link receive flow control digit CRC error
2. CRC Data Error: Data link receive data CRC error.
3. Replay Error: Transmit replay error.
4. Recovery Error: Transmit recovery error.

To check the nvlink counters for all the nvlink present in gpu with gpu Id 0:

```
# dcgmi nvlink --errors -g 0
+-----+
| GPU ID: 0 | NVLINK Error Counts |
+-----+
|Link 0     | CRC FLIT Error       | 0 |
|Link 0     | CRC Data Error       | 0 |
|Link 0     | Replay Error         | 0 |
|Link 0     | Recovery Error       | 0 |
|Link 1     | CRC FLIT Error       | 0 |
|Link 1     | CRC Data Error       | 0 |
|Link 1     | Replay Error         | 0 |
|Link 1     | Recovery Error       | 0 |
|Link 2     | CRC FLIT Error       | 0 |
|Link 2     | CRC Data Error       | 0 |
|Link 2     | Replay Error         | 0 |
|Link 2     | Recovery Error       | 0 |
|Link 3     | CRC FLIT Error       | 0 |
|Link 3     | CRC Data Error       | 0 |
|Link 3     | Replay Error         | 0 |
|Link 3     | Recovery Error       | 0 |
+-----+
```

## 3.8. Field Groups

DCGM provides predefined groups of fields like job statistics, process statistics, and health for ease of use. Additionally, DCGM allows users to create their own custom groups of fields called field groups. Users can watch a group of fields on a group of GPUs and then retrieve either the latest values or a range of values of every field in a field group for every GPU in a group.

Field groups are not used directly in DCGMI, but you can still look at them and manage them from DCGMI.

To see all of the active field groups on a system, run:

```
# dcgmi fieldgroup -l
4 field groups found.
+-----+
| FIELD GROUPS |
+-----+
```

```

+-----+
| ID      | 1 |
| Name    | DCGM_INTERNAL_1SEC |
| Field IDs | 38, 73, 86, 112, 113, 119, 73, 51, 47, 46, 66, 72, 61, 118,... |
+-----+
| ID      | 2 |
| Name    | DCGM_INTERNAL_30SEC |
| Field IDs | 124, 125, 126, 130, 131, 132, 133, 134, 135, 136, 137, 138,... |
+-----+
| ID      | 3 |
| Name    | DCGM_INTERNAL_HOURLY |
| Field IDs | 117, 55, 56, 64, 62, 63, 6, 5, 26, 8, 17, 107, 22, 108, 30, 31 |
+-----+
| ID      | 4 |
| Name    | DCGM_INTERNAL_JOB |
| Field IDs | 111, 65, 36, 37, 38, 101, 102, 77, 78, 40, 41, 121, 115, 11... |
+-----+

```

If you want to create your own field group, pick a unique name for it, decide which field IDs you want inside of it, and run:

```
# dcgmi fieldgroup -c mygroupname -f 50,51,52
Successfully created field group "mygroupname" with a field group ID of 5
```

Note that field IDs come from `dcgm_fields.h` and are the macros that start with `DCGM_FI_`.

Once you have created a field group, you can query its info:

```
#dcgmi fieldgroup -i --fieldgroup 5
+-----+
| FIELD GROUPS |
+-----+
| ID      | 5 |
| Name    | mygroupname |
| Field IDs | 50, 51, 52 |
+-----+
```

If you want to delete a field group, run the following command:

```
# dcgmi fieldgroup -d -g 5
Successfully removed field group 5
```

Note that DCGM creates a few field groups internally. Field groups that are created internally, like the ones above, cannot be removed. Here is an example of trying to delete a DCGM-internal field group:

```
# dcgmi fieldgroup -d -g 1
Error: Cannot destroy field group 1. Return: No permission.
```

## 3.9. Link Status

In DCGM 1.5, you can query the status of the NVLinks of the GPUs and NVSwitches attached to the system with the following command:

```
# dcgmi nvlink --link-status
+-----+
| NvLink Link Status |
+-----+
GPUs:
```

```

gpuId 0:
  U U U U U U
gpuId 1:
  U U U U U U
gpuId 2:
  U U U U U U
gpuId 3:
  U U U U U U
gpuId 4:
  U U U U U U
gpuId 5:
  U U U U U U
gpuId 6:
  U U U U U U
gpuId 7:
  U U U U U U
gpuId 8:
  U U U U U U
gpuId 9:
  U U U U U U
gpuId 10:
  U U U U U U
gpuId 11:
  U U U U U U
gpuId 12:
  U U U U U U
gpuId 13:
  U U U U U U
gpuId 14:
  U U U U U U
gpuId 15:
  U U U U U U
NvSwitches:
physicalId 8:
  U U U U U U X X U U U U U U U U U
physicalId 9:
  U U U U U U U U U U U U U U X X U U
physicalId 10:
  U U U U U U U U U U U U X U U U X U
physicalId 11:
  U U U U U U X X U U U U U U U U U U
physicalId 12:
  U U U U X U U U U U U U U U U X U
physicalId 13:
  U U U U X U U U U U U U U U U X U
physicalId 24:
  U U U U U U X X U U U U U U U U U U
physicalId 25:
  U U U U U U U U U U U U U U X X U U
physicalId 26:
  U U U U U U U U U U U X U U U X U
physicalId 27:
  U U U U U U X X U U U U U U U U U U
physicalId 28:
  U U U U X U U U U U U U U U U X U
physicalId 29:
  U U U U X U U U U U U U U U U X U

```

Key: Up=U, Down=D, Disabled=X, Not Supported=\_

## 3.10. Profiling Metrics

As GPU-enabled servers become more common in the datacenter, it becomes important to better understand applications' performance and the utilization of GPU resources in

the cluster. Profiling metrics in DCGM enables the collection of a set of metrics using the hardware counters on the GPU. DCGM provides access to device-level metrics at low performance overhead in a continuous manner. This feature is supported in production starting with DCGM 1.7.

DCGM includes a new profiling module to provide access to these metrics. The new metrics are available as new fields (i.e. new IDs) via the regular DCGM APIs (such as the C, Python, Go bindings or the `dcgmi` command line utility). The installer packages also include an example CUDA based test load generator (called `dcgmproftester`) to demonstrate the new capabilities.

### 3.10.1. Metrics

The following new device-level profiling metrics are supported. The definitions and corresponding DCGM field IDs are listed. By default, DCGM provides the metrics at a sample rate of 1Hz (every 1000ms). Users can query the metrics at any configurable frequency (minimum is 100ms) from DCGM (for example, see `dcgmi dmon -d` ).

Table 2 Device Level GPU Metrics

Metric	Definition	DCGM Field Name (DCGM_FI_*) and ID
Graphics Engine Activity	<p>The fraction of time any portion of the graphics or compute engines were active.</p> <p>The graphics engine is active if a graphics/compute context is bound and the graphics/compute pipe is busy.</p> <p>The value represents an average over a time interval and is not an instantaneous value.</p>	PROF_GR_ENGINE_ACTIVE (ID: 1001)
SM Activity	<p>The fraction of time at least one warp was active on a multiprocessor, averaged over all multiprocessors. Note that “active” does not necessarily mean a warp is actively computing. For instance, warps waiting on memory requests are considered active.</p> <p>The value represents an average over a time interval and is not an instantaneous value. A value of 0.8 or greater is necessary, but not sufficient, for effective use of the GPU. A value less than 0.5 likely indicates ineffective GPU usage.</p> <p>Given a simplified GPU architectural view, if a GPU has N SMs then a kernel using N</p>	PROF_SM_ACTIVE (ID: 1002)

Metric	Definition	DCGM Field Name (DCGM_FI_*) and ID
	<p>blocks that runs over the entire time interval will correspond to an activity of 1 (100%). A kernel using N/5 blocks that runs over the entire time interval will correspond to an activity of 0.2 (20%). A kernel using N blocks that runs over one fifth of the time interval, with the SMs otherwise idle, will also have an activity of 0.2 (20%). The value is insensitive to the number of threads per block (see <code>DCGM_FI_PROF_SM_OCCUPANCY</code>).</p>	
SM Occupancy	<p>The fraction of resident warps on a multiprocessor, relative to the maximum number of concurrent warps supported on a multiprocessor. The value represents an average over a time interval and is not an instantaneous value.</p> <p>Higher occupancy does not necessarily indicate better GPU usage. For GPU memory bandwidth limited workloads (see <code>DCGM_FI_PROF_DRAM_ACTIVE</code>), higher occupancy is indicative of more effective GPU usage. However if the workload is compute limited (i.e., not GPU memory bandwidth or latency limited), then higher occupancy does not necessarily correlate with more effective GPU usage.</p> <p>Calculating occupancy is not simple and depends on factors such as the GPU properties, the number of threads per block, registers per thread, and shared memory per block. Use the <a href="#">CUDA Occupancy Calculator</a> to explore various occupancy scenarios.</p>	PROF_SM_OCCUPANCY (ID: 1003)
Tensor Activity	<p>The fraction of cycles the tensor (HMMA / IMMA) pipe was active. The value represents an average over a time interval and is not an instantaneous value.</p> <p>Higher values indicate higher utilization of the Tensor Cores. An activity of 1 (100%) is equivalent to issuing a tensor instruction every other cycle</p>	PROF_PIPE_TENSOR_ACTIVE (ID: 1004)



Metric	Definition	DCGM Field Name (DCGM_FI_*) and ID
	<p>for the entire time interval. An activity of 0.2 (20%) could indicate 20% of the SMs are at 100% utilization over the entire time period, 100% of the SMs are at 20% utilization over the entire time period, 100% of the SMs are at 100% utilization for 20% of the time period, or any combination in between (see <code>DCGM_FI_PROF_SM_ACTIVE</code> to help disambiguate these possibilities).</p>	
FP64 Engine Activity	<p>The fraction of cycles the FP64 (double precision) pipe was active. The value represents an average over a time interval and is not an instantaneous value.</p> <p>Higher values indicate higher utilization of the FP64 cores. An activity of 1 (100%) is equivalent to a FP64 instruction on every SM every fourth cycle on Volta over the entire time interval. An activity of 0.2 (20%) could indicate 20% of the SMs are at 100% utilization over the entire time period, 100% of the SMs are at 20% utilization over the entire time period, 100% of the SMs are at 100% utilization for 20% of the time period, or any combination in between (see <code>DCGM_FI_PROF_SM_ACTIVE</code> to help disambiguate these possibilities).</p>	PROF_PIPE_FP64_ACTIVE (ID: 1006)
FP32 Engine Activity	<p>The fraction of cycles the FMA (FP32 (single precision), and integer) pipe was active. The value represents an average over a time interval and is not an instantaneous value.</p> <p>Higher values indicate higher utilization of the FP32 cores. An activity of 1 (100%) is equivalent to a FP32 instruction every other cycle over the entire time interval. An activity of 0.2 (20%) could indicate 20% of the SMs are at 100% utilization over the entire time period, 100% of the SMs are at 20% utilization over the entire time period, 100% of the SMs are at 100% utilization</p>	PROF_PIPE_FP32_ACTIVE (ID: 1007)

Metric	Definition	DCGM Field Name (DCGM_FI_*) and ID
	for 20% of the time period, or any combination in between (see <code>DCGM_FI_PROF_SM_ACTIVE</code> to help disambiguate these possibilities).	
FP16 Engine Activity	<p>The fraction of cycles the FP16 (half precision) pipe was active. The value represents an average over a time interval and is not an instantaneous value.</p> <p>Higher values indicate higher utilization of the FP16 cores. An activity of 1 (100%) is equivalent to a FP16 instruction every other cycle over the entire time interval. An activity of 0.2 (20%) could indicate 20% of the SMs are at 100% utilization over the entire time period, 100% of the SMs are at 20% utilization over the entire time period, 100% of the SMs are at 100% utilization for 20% of the time period, or any combination in between (see <code>DCGM_FI_PROF_SM_ACTIVE</code> to help disambiguate these possibilities).</p>	PROF_PIPE_FP16_ACTIVE (ID: 1008)
Memory BW Utilization	<p>The fraction of cycles where data was sent to or received from device memory. The value represents an average over a time interval and is not an instantaneous value.</p> <p>Higher values indicate higher utilization of device memory. An activity of 1 (100%) is equivalent to a DRAM instruction every cycle over the entire time interval (in practice a peak of ~0.8 (80%) is the maximum achievable). An activity of 0.2 (20%) indicates that 20% of the cycles are reading from or writing to device memory over the time interval.</p>	PROF_DRAM_ACTIVE (ID: 1005)
NVLink Bandwidth	<p>The rate of data transmitted / received over NVLink, not including protocol headers, in bytes per second. The value represents an average over a time interval and is not an instantaneous value.</p> <p>The rate is averaged over the time interval. For example,</p>	PROF_NVLINK_TX_BYTES (1011) and PROF_NVLINK_RX_BYTES (1012)

Metric	Definition	DCGM Field Name (DCGM_FI_*) and ID
	if 1 GB of data is transferred over 1 second, the rate is 1 GB/s regardless of the data transferred at a constant rate or in bursts. The theoretical maximum NVLink Gen2 bandwidth is 25 GB/s per link per direction.	
PCIe Bandwidth	<p>The rate of data transmitted / received over the PCIe bus, including both protocol headers and data payloads, in bytes per second. The value represents an average over a time interval and is not an instantaneous value.</p> <p>The rate is averaged over the time interval. For example, if 1 GB of data is transferred over 1 second, the rate is 1 GB/s regardless of the data transferred at a constant rate or in bursts. The theoretical maximum PCIe Gen3 bandwidth is 985 MB/s per lane.</p>	PROF_PCIE_[T R]X_BYTES (ID: 1009 (TX); 1010 (RX))

Profiling of the GPU counters requires administrator privileges starting with Linux drivers 418.43 or later. This is documented [here](#). When using profiling metrics from DCGM, ensure that `nv-hostengine` is started with superuser privileges.

### 3.10.2. Multiplexing of Profiling Counters

Some metrics require multiple passes to be collected and therefore all metrics cannot be collected together. Due to hardware limitations on the GPUs, only certain groups of metrics can be read together. For example, SM Activity | SM Occupancy cannot be collected together with Tensor Utilization on V100 but can be done on T4. To overcome these hardware limitations, DCGM supports automatic multiplexing of metrics by statistically sampling the requested metrics and performing the groupings internally. This may be transparent to users who requested metrics that may not have been able to be collected together.

A side-effect of multiplexing is that collection at higher frequencies will result in zeroes returned as DCGM attempts to group metrics together for collection.

The metrics that can be collected together for a specific GPU can be determined by running the following command:

```
$ dcgmi profile -l -i 0
+-----+-----+
+-----+-----+
| Group.Subgroup | Field ID | Field Tag
|
```

```

+-----+-----+
+-----+-----+
| A.1          | 1002      | sm_active
| |
| A.1          | 1003      | sm_occupancy
| |
| A.1          | 1004      | tensor_active
| |
| A.1          | 1007      | fp32_active
| |
| A.2          | 1006      | fp64_active
| |
| A.3          | 1008      | fp16_active
| |
| B.0          | 1005      | dram_active
| |
| C.0          | 1009      | pcie_tx_bytes
| |
| C.0          | 1010      | pcie_rx_bytes
| |
| D.0          | 1001      | gr_engine_active
| |
| E.0          | 1011      | nvlink_tx_bytes
| |
| E.0          | 1012      | nvlink_rx_bytes
| |
+-----+-----+
+-----+-----+

```

From the output above, we can determine that for this GPU (in this example, an NVIDIA T4), a metric from each letter group can be collected without multiplexing. From this example, a metric from **A.1** can be collected with another metric from **A.1** without multiplexing. A metric from **A.1** will be multiplexed with another metric from **A.2** or **A.3**. Metrics from different letter groups can be combined for concurrent collection (without requiring multiplexing by DCGM).

Building on this example further, on T4 these metrics can be collected together without multiplexing:

```
sm_active + sm_occupancy + tensor_active + fp32_active
```

The above DCGM command will show what groupings are supported by the hardware for concurrent collection.

### 3.10.3. Profiling Sampling Rate

By default, DCGM provides the metrics at a sample rate of 1Hz (every 1000ms). Users can query the metrics at any configurable frequency (minimum is 100ms) from DCGM. In general, DCGM is not designed for very high frequency sampling due to the total time involved in the collection/processing of metrics from the hardware counters and the driver.

The update frequency can be modified by setting the value in the `dcgmProfUnwatchFields_v1` structure that is passed to `dcgmProfWatchFields` when watching the [profiling metrics](#).

### 3.10.4. Concurrent Usage of NVIDIA Profiling Tools

Due to current hardware limitations, collection of profiling metrics with DCGM will conflict with usage of other developer tools from NVIDIA such as Nsight Systems or Nsight Compute. Users may encounter an error from DCGM (either with `dcgmi` or when using the APIs) such as:

**Error setting watches. Result: The requested operation could not be completed because the affected resource is in use.**

To allow DCGM to co-exist with the usage of other profiling tools, it is recommended to pause metrics collection with DCGM when the tools are in use and then resume after the usage of the tools is complete.

With `dcgmi`, the `--pause` and `--resume` options can be used:

```
$ dcgmi --pause / --resume
```

When using DCGM APIs, the following APIs can be called from the monitoring process:

`dcgmProfPause()` and `dcgmProfResume()`

When paused, DCGM will publish **BLANK** values for profiling metrics. These **BLANK** values can be tested with `DCGM_FP64_IS_BLANK(value)` in the C or Python bindings.

### 3.10.5. CUDA Test Generator (dcgmproftester)

`dcgmproftester` is a CUDA load generator. It can be used to generate deterministic CUDA workloads for reading and validating GPU metrics. The tool is shipped as a simple x86\_64 Linux binary along with the CUDA kernels compiled to PTX. Customers can use the tool in conjunction with `dcgmi` to quickly generate a load on the GPU and view the metrics reported by DCGM via `dcgmi dmon` on stdout.

`dcgmproftester` takes two important arguments as input: `-t` for generating load for a particular metric (for example use 1004 to generate a half-precision matrix-multiply-accumulate for the Tensor Cores) and `-d` for specifying the test duration. Add `--no-dcgm-validation` to let `dcgmproftester` generate test loads only.

For a list of all the field IDs that can be used to generate specific test loads, see the table in the Profiling Metrics section. The rest of this section includes some examples using the `dcgmi` command line utility.

For example in a console, generate a load for the TensorCores on A100 for 30seconds. As can be seen, the A100 is able to achieve close to 253TFLOps of FP16 performance using the TensorCores.

```
$ /usr/bin/dcgmproftester11 --no-dcgm-validation -t 1004 -d 10
Skipping CreateDcgmGroups() since DCGM validation is disabled
Skipping CreateDcgmGroups() since DCGM validation is disabled
Skipping WatchFields() since DCGM validation is disabled
Skipping CreateDcgmGroups() since DCGM validation is disabled
```

```

Worker 0:0[1004]: TensorEngineActive: generated ???, dcgm 0.000 (250362.2
gflops)
Worker 0:0[1004]: TensorEngineActive: generated ???, dcgm 0.000 (252917.0
gflops)
Worker 0:0[1004]: TensorEngineActive: generated ???, dcgm 0.000 (253971.7
gflops)
Worker 0:0[1004]: TensorEngineActive: generated ???, dcgm 0.000 (253700.2
gflops)
Worker 0:0[1004]: TensorEngineActive: generated ???, dcgm 0.000 (252599.0
gflops)
Worker 0:0[1004]: TensorEngineActive: generated ???, dcgm 0.000 (253134.6
gflops)
Worker 0:0[1004]: TensorEngineActive: generated ???, dcgm 0.000 (252676.7
gflops)
Worker 0:0[1004]: TensorEngineActive: generated ???, dcgm 0.000 (252861.4
gflops)
Worker 0:0[1004]: TensorEngineActive: generated ???, dcgm 0.000 (252764.1
gflops)
Worker 0:0[1004]: TensorEngineActive: generated ???, dcgm 0.000 (253109.4
gflops)
Worker 0:0[1004]: Message: Bus ID 00000000:00:04.0 mapped to cuda device ID 0
DCGM CudaContext Init completed successfully.

CU_DEVICE_ATTRIBUTE_MAX_THREADS_PER_MULTIPROCESSOR: 2048
CUDA_VISIBLE_DEVICES:
CU_DEVICE_ATTRIBUTE_MULTIPROCESSOR_COUNT: 108
CU_DEVICE_ATTRIBUTE_MAX_SHARED_MEMORY_PER_MULTIPROCESSOR: 167936
CU_DEVICE_ATTRIBUTE_COMPUTE_CAPABILITY_MAJOR: 8
CU_DEVICE_ATTRIBUTE_COMPUTE_CAPABILITY_MINOR: 0
CU_DEVICE_ATTRIBUTE_GLOBAL_MEMORY_BUS_WIDTH: 5120
CU_DEVICE_ATTRIBUTE_MEMORY_CLOCK_RATE: 1215
Max Memory bandwidth: 1555200000000 bytes (1555.2 GiB)
CU_DEVICE_ATTRIBUTE_ECC_SUPPORT: true

```

In another console, use the `dcgmi dmon -e` command to view the various performance metrics (streamed to stdout) reported by DCGM as the CUDA workload runs on the GPU. In this example, DCGM reports the GPU activity, TensorCore activity and Memory utilization at a frequency of 1Hz (or 1000ms). As can be seen, the GPU is busy doing work (~99% of Graphics Activity showing that the SMs are busy), with the TensorCore activity pegged to ~93%. Note that `dcgmi` is currently returning the metrics for GPU ID: 0. On a multi-GPU system, you can specify the GPU ID for which DCGM should return the metrics. By default, the metrics are returned for all the GPUs in the system.

```

$ dcgmi dmon -e 1001,1004,1005
# Entity   GRACT   TENSO   DRAMA
   Id
GPU 0     0.000   0.000   0.000
GPU 0     0.000   0.000   0.000
GPU 0     0.000   0.000   0.000
GPU 0     0.552   0.527   0.000
GPU 0     0.969   0.928   0.000
GPU 0     0.973   0.931   0.000
GPU 0     0.971   0.929   0.000
GPU 0     0.969   0.927   0.000
GPU 0     0.971   0.929   0.000
GPU 0     0.971   0.930   0.000
GPU 0     0.973   0.931   0.000
GPU 0     0.974   0.931   0.000
GPU 0     0.971   0.930   0.000
GPU 0     0.974   0.932   0.000
GPU 0     0.972   0.930   0.000

```

### 3.10.6. Metrics on Multi-Instance GPU

The new Multi-Instance GPU (MIG) feature allows the NVIDIA A100 GPU to be securely partitioned into up to seven separate GPU Instances for CUDA applications, providing multiple users with separate GPU resources for optimal GPU utilization. This feature is particularly beneficial for workloads that do not fully saturate the GPU's compute capacity and therefore users may want to run different workloads in parallel to maximize utilization. For more information on MIG, refer to the [MIG User Guide](#).

DCGM can provide metrics for workloads that are running on MIG devices. DCGM offers two views of the metrics for MIG:

- ▶ GPU device-level metrics
- ▶ MIG device (either GPU Instance or Compute Instance) granularity of the metrics

#### 3.10.6.1. Example 1

In this example, let's generate a CUDA workload using `dcgmproftester` and observe metrics using `dcgmi dmon`.

In this example, we follow these steps to demonstrate the collection of metrics for MIG devices:

- ▶ Create MIG devices (assumes that the GPU has MIG mode enabled)
- ▶ Verify DCGM can list the devices
- ▶ Create a group of devices for DCGM to monitor
- ▶ Run CUDA workloads on the desired MIG device(s)
- ▶ Use `dcgmi dmon` to stream metrics

#### Step 1: Create MIG Devices

Notice that we have partitioned the GPU into two MIG devices with the 3g.20gb profiles.

```
$ sudo nvidia-smi mig -cgi 9,9 -C
...
-----+-----
| MIG devices:                                     |
+-----+-----+-----+-----+-----+-----+-----+-----+
| GPU  GI  CI  MIG |           Memory-Usage | Vol |           Shared | | | | | | | |
|      ID ID  Dev |           BAR1-Usage | SM  Unc| CE  ENC  DEC  OFA  JPG |
|      |      |      |      |           |      ECC|      |      |      |      |      |
+-----+-----+-----+-----+-----+-----+-----+-----+
| 0    1  0  0 | 11MiB / 20096MiB | 42  0 | 3  0  2  0  0 |
|      |      |      |      | 0MiB / 32767MiB |      |      |      |      |      |
+-----+-----+-----+-----+-----+-----+-----+-----+
| 0    2  0  1 | 11MiB / 20096MiB | 42  0 | 3  0  2  0  0 |
|      |      |      |      | 0MiB / 32767MiB |      |      |      |      |      |
+-----+-----+-----+-----+-----+-----+-----+-----+

```

#### Step 2: Verify enumeration by DCGM

We can also observe the devices enumerated by DCGM:

```

$ dcgmi discovery -c
+-----+
| Instance Hierarchy
|
+=====+
+-----+
| GPU 0          | GPU GPU-5fd15f35-e148-2992-4ecb-9825e534f253 (EntityID: 0)
|   |
| -> I 0/1       | GPU Instance (EntityID: 0)
|   |
|   -> CI 0/1/0  | Compute Instance (EntityID: 0)
|   |
|   -> I 0/2     | GPU Instance (EntityID: 1)
|   |
|   -> CI 0/2/0  | Compute Instance (EntityID: 1)
|
+-----+
+-----+

```

### Step 3: Creation of MIG device groups

Create groups of devices for DCGM to monitor. In this example, we will add the GPU and the two GPU Instances (using entity IDs 0 and 1) to the group:

```

$ dcgmi group -c mig-ex1 -a 0,i:0,i:1
Successfully created group "mig-ex1" with a group ID of 8
Specified entity ID is valid but unknown: i:0. ParsedResult: ParsedGpu(i:0)
Specified entity ID is valid but unknown: i:1. ParsedResult: ParsedGpu(i:1)
Add to group operation successful.

```

Now, we can list the devices added to the group and see that the group contains the GPU (GPU:0), GPU Instances (0 and 1):

```

$ dcgmi group -l
+-----+
| GROUPS
| 1 group found.
+-----+
| Groups
| -> 8
|   -> Group ID   | 8
|   -> Group Name | mig-ex1
|   -> Entities   | GPU 0, GPU_I 0, GPU_I 1
+-----+

```

### Step 4: Run CUDA workloads

Launch **dcgmproftester**. Note that **dcgmproftester** will run on all GPU instances available on the GPU. There is currently no way to limit the GPU instances from **dcgmproftester** (though one could do this by running a **dcgmproftester** container, which we will see in the next example).



```

$ sudo dcgmpofstester11 --no-dcgm-validation -t 1004 -d 120
Skipping CreateDcgmGroups() since DCGM validation is disabled
Skipping CreateDcgmGroups() since DCGM validation is disabled
Skipping CreateDcgmGroups() since DCGM validation is disabled
Skipping WatchFields() since DCGM validation is disabled
Skipping CreateDcgmGroups() since DCGM validation is disabled
Worker 0:0[1004]: TensorEngineActive: generated ???, dcgm { GPU: 0.000, GI:
0.000, CI: 0.000 } (102659.5 gflops)
Worker 0:1[1004]: TensorEngineActive: generated ???, dcgm { GPU: 0.000, GI:
0.000, CI: 0.000 } (102659.8 gflops)
Worker 0:0[1004]: TensorEngineActive: generated ???, dcgm { GPU: 0.000, GI:
0.000, CI: 0.000 } (107747.3 gflops)
Worker 0:1[1004]: TensorEngineActive: generated ???, dcgm { GPU: 0.000, GI:
0.000, CI: 0.000 } (107787.3 gflops)
Worker 0:0[1004]: TensorEngineActive: generated ???, dcgm { GPU: 0.000, GI:
0.000, CI: 0.000 } (108107.6 gflops)
Worker 0:1[1004]: TensorEngineActive: generated ???, dcgm { GPU: 0.000, GI:
0.000, CI: 0.000 } (108102.3 gflops)
Worker 0:0[1004]: TensorEngineActive: generated ???, dcgm { GPU: 0.000, GI:
0.000, CI: 0.000 } (108001.2 gflops)

snip...snip

Worker 0:0[1004]: Message: DCGM CudaContext Init completed successfully.

CU_DEVICE_ATTRIBUTE_MAX_THREADS_PER_MULTIPROCESSOR: 2048
CUDA_VISIBLE_DEVICES: MIG-GPU-5fd15f35-e148-2992-4ecb-9825e534f253/1/0
CU_DEVICE_ATTRIBUTE_MULTIPROCESSOR_COUNT: 42
CU_DEVICE_ATTRIBUTE_MAX_SHARED_MEMORY_PER_MULTIPROCESSOR: 167936
CU_DEVICE_ATTRIBUTE_COMPUTE_CAPABILITY_MAJOR: 8
CU_DEVICE_ATTRIBUTE_COMPUTE_CAPABILITY_MINOR: 0
CU_DEVICE_ATTRIBUTE_GLOBAL_MEMORY_BUS_WIDTH: 5120
CU_DEVICE_ATTRIBUTE_MEMORY_CLOCK_RATE: 1215
Max Memory bandwidth: 1555200000000 bytes (1555.2 GiB)
CU_DEVICE_ATTRIBUTE_ECC_SUPPORT: true

Worker 0:1[1004]: Message: DCGM CudaContext Init completed successfully.

CU_DEVICE_ATTRIBUTE_MAX_THREADS_PER_MULTIPROCESSOR: 2048
CUDA_VISIBLE_DEVICES: MIG-GPU-5fd15f35-e148-2992-4ecb-9825e534f253/2/0
CU_DEVICE_ATTRIBUTE_MULTIPROCESSOR_COUNT: 42
CU_DEVICE_ATTRIBUTE_MAX_SHARED_MEMORY_PER_MULTIPROCESSOR: 167936
CU_DEVICE_ATTRIBUTE_COMPUTE_CAPABILITY_MAJOR: 8
CU_DEVICE_ATTRIBUTE_COMPUTE_CAPABILITY_MINOR: 0
CU_DEVICE_ATTRIBUTE_GLOBAL_MEMORY_BUS_WIDTH: 5120
CU_DEVICE_ATTRIBUTE_MEMORY_CLOCK_RATE: 1215
Max Memory bandwidth: 1555200000000 bytes (1555.2 GiB)
CU_DEVICE_ATTRIBUTE_ECC_SUPPORT: true

Skipping UnwatchFields() since DCGM validation is disabled

```

### Step 5: Stream metrics via `dcgmi dmon`

Now in another window, we can observe the metrics being attributed to each MIG device using `dcgmi dmon`. Notice that in this example, we show the GPU Activity (1001) and the Tensor Core Utilization (1004) for the group 8 that we created in Step 3.

```

$ dcgmi dmon -e 1001,1004 -g 8
# Entity GRACT TENSO
  Id
  GPU 0 0.000 0.000
  GPU-I 0 0.000 0.000
  GPU-I 1 0.000 0.000

```

```

GPU 0 0.000 0.000
GPU-I 0 0.000 0.000
GPU-I 1 0.000 0.000
GPU 0 0.457 0.442
GPU-I 0 0.534 0.516
GPU-I 1 0.533 0.515
GPU 0 0.845 0.816
GPU-I 0 0.986 0.953
GPU-I 1 0.985 0.952
GPU 0 0.846 0.817
GPU-I 0 0.987 0.953
GPU-I 1 0.986 0.953
GPU 0 0.846 0.817
GPU-I 0 0.987 0.954
GPU-I 1 0.986 0.953
GPU 0 0.843 0.815
GPU-I 0 0.985 0.951
GPU-I 1 0.983 0.950
GPU 0 0.845 0.817
GPU-I 0 0.987 0.953
GPU-I 1 0.985 0.952
GPU 0 0.844 0.816
GPU-I 0 0.985 0.952
GPU-I 1 0.984 0.951
GPU 0 0.845 0.816
GPU-I 0 0.986 0.952
GPU-I 1 0.985 0.952

```

## Understanding Metrics

To understand the metrics attribution, GRACT is calculated based on the number of allocated compute resources to the total number of compute resources available on the GPU. We can see the total number of compute resources (SMs) using the `nvidia-smi` command:

```

$ sudo nvidia-smi mig -lgip
+-----+
| GPU instance profiles:
| GPU   Name           ID   Instances   Memory   P2P   SM   DEC   ENC
|      Name           ID   Free/Total  GiB     No    CE   JPEG  OFA
|=====+-----+
|   0  MIG 1g.5gb      19    0/7        4.75    No    14   0    0
|                                     1    0    0
+-----+-----+
|   0  MIG 2g.10gb     14    0/3        9.75    No    28   1    0
|                                     2    0    0
+-----+-----+
|   0  MIG 3g.20gb     9     0/2       19.62    No    42   2    0
|                                     3    0    0
+-----+-----+
|   0  MIG 4g.20gb     5     0/1       19.62    No    56   2    0
|                                     4    0    0
+-----+-----+
|   0  MIG 7g.40gb     0     0/1       39.50    No    98   5    0
|                                     7    1    1
+-----+-----+

```

Because the MIG geometry in this example is **3g.20gb**, the compute resources are = **2\*42/98** or **85.71%**. We can now interpret **GRACT** from the `dcgm` `dmon` output:

```
GPU 0 0.845 0.816
GPU-I 0 0.986 0.952
GPU-I 1 0.985 0.952
```

Since each GPU instance is **98.6%** active, the entire GPU = **0.8571\*0.986** or **84.5%** utilized. The same interpretation can be extended to Tensor Core utilization.

### 3.10.7. Platform Support

Profiling metrics are currently supported for the following GPU products on Linux x86\_64, Arm64 (aarch64) and POWER (ppc64le) platforms:

- ▶ NVIDIA A100, A40
- ▶ NVIDIA V100
- ▶ NVIDIA T4

R418.87.00+ Tesla Linux drivers downloaded from the NVIDIA driver downloads site.

# Chapter 4.

## INTEGRATING WITH DCGM

### 4.1. Integrating with DCGM Reader

DcgmReader.py is a class meant to facilitate gathering telemetry from DCGM so that the information can be viewed directly or integrated elsewhere. The sdk\_samples directory contains a simple script which uses DcgmReader in DcgmReaderExample.py. The directory also contains other examples of how DcgmReader can be used to integrate into tools such as collectd (dcgm\_collectd.py), Prometheus (dcgm\_prometheus.py).

This section will walk through two simple ways of using DcgmReader to easily gather information from DCGM.

First, let's imagine that you want to publish some telemetry from DCGM on a message bus such as ZMQ. We can access this through two simple methods, the first of which asks for a dictionary.

All examples here assume that you have DCGM installed and nv-hostengine active locally.

#### 4.1.1. Reading Using the Dictionary

```
# dictionary_reader_example.py
from DcgmReader import DcgmReader
import zmq
import time

def main():
    dr = DcgmReader()
    context = zmq.Context()
    socket = context.socket(zmq.PUB)
    socket.bind("tcp://*:4096")
    while True:
        '''
        GetLatestGpuValuesAsFieldDict() gives us a dictionary that maps
        gpu ids to the GPU value dictionary. The GPU value dictionary maps each
        field name to the value for that field. This will publish each in the format
        GPU:<GPU ID>:fieldTag=value
```

```

NOTE: if you prefer to use field ids instead of field tags
(names) see
    GetLatestGpuValueAsFieldIdDict()
    '''
    data = dr.GetLatestGpuValuesAsFieldDict()
    for gpuId in data:
        for fieldTag in data[gpuId]:
            msg = "GPU:%s:%s=%s" % (str(gpuId), fieldTag,
val.value)
            self.m_zmqSocket.send("%s %s" % (fieldTag,
message))
if __name__ == '__main__':
    main()

```

This method permits you to use DcgmReader without learning much about it.

## 4.1.2. Reading Using Inheritance

Using inheritance allows finer-grained controls.

```

# inheritance_reader_example.py
from DcgmReader import DcgmReader
import zmq
import time

class DcgmPublisher(DcgmReader):
    # Have our constructor also open a ZMQ socket for publishing.
    def __init__(self, port=4096):
        DcgmReader.__init__(self)
        context = zmq.Context()
        self.m_zmqSocket = context.socket(zmq.PUB)
        self.m_zmqSocket.bind("tcp://*:%d" % (port))

        '''
        Publish the fieldTag as the topic and the message data as
        "GPU:<GPU ID>:fieldTag=value"
        This overrides the method in DcgmReader for what to do with each
        field. If you want additional controls, consider overriding
        CustomDataHandler from the parent class.
        '''

    def CustomFieldHandler(self, gpuId, fieldId, fieldTag, val):
        topic = fieldTag
        message = "GPU:%s:%s=%s" % (str(gpuId), fieldTag, val.value)
        self.m_zmqSocket.send("%s %s" % (topic, message))

def main():
    dp = DcgmPublisher()

    while True:
        # Process is a method in DcgmReader that gets the data and starts
        # processing it, resulting in our version of CustomFieldHandler
        # getting called.
        dp.Process()
        time.sleep(15)

if __name__ == '__main__':
    main()

```

This method grants you more control over DcgmReader.

### 4.1.3. Completing the Proof of Concept

Either script – when run with DCGM installed and an active nv-hostengine - will publish data on port 4096. The following script will subscribe and print that data.



To run the subscriber from a different host, simply change localhost on line 5 to the IP address of the remote machine that is publishing data from DCGM. As is, the script will connect locally.

```
# subscriber_example.py
import zmq

port = 4096
context = zmq.Context()
socket = context.socket(zmq.SUB)
# Change localhost to the ip addr of the publisher if remote
socket.connect("tcp://localhost:%d" % (port))
socket.setsockopt(zmq.SUBSCRIBE, '')

while True:
    update = socket.recv()
    topic, message = update.split()
    print message
```

### 4.1.4. Additional Customization

DcgmReader gathers the following fields by default:

```
defaultFieldIds = [
    dcgm_fields.DCGM_FI_DRIVER_VERSION,
    dcgm_fields.DCGM_FI_NVML_VERSION,
    dcgm_fields.DCGM_FI_PROCESS_NAME,
    dcgm_fields.DCGM_FI_DEV_POWER_USAGE,
    dcgm_fields.DCGM_FI_DEV_GPU_TEMP,
    dcgm_fields.DCGM_FI_DEV_SM_CLOCK,
    dcgm_fields.DCGM_FI_DEV_GPU_UTIL,
    dcgm_fields.DCGM_FI_DEV_RETIRED_PENDING,
    dcgm_fields.DCGM_FI_DEV_RETIRED_SBE,
    dcgm_fields.DCGM_FI_DEV_RETIRED_DBE,
    dcgm_fields.DCGM_FI_DEV_ECC_SBE_VOL_TOTAL,
    dcgm_fields.DCGM_FI_DEV_ECC_DBE_VOL_TOTAL,
    dcgm_fields.DCGM_FI_DEV_ECC_SBE_AGG_TOTAL,
    dcgm_fields.DCGM_FI_DEV_ECC_DBE_AGG_TOTAL,
    dcgm_fields.DCGM_FI_DEV_FB_TOTAL,
    dcgm_fields.DCGM_FI_DEV_FB_FREE,
    dcgm_fields.DCGM_FI_DEV_FB_USED,
    dcgm_fields.DCGM_FI_DEV_PCIE_REPLAY_COUNTER,
    dcgm_fields.DCGM_FI_DEV_COMPUTE_PIDS,
    dcgm_fields.DCGM_FI_DEV_POWER_VIOLATION,
    dcgm_fields.DCGM_FI_DEV_THERMAL_VIOLATION,
    dcgm_fields.DCGM_FI_DEV_XID_ERRORS,
    dcgm_fields.DCGM_FI_DEV_NVLINK_CRC_FLIT_ERROR_COUNT_TOTAL,
    dcgm_fields.DCGM_FI_DEV_NVLINK_CRC_DATA_ERROR_COUNT_TOTAL,
    dcgm_fields.DCGM_FI_DEV_NVLINK_REPLAY_ERROR_COUNT_TOTAL,
    dcgm_fields.DCGM_FI_DEV_NVLINK_RECOVERY_ERROR_COUNT_TOTAL
]
```

There are hundreds more fields that DCGM provides, and you may be interested in monitoring different ones. You can control this in your script by instantiating `DcgmReader` with parameters:

```
# custom_fields_example.py
myFieldIds = [
    dcgm_fields.DCGM_FI_DEV_SM_CLOCK,
    dcgm_fields.DCGM_FI_DEV_MEM_CLOCK,
    dcgm_fields.DCGM_FI_DEV_APP_CLOCK,
    dcgm_fields.DCGM_FI_DEV_MEMORY_TEMP,
    dcgm_fields.DCGM_FI_DEV_GPU_TEMP,
    dcgm_fields.DCGM_FI_DEV_POWER_USAGE,
    dcgm_fields.DCGM_FI_DEV_GPU_UTIL,
    dcgm_fields.DCGM_FI_DEV_MEM_COPY_UTIL,
    dcgm_fields.DCGM_FI_DEV_COMPUTE_FIDS]
...
# In main(), change the instantiation:
dr = DcgmReader(fieldIds=myFieldIds)
...
```

You can control other behaviors of `DcgmReader` using these additional parameters:

- ▶ **hostname:** defaults to localhost. Controls the hostname[:port] where we connected to DCGM.
- ▶ **fieldIds:** explained above. Controls the fields we are going to watch and read in DCGM.
- ▶ **updateFrequency:** defaults to 10 seconds (specified in microseconds). Controls how often DCGM refreshes each field value.
- ▶ **maxKeepAge:** defaults to 1 hour (specified in seconds). Controls how long DCGM keeps data for each of the specified fields.
- ▶ **ignoreList:** defaults to an empty array. Specifies field ids that should be retrieved but should be ignored for processing. Usually used for metadata. •
- ▶ **fieldGroupName:** defaults to `dcgm_fieldgroupData`. Controls the name that `DcgmReader` gives to the group of fields we are watching. This is useful for running multiple instances of `DcgmReader` simultaneously

## 4.2. Integrating with Prometheus and Grafana

### 4.2.1. Starting the Prometheus Server

On the server side, configure Prometheus to read (scrape) the data being published by the `dcgm_prometheus` client. Just add a job to the `scrape_configs` section of the yaml Prometheus configuration file. See the following section of a working configuration:

```
# A scrape configuration containing exactly one endpoint to scrape:
scrape_configs:
  # The job name is added as a label `job=<job_name>` to any timeseries scraped
  # from this config.
  - job_name: 'dcgm'

    # metrics_path defaults to '/metrics'
    # scheme defaults to 'http'.
```

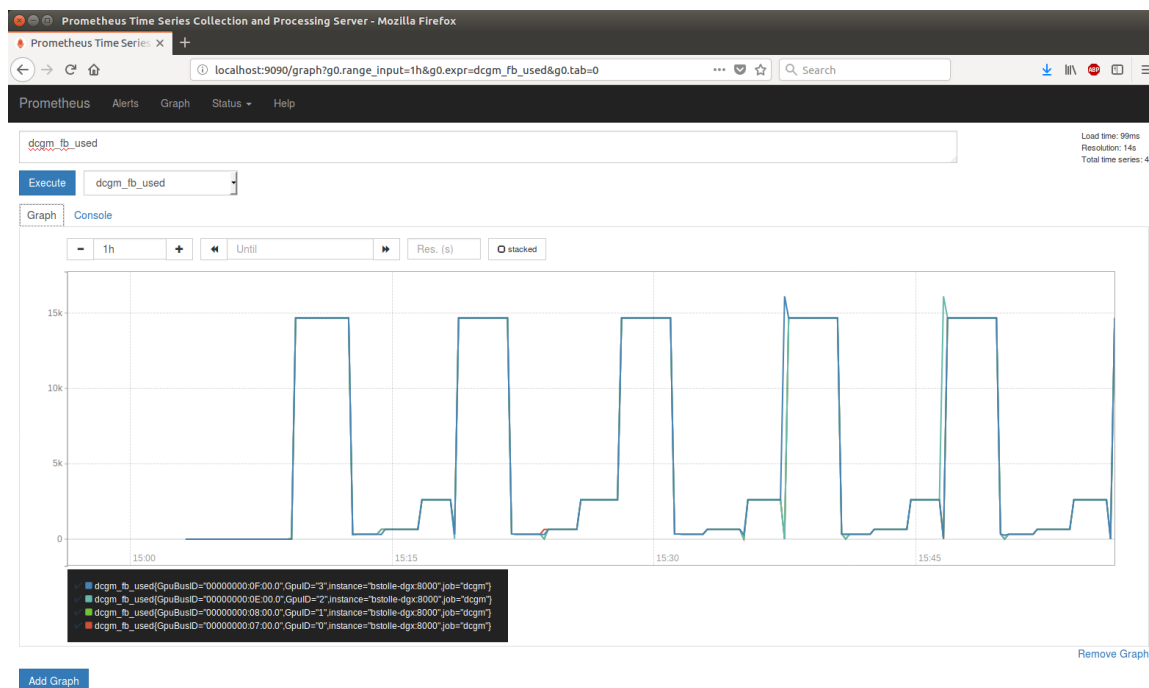
```
static_configs:
  - targets: ['hostnameWhereClientIsRunning:8000']
```

Replace 'hostnameWhereClientIsRunning' with the name or ip address of the host where the client is running, or localhost if both are executing on the same host.

Once the configure file has been updated, launch Prometheus with the specified configuration file:

```
$ ./prometheus --config.file=prometheus.yml
```

Verify that Prometheus is up and running by opening a browser to <http://localhost:9090>. Select a metric in the box next to the 'Execute' button, click the 'Execute' button, and then select the 'Graph' tab. The page should display:



## 4.2.2. Starting the Prometheus Client

The script `dcm_prometheus.py` is provided as a fully functional Prometheus client that will publish timeseries data on a port to be read (scraped) by Prometheus. By default, this script will publish common fields read from a DCGM instance running locally every 10 seconds to `localhost:8000`. Information on controlling what is published, how often, and on what port will be in the section on customization.

On the client side, start this script. It can either connect to a standalone host engine or run on embedded in the script. To start an embedded host engine and check that it is publishing:

```
$ python dcm_prometheus.py -e
$ curl localhost:8000 > tmp.txt
```



```

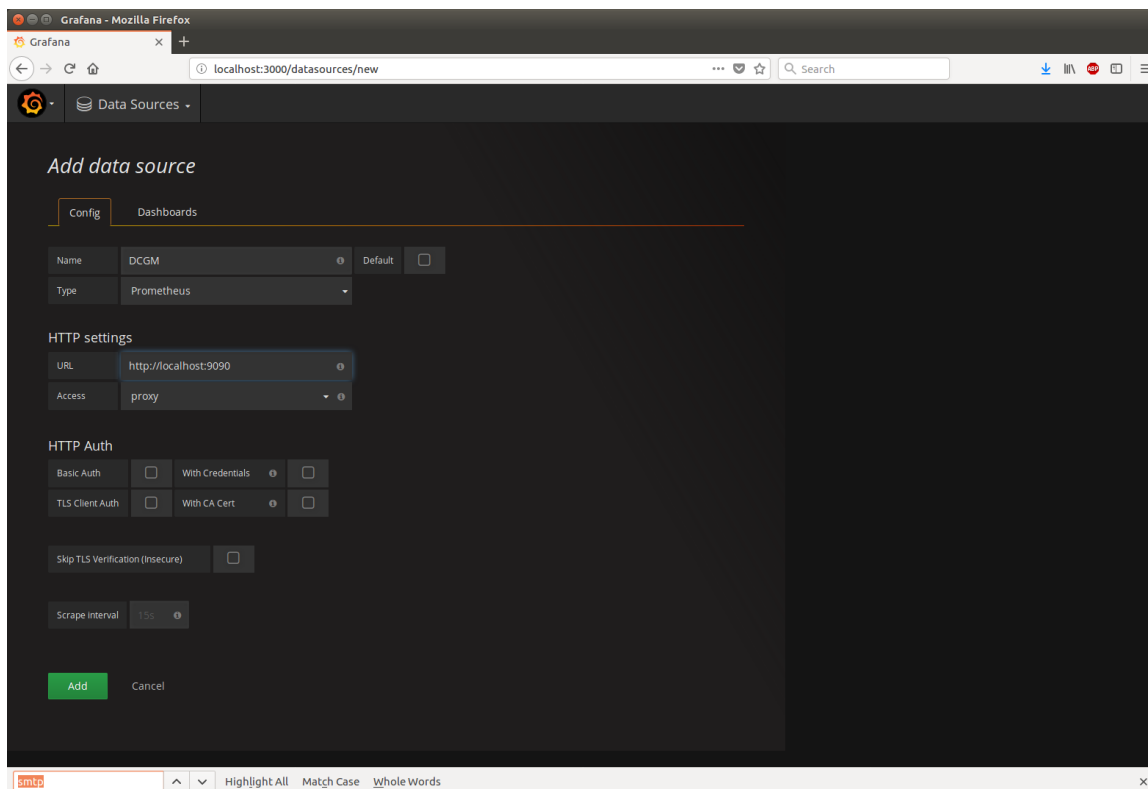
# HELP dcgm_sm_clock DCGM_PROMETHEUS
# TYPE dcgm_sm_clock gauge
dcgm_sm_clock{GpuBusID="00000000:08:00.0",GpuID="1"} 1480.0
dcgm_sm_clock{GpuBusID="00000000:07:00.0",GpuID="0"} 1480.0
dcgm_sm_clock{GpuBusID="00000000:0E:00.0",GpuID="2"} 1480.0
dcgm_sm_clock{GpuBusID="00000000:0F:00.0",GpuID="3"} 1480.0
# HELP dcgm_nvlink_flit_crc_error_count_total DCGM_PROMETHEUS
# TYPE dcgm_nvlink_flit_crc_error_count_total gauge
dcgm_nvlink_flit_crc_error_count_total{GpuBusID="00000000:08:00.0",GpuID="1"}
0.0
dcgm_nvlink_flit_crc_error_count_total{GpuBusID="00000000:0E:00.0",GpuID="2"}
0.0
dcgm_nvlink_flit_crc_error_count_total{GpuBusID="00000000:0F:00.0",GpuID="3"}
0.0
# HELP dcgm_power_usage DCGM_PROMETHEUS
# TYPE dcgm_power_usage gauge
dcgm_power_usage{GpuBusID="00000000:08:00.0",GpuID="1"} 294.969
dcgm_power_usage{GpuBusID="00000000:07:00.0",GpuID="0"} 273.121
dcgm_power_usage{GpuBusID="00000000:0E:00.0",GpuID="2"} 280.484
dcgm_power_usage{GpuBusID="00000000:0F:00.0",GpuID="3"} 281.301
# HELP dcgm_nvlink_data_crc_error_count_total DCGM_PROMETHEUS
# TYPE dcgm_nvlink_data_crc_error_count_total gauge
dcgm_nvlink_data_crc_error_count_total{GpuBusID="00000000:08:00.0",GpuID="1"}
0.0
dcgm_nvlink_data_crc_error_count_total{GpuBusID="00000000:0E:00.0",GpuID="2"}
0.0
dcgm_nvlink_data_crc_error_count_total{GpuBusID="00000000:0F:00.0",GpuID="3"}
0.0
...

```

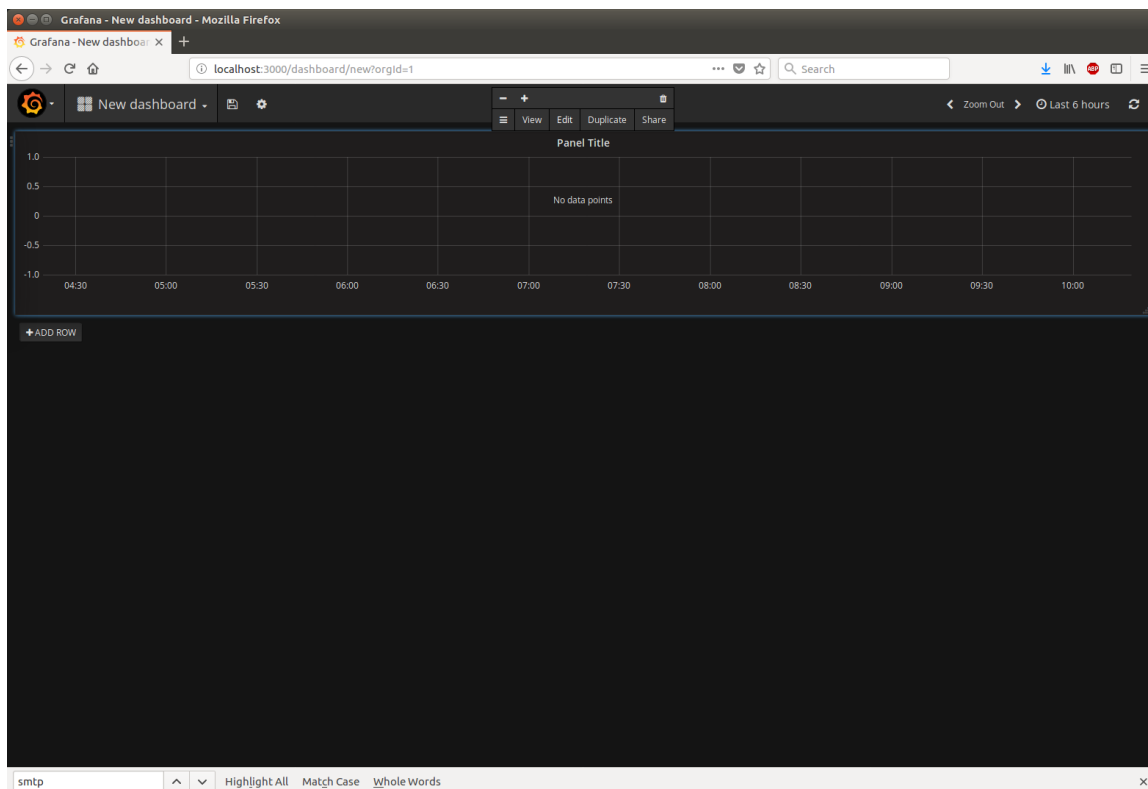
The number of GPUs may vary, and the published field ids can be changed through configuration, but the output should conform to the above format.

### 4.2.3. Integrating with Grafana

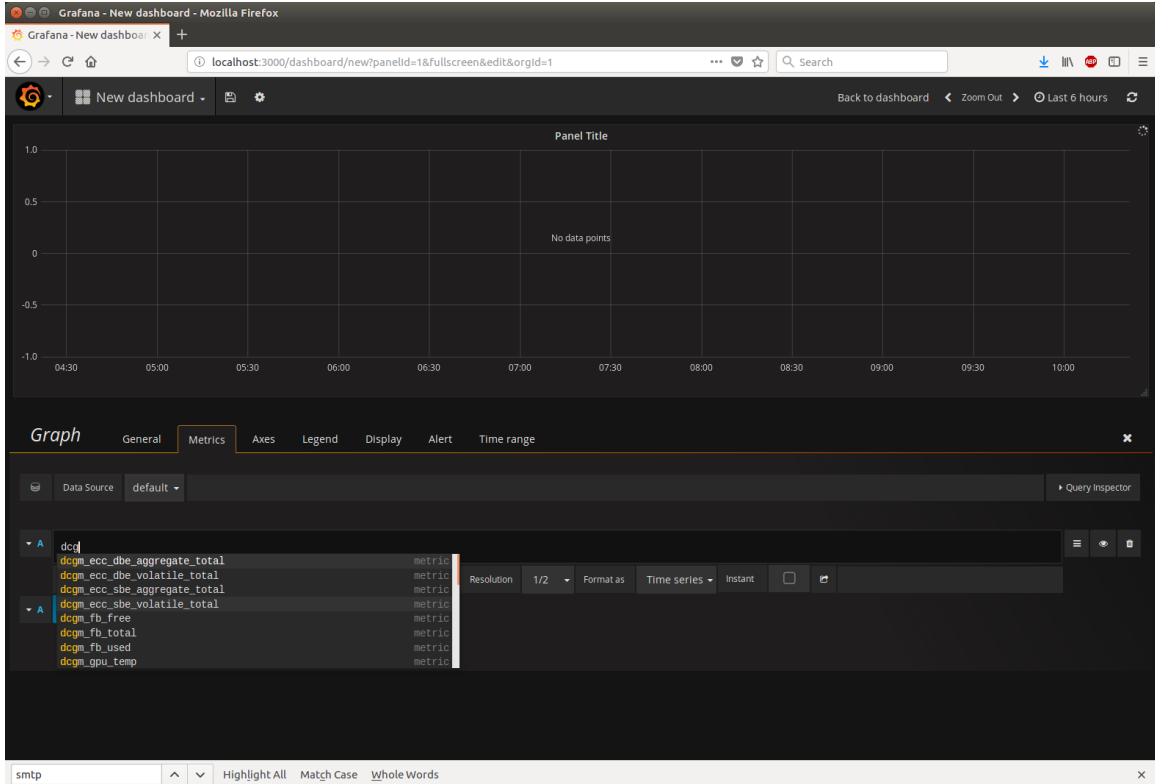
Grafana offers additional features such as configurable dashboards and integration with Grafana is straightforward. Install and launch Grafana, and then open a browser to <http://localhost:3000>. The default login / password is admin / admin. After logging in, click on the Grafana icon and select the 'Data Sources' option. Configure the Prometheus server as a data source:



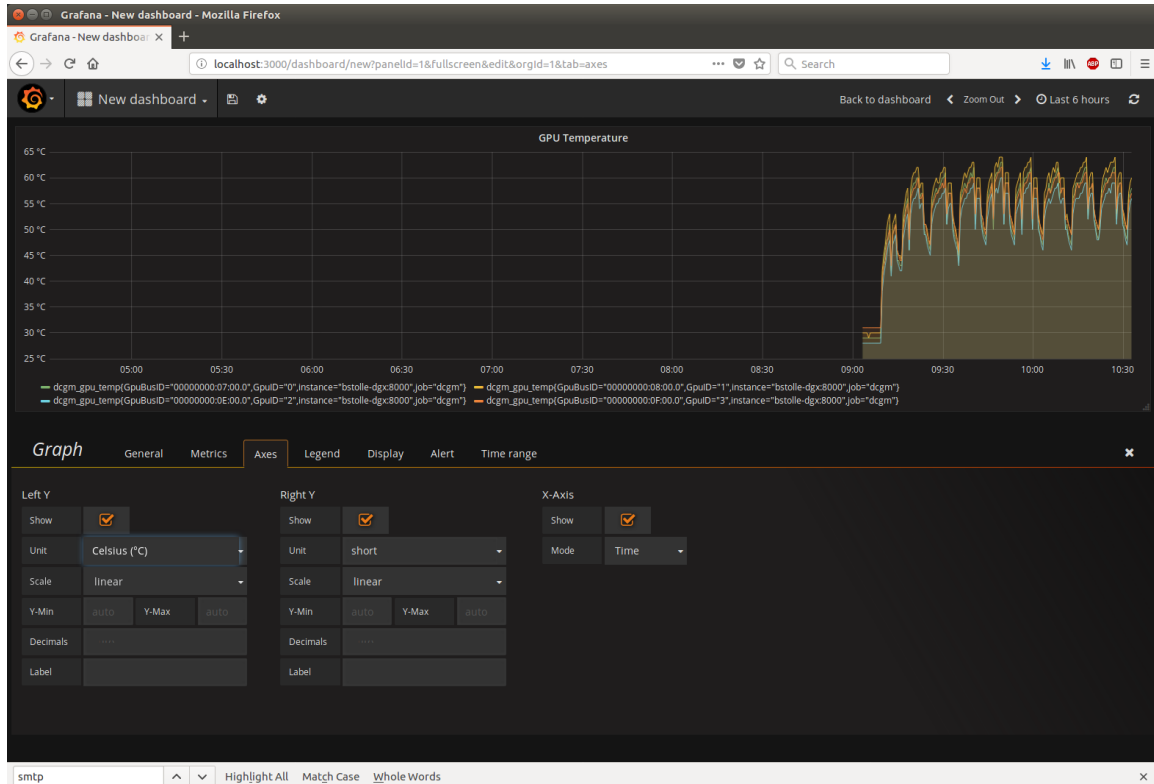
Click 'Add' and then create a dashboard using the data that is scraped from the DCGM Prometheus client. Click the Grafana icon again and then Dashboards -> New. There are a lot of ways to customize dashboards; to create a dashboard with graphs, click the 'Graph' option at the top. Select 'Panel Title' and then 'Edit':



Type `dcgm` into the metric name box as shown below, and Grafana will offer you auto-completion options for the DCGM fields you have configured. If this doesn't happen, then the data source wasn't configured correctly, or Prometheus has stopped running.



Use the different tabs to customize the graph as desired. This graph has the metric `dcm_gpu_temp` selected, and the title changed via the 'General', plus the units set to Celsius via the Axes tab.



## 4.2.4. Customizing the Prometheus Client

The DCGM Prometheus client can be controlled using command line parameters:

- ▶ `-n, --hostname`: specifies the hostname of the DCGM instance we're querying for data. Default: localhost. Mutually exclusive with `-e`.
- ▶ `-e, --embedded`: start an embedded hostengine from this script instead of connecting to a standalone hostengine. Mutually exclusive with `-n`.
- ▶ `-p, --publish-port`: specifies the port where data is published. Default: 8000. Please note that if you change this you'll need to change the Prometheus configuration accordingly.
- ▶ `-i, --interval`: specifies the interval at which DCGM is queried and data is published in seconds. Default: 10.
- ▶ `-l, --ignore-list`: specifies fields queried but not published. Default: DCGM\_FI\_DEV\_PCI\_BUSID (57).
- ▶ `--log-file`: Specifies the path to a log file. If this is used without `--log-level`, then only critical information is logged.
- ▶ `--log-level`: One of CRITICAL (0), ERROR (1), WARNING (2), INFO (3), or DEBUG (4) to specify what kind of information should be logged. If this is used without `--log-file`, then the information is logged to stdout.
- ▶ `-f, --field-ids`: specifies the list of fields queried and published from DCGM. Default:

```
DCGM_FI_DEV_PCI_BUSID (57)
DCGM_FI_DEV_POWER_USAGE (155)
DCGM_FI_DEV_GPU_TEMP (150)
DCGM_FI_DEV_SM_CLOCK (100)
```

```

DCGM_FI_DEV_GPU_UTIL (203)
DCGM_FI_DEV_RETIRED_PENDING (392)
DCGM_FI_DEV_RETIRED_SBE (390)
DCGM_FI_DEV_RETIRED_DBE (391)
DCGM_FI_DEV_ECC_SBE_AGG_TOTAL (312)
DCGM_FI_DEV_ECC_DBE_AGG_TOTAL (313)
DCGM_FI_DEV_FB_TOTAL (250)
DCGM_FI_DEV_FB_FREE (251)
DCGM_FI_DEV_FB_USED (252)
DCGM_FI_DEV_PCIE_REPLAY_COUNTER (202)
DCGM_FI_DEV_ECC_SBE_VOL_TOTAL (310)
DCGM_FI_DEV_ECC_DBE_VOL_TOTAL (311)
DCGM_FI_DEV_POWER_VIOLATION (240)
DCGM_FI_DEV_THERMAL_VIOLATION (241)
DCGM_FI_DEV_XID_ERRORS (230)
DCGM_FI_DEV_NVLINK_CRC_FLIT_ERROR_COUNT_TOTAL (409)
DCGM_FI_DEV_NVLINK_CRC_DATA_ERROR_COUNT_TOTAL (419)
DCGM_FI_DEV_NVLINK_REPLAY_ERROR_COUNT_TOTAL (429)
DCGM_FI_DEV_NVLINK_RECOVERY_ERROR_COUNT_TOTAL (439)

```

## Example Usages

```

#Change the DCGM host to one named sel:
$ python dcmg\_prometheus.py -n sel
# Change the port:
$ python dcmg\_prometheus.py -p 10101
# Change the interval
$ python dcmg\_prometheus.py -i 20
# Change the ignore list and publish list:
$ python dcmg\_prometheus.py -l 523 -f 523,310,311,312

```

# Chapter 5.

## DCGM DIAGNOSTICS

### 5.1. Overview

The NVIDIA Validation Suite (NVVS) is now called DCGM Diagnostics. As of DCGM v1.5, running NVVS as a standalone utility is now deprecated and all the functionality (including command line options) is available via the DCGM command-line utility ('dcgmi'). For brevity, the rest of the document may use *DCGM Diagnostics* and *NVVS* interchangeably.

#### 5.1.1. DCGM Diagnostics Goals

DCGM Diagnostics are designed to:

1. Provide a system-level tool, in production environments, to assess cluster readiness levels before a workload is deployed.
2. Facilitate multiple run modes:
  - ▶ Interactive via an administrator or user in plain text.
  - ▶ Scripted via another tool with easily parseable output.
3. Provide multiple test timeframes to facilitate different preparedness or failure conditions:
  - ▶ Level 1 tests to use as a readiness metric
  - ▶ Level 2 tests to use as an epilogue on failure
  - ▶ Level 3 tests to be run by an administrator as post-mortem
4. Integrate the following concepts into a single tool to discover deployment, system software and hardware configuration issues, basic diagnostics, integration issues, and relative system performance.
  - ▶ Deployment and Software Issues
    - ▶ NVML library access and versioning
    - ▶ CUDA library access and versioning
    - ▶ Software conflicts

- ▶ Hardware Issues and Diagnostics
    - ▶ Pending Page Retirements
    - ▶ PCIe interface checks
    - ▶ NVLink interface checks
    - ▶ Framebuffer and memory checks
    - ▶ Compute engine checks
  - ▶ Integration Issues
    - ▶ PCIe replay counter checks
    - ▶ Topological limitations
    - ▶ Permissions, driver, and cgroups checks
    - ▶ Basic power and thermal constraint checks
  - ▶ Stress Checks
    - ▶ Power and thermal stress
    - ▶ Throughput stress
    - ▶ Constant relative system performance
    - ▶ Maximum relative system performance
    - ▶ Memory Bandwidth
5. Provide troubleshooting help
  6. Easily integrate into *Cluster Scheduler* and *Cluster Management* applications
  7. Reduce downtime and failed GPU jobs

## 5.1.2. Beyond the Scope of the DCGM Diagnostics

DCGM Diagnostics are not designed to:

1. Provide comprehensive hardware diagnostics
2. Actively fix problems
3. Replace the field diagnosis tools. Please refer to <http://docs.nvidia.com/deploy/hw-field-diag/index.html> for that process.
4. Facilitate any RMA process. Please refer to <http://docs.nvidia.com/deploy/rma-process/index.html> for those procedures.

## 5.1.3. Dependencies

- ▶ DCGM Diagnostics require a NVIDIA Linux driver to be installed. Both the standard display driver and Tesla Recommended Driver will work. You can obtain a driver from <http://www.nvidia.com/object/unix.html>.
- ▶ DCGM Diagnostics require the standard C++ runtime library with GLIBCXX of at least version 3.4.5 or greater.

## 5.1.4. Supported Products

DCGM Diagnostics support NVIDIA Data center GPUs running on 64-bit Linux (bare metal) operating systems. NVIDIA<sup>®</sup> Tesla<sup>™</sup> Line:

- ▶ All Kepler, Maxwell, Pascal, Volta, Turing and NVIDIA Ampere architecture GPUs



## 5.2. Using DCGM Diagnostics

The various command line options of DCGM Diagnostics are designed to control general execution parameters, whereas detailed changes to execution behavior are contained within the configuration files detailed in the next chapter.

### 5.2.1. Command line options

The various options for `dcgmi diag` are as follows:

Short option	Long option	Description
	<code>--statspath</code>	Write the plugin statistics to a given path rather than the current directory.
<code>-a</code>	<code>--appendLog</code>	When generating a debug logfile, do not overwrite the contents of a current log. Used in conjunction with the <code>-d</code> and <code>-l</code> options.
<code>-c</code>	<code>--configfile</code>	Specify the configuration file to be used. The default is that no config file is used.
<code>-i</code>	<code>--gpuList</code>	Comma separated list of the indexes of the GPUs to run NVVS on. This cannot be used in conjunction with <code>-g</code> (group). If neither are specified, then the diagnostic is run on all GPUs.
<code>-j</code>	<code>--jsonOutput</code>	Provide the output in JSON instead of text.
<code>-d</code>	<code>--debugLevel</code>	Specify the debug level for the output log. The range is 0 to 5 with 5 being the most verbose.
	<code>--debugLogFile</code>	Specify the logfile for debug information. This will produce an encrypted log file intended to be returned to NVIDIA for post-run analysis after an error.
	<code>--plugin-path</code>	Specify a custom path for the NVVS plugins. The plugins must have the same permissions and owner as the NVVS executable.
<code>-r</code>	<code>--run</code>	Run a specific test or test suite. Test suites are 1 (short), 2 (medium), or 3 (long). Use quotes to specify individual tests, and use commas to separate multiple tests. For example: <code>-p "diagnostic,sm stress"</code> . This argument is mandatory.

Short option	Long option	Description
<i>-p</i>	<i>--parameters</i>	Specify test parameters via the command-line. Use quotes around the argument, and separate the arguments using ';'. For example: <code>-p "sm stress.test_duration=150;diagnostic.test_duration=150"</code> would set the test duration for the hardware Diagnostic and the SM Stress test to 150 seconds each.
	<i>--host</i>	Specifies the host of the nv-hostengine we want to connect to. Defaults to localhost.
	<i>--statsonfail</i>	Output statistic logs only if a test failure is encountered.
	<i>throttle-mask</i>	Specify which throttling reasons should be ignored. You can provide a comma separated list of reasons. For example, specifying 'HW_SLOWDOWN,SW_THERMAL' would ignore the HW_SLOWDOWN and SW_THERMAL throttling reasons. Alternatively, you can specify the integer value of the ignore bitmask. For the bitmask, multiple reasons may be specified by the sum of their bit masks. For example, specifying '40' would ignore the HW_SLOWDOWN and SW_THERMAL throttling reasons. Valid throttling reasons and their corresponding bitmasks (given in parentheses) are: "HW_SLOWDOWN (8) SW_THERMAL (32) HW_THERMAL (64) HW_POWER_BRAKE (128)
	<i>--train</i>	Runs the diagnostic iteratively and generate a configure file of the golden values for this system based on the results of multiple runs of the diagnostic tests. This should be used when you wish to restrict what the acceptable standards for the plugins are to ensure that your system conforms to a higher standard. This is intended for systems which have a known, stable configuration. This is a beta feature for the 1.6 release.
	<i>--force</i>	Ignore non-fatal errors and train the diagnostic. For example, if too great coefficient of variance is found among the test runs, then the results would normally be thrown out and no file would

Short option	Long option	Description
		be generated. <code>--force</code> will create the file and ignore these conditions.
	<code>--training-iterations</code>	Specifies the number of times the diagnostic tests are each run during training. The default is 4.
	<code>--training-variance</code>	Specifies the acceptable coefficient of variance required to trust the data and generate a golden values configuration file in training. The default is 5, which means the coefficient of variance has to be .05 or less to trust the data.
	<code>--training-tolerance</code>	The percentage that the golden value should be scaled for tolerance when producing the file. For example, if 10 were specified, then values would be adjusted to tolerate 10% off of the standard before writing the config file so that runs do not have to achieve exactly the same result (or better) as the training runs. Default is 5.
	<code>--golden-values-filename</code>	Specify the filename of the golden values file. These files are written to the <code>/tmp</code> dir, and the default name is <code>golden_values.yml</code> .
<code>-v</code>	<code>--verbose</code>	Enable verbose output.
<code>-g</code>	<code>--group</code>	Specifies the list of GPUs on which the diagnostic should run. If no group is specified, the diagnostic is run on all GPUs.
<code>-h</code>	<code>--help</code>	Display usage information and exit.

NVVS has been deprecated. The various options for NVVS are as follows:

Short option	Long option	Description
	<code>--statspath</code>	Write the plugin statistics to a given path rather than the current directory.
<code>-a</code>	<code>--appendLog</code>	When generating a debug logfile, do not overwrite the contents of a current log. Used in conjunction with the <code>-d</code> and <code>-l</code> options.
<code>-c</code>	<code>--config</code>	Specify the configuration file to be used. The default is <code>/etc/nvidia-validation-suite/nvvs.conf</code>

Short option	Long option	Description
	<i>--configless</i>	Run NVVS in a configless mode. Executes a "long" test on all supported GPUs.
<i>-d</i>	<i>--debugLevel</i>	Specify the debug level for the output log. The range is 0 to 5 with 5 being the most verbose. Used in conjunction with the <i>-l</i> flag.
<i>-g</i>	<i>--listGpus</i>	List the GPUs available and exit. This will only list GPUs that are supported by NVVS.
<i>-i</i>	<i>--indexes</i>	Comma separated list of indexes to run NVVS on.
<i>-j</i>	<i>--jsonOutput</i>	Instructs nvvs to format the output as JSON.
<i>-l</i>	<i>--debugLogFile</i>	Specify the logfile for debug information. This will produce an encrypted log file intended to be returned to NVIDIA for post-run analysis after an error.
	<i>--quiet</i>	No console output given. See logs and return code for errors.
<i>-p</i>	<i>--pluginpath</i>	Specify a custom path for the NVVS plugins.
<i>-s</i>	<i>--scriptable</i>	Produce output in a colon-separated, more script-friendly and parseable format.
	<i>--specifiedtest</i>	Run a specific test in a configless mode. Multiple word tests should be in quotes, and if more than one test is specified it should be comma-separated.
	<i>--parameters</i>	Specify test parameters via the command-line. For example: <i>--parameters "sm stress.test_duration=300"</i> would set the test duration for the SM Stress test to 300 seconds.
	<i>--statsonfail</i>	Output statistic logs only if a test failure is encountered.
<i>-t</i>	<i>--listTests</i>	List the tests available to be executed through NVVS and exit. This will list only the readily loadable tests given the current path and library conditions.
<i>-v</i>	<i>--verbose</i>	Enable verbose reporting.
	<i>--version</i>	Displays the version information and exits.

Short option	Long option	Description
<code>-h</code>	<code>--help</code>	Display usage information and exit.

## 5.2.2. Usage Examples

To display the list of GPUs available on the system.

```
user@hostname
$ nvvs -g

NVIDIA Validation Suite (version 352.00)

Supported GPUs available:
[0000:01:00.0] -- Tesla K40c
[0000:05:00.0] -- Tesla K20c
[0000:06:00.0] -- Tesla K20c
```

An example "quick" test (explained later) using a custom configuration file.

```
user@hostname
$ nvvs -c Tesla_K40c_quick.conf

NVIDIA Validation Suite (version 352.00)

Software
Blacklist ..... PASS
NVML Library ..... PASS
CUDA Main Library ..... PASS
CUDA Toolkit Libraries ..... PASS
Permissions and OS-related Blocks ..... PASS
Persistence Mode ..... PASS
Environmental Variables ..... PASS
```

To output an encrypted debug file at the highest debug level to send to NVIDIA for analysis after a problem.

```
user@hostname
$ nvvs -c Tesla_K40c_medium.conf -d 5 -l debug.log

NVIDIA Validation Suite (version 352.00)

Software
Blacklist ..... PASS
NVML Library ..... PASS
CUDA Main Library ..... PASS
CUDA Toolkit Libraries ..... PASS
Permissions and OS-related Blocks ..... PASS
Persistence Mode ..... PASS
Environmental Variables ..... PASS
Hardware
Memory GPU0 ..... PASS
Integration
PCIe ..... FAIL
*** GPU 0 is running at PCI link width 8X, which is below the minimum
allowed link width of 16X (parameter:
min_pci_width)"
```

The output file, `debug.log` would then be returned to NVIDIA.

### 5.2.3. Configuration file

The NVVS configuration file is a **YAML**-formatted (e.g. human-readable JSON) text file with three main stanzas controlling the various tests and their execution.

The general format of a configuration file consists of:

```
%YAML 1.2
---

globals:
  key1: value
  key2: value

test_suite_name:
- test_class_name1:
  test_name1:
    key1: value
    key2: value
  subtests:
    subtest_name1:
      key1: value
      key2: value
  test_name2:
    key1: value
    key2: value
- test_class_name2:
  test_name3:
    key1: value
    key2: value

gpus:
- gpuset: name
  properties:
    key1: value
    key2: value
  tests:
    name: test_suite_name
```

There are three distinct sections: *globals*, *test\_suite\_name*, and *gpus* each with its own subsection of parameters and as is with any YAML document, **indentation is important** thus if errors are generated from your own configuration files please refer to this example for indentation reference.

### 5.2.4. Global parameters

Keyword	Value Type	Description
logfile	String	The prefix for all detailed test data able to be used for post-processing.
logfile_type	String	Can be <i>json</i> , <i>text</i> , or <i>binary</i> . Used in conjunction with the logfile global parameter. Default is JSON.
scriptable	Boolean	Accepts <i>true</i> , or <i>false</i> . Produces a script-friendly, colon-separated

Keyword	Value Type	Description
		output and is identical to the <code>-s</code> command line parameter.
<code>serial_override</code>	Boolean	Accepts <i>true</i> , or <i>false</i> . Some tests are designed to run in parallel if multiple GPUs are given. This parameter overrides that behavior serializing execution across all tests.
<code>require_persistence_mode</code>	Boolean	Accepts <i>true</i> , or <i>false</i> . Persistence mode is a prerequisite for some tests, this global overrides that requirement and should only be used if it is not possible to activate persistence mode on your system.

## 5.2.5. GPU parameters

The `gpus` stanza may consist of one or more `gpuset`s which will each match zero or more GPUs on the system based on their *properties*(a match of zero will produce an error).

GPUs are matched based on the following criteria with their configuration file keywords in parenthesis:

- ▶ Name of the GPU, i.e. Tesla K40c (*name*)
- ▶ Brand of the GPU, i.e. Tesla (*brand*)
- ▶ A comma separated list of indexes (*index*)
- ▶ The GPU UUID (*uuid*)
- ▶ or the PCIe Bus ID (*busid*)

The matching rules are based off of exclusion. First, the list of supported GPUs is taken and if no *properties* tag is given then all GPUs will be used in the test. Because a UUID or PCIe Bus ID can only match a single GPU, if those properties are given then only that GPU will be used if found. The remaining properties, *index*, *brand*, and *name* work in an "AND" fashion such that, if specified, the result must match at least one GPU on the system for a test to be performed.

For example, if *name* is set to "Tesla K40c" and *index* is set to "0" NVVS will error if index 0 is not a Tesla K40c. By specifying both *brand* and *index* a user may limit a test to specific "Tesla" cards for example. **In this version of NVVS, all matching GPUs must be homogeneous.**

The second identifier for a `gpuset` is *tests*. This parameter specifies either the suite of tests that a user wishes to run or the test itself.

At present the following suites are available:

- ▶ *Quick* -- meant as a pre-run sanity check to ensure that the GPUs are ready for a job. Currently runs the Deployment tests described in the next chapter.
- ▶ *Medium* -- meant as a quick, post-error check to make sure that nothing very obvious such as ECC enablement or double-bit errors have occurred on a GPU.

Currently runs the Deployment, Memory/Hardware, and PCIe/Bandwidth tests. The Hardware tests are meant to be relatively short to find obvious issues.

- ▶ *Long* -- meant as a more extensive check to find potential power and/or performance problems within a cluster. Currently runs an extensive test that involves Deployment, Memory/Hardware, PCI/Bandwidth, Power, Stress, and Memory Bandwidth. The Hardware tests will run in a longer-term iterative mode that are meant to try and capture transient failures as well as obvious issues.

An individual test can also be specified. Currently the keywords are: *Memory*, *Diagnostic*, *Targeted Stress*, *Targeted Power*, *PCIe*, *SM Stress*, and *Memory Bandwidth*. Please see the "custom" section in the next subchapter to configure and tweak the parameters when this method is used.

## 5.2.6. Test Parameters

The format of the NVVS configuration file is designed for extensibility. Each test suite above can be customized in a number of ways described in detail in the following chapter for each test. Individual tests belong to a specific class of functionality which, when wanting to customize specific parameters, must also be specified.

The classes and the respective tests they perform are as follows:

Class name	Tests	Brief description
Software	Deployment	Checks for various runtime libraries, persistence mode, permissions, environmental variables, and blacklisted drivers.
Hardware	Diagnostic	Execute a series of hardware diagnostics meant to exercise a GPU or GPUs to their factory specified limits.
Integration	PCIe	Test host to GPU, GPU to host, and P2P (if possible) bandwidth. P2P between GPUs occurs over NVLink (if possible) or PCIe.
Stress	Targeted Stress	Sustain a specific targeted stress level for a given amount of time.
	Targeted Power	Sustain a specific targeted power level for a given amount of time.
	SM Stress	Sustain a workload on the Streaming Multiprocessors (SMs) of the GPU for a given amount of time.
	Memory Bandwidth	Verify that a certain memory bandwidth can be achieved on the framebuffer of the GPU.



Some tests also have subtests that can be enabled by using the *subtests* keyword and then hierarchically adding the subtest parameters desired beneath. An example would be the PCIe Bandwidth test which may have a section that looks similar to this:

```
long:
- integration:
  pci:
    test_unpinned: false
    subtests:
      h2d_d2h_single_pinned:
        min_bandwidth: 20
        min_pci_width: 16
```

When only a specific test is given in the GPU set portion of the configuration file, both the suite and class of the test are *custom*. For example:

```
%YAML 1.2
---

globals:
  logfile: nvvs.log

custom:
- custom:
  targeted stress:
    test_duration: 60

gpus:
- gpuset: all_K40c
  properties:
    name: Tesla K40c
  tests:
    - name: targeted stress
```

## 5.3. Overview of Plugins

The NVIDIA Validation Suite consists of a series of plugins that are each designed to accomplish a different goal.

### 5.3.1. Deployment Plugin

The deployment plugin's purpose is to verify the compute environment is ready to run Cuda applications and is able to load the NVML library.

#### Preconditions

- ▶ `LD_LIBRARY_PATH` must include the path to the cuda libraries, which for version X.Y of Cuda is normally `/usr/local/cuda-X.Y/lib64`, which can be set by running `export LD_LIBRARY_PATH=/usr/local/cuda-X.Y/lib64`
- ▶ The linux nouveau driver must not be running, and should be blacklisted since it will conflict with the nvidia driver

**Configuration Parameters**

*None at this time.*

**Stat Outputs**

*None at this time.*

**Failure**

The plugin will fail if:

- ▶ The corresponding device nodes for the target GPU(s) are being blocked by the operating system (e.g. cgroups) or exist without r/w permissions for the current user.
- ▶ The NVML library libnvidia-ml.so cannot be loaded
- ▶ The Cuda runtime libraries cannot be loaded
- ▶ The **nouveau** driver is found to be loaded
- ▶ Any pages are pending retirement on the target GPU(s)
- ▶ Any other graphics processes are running on the target GPU(s) while the plugin runs

## 5.3.2. PCIe - GPU Bandwidth Plugin

The GPU bandwidth plugin's purpose is to measure the bandwidth and latency to and from the GPUs and the host.

**Preconditions**

*None*

**Sub Tests**

The plugin consists of several self-tests that each measure a different aspect of bandwidth or latency. Each subtest has either a pinned/unpinned pair or a p2p enabled/p2p disabled pair of identical tests. Pinned/unpinned tests use either pinned or unpinned memory when copying data between the host and the GPUs.

This plugin will use NvLink to communicate between GPUs when possible. Otherwise, communication between GPUs will occur over PCIe

Each sub test is represented with a tag that is used both for specifying configuration parameters for the sub test and for outputting stats for the sub test. P2p enabled/p2p disabled tests enable or disable GPUs on the same card talking to each other directly rather than through the PCIe bus.

Sub Test Tag	Pinned/Unpinned	Description
	P2P Enabled/P2P Disabled	
h2d_d2h_single_pinned	Pinned	Device <-> Host Bandwidth, one GPU at a time
h2d_d2h_single_unpinned	Unpinned	Device <-> Host Bandwidth, one GPU at a time
h2d_d2h_concurrent_pinned	Pinned	Device <-> Host Bandwidth, all GPUs concurrently
h2d_d2h_concurrent_unpinned	Unpinned	Device <-> Host Bandwidth, all GPUs concurrently
h2d_d2h_latency_pinned	Pinned	Device <-> Host Latency, one GPU at a time
h2d_d2h_latency_unpinned	Unpinned	Device <-> Host Latency, one GPU at a time
p2p_bw_p2p_enabled	P2P Enabled	Device <-> Device bandwidth one GPU pair at a time
p2p_bw_p2p_disabled	P2P Disabled	Device <-> Device bandwidth one GPU pair at a time
p2p_bw_concurrent_p2p_enabled	P2P Enabled	Device <-> Device bandwidth, concurrently, focusing on bandwidth between GPUs between GPUs likely to be directly connected to each other -> for each (index / 2) and (index / 2)+1
p2p_bw_concurrent_p2p_disabled	P2P Disabled	Device <-> Device bandwidth, concurrently, focusing on bandwidth between GPUs between GPUs likely to be directly connected to each other -> for each (index / 2) and (index / 2)+1
1d_exch_bw_p2p_enabled	P2P Enabled	Device <-> Device bandwidth, concurrently, focusing on bandwidth between gpus, every GPU either sending to the gpu with the index higher than itself

Sub Test Tag	Pinned/Unpinned	Description
	P2P Enabled/P2P Disabled	
		(l2r) or to the gpu with the index lower than itself (r2l)
1d_exch_bw_p2p_disabled	P2P Disabled	Device <-> Device bandwidth, concurrently, focusing on bandwidth between gpus, every GPU either sending to the gpu with the index higher than itself (l2r) or to the gpu with the index lower than itself (r2l)
p2p_latency_p2p_enabled	P2P Enabled	Device <-> Device Latency, one GPU pair at a time
p2p_latency_p2p_disabled	P2P Disabled	Device <-> Device Latency, one GPU pair at a time

### Configuration Parameters- Global

Parameter Name	Type	Default	Value Range	Description
test_pinned	Bool	True	True/False	Include subtests that test using pinned memory.
test_unpinned	Bool	True	True/False	Include subtests that test using unpinned memory.
test_p2p_on	Bool	True	True/False	Include subtests that require peer to peer (P2P) memory transfers between cards to occur.
test_p2p_off	Bool	True	True/False	Include subtests that do not require peer to peer (P2P) memory transfers between cards to occur.

Parameter Name	Type	Default	Value Range	Description
max_pcie_replays	Float	80.0	1.0 - 1000000.0	Maximum number of PCIe replays to allow per GPU for the duration of this plugin. This is based on an expected replay rate <8 per minute for PCIe Gen 3.0, assuming this plugin will run for less than a minute and allowing 10x as many replays before failure.

### Configuration Parameters- Sub Test

Parameter Name	Default (Range)	Affected Sub Tests	Description
min_bandwidth	<i>Null</i> <i>(0.0 - 100.0)</i>	h2d_d2h_single_pinned, h2d_d2h_single_unpinned, h2d_d2h_concurrent_pinned, h2d_d2h_concurrent_unpinned	Minimum bandwidth in GB/s that must be reached for this sub-test to pass.
max_latency	100,000.0 <i>(0.0 - 1,000,000.0)</i>	h2d_d2h_latency_pinned, h2d_d2h_latency_unpinned	Latency in microseconds that cannot be exceeded for this sub-test to pass.
min_pci_generation	1.0 <i>(1.0 - 3.0)</i>	h2d_d2h_single_pinned, h2d_d2h_single_unpinned	Minimum allowed PCI generation that the GPU must be at or exceed for this sub-test to pass.
min_pci_width	1.0 <i>(1.0 - 16.0)</i>	h2d_d2h_single_pinned, h2d_d2h_single_unpinned	Minimum allowed PCI width that the GPU must be at or exceed for this sub-test to pass. For example, 16x = 16.0.

### Stat Outputs - Global

Stat Name	Stat Scope	Type	Description
pcie_replay_count	GPU	Float	The per second reading of PCIe replays that have

Stat Name	Stat Scope	Type	Description
			occurred since the start of the GPU Bandwidth plugin.

### Stat Outputs -Sub Test

Stats for the GPU Bandwidth test are also output on a test by test basis, using the sub test name as the group name key. The following stats sections are organized by sub test.

#### h2d d2h single pinned/h2d d2h single unpinned

Stat Name	Type	Description
<i>N_h2d</i>	Float	Average bandwidth from host to device for device <i>N</i>
<i>N_d2h</i>	Float	Average bandwidth from device to host for device <i>N</i>
<i>N_bidir</i>	Float	Average bandwidth from device to host and host to device at the same time for device <i>N</i>

#### h2d d2h concurrent pinned/h2d d2h concurrent unpinned

Stat Name	Type	Description
<i>N_h2d</i>	Float	Average bandwidth from host to device for device <i>N</i>
<i>N_d2h</i>	Float	Average bandwidth from device to host for device <i>N</i>
<i>N_bidir</i>	Float	Average bandwidth from device to host and host to device at the same time for device <i>N</i>
sum_bidir	Float	Sum of the average bandwidth from device to host and host to device for all devices.
sum_h2d	Float	Sum of the average bandwidth from host to device for all devices.
sum_d2h	Float	Sum of the average bandwidth from device to host for all devices.

**h2d d2h latency pinned/h2d d2h latency unpinned**

Stat Name	Type	Description
<i>N_h2d</i>	Float	Average latency from host to device for device <i>N</i>
<i>N_d2h</i>	Float	Average latency from device to host for device <i>N</i>
<i>N_bidir</i>	Float	Average latency from device to host and host to device at the same time for device <i>N</i>

**p2p bw p2p enabled/p2p bw p2p disabled**

Stat Name	Type	Description
<i>N_M_onedir</i>	Float	Average bandwidth from device <i>N</i> to device <i>M</i> , copying one direction at a time.
<i>N_M_bidir</i>	Float	Average bandwidth from device <i>N</i> to device <i>M</i> , copying both directions at the same time.

**p2p bw concurrent p2p enabled/p2p bw concurrent p2p disabled**

Stat Name	Type	Description
<i>l2r_N_M</i>	Float	Average bandwidth from device <i>N</i> to device <i>M</i>
<i>r2l_N_M</i>	Float	Average bandwidth from device <i>M</i> to device <i>N</i>
<i>bidir_N_M</i>	Float	Average bandwidth from device <i>M</i> to device <i>N</i> , copying concurrently
<i>r2l_sum</i>	Float	Sum of average bandwidth for all right ( <i>M</i> ) to left ( <i>N</i> ) copies
<i>r2l_sum</i>	Float	Sum of average bidirectional bandwidth for all right ( <i>M</i> ) to left ( <i>N</i> ) and left to right copies

**1d exch bw p2p enabled/1d exch bw p2p disabled**

Stat Name	Type	Description
l2r_ <i>N</i>	Float	Average bandwidth from device <i>N</i> to device <i>N+1</i>
r2l_ <i>N</i>	Float	Average bandwidth from device <i>N</i> to device <i>N-1</i>
l2r_sum	Float	Sum of all l2r average bandwidth stats
r2l_sum	Float	Sum of all l2r average bandwidth stats

### p2p latency p2p enabled/p2p latency p2p disabled

Stat Name	Type	Description
<i>N_M</i>	Float	Average latency from device <i>N</i> to device <i>M</i>

### Failure

The plugin will fail if:

- ▶ The latency exceeds the configured threshold for relevant tests.
- ▶ The bandwidth cannot exceed the configured threshold for relevant tests.
- ▶ If the number of PCIe retransmits exceeds a user-provided threshold.

## 5.3.3. Memory Bandwidth Plugin

The purpose of the Memory Bandwidth plugin is to validate that the bandwidth of the framebuffer of the GPU is above a preconfigured threshold.

### Preconditions

*This plugin only runs on GV100 GPUs at this time.*

### Configuration Parameters

Parameter Name	Type	Default	Value Range	Description
minimum_bandwidth	Float	Differs per GPU	1.0 - 1000000.0	Minimum framebuffer bandwidth threshold that must be achieved in order to pass



Parameter Name	Type	Default	Value Range	Description
				this test in MB/sec.

### Stat Outputs

Stat Name	Stat Scope	Type	Description
power_usage	GPU	Time series Float	Per second power usage of each GPU in watts. Note that for multi-GPU boards, each GPU gets a fraction of the power budget of the board.
memory_clock	GPU	Time series Float	Per second clock rate of the GPU's memory in MHZ
nvml_events	GPU	Time series Int64	Any events that were read with nvmlEventSetWait during the test and the timestamp it was read it.

### Failure

The plugin will fail if:

- ▶ the minimum bandwidth specified in *minimum\_bandwidth* cannot be achieved.
- ▶ If GPU double bit ECC errors occur or the configured amount of SBE errors occur.
- ▶ If a critical XID occurs

## 5.3.4. SM Stress Plugin

The SM performance plugin's purpose is to bring the Streaming Multiprocessors (SMs) of the target GPU(s) to a target performance level in gigaflops by doing large matrix multiplications using cublas. Unlike the Targeted Stress plugin, the SM stress plugin does not copy the source arrays to the GPU before every matrix multiplication. This allows the SM performance plugin's performance to not be capped by device to host bandwidth. The plugin calculates how many matrix operations per second are necessary to achieve the configured performance target and fails if it cannot achieve that target.

This plugin should be used to watch for thermal, power and related anomalies while the target GPU(s) are under realistic load conditions. By setting the appropriate parameters

a user can ensure that all GPUs in a node or cluster reach desired performance levels. Further analysis of the generated stats can also show variations in the required power, clocks or temperatures to reach these targets, and thus highlight GPUs or nodes that are operating less efficiently.

## Preconditions

*None*

## Configuration Parameters

Parameter Name	Type	Default	Value Range	Description
test_duration	Float	90.0	30.0 - 3600.0	How long the performance test should run for in seconds. It is recommended to set this to at least 30 seconds for performance to stabilize.
temperature_max	Float	<i>Null</i>	30.0 - 120.0	The maximum temperature in C the card is allowed to reach during the test. Note that this check is disabled by default. Use <code>nvidia-smi -q</code> to see the normal temperature limits of your device.
target_stress	Float	<i>Null</i>	SKU dependent	The maximum relative performance each card will attempt to achieve.

## Stat Outputs

Stat Name	Stat Scope	Type	Description
power_usage	GPU	Time series Float	Per second power usage of each GPU in

Stat Name	Stat Scope	Type	Description
			watts. Note that for multi-GPU boards, each GPU gets a fraction of the power budget of the board.
graphics_clock	GPU	Time series Float	Per second clock rate of each GPU in MHZ
memory_clock	GPU	Time series Float	Per second clock rate of the GPU's memory in MHZ
nvml_events	GPU	Time series Int64	Any events that were read with nvmlEventSetWait - including single or double bit errors or XID errors - during the test.
power_violation	GPU	Time series Float	Percentage of time this GPU was violating power constraints.
gpu_temperature	GPU	Time series Float	Per second temperature of the GPU in degrees C
perf_gflops	GPU	Time series Float	The per second reading of average gflops since the test began.
flops_per_op	GPU	Float	Flops (floating point operations) per operation queued to the GPU stream. One operation is one call to cublasSgemm or cublasDgemm
bytes_copied_per_op	GPU	Float	How many bytes are copied to + from the GPU per operation

Stat Name	Stat Scope	Type	Description
num_cuda_streams	GPU	Float	How many cuda streams were used per gpu to queue operations to the GPUs
try_ops_per_sec	GPU	Float	Calculated number of ops/second necessary to achieve target gigaflops

### Failure

The plugin will fail if:

- ▶ The GPU temperature exceeds a user-provided threshold.
- ▶ If thermal violation counters increase
- ▶ If the target performance level cannot be reached
- ▶ If GPU double bit ECC errors occur or the configured amount of SBE errors occur.
- ▶ If a critical XID occurs

### 5.3.5. Hardware Diagnostic Plugin

The HW Diagnostic Plugin is designed to identify HW failures on GPU silicon and board-level components, extending out to the PCIE and NVLINK interfaces. It is not intended to identify HW or system level issues beyond the NVIDIA-provided HW. Nor is it intended to identify SW level issues above the HW, e.g. in the NVIDIA driver stack. The plugin runs a series of tests that target GPU computational correctness, GDDR/HBM memory resiliency, GPU and SRAM high power operation, SM stress and NVLINK/PCIE correctness. The plugin can run with several combinations of tests corresponding to medium and long NVVS operational modes. This plugin will take about three minutes to execute.

The plugin produces a simple pass/fail output. A failing output means that a potential HW issue has been found. However, the NVVS HW Diagnostic Plugin is not by itself a justification for GPU RMA. Any failure in the plugin should be followed by execution of the full NVIDIA Field Diagnostic after the machine has been taken offline. Only a failure of the Field Diagnostic tool constitutes grounds for RMA. Since the NVVS HW Diagnostic Plugin is a functional subset of the Field Diagnostic a failure in the plugin is a strong indicator of a future Field Diagnostic failure.

### Preconditions

- ▶ No other GPU processes can be running.

## Configuration Parameters

Parameter Name	Type	Default	Value Range	Description
test_duration	Float	180.0	30.0 - 3600.0	How long the performance test should run for in seconds. It is recommended to set this to at least 30 seconds to make sure you actually get some stress from the test.
use_doubles	Boolean	False	True or False	If set to true, tells the test to use double-point precision in its calculations. By default, it is false and the test will use floating point precision.
temperature_max	Float	100.0	30.0 - 120.0	The maximum temperature in C that the card is allowed to reach during the test. Use <code>nvidia-smi -q</code> to see the normal temperature limits of your device.

## Stat Outputs

Stat Name	Stat Scope	Type	Description
power_usage	GPU	Time series Float	Per second power usage of each GPU in watts. Note that for multi-GPU boards, each GPU gets a fraction of the power budget of the board.

Stat Name	Stat Scope	Type	Description
graphics_clock	GPU	Time series Float	Per second clock rate of each GPU in MHZ
memory_clock	GPU	Time series Float	Per second clock rate of the GPU's memory in MHZ
nvml_events	GPU	Time series Int64	Any events that were read with nvmlEventSetWait - including single or double bit errors or XID errors - during the test.
power_violation	GPU	Time series Float	Percentage of time this GPU was violating power constraints.
gpu_temperature	GPU	Time series Float	Per second temperature of the GPU in degrees C
thermal_violation	GPU	Time series Float	Percentage of time this GPU was violating thermal constraints.
perf_gflops	GPU	Time Series Float	The per second reading of average gflops since the test began.

## Failure

The plugin will fail if:

- ▶ The corresponding device nodes for the target GPU(s) are being blocked by the operating system (e.g. cgroups) or exist without r/w permissions for the current user.
- ▶ Other GPU processes are running
- ▶ A hardware issue has been detected. *This is not an RMA actionable failure but rather an indication that more investigation is required.*
- ▶ The temperature reaches unacceptable levels during the test.
- ▶ If GPU double bit ECC errors occur or the configured amount of SBE errors occur.
- ▶ If a critical XID occurs

### 5.3.6. Targeted Stress Plugin

The Targeted Stress plugin's purpose is to bring the GPU to a target performance level in gigaflops by doing large matrix multiplications using cublas. The plugin calculates how many matrix operations per second are necessary to achieve the configured performance target and fails if it cannot achieve that target.

This plugin should be used to watch for thermal, power and related anomalies while the target GPU(s) are under realistic load conditions. By setting the appropriate parameters a user can ensure that all GPUs in a node or cluster reach desired performance levels. Further analysis of the generated stats can also show variations in the required power, clocks or temperatures to reach these targets, and thus highlight GPUs or nodes that are operating less efficiently.

#### Preconditions

*None*

#### Configuration Parameters

Parameter Name	Type	Default	Value Range	Description
test_duration	Float	120.0	30.0 - 3600.0	How long the Targeted Stress test should run for in seconds. It is recommended to set this to at least 30 seconds for performance to stabilize.
temperature_max	Float	<i>Null</i>	30.0 - 120.0	The maximum temperature in C the card is allowed to reach during the test. Note that this check is disabled by default. Use <code>nvidia-smi -q</code> to see the normal temperature limits of your device.
target_stress	Float	<i>Null</i>	SKU dependent	The maximum relative stress each

Parameter Name	Type	Default	Value Range	Description
				card will attempt to achieve.
max_pcie_replays	Float	160.0	1.0 - 1000000.0	Maximum number of PCIe replays to allow per GPU for the duration of this plugin. This is based on an expected replay rate <8 per minute for PCIe Gen 3.0, assuming this plugin will run for 2 minutes (configurable) and allowing 10x as many replays before failure.

### Stat Outputs

Stat Name	Stat Scope	Type	Description
power_usage	GPU	Time series Float	Per second power usage of each GPU in watts. Note that for multi-GPU boards, each GPU gets a fraction of the power budget of the board.
graphics_clock	GPU	Time series Float	Per second clock rate of each GPU in MHZ
memory_clock	GPU	Time series Float	Per second clock rate of the GPU's memory in MHZ
nvml_events	GPU	Time series Int64	Any events that were read with nvmlEventSetWait during the test and



Stat Name	Stat Scope	Type	Description
			the timestamp it was read it.
power_violation	GPU	Time series Float	Percentage of time this GPU was violating power constraints.
gpu_temperature	GPU	Time series Float	Per second temperature of the GPU in degrees C
perf_gflops	GPU	Time series Float	The per second reading of average gflops since the test began.
flops_per_op	GPU	Float	Flops (floating point operations) per operation queued to the GPU stream. One operation is one call to cublasSgemm or cublasDgemm
bytes_copied_per_op	GPU	Float	How many bytes are copied to + from the GPU per operation
num_cuda_streams	GPU	Float	How many cuda streams were used per gpu to queue operations to the GPUs
try_ops_per_sec	GPU	Float	Calculated number of ops/second necessary to achieve target gigaflops
pcie_replay_count	GPU	Float	The per second reading of PCIe replays that have occurred since the start of the Targeted Stress plugin.

## Failure

The plugin will fail if:

- ▶ The GPU temperature exceeds a user-provided threshold.
- ▶ If temperature violation counters increase
- ▶ If the target stress level cannot be reached
- ▶ If GPU double bit ECC errors occur or the configured amount of SBE errors occur.
- ▶ If the number of PCIe retransmits exceeds a user-provided threshold.
- ▶ A critical XID occurs

## 5.3.7. Power Plugin

The purpose of the power plugin is to bring the GPUs to a preconfigured power level in watts by gradually increasing the compute load on the GPUs until the desired power level is achieved. This verifies that the GPUs can sustain a power level for a reasonable amount of time without problems like thermal violations arising.

### Preconditions

*None*

### Configuration Parameters

Parameter Name	Type	Default	Value Range	Description
test_duration	Float	120.0	30.0 - 3600.0	How long the performance test should run for in seconds. It is recommended to set this to at least 60 seconds for performance to stabilize.
temperature_max	Float	<i>Null</i>	30.0 - 120.0	The maximum temperature in C the card is allowed to reach during the test. Note that this check is disabled by default. Use <code>nvidia-smi -q</code> to see the normal temperature

Parameter Name	Type	Default	Value Range	Description
				limits of your device.
target_power	Float	Differs per GPU	Differs per GPU. Defaults to TDP - 1 watt.	What power level in wattage we should try to maintain. If this is set to greater than the enforced power limit of the GPU, then we will try to power cap the device

### Stat Outputs

Stat Name	Stat Scope	Type	Description
power_usage	GPU	Time series Float	Per second power usage of each GPU in watts. Note that for multi-GPU boards, each GPU gets a fraction of the power budget of the board.
graphics_clock	GPU	Time series Float	Per second clock rate of each GPU in MHZ
memory_clock	GPU	Time series Float	Per second clock rate of the GPU's memory in MHZ
nvml_events	GPU	Time series Int64	Any events that were read with nvmlEventSetWait during the test and the timestamp it was read it.
power_violation	GPU	Time series Float	Percentage of time this GPU was violating power constraints.

Stat Name	Stat Scope	Type	Description
gpu_temperature	GPU	Time series Float	Per second temperature of the GPU in degrees C

## Failure

The plugin will fail if:

- ▶ The GPU temperature exceeds a user-provided threshold.
- ▶ If temperature violation counters increase
- ▶ If the target performance level cannot be reached
- ▶ If GPU double bit ECC errors occur or the configured amount of SBE errors occur.
- ▶ If a critical XID occurs

## 5.4. Test Output

The output of tests can be collected by setting the "logfile" global parameter which represents the prefix for the detailed outputs produced by each test. The default type of output is JSON but text and binary outputs are available as well. The latter two are meant more for parsing and direct reading by custom consumers respectively so this portion of the document will focus on the JSON output.

### 5.4.1. JSON Output

The JSON output format is keyed based off of the "stats" keys given in each test overview from Chapter 3. These standard JSON files can be processed in any number of ways but two example Python scripts have been provided to aid in visualization in the default installation directory.. The first is a JSON to comma-separated value script (json2csv.py) which can be used to import key values in to a graphing spreadsheet. Proper usage would be:

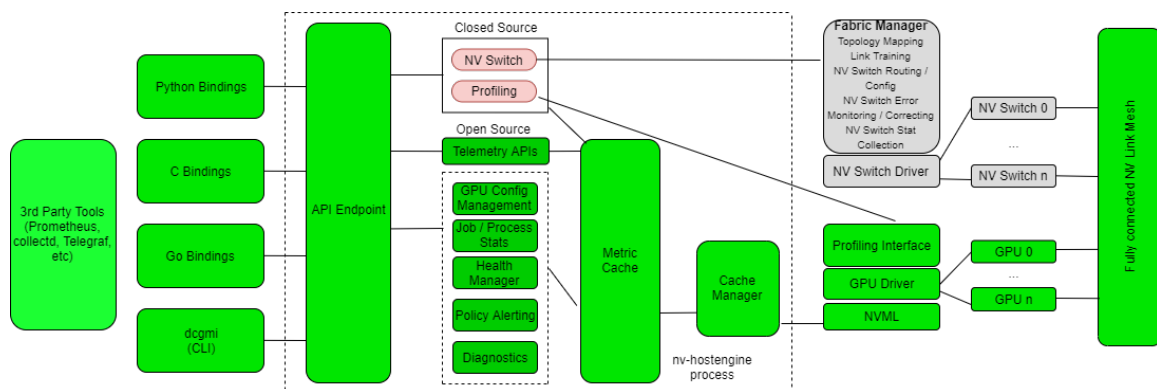
```
user@hostname
$ python json2csv.py -i stats_targeted_performance.json -o stats.csv -k
  gpu_temperature,power_usage
```

Also provided is an example Python script that uses the [pygal](#) library to generate readily viewable scalar vector graphics charts (json2svg.py), able to be opened in any browser. Proper usage would be:

```
user@hostname
$ python json2svg.py -i stats_targeted_performance.json -o stats.svg -k
  gpu_temperature,power_usage
```

# Chapter 6. DCGM MODULARITY

DCGM supports modularity where the different functional/feature areas of DCGM are separated into different shared libraries. These shared libraries are lazy-loaded by DCGM when first used by a corresponding API or DCGMI call. If you never want a module to be loaded, you can blacklist that module using `dcgmi`, API calls, or `nv-hostengine` command-line arguments. Additionally, you can remove the `so.1` file of the module you want to permanently blacklist, and DCGM will behave as if the library is blacklisted.



## 6.1. Module List

The following modules have been added to DCGM.

Module ID	#	Description
DcgmModuleIdNvSwitch	1	Manages NVSwitches and is required in order for DGX-2 / HGX-2 systems to function properly. This can be loaded explicitly by adding “-l -g” to your nv-hostengine command line.  Requires nv-hostengine to run as root.
DcgmModuleIdVGPU	2	Provides telemetry on paravirtualized GPUs.

Module ID	#	Description
DcgmModuleIdIntrospect	3	Provides time-series data about the running state of nv-hostengine.
DcgmModuleIdHealth	4	Provides passive health checks of GPUs and NVSwitches
DcgmModuleIdPolicy	5	Allows users to register callbacks based off GPU events like XIDs and overtemp.
DcgmModuleIdConfig	6	Allows users to set GPU configuration. Requires nv-hostengine to run as root.
DcgmModuleIdDiag	7	Enables users to call the DCGM GPU Diagnostic

## 6.2. Blacklisting Modules

Users may prevent DCGM from loading modules by providing a command-line option to nv-hostengine when they run it. The argument to this command line is the # column in the table above.

For instance, to start nv-hostengine with the introspection (3) and health (4) modules blacklisted, you would change nv-hostengine's service file to pass the following arguments: **nv-hostengine --blacklist-modules 3,4**

Note that NVSwitch must be explicitly loaded with the -l and -g options. To only load the NVSwitch module and blacklist all others, use the following command line:

```
nv-hostengine -l -g --blacklist-modules 2,3,4,5,6,7
```

You can query the status of all of the dcgm modules with the following command:

```
#dcgmi modules -l
+-----+
| List Modules |
| Status: Success |
+-----+
| Module ID | Name | State |
+-----+
| 0 | Core | Loaded |
| 1 | NvSwitch | Not loaded |
| 2 | VGPU | Not loaded |
| 3 | Introspection | Not loaded |
| 4 | Health | Not loaded |
| 5 | Policy | Not loaded |
| 6 | Config | Not loaded |
| 7 | Diag | Not loaded |
+-----+
```

Only modules that are Not Loaded can be blacklisted.

To blacklist a module, take note of its module name from the table above. We'll blacklist module Policy for this example:

```
#dcgmi modules --blacklist Policy
+-----+
| Blacklist Module |
| Status: Success |
| Successfully blacklisted module Policy |
+-----+
```

Once a module has been blacklisted, you can verify that by listing modules again:

```
dcgmi modules -l
```

```
+-----+-----+
| List Modules
| Status: Success
+-----+-----+
| Module ID | Name           | State
+-----+-----+
| 0         | Core          | Loaded
| 1         | NvSwitch      | Not loaded
| 2         | VGPU          | Not loaded
| 3         | Introspection | Not loaded
| 4         | Health        | Not loaded
| 5         | Policy        | Blacklisted
| 6         | Config        | Not loaded
| 7         | Diag          | Not loaded
+-----+-----+
```

Module ID	Name	State
0	Core	Loaded
1	NvSwitch	Not loaded
2	VGPU	Not loaded
3	Introspection	Not loaded
4	Health	Not loaded
5	Policy	Blacklisted
6	Config	Not loaded
7	Diag	Not loaded

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