

NVIDIA cuDNN

Best Practices | NVIDIA Docs

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Chapter 1. Introduction



ATTENTION: These guidelines are applicable to 3D convolution and deconvolution functions starting in NVIDIA® CUDA® Deep Neural Network library™ (cuDNN) v7.6.3.

This document provides guidelines for setting the cuDNN library parameters to enhance the performance of 3D convolutions. Specifically, these guidelines are focused on settings such as filter sizes, padding and dilation settings. Additionally, an application-specific use-case, namely, medical imaging, is presented to demonstrate the performance enhancement of 3D convolutions with these recommended settings.

Specifically, these guidelines are applicable to the following functions and their associated data types:

- cudnnConvolutionForward()
- cudnnConvolutionBackwardData()
- <u>cudnnConvolutionBackwardFilter()</u>

For more information, see the <u>cuDNN Developer Guide</u> and <u>cuDNN API</u>.

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Chapter 2. Best Practices For Medical Imaging

To optimize your performance in your model, ensure you meet the following general quidelines:

Layout

The layout is in NCHW format.

Filter size

The filter size is Tx1x1, Tx2x2, Tx3x3, Tx5x5, where T is a positive integer. There are additional limits for the value of T in wgrad and strided dgrad.

Stride

Arbitrary for forward and backward filter; dgrad/deconv: 1x1x1 or 2x2x2 with 2x2x2 filter.

Dilation

The dilation is 1x1x1.

Platform

The platform is Volta, Turing, and Ampere with input/output channels divisible by 8.

Batch/image size

cuDNN will fallback to non-Tensor Core kernel if it determines that the workspace required is larger than 256MB of GPU memory. The workspace required depends on many factors. For the Tensor Core kernels, the workspace size generally scales linearly with output tensor size. Therefore, this can be mitigated by using smaller image sizes or minibatch sizes.

2.1. Recommended Settings In cuDNN While Performing 3D Convolutions

The following tables show the specific improvements that were made in each release.

2.1.1. cuDNN 8.x.x Recommended Settings

Recommended settings while performing 3D convolutions for cuDNN 8.x.x.

		8.0.3 - 8.2.0 EA	8.0.0 and 8.0.1 Preview - 8.0.2		
Platform		NVIDIA Ampere GPU architecture			
		NVIDIA Turing GPU architecture			
		NVIDIA Volta GPU architecture			
Convolution (3D or 2D)		3D ar	nd 2D		
Convolution or deconvo	lution (fprop, dgrad, or	fprop			
		dg:	rad		
		wg	rad		
Grouped convolution	Yes or No	Ye	es		
	Group size	<pre>C_per_group == K_per_group == {4,8,16,32,64,128,256</pre>			
Data layout format (NHW	C/NCHW) ¹	NDHWC			
Input/output precision (FP16, FP32, or FP64)	FP16 and FP32 ²			
Accumulator (compute) FP64)	precision (FP16, FP32, or	FP32			
Filter (kernel) sizes		No limitation			
Padding		No lim	itation		
Image sizes		2GB limitatio	n for a tensor		
Number of channels	С	0 ma	od 8		
	К	0 mod 8			
Convolution mode		Cross-correlation and convolution			
Strides		dgrad: 1x1x1 or 2x2x2			
Dilation		No limitation			
Data pointer alignment		All data pointers are 16-bytes aligned.			

2.1.2. cuDNN 7.6.x Recommended Settings

Recommended settings while performing 3D convolutions for cuDNN 7.6.x.

	7.6.5	7.6.4	7.6.2	7.6.1
Platform	Turing Volta		Volta	
Convolution (3D or 2D)	3D and 2D		3D	
Convolution or deconvolution (fprop, dgrad, or wgrad)	_	rop	fprop dgrad	fprop dgrad

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¹ NHWC/NCHW corresponds to NDHWC/NCDHW in 3D convolution.
2 With CUDNN_TENSOROP_MATH_ALLOW_CONVERSION pre-Ampere. Default TF32 math in Ampere.

		7.6.5	7.6.4	7.6.2	7.6.1
			wgrad		wgrad
Grouped Yes or No		Yes			lo
convolution	Group size	== K	per_group _per_group 4,8,16,32}	٨	IA
Data layout fo	ormat (NHWC/NCHW)3		NCDHW	'	NCDHW ⁴
Input/output FP64)	precision (FP16, FP32, or		FP16	FP16 or FP32	FP16 ⁵ or FP32 ⁶
Accumulator FP32, or FP64	(compute) precision (FP16, 4)		FP32	Better to be the same with input/ output precision.	FP32
Filter (kernel) sizes		2x2x2		1x1x1
			T^7x1x1		2x2x2
			Tx2x2		3x3x3
			Tx3x3		5x5x5
			Tx5x5		Tx1x1
					Tx2x2
			Tx3x3		
			Tx5x5		
					Tx1x1
					Tx2x2
					Tx3x3
					Tx5x5
Padding		No limitation		Filter // 2 ⁸	
Image sizes		256 1	256 MB WS limit		256 MB WS limit
Number of C		Arbitrary		0 mod 8	
channels	K	Arbitrary		0 mod 8	
Convolution mode			correlation for	No lim	nitation
		dgrad; otherwise, both modes		Cross-co	orrelation
Strides		1x1x1 and 2x2x2 strides for dgrad		2x2x2	1x1x1

NHWC/NCHW corresponds to NDHWC/NCDHW in 3D convolution.
With NCHW <> NH
FP16: CUDI

With NCHW <> NHWC format transformation.
FP16: CUDNN_TENSOROP_MATH
FP32: CUDNN_TENSOROP_MATH_ALLOW_CONVERSION
An arbitrary positive value.

padding = filter // 2

	7.6.5	7.6.4	7.6.2	7.6.1
			Arbitrary stride	
Dilation	1x1x1			

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Chapter 3. Medical Imaging Performance

The following table shows the average speed-up of **unique cuDNN 3D convolution calls** for each network on V100 and A100 GPUs that satisfies the conditions in <u>Best Practices For Medical Imaging</u>. The end-to-end training performance will depend on a number of factors, such as framework overhead, kernel run time, and model architecture type.

3.1. Average Speedup Of Unique cuDNN 3D Convolutions API Calls

3.1.1. cuDNN 8.x.x Average Speedup

cuDNN version 8.2.0 EA compared to 7.6.5

Table 1. Average speed-up of unique cuDNN (version 8.2.0 EA compared to 7.6.5) 3D convolution API calls on V100 and A100 for both FP16 and FP32.

		A100 8.2.0 EA vs V100 7.6.5		V100 8.2.0 EA vs V100 7.6.5	
<u>Model</u>	Batchsize	FP16	FP32	FP16	FP32
V-Net (3D-	2	2.3x	7.3x	2.2x	2.5x
Image	8	3.4x	5.9x	2.4x	1.8x
segmentation)	16	4.1x	6.8x	2.5x	2.1x
	32	5.8x	5.1x	3.3x	1.6x
3D-UNet	2	6.8x	5.9x	3.4x	1.5x
(3D-Image Segmentation)	4	10.5x	2.6x	5.1x	1.6x

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cuDNN version 8.1.1 compared to 7.6.5

Table 2. Average speed-up of unique cuDNN (version 8.1.1 compared to 7.6.5) 3D convolution API calls on V100 and A100 for both FP16 and FP32.

		A100 8.1.1 vs V100 7.6.5		V100 8.1.1 vs V100 7.6.5	
Model	Batchsize	FP16	FP32	FP16	FP32
V-Net (3D-	2	2.3x	6.8x	2.1x	2.4x
Image segmentation)	8	3.2x	5.1x	2.3x	1.8x
	16	3.8x	5.9x	2.3x	2.1x
	32	5.4x	4.4x	3.1x	1.6x
3D-UNet (3D-Image Segmentation)	2	7.2x	6.3x	3.4x	1.5x
	4	11x	2.6x	4.9x	1.6x

cuDNN version 8.1.0 compared to 7.6.5

Table 3. Average speed-up of unique cuDNN (version 8.1.0 compared to 7.6.5) 3D convolution API calls on V100 and A100 for both FP16 and FP32.

		A100 8.1.0 vs V100 7.6.5		V100 8.1.0 vs V100 7.6.5	
Model	Batchsize	FP16	FP32	FP16	FP32
V-Net (3D-	2	2.4x	7.3x	2.2x	2.4x
Image	8	3.4x	5.3x	2.3x	1.8x
segmentation)	16	3.9x	6x	2.3x	2.1x
	32	5.5x	4.4x	3.1x	1.6x
3D-UNet	2	7.3x	6.4x	3.5x	1.5x
(3D-Image Segmentation)	4	11.2x	2.6x	5x	1.6x

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Chapter 4. Medical Imaging Limitations

Your application will be functional but slow if the model has:

- ▶ Channel counts lower than 32 (gets worse the lower it is)
- Data gradients for convolutions with stride

If the above is in the network, use cuDNNFind to get the best option.

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