cuDNN API Reference
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Chapter 1. Introduction

NVIDIA® CUDA® Deep Neural Network library™ (cuDNN) offers a context-based API that allows for easy multithreading and [optional] interoperability with NVIDIA® CUDA® streams. The cuDNN Datatypes Reference API describes all the types and enums of the cuDNN library API. The cuDNN API Reference describes the API of all the routines in the cuDNN library.

The cuDNN library as well as this API document has been split into the following libraries:

- **cudnn_ops_infer** - This entity contains the routines related to cuDNN context creation and destruction, tensor descriptor management, tensor utility routines, and the inference portion of common ML algorithms such as batch normalization, softmax, dropout, etc.

- **cudnn_ops_train** - This entity contains common training routines and algorithms, such as batch normalization, softmax, dropout, etc. The `cudnn_ops_infer` library depends on `cudnn_ops_infer`.

- **cudnn_cnn_infer** - This entity contains all routines related to convolutional neural networks needed at inference time. The `cudnn_cnn_infer` library depends on `cudnn_ops_infer`.

- **cudnn_cnn_train** - This entity contains all routines related to convolutional neural networks needed during training time. The `cudnn_cnn_train` library depends on `cudnn_ops_infer`, `cudnn_ops_train`, and `cudnn_cnn_infer`.

- **cudnn_adv_infer** - This entity contains all other features and algorithms. This includes RNNs, CTC loss, and Multihead Attention. The `cudnn_adv_infer` library depends on `cudnn_ops_infer`.

- **cudnn_adv_train** - This entity contains all the training counterparts of `cudnn_adv_infer`. The `cudnn_adv_train` library depends on `cudnn_ops_infer`, `cudnn_ops_train`, and `cudnn_adv_infer`.

- **cudnn** - This is an optional shim layer between the application layer and the cuDNN code. This layer opportunistically opens the correct library for the API at runtime.
Chapter 2. Added, Deprecated, And Removed API Functions

2.1. API Changes For cuDNN 8.0.2

The following tables show which API functions were added, deprecated, and removed for the cuDNN 8.0.2.

Table 1. API functions and data types that were added

<table>
<thead>
<tr>
<th>New functions and data types</th>
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<tbody>
<tr>
<td>cudnnRNNBackwardData_v8()</td>
</tr>
<tr>
<td>cudnnRNNBackwardWeights_v8()</td>
</tr>
</tbody>
</table>

2.2. API Changes For cuDNN 8.0.0 Preview

The following tables show which API functions were added, deprecated, and removed for the cuDNN 8.0.0 Preview Release.

Table 2. API functions and data types that were added

<table>
<thead>
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<th>New functions and data types</th>
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<tr>
<td>cudnnAdvInferVersionCheck()</td>
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<td>cudnnAdvTrainVersionCheck()</td>
</tr>
<tr>
<td>cudnnBackendAttributeName_t</td>
</tr>
<tr>
<td>cudnnBackendAttributeType_t</td>
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<tr>
<td>cudnnBackendCreateDescriptor()</td>
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<tr>
<td>cudnnBackendDescriptor_t</td>
</tr>
<tr>
<td>cudnnBackendDescriptorType_t</td>
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<tr>
<td>New functions and data types</td>
</tr>
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<td>-----------------------------</td>
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<td>cudnnBackendDestroyDescriptor()</td>
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<td>cudnnBackendExecute()</td>
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<td>cudnnBackendFinalize()</td>
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<td>cudnnBackendGetAttribute()</td>
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<td>cudnnBackendInitialize()</td>
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<td>cudnnBackendKnobType_t</td>
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<td>cudnnBackendLayoutType_t</td>
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<td>cudnnCTCloss_v8()</td>
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<tr>
<td>cudnnDeriveNormTensorDescriptor()</td>
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<td>cudnnGetFilterSizeInBytes()</td>
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<td>cudnnGetFoldedConvBackwardDataDescriptors()</td>
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<td>cudnnGetRNNDesciptor_v8()</td>
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<td>cudnnGetRNNMatrixMathType()</td>
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<th>Function</th>
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<td>cudnnRNNBackwardData_v8()</td>
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<td>cudnnSetRNNDescriptor_v8()</td>
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<tr>
<td>cudnnSeverity_t</td>
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For our deprecation policy, refer to the [Backward Compatibility And Deprecation Policy](#) section in the *cuDNN Developer Guide*.

### Table 3. API functions and data types that were deprecated

<table>
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<td>cudnnGetRNNProjectionLayers()</td>
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## Table 4. API functions and data types that were removed

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<tr>
<td>cudnnConvolutionBwdFilterPreference_t</td>
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<tr>
<td>cudnnConvolutionFwdPreference_t</td>
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### Removed functions and data types

<table>
<thead>
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<th>Function</th>
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<tbody>
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<td>cudnnGetConvolutionBackwardDataAlgorithm()</td>
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<td>cudnnGetConvolutionBackwardFilterAlgorithm()</td>
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<td>cudnnGetConvolutionForwardAlgorithm()</td>
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<tr>
<td>cudnnSetRNNDescriptor()</td>
</tr>
</tbody>
</table>
Chapter 3. cudnn_ops_infer.so Library

3.1. Data Type References

3.1.1. Pointer To Opaque Struct Types

3.1.1.1. cudnnActivationDescriptor_t

cudnnActivationDescriptor_t is a pointer to an opaque structure holding the description of an activation operation. cudnnCreateActivationDescriptor() is used to create one instance, and cudnnSetActivationDescriptor() must be used to initialize this instance.

3.1.1.2. cudnnCTCLossDescriptor_t

cudnnCTCLossDescriptor_t is a pointer to an opaque structure holding the description of a CTC loss operation. cudnnCreateCTCLossDescriptor() is used to create one instance, cudnnSetCTCLossDescriptor() is used to initialize this instance, and cudnnDestroyCTCLossDescriptor() is used to destroy this instance.

3.1.1.3. cudnnDropoutDescriptor_t

cudnnDropoutDescriptor_t is a pointer to an opaque structure holding the description of a dropout operation. cudnnCreateDropoutDescriptor() is used to create one instance, cudnnSetDropoutDescriptor() is used to initialize this instance, cudnnDestroyDropoutDescriptor() is used to destroy this instance, cudnnGetDropoutDescriptor() is used to query fields of a previously initialized instance, cudnnRestoreDropoutDescriptor() is used to restore an instance to a previously saved off state.

3.1.1.4. cudnnFilterDescriptor_t

cudnnFilterDescriptor_t is a pointer to an opaque structure holding the description of a filter dataset. cudnnCreateFilterDescriptor() is used to create one instance, and
cudnnSetFilter4dDescriptor() or cudnnSetFilterNdDescriptor() must be used to initialize this instance.

3.1.1.5. cudnnHandle_t

cudnnHandle_t is a pointer to an opaque structure holding the cuDNN library context. The cuDNN library context must be created using cudnnCreate() and the returned handle must be passed to all subsequent library function calls. The context should be destroyed at the end using cudnnDestroy(). The context is associated with only one GPU device, the current device at the time of the call to cudnnCreate(). However, multiple contexts can be created on the same GPU device.

3.1.1.6. cudnnLRNDescriptor_t

cudnnLRNDescriptor_t is a pointer to an opaque structure holding the parameters of a local response normalization. cudnnCreateLRNDescriptor() is used to create one instance, and the routine cudnnSetLRNDescriptor() must be used to initialize this instance.

3.1.1.7. cudnnOpTensorDescriptor_t

cudnnOpTensorDescriptor_t is a pointer to an opaque structure holding the description of a Tensor Core operation, used as a parameter to cudnnOpTensor[]. cudnnCreateOpTensorDescriptor() is used to create one instance, and cudnnSetOpTensorDescriptor() must be used to initialize this instance.

3.1.1.8. cudnnPoolingDescriptor_t

cudnnPoolingDescriptor_t is a pointer to an opaque structure holding the description of a pooling operation. cudnnCreatePoolingDescriptor() is used to create one instance, and cudnnSetPoolingNdDescriptor() or cudnnSetPooling2dDescriptor() must be used to initialize this instance.

3.1.1.9. cudnnReduceTensorDescriptor_t

cudnnReduceTensorDescriptor_t is a pointer to an opaque structure holding the description of a tensor reduction operation, used as a parameter to cudnnReduceTensor[]. cudnnCreateReduceTensorDescriptor() is used to create one instance, and cudnnSetReduceTensorDescriptor() must be used to initialize this instance.

3.1.1.10. cudnnSpatialTransformerDescriptor_t

cudnnSpatialTransformerDescriptor_t is a pointer to an opaque structure holding the description of a spatial transformation operation. cudnnCreateSpatialTransformerDescriptor() is used to create one instance, cudnnSetSpatialTransformerNdDescriptor() is used to initialize this instance, and cudnnDestroySpatialTransformerDescriptor() is used to destroy this instance.

3.1.1.11. cudnnTensorDescriptor_t
cudnnCreateTensorDescriptor_t is a pointer to an opaque structure holding
the description of a generic n-D dataset. cudnnCreateTensorDescriptor() is used
to create one instance, and one of the routines cudnnSetTensorNdDescriptor(),
cudnnSetTensor4dDescriptor() or cudnnSetTensor4dDescriptorEx() must be used to initialize
this instance.

3.1.1.12. cudnnTensorTransformDescriptor_t

cudnnTensorTransformDescriptor_t is an opaque structure containing the description of
the tensor transform. Use the cudnnCreateTensorTransformDescriptor() function to create an
instance of this descriptor, and cudnnDestroyTensorTransformDescriptor() function to destroy
a previously created instance.

3.1.2. Enumeration Types

3.1.2.1. cudnnActivationMode_t

cudnnActivationMode_t is an enumerated type used to select the neuron activation
function used in cudnnActivationForward(), cudnnActivationBackward(), and
cudnnConvolutionBiasActivationForward().

Values

CUDNN_ACTIVATION_SIGMOID

Selects the sigmoid function.

CUDNN_ACTIVATION_RELU

Selects the rectified linear function.

CUDNN_ACTIVATION_TANH

Selects the hyperbolic tangent function.

CUDNN_ACTIVATION_CLIPPED_RELU

Selects the clipped rectified linear function.

CUDNN_ACTIVATION_ELU

Selects the exponential linear function.

CUDNN_ACTIVATION_IDENTITY

Selects the identity function, intended for bypassing the activation step in
cudnnConvolutionBiasActivationForward(). (The cudnnConvolutionBiasActivationForward() function must use CUDNN_CONVOLUTION_FWD_ALGO_IMPLICIT_PRECOMP_GEMM.) Does not work with cudnnActivationForward() or cudnnActivationBackward().

3.1.2.2. cudnnAlgorithm_t

This function has been deprecated in cuDNN 8.0.
3.1.2.3. **cudnnBatchNormMode_t**

cudnnBatchNormMode_t is an enumerated type used to specify the mode of operation in cudnnBatchNormalizationForwardInference[], cudnnBatchNormalizationForwardTraining[], cudnnBatchNormalizationBackward[], and cudnnDeriveBNTensorDescriptor[] routines.

**Values**

**CUDNN_BATCHNORM_PER_ACTIVATION**

Normalization is performed per-activation. This mode is intended to be used after the non-convolutional network layers. In this mode, the tensor dimensions of bnBias and bnScale and the parameters used in the cudnnBatchNormalization* functions, are 1xCxHxW.

**CUDNN_BATCHNORM_SPATIAL**

Normalization is performed over N+spatial dimensions. This mode is intended for use after convolutional layers (where spatial invariance is desired). In this mode the bnBias and bnScale tensor dimensions are 1xCx1x1.

**CUDNN_BATCHNORM_SPATIAL_PERSISTENT**

This mode is similar to CUDNN_BATCHNORM_SPATIAL but it can be faster for some tasks.

An optimized path may be selected for CUDNN_DATA_FLOAT and CUDNN_DATA_HALF types, compute capability 6.0 or higher for the following two batch normalization API calls: cudnnBatchNormalizationForwardTraining[], and cudnnBatchNormalizationBackward[]. In the case of cudnnBatchNormalizationBackward[], the savedMean and savedInvVariance arguments should not be NULL.

The rest of this section applies to NCHW mode only:

This mode may use a scaled atomic integer reduction that is deterministic but imposes more restrictions on the input data range. When a numerical overflow occurs, the algorithm may produce NaN-s or Inf-s (infinity) in output buffers.

When Inf-s/NaN-s are present in the input data, the output in this mode is the same as from a pure floating-point implementation.

For finite but very large input values, the algorithm may encounter overflows more frequently due to a lower dynamic range and emit Inf-s/NaN-s while CUDNN_BATCHNORM_SPATIAL will produce finite results. The user can invoke cudnnQueryRuntimeError[] to check if a numerical overflow occurred in this mode.

3.1.2.4. **cudnnBatchNormOps_t**

cudnnBatchNormOps_t is an enumerated type used to specify the mode of operation in cudnnGetBatchNormalizationForwardTrainingExWorkspaceSize[], cudnnBatchNormalizationForwardTrainingEx[], cudnnGetBatchNormalizationBackwardExWorkspaceSize[].
cudnnBatchNormalizationBackwardEx(), and cudnnGetBatchNormalizationTrainingExReserveSpaceSize() functions.

Values

CUDNN_BATCHNORM_OPS_BN
Only batch normalization is performed, per-activation.

CUDNN_BATCHNORM_OPS_BN_ACTIVATION
First, the batch normalization is performed, and then the activation is performed.

CUDNN_BATCHNORM_OPS_BN_ADD_ACTIVATION
Performs the batch normalization, then element-wise addition, followed by the activation operation.

3.1.2.5. cudnnCTCLossAlgo_t
cudnnCTCLossAlgo_t is an enumerated type that exposes the different algorithms available to execute the CTC loss operation.

Values

CUDNN_CTC_LOSS_ALGO_DETERMINISTIC
Results are guaranteed to be reproducible.

CUDNN_CTC_LOSS_ALGO_NON_DETERMINISTIC
Results are not guaranteed to be reproducible.

3.1.2.6. cudnnDataType_t
cudnnDataType_t is an enumerated type indicating the data type to which a tensor descriptor or filter descriptor refers.

Values

CUDNN_DATA_FLOAT
The data is a 32-bit single-precision floating-point (float).

CUDNN_DATA_DOUBLE
The data is a 64-bit double-precision floating-point (double).

CUDNN_DATA_HALF
The data is a 16-bit floating-point.

CUDNN_DATA_INT8
The data is an 8-bit signed integer.
CUDDN_DATA_UINT8

The data is an 8-bit unsigned integer.

CUDDN_DATA_INT32

The data is a 32-bit signed integer.

CUDDN_DATA_INT8x4

The data is 32-bit elements each composed of 4 8-bit signed integers. This data type is only supported with tensor format CUDNN_TENSOR_NCHW_VECT_C.

CUDDN_DATA_INT8x32

The data is 32-element vectors, each element being an 8-bit signed integer. This data type is only supported with the tensor format CUDNN_TENSOR_NCHW_VECT_C. Moreover, this data type can only be used with algo 1, meaning, CUDNN_CONVOLUTION_FWD_ALGO_IMPLICIT_PRECOMP_GEMM. For more information, see cudnnConvolutionFwdAlgo_t.

CUDDN_DATA_UINT8x4

The data is 32-bit elements each composed of 4 8-bit unsigned integers. This data type is only supported with tensor format CUDNN_TENSOR_NCHW_VECT_C.

3.1.2.7. cudnnDeterminism_t

cudnnDeterminism_t is an enumerated type used to indicate if the computed results are deterministic (reproducible). For more information, see Reproducibility [determinism].

Values

CUDDN_NON_DETERMINISTIC

Results are not guaranteed to be reproducible.

CUDDN_DETERMINISTIC

Results are guaranteed to be reproducible.

3.1.2.8. cudnnDivNormMode_t

cudnnDivNormMode_t is an enumerated type used to specify the mode of operation in cudnnDivisiveNormalizationForward[] and cudnnDivisiveNormalizationBackward[].
Values

**CUDNN_DIVNORM_PRECOMPUTED_MEANS**

The means tensor data pointer is expected to contain means or other kernel convolution values precomputed by the user. The means pointer can also be **NULL**, in that case, it’s considered to be filled with zeroes. This is equivalent to spatial LRN.

**Note:** In the backward pass, the means are treated as independent inputs and the gradient over means is computed independently. In this mode, to yield a net gradient over the entire LCN computational graph, the `destDiffMeans` result should be backpropagated through the user’s means layer (which can be implemented using average pooling) and added to the `destDiffData` tensor produced by `cudnnDivisiveNormalizationBackward()`.

### 3.1.2.9. `cudnnErrQueryMode_t`

cudnnErrQueryMode_t is an enumerated type passed to `cudnnQueryRuntimeError` to select the remote kernel error query mode.

**Values**

**CUDNN_ERRQUERY_RAWCODE**

Read the error storage location regardless of the kernel completion status.

**CUDNN_ERRQUERY_NONBLOCKING**

Report if all tasks in the user stream of the cuDNN handle were completed. If that is the case, report the remote kernel error code.

**CUDNN_ERRQUERY_BLOCKING**

Wait for all tasks to complete in the user stream before reporting the remote kernel error code.

### 3.1.2.10. `cudnnFoldingDirection_t`

cudnnFoldingDirection_t is an enumerated type used to select the folding direction. For more information, see `cudnnTensorTransformDescriptor_t`.

**Data Member**

**CUDNN_TRANSFORM_FOLD = 0U**

Selects folding.

**CUDNN_TRANSFORM_UNFOLD = 1U**

Selects unfolding.
3.1.2.11. **cudnnIndicesType_t**

*cudnnIndicesType_t* is an enumerated type used to indicate the data type for the indices to be computed by the *cudnnReduceTensor[]* routine. This enumerated type is used as a field for the *cudnnReduceTensorDescriptor_t* descriptor.

**Values**

- **CUDNN_32BIT_INDICES**
  - Compute unsigned int indices.
- **CUDNN_64BIT_INDICES**
  - Compute unsigned long indices.
- **CUDNN_16BIT_INDICES**
  - Compute unsigned short indices.
- **CUDNN_8BIT_INDICES**
  - Compute unsigned char indices.

3.1.2.12. **cudnnLRNMode_t**

*cudnnLRNMode_t* is an enumerated type used to specify the mode of operation in *cudnnLRNCrossChannelForward[]* and *cudnnLRNCrossChannelBackward[]*.

**Values**

- **CUDNN_LRN_CROSS_CHANNEL_DIM1**
  - LRN computation is performed across tensor’s dimension dimA[1].

3.1.2.13. **cudnnMathType_t**

*cudnnMathType_t* is an enumerated type used to indicate if the use of Tensor Core operations is permitted in a given library routine.

**Values**

- **CUDNN_DEFAULT_MATH**
  - Tensor Core operations are not used on pre-NVIDIA A100 GPU devices. On A100 GPU devices, Tensor Core TF32 operation is permitted.
- **CUDNN_TENSOR_OP_MATH**
  - The use of Tensor Core operations is permitted but will not actively perform datatype down conversion on tensors in order to utilize Tensor Cores.
CUDNN_TENSOR_OP_MATH_ALLOW_CONVERSION

The use of Tensor Core operations is permitted and will actively perform datatype down
conversion on tensors in order to utilize Tensor Cores.

CUDNN_FMA_MATH

Restricted to only kernels that use FMA instructions.

On pre-NVIDIA A100 GPU devices, CUDNN_DEFAULT_MATH and CUDNN_FMA_MATH have the same
behavior: Tensor Core kernels will not be selected. With NVIDIA Ampere GPU architecture
and CUDA Toolkit 11, CUDNN_DEFAULT_MATH permits TF32 Tensor Core operation and
CUDNN_FMA_MATH does not. The TF32 behavior for CUDNN_DEFAULT_MATH can be explicitly
disabled by the environment variable NVIDIA_TF32_OVERRIDE=0.

3.1.2.14. cudnnNanPropagation_t

cudnnNanPropagation_t is an enumerated type used to indicate if a given routine
should propagate Nan numbers. This enumerated type is used as a field for the
cudnnActivationDescriptor_t descriptor and cudnnPoolingDescriptor_t descriptor.

Values

CUDNN_NOT_PROPAGATE_NAN

Nan numbers are not propagated.

CUDNN_PROPAGATE_NAN

Nan numbers are propagated.

3.1.2.15. cudnnNormAlgo_t

cudnnNormAlgo_t is an enumerated type used to specify the algorithm to execute the
normalization operation.

Values

CUDNN_NORM_ALGO_STANDARD

Standard normalization is performed.

CUDNN_NORM_ALGO_PERSIST

This mode is similar to CUDNN_NORM_ALGO_STANDARD, however it only supports
CUDNN_NORM_PER_CHANNEL and can be faster for some tasks.

An optimized path may be selected for CUDNN_DATA_FLOAT and CUDNN_DATA_HALF
types, compute capability 6.0 or higher for the following two normalization API calls:
cudnnNormalizationForwardTraining[] and cudnnNormalizationBackward[]. In the case of
cudnnNormalizationBackward[], the savedMean and savedInvVariance arguments should
not be NULL.
The rest of this section applies to NCHW mode only: This mode may use a scaled atomic integer reduction that is deterministic but imposes more restrictions on the input data range. When a numerical overflow occurs, the algorithm may produce NaN-s or Inf-s (infinity) in output buffers.

When Inf-s/NaN-s are present in the input data, the output in this mode is the same as from a pure floating-point implementation.

For finite but very large input values, the algorithm may encounter overflows more frequently due to a lower dynamic range and emit Inf-s/NaN-s while CUDNN_NORM_ALGO_STANDARD will produce finite results. The user can invoke cudnnQueryRuntimeError() to check if a numerical overflow occurred in this mode.

3.1.2.16. cudnnNormMode_t

cudnnNormMode_t is an enumerated type used to specify the mode of operation in cudnnNormalizationForwardInference(), cudnnNormalizationForwardTraining(), cudnnBatchNormalizationBackward(), cudnnGetNormalizationForwardTrainingWorkspaceSize(), cudnnGetNormalizationBackwardWorkspaceSize(), and cudnnGetNormalizationTrainingReserveSpaceSize() routines.

Values

CUDNN_NORM_PER_ACTIVATION

Normalization is performed per-activation. This mode is intended to be used after the non-convolutional network layers. In this mode, the tensor dimensions of normBias and normScale and the parameters used in the cudnnNormalization* functions, are 1xCxHxW.

CUDNN_NORM_PER_CHANNEL

Normalization is performed per-channel over N+spatial dimensions. This mode is intended for use after convolutional layers (where spatial invariance is desired). In this mode, the normBias and normScale tensor dimensions are 1xCx1x1.

3.1.2.17. cudnnNormOps_t

cudnnNormOps_t is an enumerated type used to specify the mode of operation in cudnnGetNormalizationForwardTrainingWorkspaceSize(), cudnnNormalizationForwardTraining(), cudnnGetNormalizationBackwardWorkspaceSize(), cudnnNormalizationBackward(), and cudnnGetNormalizationTrainingReserveSpaceSize() functions.

Values

CUDNN_NORM_OPS_NORM

Only normalization is performed.
CUDNN_NORM_OPS_NORM_ACTIVATION

First, the normalization is performed, then the activation is performed.

CUDNN_NORM_OPS_NORM_ADD_ACTIVATION

Performs the normalization, then element-wise addition, followed by the activation operation.

3.1.2.18. cudnnOpTensorOp_t

cudnnOpTensorOp_t is an enumerated type used to indicate the Tensor Core operation to be used by the cudnnOpTensor() routine. This enumerated type is used as a field for the cudnnOpTensorDescriptor_t descriptor.

Values

CUDNN_OP_TENSOR_ADD
The operation to be performed is addition.

CUDNN_OP_TENSOR_MUL
The operation to be performed is multiplication.

CUDNN_OP_TENSOR_MIN
The operation to be performed is a minimum comparison.

CUDNN_OP_TENSOR_MAX
The operation to be performed is a maximum comparison.

CUDNN_OP_TENSOR_SQRT
The operation to be performed is square root, performed on only the A tensor.

CUDNN_OP_TENSOR_NOT
The operation to be performed is negation, performed on only the A tensor.

3.1.2.19. cudnnPoolingMode_t

cudnnPoolingMode_t is an enumerated type passed to cudnnSetPooling2dDescriptor() to select the pooling method to be used by cudnnPoolingForward() and cudnnPoolingBackward().

Values

CUDNN_POOLING_MAX
The maximum value inside the pooling window is used.

CUDNN_POOLING_AVERAGE_COUNT_INCLUDE_PADDING
Values inside the pooling window are averaged. The number of elements used to calculate the average includes spatial locations falling in the padding region.
**CUDNN_POOLING_AVERAGE_COUNT_EXCLUDE_PADDING**

Values inside the pooling window are averaged. The number of elements used to calculate the average excludes spatial locations falling in the padding region.

**CUDNN_POOLING_MAX_DETERMINISTIC**

The maximum value inside the pooling window is used. The algorithm used is deterministic.

### 3.1.2.20. `cudnnReduceTensorIndices_t`

`cudnnReduceTensorIndices_t` is an enumerated type used to indicate whether indices are to be computed by the `cudnnReduceTensor()` routine. This enumerated type is used as a field for the `cudnnReduceTensorDescriptor_t` descriptor.

**Values**

- **CUDNN_REDUCE_TENSOR_NO_INDICES**
  Do not compute indices.

- **CUDNN_REDUCE_TENSOR_FLATTENED_INDICES**
  Compute indices. The resulting indices are relative, and flattened.

### 3.1.2.21. `cudnnReduceTensorOp_t`

`cudnnReduceTensorOp_t` is an enumerated type used to indicate the Tensor Core operation to be used by the `cudnnReduceTensor()` routine. This enumerated type is used as a field for the `cudnnReduceTensorDescriptor_t` descriptor.

**Values**

- **CUDNN_REDUCE_TENSOR_ADD**
  The operation to be performed is addition.

- **CUDNN_REDUCE_TENSOR_MUL**
  The operation to be performed is multiplication.

- **CUDNN_REDUCE_TENSOR_MIN**
  The operation to be performed is a minimum comparison.

- **CUDNN_REDUCE_TENSOR_MAX**
  The operation to be performed is a maximum comparison.

- **CUDNN_REDUCE_TENSOR_AMAX**
  The operation to be performed is a maximum comparison of absolute values.

- **CUDNN_REDUCE_TENSOR_AVG**
  The operation to be performed is averaging.
**CUDNN_REDUCE_TENSOR_NORM1**

The operation to be performed is addition of absolute values.

**CUDNN_REDUCE_TENSOR_NORM2**

The operation to be performed is a square root of the sum of squares.

**CUDNN_REDUCE_TENSOR_MUL_NO_ZEROS**

The operation to be performed is multiplication, not including elements of value zero.

### 3.1.2.22. **cudnnRNNAlgo_t**

`cudnnRNNAlgo_t` is an enumerated type used to specify the algorithm used in the `cudnnRNNForwardInference()`, `cudnnRNNForwardTraining()`, `cudnnRNNBackwardData()` and `cudnnRNNBackwardWeights()` routines.

**Values**

**CUDNN_RNN_ALGO_STANDARD**

Each RNN layer is executed as a sequence of operations. This algorithm is expected to have robust performance across a wide range of network parameters.

**CUDNN_RNN_ALGO_PERSIST_STATIC**

The recurrent parts of the network are executed using a *persistent kernel* approach. This method is expected to be fast when the first dimension of the input tensor is small (meaning, a small minibatch).

**CUDNN_RNN_ALGO_PERSIST_STATIC** is only supported on devices with compute capability \( \geq 6.0 \).

**CUDNN_RNN_ALGO_PERSIST_DYNAMIC**

The recurrent parts of the network are executed using a *persistent kernel* approach. This method is expected to be fast when the first dimension of the input tensor is small (meaning, a small minibatch). When using **CUDNN_RNN_ALGO_PERSIST_DYNAMIC** persistent kernels are prepared at runtime and are able to optimize using the specific parameters of the network and active GPU. As such, when using **CUDNN_RNN_ALGO_PERSIST_DYNAMIC** a one-time plan preparation stage must be executed. These plans can then be reused in repeated calls with the same model parameters.

The limits on the maximum number of hidden units supported when using **CUDNN_RNN_ALGO_PERSIST_DYNAMIC** are significantly higher than the limits when using **CUDNN_RNN_ALGO_PERSIST_STATIC**, however throughput is likely to significantly reduce when exceeding the maximums supported by **CUDNN_RNN_ALGO_PERSIST_STATIC**. In this regime, this method will still outperform **CUDNN_RNN_ALGO_STANDARD** for some cases.

**CUDNN_RNN_ALGO_PERSIST_DYNAMIC** is only supported on devices with compute capability \( \geq 6.0 \) on Linux machines.
3.1.2.23. `cudnnSamplerType_t`

`cudnnSamplerType_t` is an enumerated type passed to `cudnnSetSpatialTransformerNdDescriptor()` to select the sampler type to be used by `cudnnSpatialTfSamplerForward()` and `cudnnSpatialTfSamplerBackward()`.

**Values**

- **CUDNN_SAMPLER_BILINEAR**
  - Selects the bilinear sampler.

3.1.2.24. `cudnnSeverity_t`

`cudnnSeverity_t` is an enumerated type passed to the customized callback function for logging that users may set. This enumerate describes the severity level of the item, so the customized logging call back may react differently.

**Values**

- **CUDNN_SEV_FATAL**
  - This value indicates a fatal error emitted by cuDNN.

- **CUDNN_SEV_ERROR**
  - This value indicates a normal error emitted by cuDNN.

- **CUDNN_SEV_WARNING**
  - This value indicates a warning emitted by cuDNN.

- **CUDNN_SEV_INFO**
  - This value indicates a piece of information [for example, API log] emitted by cuDNN.

3.1.2.25. `cudnnSoftmaxAlgorithm_t`

`cudnnSoftmaxAlgorithm_t` is used to select an implementation of the softmax function used in `cudnnSoftmaxForward()` and `cudnnSoftmaxBackward()`.

**Values**

- **CUDNN_SOFTMAX_FAST**
  - This implementation applies the straightforward softmax operation.

- **CUDNN_SOFTMAX_ACCURATE**
  - This implementation scales each point of the softmax input domain by its maximum value to avoid potential floating point overflows in the softmax evaluation.
**CUDNN_SOFTMAX_LOG**

This entry performs the log softmax operation, avoiding overflows by scaling each point in the input domain as in CUDNN_SOFTMAX_ACCURATE.

### 3.1.2.26. cudnnSoftmaxMode_t

cudnnSoftmaxMode_t is used to select over which data the cudnnSoftmaxForward() and cudnnSoftmaxBackward() are computing their results.

**Values**

**CUDNN_SOFTMAX_MODE_INSTANCE**

The softmax operation is computed per image \( N \) across the dimensions \( C, H, W \).

**CUDNN_SOFTMAX_MODE_CHANNEL**

The softmax operation is computed per spatial location \( H, W \) per image \( N \) across the dimension \( C \).

### 3.1.2.27. cudnnStatus_t

cudnnStatus_t is an enumerated type used for function status returns. All cuDNN library functions return their status, which can be one of the following values:

**Values**

**CUDNN_STATUS_SUCCESS**

The operation was completed successfully.

**CUDNN_STATUS_NOT_INITIALIZED**

The cuDNN library was not initialized properly. This error is usually returned when a call to cudnnCreate() fails or when cudnnCreate() has not been called prior to calling another cuDNN routine. In the former case, it is usually due to an error in the CUDA Runtime API called by cudnnCreate() or by an error in the hardware setup.

**CUDNN_STATUS_ALLOC_FAILED**

Resource allocation failed inside the cuDNN library. This is usually caused by an internal cudaMalloc() failure.

To correct, prior to the function call, deallocate previously allocated memory as much as possible.

**CUDNN_STATUS_BAD_PARAM**

An incorrect value or parameter was passed to the function.

To correct, ensure that all the parameters being passed have valid values.
CUDNN_STATUS_ARCH_MISMATCH
The function requires a feature absent from the current GPU device. Note that cuDNN only supports devices with compute capabilities greater than or equal to 3.0.
To correct, compile and run the application on a device with appropriate compute capability.

CUDNN_STATUS_MAPPING_ERROR
An access to GPU memory space failed, which is usually caused by a failure to bind a texture.
To correct, prior to the function call, unbind any previously bound textures.
Otherwise, this may indicate an internal error/bug in the library.

CUDNN_STATUS_EXECUTION_FAILED
The GPU program failed to execute. This is usually caused by a failure to launch some cuDNN kernel on the GPU, which can occur for multiple reasons.
To correct, check that the hardware, an appropriate version of the driver, and the cuDNN library are correctly installed.
Otherwise, this may indicate an internal error/bug in the library.

CUDNN_STATUS_INTERNAL_ERROR
An internal cuDNN operation failed.

CUDNN_STATUS_NOT_SUPPORTED
The functionality requested is not presently supported by cuDNN.

CUDNN_STATUS_LICENSE_ERROR
The functionality requested requires some license and an error was detected when trying to check the current licensing. This error can happen if the license is not present or is expired or if the environment variable NVIDIA_LICENSE_FILE is not set properly.

CUDNN_STATUS_RUNTIME_PREREQUISITE_MISSING
The runtime library that is required by RNN calls (libcuda.so or nvcuda.dll) cannot be found in predefined search paths.

CUDNN_STATUS_RUNTIME_IN_PROGRESS
Some tasks in the user stream are not completed.

CUDNN_STATUS_RUNTIME_FP_OVERFLOW
Numerical overflow occurred during the GPU kernel execution.

3.1.2.28. cudnnTensorFormat_t

cudnnTensorFormat_t is an enumerated type used by cudnnSetTensor4dDescriptor() to create a tensor with a pre-defined layout. For a detailed explanation of how these tensors are arranged in memory, see the Data Layout Formats section in the cudNN Developer Guide.
Values

**CUDNN_TENSOR_NCHW**

This tensor format specifies that the data is laid out in the following order: batch size, feature maps, rows, columns. The strides are implicitly defined in such a way that the data are contiguous in memory with no padding between images, feature maps, rows, and columns; the columns are the inner dimension and the images are the outermost dimension.

**CUDNN_TENSOR_NHWC**

This tensor format specifies that the data is laid out in the following order: batch size, rows, columns, feature maps. The strides are implicitly defined in such a way that the data are contiguous in memory with no padding between images, rows, columns, and feature maps; the feature maps are the inner dimension and the images are the outermost dimension.

**CUDNN_TENSOR_NCHW_VECT_C**

This tensor format specifies that the data is laid out in the following order: batch size, feature maps, rows, columns. However, each element of the tensor is a vector of multiple feature maps. The length of the vector is carried by the data type of the tensor. The strides are implicitly defined in such a way that the data are contiguous in memory with no padding between images, feature maps, rows, and columns; the columns are the inner dimension and the images are the outermost dimension. This format is only supported with tensor data types CUDNN_DATA_INT8x4, CUDNN_DATA_INT8x32, and CUDNN_DATA_UINT8x4.

The **CUDNN_TENSOR_NCHW_VECT_C** can also be interpreted in the following way: The NCHW INT8x32 format is really \( N \times (C/32) \times H \times W \times 32 \) (32 Cs for every \( W \)), just as the NCHW INT8x4 format is \( N \times (C/4) \times H \times W \times 4 \) (4 Cs for every \( W \)). Hence, the **VECT_C** name - each \( W \) is a vector (4 or 32) of Cs.

### 3.2. API Functions

#### 3.2.1. cudnnActivationForward()

```c
int cudnnStatus_t cudnnActivationForward(
    cudnnHandle_t handle,
    cudnnActivationDescriptor_t activationDesc,
    const void *alpha,
    const cudnnTensorDescriptor_t xDesc,
    const void *x,
    const void *beta,
    const cudnnTensorDescriptor_t yDesc,
    void *y)
```

This routine applies a specified neuron activation function element-wise over each input value.

**Note:**
In-place operation is allowed for this routine; meaning, xData and yData pointers may be equal. However, this requires xDesc and yDesc descriptors to be identical (particularly, the strides of the input and output must match for an in-place operation to be allowed).

All tensor formats are supported for 4 and 5 dimensions, however, the best performance is obtained when the strides of xDesc and yDesc are equal and HW-packed. For more than 5 dimensions the tensors must have their spatial dimensions packed.

Parameters

**handle**

*Input*. Handle to a previously created cuDNN context. For more information, see `cudnnHandle_t`.

**activationDesc**

*Input*. Activation descriptor. For more information, see `cudnnActivationDescriptor_t`.

**alpha, beta**

*Input*. Pointers to scaling factors [in host memory] used to blend the computation result with prior value in the output layer as follows:

\[
\text{dstValue} = \alpha[0] \times \text{result} + \beta[0] \times \text{priorDstValue}
\]

For more information, see Scaling Parameters in the cuDNN Developer Guide.

**xDesc**

*Input*. Handle to the previously initialized input tensor descriptor. For more information, see `cudnnTensorDescriptor_t`.

**x**

*Input*. Data pointer to GPU memory associated with the tensor descriptor xDesc.

**yDesc**

*Input*. Handle to the previously initialized output tensor descriptor.

**y**

*Output*. Data pointer to GPU memory associated with the output tensor descriptor yDesc.

Returns

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The parameter `mode` has an invalid enumerant value.
- The dimensions `n, c, h, w` of the input tensor and output tensor differ.
The datatype of the input tensor and output tensor differs.

- The strides nStride, cStride, hStride, wStride of the input tensor and output tensor differ and in-place operation is used (meaning, x and y pointers are equal).

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

### 3.2.2. `cudnnAddTensor()`

```c
#include <cudnn.h>

cudnnStatus_t cudnnAddTensor(
    cudnnHandle_t                     handle,
    const void                       *alpha,
    const cudnnTensorDescriptor_t     aDesc,
    const void                       *A,
    const void                       *beta,
    const cudnnTensorDescriptor_t     cDesc,
    void                             *C)
```

This function adds the scaled values of a bias tensor to another tensor. Each dimension of the bias tensor A must match the corresponding dimension of the destination tensor C or must be equal to 1. In the latter case, the same value from the bias tensor for those dimensions will be used to blend into the C tensor.

**Note:** Up to dimension 5, all tensor formats are supported. Beyond those dimensions, this routine is not supported

#### Parameters

**handle**

*Input.* Handle to a previously created cuDNN context. For more information, see `cudnnHandle_t`.

**alpha, beta**

*Input.* Pointers to scaling factors [in host memory] used to blend the source value with the prior value in the destination tensor as follows:

\[
\text{dstValue} = \text{alpha}[0] \times \text{srcValue} + \text{beta}[0] \times \text{priorDstValue}
\]

For more information, see Scaling Parameters in the cuDNN Developer Guide.

**aDesc**

*Input.* Handle to a previously initialized tensor descriptor. For more information, see `cudnnTensorDescriptor_t`.

**A**

*Input.* Pointer to data of the tensor described by the aDesc descriptor.

**cDesc**

*Input.* Handle to a previously initialized tensor descriptor.
cudnn_batch_normalization_forward_inference.so Library

cuDNN API Reference

Input/Output. Pointer to data of the tensor described by the cDesc descriptor.

Returns

**CUDNN_STATUS_SUCCESS**

The function executed successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

The dimensions of the bias tensor refer to an amount of data that is incompatible with the output tensor dimensions or the dataType of the two tensor descriptors are different.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

### 3.2.3. cudnnBatchNormalizationForwardInference()

```c
    cudnnStatus_t cudnnBatchNormalizationForwardInference(
    cudnnHandle_t handle,    // handle,
    cudnnBatchNormMode_t mode,    // mode,
    const void *alpha,    // alpha,
    const void *beta,    // beta,
    const cudnnTensorDescriptor_t xDesc,    // xDesc,
    const void *x,    // x,
    const cudnnTensorDescriptor_t yDesc,    // yDesc,
    void *y,    // y,
    const cudnnTensorDescriptor_t bnScaleBiasMeanVarDesc,    // bnScaleBiasMeanVarDesc,
    const void *bnScale,    // bnScale,
    const void *bnBias,    // bnBias,
    const void *estimatedMean,    // estimatedMean,
    const void *estimatedVariance,    // estimatedVariance,
    double epsilon)    // epsilon)
```

This function performs the forward batch normalization layer computation for the inference phase. This layer is based on the paper [Batch Normalization: Accelerating Deep Network Training by Reducing Internal Covariate Shift](https://arxiv.org/abs/1502.03167), S. Ioffe, C. Szegedy, 2015.

**Note:**

- Only 4D and 5D tensors are supported.
- The input transformation performed by this function is defined as:

  \[
  y = \beta y + \alpha [\text{bnBias} + (\text{bnScale} \times (x - \text{estimatedMean})/\sqrt{\epsilon + \text{estimatedVariance}})]
  \]

- The epsilon value has to be the same during training, backpropagation and inference.
- For the training phase, use `cudnnBatchNormalizationForwardTraining()`.
- Higher performance can be obtained when HW-packed tensors are used for all of x and dx.

For more information, see `cudnnDeriveBNTensorDescriptor()` for the secondary tensor descriptor generation for the parameters used in this function.
Parameters

**handle**

*Input.* Handle to a previously created cuDNN library descriptor. For more information, see `cudnnHandle_t`.

**mode**

*Input.* Mode of operation [spatial or per-activation]. For more information, see `cudnnBatchNormMode_t`.

**alpha, beta**

*Inputs.* Pointers to scaling factors (in host memory) used to blend the layer output value with prior value in the destination tensor as follows:

\[
dstValue = \alpha[0] \cdot \text{resultValue} + \beta[0] \cdot \text{priorDstValue}
\]

For more information, see Scaling Parameters in the cuDNN Developer Guide.

**xDesc, yDesc**

*Input.* Handles to the previously initialized tensor descriptors.

**x**

*Input.* Data pointer to GPU memory associated with the tensor descriptor xDesc, for the layer’s x input data.

**y**

*Input.* Data pointer to GPU memory associated with the tensor descriptor yDesc, for the y output of the batch normalization layer.

**bnScaleBiasMeanVarDesc, bnScale, bnBias**

*Inputs.* Tensor descriptors and pointers in device memory for the batch normalization scale and bias parameters (in the original paper bias is referred to as beta and scale as gamma).

**estimatedMean, estimatedVariance**

*Inputs.* Mean and variance tensors (these have the same descriptor as the bias and scale). The resultRunningMean and resultRunningVariance, accumulated during the training phase from the `cudnnBatchNormalizationForwardTraining` call, should be passed as inputs here.

**epsilon**

*Input.* Epsilon value used in the batch normalization formula. Its value should be equal to or greater than the value defined for `CUDNN_BN_MIN_EPSILON` in `cudnn.h`.

Supported configurations

This function supports the following combinations of data types for various descriptors.
Table 5. Supported configurations

<table>
<thead>
<tr>
<th>Data Type Configurations</th>
<th>xDesc</th>
<th>bnScaleBiasMeanVarDesc</th>
<th>alpha, beta</th>
<th>yDesc</th>
</tr>
</thead>
<tbody>
<tr>
<td>INT8_CONFIG</td>
<td>CUDNN_DATA_INT8</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_INT8</td>
</tr>
<tr>
<td>PSEUDO_HALF_CONFIG</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
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</tr>
<tr>
<td>FLOAT_CONFIG</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
</tr>
<tr>
<td>DOUBLE_CONFIG</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
</tr>
</tbody>
</table>

Returns

**CUDNN_STATUS_SUCCESS**

The computation was performed successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- One of the pointers alpha, beta, x, y, bnScale, bnBias, estimatedMean, estimatedInvVariance is NULL.
- The number of xDesc or yDesc tensor descriptor dimensions is not within the range of [4, 5] (only 4D and 5D tensors are supported.)
- bnScaleBiasMeanVarDesc dimensions are not 1xCx1x1 for 4D and 1xCx1x1x1 for 5D for spatial, and are not 1xCxHxW for 4D and 1xCxDxHxW for 5D for per-activation mode.
- epsilon value is less than CUDNN_BN_MIN_EPSILON.
- Dimensions or data types mismatch for xDesc, yDesc.

3.2.4. **cudnnCopyAlgorithmDescriptor()**

This function has been deprecated in cuDNN 8.0.

3.2.5. **cudnnCreate()**

cudnnStatus_t cudnnCreate(cudnnHandle_t *handle)

This function initializes the cuDNN library and creates a handle to an opaque structure holding the cuDNN library context. It allocates hardware resources on the host and device and must be called prior to making any other cuDNN library calls.

The cuDNN library handle is tied to the current CUDA device (context). To use the library on multiple devices, one cuDNN handle needs to be created for each device.

For a given device, multiple cuDNN handles with different configurations [for example, different current CUDA streams] may be created. Because cudnnCreate() allocates some internal resources, the release of those resources by calling cudnnDestroy() will implicitly call
cudaDeviceSynchronize; therefore, the recommended best practice is to call cudnnCreate/cudnnDestroy outside of performance-critical code paths.

For multithreaded applications that use the same device from different threads, the recommended programming model is to create one [or a few, as is convenient] cuDNN handle[s] per thread and use that cuDNN handle for the entire life of the thread.

Parameters

handle

Output. Pointer to pointer where to store the address to the allocated cuDNN handle. For more information, see cudnnHandle_t.

Returns

CUDNN_STATUS_BAD_PARAM

Invalid (NULL) input pointer supplied.

CUDNN_STATUS_NOT_INITIALIZED

No compatible GPU found, CUDA driver not installed or disabled, CUDA runtime API initialization failed.

CUDNN_STATUS_ARCH_MISMATCH

NVIDIA GPU architecture is too old.

CUDNN_STATUS_ALLOC_FAILED

Host memory allocation failed.

CUDNN_STATUS_INTERNAL_ERROR

CUDA resource allocation failed.

CUDNN_STATUS_LICENSE_ERROR

cuDNN license validation failed [only when the feature is enabled].

CUDNN_STATUS_SUCCESS

cuDNN handle was created successfully.

3.2.6. cudnnCreateActivationDescriptor()

cudnnStatus_t cudnnCreateActivationDescriptor(
    cudnnActivationDescriptor_t *activationDesc)

This function creates an activation descriptor object by allocating the memory needed to hold its opaque structure. For more information, see cudnnActivationDescriptor_t.

Returns

CUDNN_STATUS_SUCCESS

The object was created successfully.
CUDNN_STATUS_ALLOC_FAILED

The resources could not be allocated.

3.2.7. cudnnCreateAlgorithmDescriptor()

This function has been deprecated in cuDNN 8.0.

```
cudnnStatus_t cudnnCreateAlgorithmDescriptor(
    cudnnAlgorithmDescriptor_t *algoDesc)
```

This function creates an algorithm descriptor object by allocating the memory needed to hold its opaque structure.

Returns

CUDNN_STATUS_SUCCESS

The object was created successfully.

CUDNN_STATUS_ALLOC_FAILED

The resources could not be allocated.

3.2.8. cudnnCreateAlgorithmPerformance()

```
cudnnStatus_t cudnnCreateAlgorithmPerformance(
    cudnnAlgorithmPerformance_t *algoPerf,
    int numberToCreate)
```

This function creates multiple algorithm performance objects by allocating the memory needed to hold their opaque structures.

Returns

CUDNN_STATUS_SUCCESS

The object was created successfully.

CUDNN_STATUS_ALLOC_FAILED

The resources could not be allocated.

3.2.9. cudnnCreateDropoutDescriptor()

```
cudnnStatus_t cudnnCreateDropoutDescriptor(
    cudnnDropoutDescriptor_t *dropoutDesc)
```

This function creates a generic dropout descriptor object by allocating the memory needed to hold its opaque structure. For more information, see cudnnDropoutDescriptor_t.

Returns

CUDNN_STATUS_SUCCESS

The object was created successfully.
CUDNN_STATUS_ALLOC_FAILED

The resources could not be allocated.

3.2.10. cudnnCreateFilterDescriptor()

cudnnStatus_t cudnnCreateFilterDescriptor(
    cudnnFilterDescriptor_t *filterDesc)

This function creates a filter descriptor object by allocating the memory needed to hold its opaque structure. For more information, see cudnnFilterDescriptor_t.

Returns

CUDNN_STATUS_SUCCESS

The object was created successfully.

CUDNN_STATUS_ALLOC_FAILED

The resources could not be allocated.

3.2.11. cudnnCreateLRNDescriptor()

cudnnStatus_t cudnnCreateLRNDescriptor(
    cudnnLRNDescriptor_t    *poolingDesc)

This function allocates the memory needed to hold the data needed for LRN and DivisiveNormalization layers operation and returns a descriptor used with subsequent layer forward and backward calls.

Returns

CUDNN_STATUS_SUCCESS

The object was created successfully.

CUDNN_STATUS_ALLOC_FAILED

The resources could not be allocated.

3.2.12. cudnnCreateOpTensorDescriptor()

cudnnStatus_t cudnnCreateOpTensorDescriptor(
    cudnnOpTensorDescriptor_t*  opTensorDesc)

This function creates a tensor pointwise math descriptor. For more information, see cudnnOpTensorDescriptor_t.

Parameters

opTensorDesc

Output. Pointer to the structure holding the description of the tensor pointwise math such as add, multiply, and more.
Returns

CUDNN_STATUS_SUCCESS
The function returned successfully.

CUDNN_STATUS_BAD_PARAM
Tensor pointwise math descriptor passed to the function is invalid.

CUDNN_STATUS_ALLOC_FAILED
Memory allocation for this tensor pointwise math descriptor failed.

3.2.13. cudnnCreatePoolingDescriptor()
cudnnStatus_t cudnnCreatePoolingDescriptor(cudnnPoolingDescriptor_t *poolingDesc)
This function creates a pooling descriptor object by allocating the memory needed to hold its opaque structure.

Returns

CUDNN_STATUS_SUCCESS
The object was created successfully.

CUDNN_STATUS_ALLOC_FAILED
The resources could not be allocated.

3.2.14. cudnnCreateReduceTensorDescriptor()
cudnnStatus_t cudnnCreateReduceTensorDescriptor(cudnnReduceTensorDescriptor_t* reduceTensorDesc)
This function creates a reduced tensor descriptor object by allocating the memory needed to hold its opaque structure.

Returns

CUDNN_STATUS_SUCCESS
The object was created successfully.

CUDNN_STATUS_BAD_PARAM
reduceTensorDesc is a NULL pointer.

CUDNN_STATUS_ALLOC_FAILED
The resources could not be allocated.

3.2.15. cudnnCreateSpatialTransformerDescriptor()
cudnnStatus_t cudnnCreateSpatialTransformerDescriptor(cudnnSpatialTransformerDescriptor_t *stDesc)
This function creates a generic spatial transformer descriptor object by allocating the memory needed to hold its opaque structure.

Returns

**CUDNN_STATUS_SUCCESS**
- The object was created successfully.

**CUDNN_STATUS_ALLOC_FAILED**
- The resources could not be allocated.

### 3.2.16. cudnnCreateTensorDescriptor()

```c
cudnnStatus_t cudnnCreateTensorDescriptor(
    cudnnTensorDescriptor_t *tensorDesc)
```

This function creates a generic tensor descriptor object by allocating the memory needed to hold its opaque structure. The data is initialized to all zeros.

**Parameters**

* tensorDesc

  _Input_. Pointer to pointer where the address to the allocated tensor descriptor object should be stored.

**Returns**

**CUDNN_STATUS_BAD_PARAM**
- Invalid input argument.

**CUDNN_STATUS_ALLOC_FAILED**
- The resources could not be allocated.

**CUDNN_STATUS_SUCCESS**
- The object was created successfully.

### 3.2.17. cudnnCreateTensorTransformDescriptor()

```c
cudnnStatus_t cudnnCreateTensorTransformDescriptor(
    cudnnTensorTransformDescriptor_t *transformDesc);
```

This function creates a tensor transform descriptor object by allocating the memory needed to hold its opaque structure. The tensor data is initialized to be all zero. Use the `cudnnSetTensorTransformDescriptor()` function to initialize the descriptor created by this function.

**Parameters**

* transformDesc

  _Output_. A pointer to an uninitialized tensor transform descriptor.
Returns

**CUDNN_STATUS_SUCCESS**
The descriptor object was created successfully.

**CUDNN_STATUS_BAD_PARAM**
The transformDesc is NULL.

**CUDNN_STATUS_ALLOC_FAILED**
The memory allocation failed.

### 3.2.18. **cudnnDeriveBNTensorDescriptor()**

```c
    cudnnStatus_t cudnnDeriveBNTensorDescriptor(
        cudnnTensorDescriptor_t derivedBnDesc,
        const cudnnTensorDescriptor_t xDesc,
        cudnnBatchNormMode_t mode)
```

This function derives a secondary tensor descriptor for the batch normalization `scale`, `invVariance`, `bnBias`, and `bnScale` sub-tensors from the layer’s `x` data descriptor.

Use the tensor descriptor produced by this function as the `bnScaleBiasMeanVarDesc` parameter for the [cudnnBatchNormalizationForwardInference()] and [cudnnBatchNormalizationForwardTraining()] functions, and as the `bnScaleBiasDiffDesc` parameter in the [cudnnBatchNormalizationBackward()] function.

The resulting dimensions will be:

- 1xCx1x1 for 4D and 1xCx1x1x1 for 5D for **BATCHNORM_MODE_SPATIAL**
- 1xCxHxW for 4D and 1xCxDxHxW for 5D for **BATCHNORM_MODE_PER_ACTIVATION**

For **HALF** input data type the resulting tensor descriptor will have a **FLOAT** type. For other data types, it will have the same type as the input data.

**Note:**

- Only 4D and 5D tensors are supported.
- The `derivedBnDesc` should be first created using [cudnnCreateTensorDescriptor()](https://docs.nvidia.com/deeplearning/repos/cudnn/docs/api/interfaces/cudnnCreateTensorDescriptor.html).
- `xDesc` is the descriptor for the layer’s `x` data and has to be set up with proper dimensions prior to calling this function.

**Parameters**

- **derivedBnDesc**
  - Output. Handle to a previously created tensor descriptor.

- **xDesc**
  - Input. Handle to a previously created and initialized layer’s `x` data descriptor.

- **mode**
  - Input. Batch normalization layer mode of operation.
Returns

**CUDNN_STATUS_SUCCESS**

The computation was performed successfully.

**CUDNN_STATUS_BAD_PARAM**

Invalid Batch Normalization mode.

### 3.2.19. `cudnnDeriveNormTensorDescriptor()`

```
cudnnStatus_t CUDNNWINAPI cudnnDeriveNormTensorDescriptor(cudnnTensorDescriptor_t derivedNormScaleBiasDesc, 
                                          cudnnTensorDescriptor_t derivedNormMeanVarDesc, 
                                          const cudnnTensorDescriptor_t xDesc, 
                                          cudnnNormMode_t mode, 
                                          int groupCnt)
```

This function derives tensor descriptors for the normalization mean, invariance, normBias, and normScale subtensors from the layer’s x data descriptor and norm mode. normalization, mean, and invariance share the same descriptor while bias and scale share the same descriptor.

Use the tensor descriptor produced by this function as the normScaleBiasDesc or normMeanVarDesc parameter for the [cudnnNormalizationForwardInference](https://docs.nvidia.com/cuda/cudnn/api/po/cudnnNormalizationForwardInference.shtml) and [cudnnNormalizationForwardTraining](https://docs.nvidia.com/cuda/cudnn/api/po/cudnnNormalizationForwardTraining.shtml) functions, and as the dNormScaleBiasDesc and normMeanVarDesc parameter in the [cudnnNormalizationBackward](https://docs.nvidia.com/cuda/cudnn/api/po/cudnnNormalizationBackward.shtml) function.

The resulting dimensions will be:

- 1xCx1x1 for 4D and 1xCx1x1x1 for 5D for CUDNN_NORM_PER_ACTIVATION
- 1xCxHxW for 4D and 1xCxDxHxW for 5D for CUDNN_NORM_PER_CHANNEL mode

For **HALF** input data type the resulting tensor descriptor will have a **FLOAT** type. For other data types, it will have the same type as the input data.

- Only 4D and 5D tensors are supported.
- The derivedNormScaleBiasDesc and derivedNormMeanVarDesc should be created first using [cudnnCreateTensorDescriptor](https://docs.nvidia.com/cuda/cudnn/api/po/cudnnCreateTensorDescriptor.shtml).
- xDesc is the descriptor for the layer’s x data and has to be set up with proper dimensions prior to calling this function.

#### Parameters

- **derivedNormScaleBiasDesc**

  *Output.* Handle to a previously created tensor descriptor.

- **derivedNormMeanVarDesc**

  *Output.* Handle to a previously created tensor descriptor.
**xDesc**

*Input*. Handle to a previously created and initialized layer’s x data descriptor.

**mode**

*Input*. The normalization layer mode of operation.

**Returns**

**CUDNN_STATUS_SUCCESS**

The computation was performed successfully.

**CUDNN_STATUS_BAD_PARAM**

Invalid Batch Normalization mode.

### 3.2.20. **cudnnDestroy**

cudnnStatus_t cudnnDestroy(cudnnHandle_t handle)

This function releases the resources used by the cuDNN handle. This function is usually the last call with a particular handle to the cuDNN handle. Because `cudnnCreate()` allocates some internal resources, the release of those resources by calling `cudnnDestroy()` will implicitly call `cudaDeviceSynchronize`; therefore, the recommended best practice is to call `cudnnCreate/cudnnDestroy` outside of performance-critical code paths.

**Parameters**

**handle**

*Input*. Pointer to the cuDNN handle to be destroyed.

**Returns**

**CUDNN_STATUS_SUCCESS**

The cuDNN context destruction was successful.

**CUDNN_STATUS_BAD_PARAM**

Invalid (NULL) pointer supplied.

### 3.2.21. **cudnnDestroyActivationDescriptor**

cudnnStatus_t cudnnDestroyActivationDescriptor(cudnnActivationDescriptor_t activationDesc)

This function destroys a previously created activation descriptor object.

**Returns**

**CUDNN_STATUS_SUCCESS**

The object was destroyed successfully.
3.2.22. **cudnnDestroyAlgorithmDescriptor()**

This function has been deprecated in cuDNN 8.0.

```cudnnStatus_t cudnnDestroyAlgorithmDescriptor(
    cudnnActivationDescriptor_t algorithmDesc)
```

This function destroys a previously created algorithm descriptor object.

**Returns**

**CUDNN_STATUS_SUCCESS**

The object was destroyed successfully.

3.2.23. **cudnnDestroyAlgorithmPerformance()**

```cudnnStatus_t cudnnDestroyAlgorithmPerformance(
    cudnnAlgorithmPerformance_t algoPerf)
```

This function destroys a previously created algorithm descriptor object.

**Returns**

**CUDNN_STATUS_SUCCESS**

The object was destroyed successfully.

3.2.24. **cudnnDestroyDropoutDescriptor()**

```cudnnStatus_t cudnnDestroyDropoutDescriptor(
    cudnnDropoutDescriptor_t dropoutDesc)
```

This function destroys a previously created dropout descriptor object.

**Returns**

**CUDNN_STATUS_SUCCESS**

The object was destroyed successfully.

3.2.25. **cudnnDestroyFilterDescriptor()**

```cudnnStatus_t cudnnDestroyFilterDescriptor(
    cudnnFilterDescriptor_t filterDesc)
```

This function destroys a previously created tensor 4D descriptor object.

**Returns**

**CUDNN_STATUS_SUCCESS**

The object was destroyed successfully.
3.2.26. **cudnnDestroyLRNDescriptor()**

cudnnStatus_t cudnnDestroyLRNDescriptor(cudnnLRNDescriptor_t lrnDesc)

This function destroys a previously created LRN descriptor object.

**Returns**

**CUDNN_STATUS_SUCCESS**

The object was destroyed successfully.

3.2.27. **cudnnDestroyOpTensorDescriptor()**

cudnnStatus_t cudnnDestroyOpTensorDescriptor(cudnnOpTensorDescriptor_t opTensorDesc)

This function deletes a tensor pointwise math descriptor object.

**Parameters**

**opTensorDesc**

*Input*. Pointer to the structure holding the description of the tensor pointwise math to be deleted.

**Returns**

**CUDNN_STATUS_SUCCESS**

The function returned successfully.

3.2.28. **cudnnDestroyPoolingDescriptor()**

cudnnStatus_t cudnnDestroyPoolingDescriptor(cudnnPoolingDescriptor_t poolingDesc)

This function destroys a previously created pooling descriptor object.

**Returns**

**CUDNN_STATUS_SUCCESS**

The object was destroyed successfully.

3.2.29. **cudnnDestroyReduceTensorDescriptor()**

cudnnStatus_t cudnnDestroyReduceTensorDescriptor(cudnnReduceTensorDescriptor_t tensorDesc)

This function destroys a previously created reduce tensor descriptor object. When the input pointer is NULL, this function performs no destroy operation.
Parameters

tensorDesc

Input. Pointer to the reduce tensor descriptor object to be destroyed.

Returns

**CUDNN_STATUS_SUCCESS**

The object was destroyed successfully.

### 3.2.30. **cudnnDestroySpatialTransformerDescriptor()**

cudnnStatus_t cudnnDestroySpatialTransformerDescriptor(
cudnnSpatialTransformerDescriptor_t stDesc)

This function destroys a previously created spatial transformer descriptor object.

Returns

**CUDNN_STATUS_SUCCESS**

The object was destroyed successfully.

### 3.2.31. **cudnnDestroyTensorDescriptor()**

cudnnStatus_t cudnnDestroyTensorDescriptor(cudnnTensorDescriptor_t tensorDesc)

This function destroys a previously created tensor descriptor object. When the input pointer is **NULL**, this function performs no destroy operation.

Parameters

**tensorDesc**

Input. Pointer to the tensor descriptor object to be destroyed.

Returns

**CUDNN_STATUS_SUCCESS**

The object was destroyed successfully.

### 3.2.32. **cudnnDestroyTensorTransformDescriptor()**

cudnnStatus_t cudnnDestroyTensorTransformDescriptor(
cudnnTensorTransformDescriptor_t transformDesc);

Destroys a previously created tensor transform descriptor.
### Parameters

**transformDesc**

*Input.* The tensor transform descriptor to be destroyed.

### Returns

**CUDNN_STATUS_SUCCESS**

The descriptor was destroyed successfully.

### 3.2.33. `cudnnDivisiveNormalizationForward()`

```c
void cudnnDivisiveNormalizationForward(
    cudnnHandle_t handle,
    cudnnLRNDescriptor_t normDesc,
    cudnnDivNormMode_t mode,
    const void *alpha,
    const cudnnTensorDescriptor_t xDesc,
    const void *x,
    const void *means,
    void *temp,
    void *temp2,
    const void *beta,
    const cudnnTensorDescriptor_t yDesc,
    void *y)
```

This function performs the forward spatial DivisiveNormalization layer computation. It divides every value in a layer by the standard deviation of its spatial neighbors as described in *What is the Best Multi-Stage Architecture for Object Recognition*, Jarrett 2009, Local Contrast Normalization Layer section. Note that DivisiveNormalization only implements the \(x / \max(c, \sigma_x)\) portion of the computation, where \(\sigma_x\) is the variance over the spatial neighborhood of \(x\). The full LCN (Local Contrastive Normalization) computation can be implemented as a two-step process:

\[
    x_m = x - \text{mean}(x); \\
y = \frac{x_m}{\max(c, \sigma(x_m))};
\]

The \(\text{mean}(x)\) which is often referred to as "subtractive normalization" portion of the computation can be implemented using cuDNN average pooling layer followed by a call to `addTensor`.

**Note:** Supported tensor formats are NCHW for 4D and NCDHW for 5D with any non-overlapping non-negative strides. Only 4D and 5D tensors are supported.

### Parameters

**handle**

*Input.* Handle to a previously created cuDNN library descriptor.

**normDesc**

*Input.* Handle to a previously initialized LRN parameter descriptor. This descriptor is used for both LRN and DivisiveNormalization layers.
divNormMode

Input. DivisiveNormalization layer mode of operation. Currently only CUDNN_DIVNORM_PRECOMPUTED_MEANS is implemented. Normalization is performed using the means input tensor that is expected to be precomputed by the user.

alpha, beta

Input. Pointers to scaling factors [in host memory] used to blend the layer output value with prior value in the destination tensor as follows:

\[
dstValue = \text{alpha}[0] \times \text{resultValue} + \text{beta}[0] \times \text{priorDstValue}
\]

For more information, see Scaling Parameters in the cuDNN Developer Guide.

xDesc, yDesc

Input. Tensor descriptor objects for the input and output tensors. Note that xDesc is shared between x, means, temp, and temp2 tensors.

x

Input. Input tensor data pointer in device memory.

means

Input. Input means tensor data pointer in device memory. Note that this tensor can be NULL (in that case its values are assumed to be zero during the computation). This tensor also doesn’t have to contain means, these can be any values, a frequently used variation is a result of convolution with a normalized positive kernel (such as Gaussian).

temp, temp2

Workspace. Temporary tensors in device memory. These are used for computing intermediate values during the forward pass. These tensors do not have to be preserved as inputs from forward to the backward pass. Both use xDesc as their descriptor.

y

Output. Pointer in device memory to a tensor for the result of the forward DivisiveNormalization computation.

Returns

CUDNN_STATUS_SUCCESS

The computation was performed successfully.

CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- One of the tensor pointers x, y, temp, temp2 is NULL.
- Number of input tensor or output tensor dimensions is outside of [4, 5] range.
- A mismatch in dimensions between any two of the input or output tensors.
- For in-place computation when pointers x == y, a mismatch in strides between the input data and output data tensors.
Alpha or beta pointer is NULL.

- LRN descriptor parameters are outside of their valid ranges.
- Any of the tensor strides are negative.

**CUDNN_STATUS_UNSUPPORTED**

The function does not support the provided configuration, for example, any of the input and output tensor strides mismatch (for the same dimension) is a non-supported configuration.

### 3.2.34. cudnnDropoutForward()

```c

cudnnStatus_t cudnnDropoutForward(
    cudnnHandle_t                       handle,
    const cudnnDropoutDescriptor_t      dropoutDesc,
    const cudnnTensorDescriptor_t       xdesc,
    const void                         *x,
    const cudnnTensorDescriptor_t       ydesc,
    void                               *y,
    void                               *reserveSpace,
    size_t                              reserveSpaceSizeInBytes)
```

This function performs forward dropout operation over `x` returning results in `y`. If dropout was used as a parameter to `cudnnSetDropoutDescriptor()`, the approximately dropout fraction of `x` values will be replaced by a 0, and the rest will be scaled by 1/(1-dropout). This function should not be running concurrently with another `cudnnDropoutForward()` function using the same states.

**Note:**

- Better performance is obtained for fully packed tensors.
- This function should not be called during inference.

**Parameters**

**handle**

*Input.* Handle to a previously created cuDNN context.

**dropoutDesc**

*Input.* Previously created dropout descriptor object.

**xDesc**

*Input.* Handle to a previously initialized tensor descriptor.

**x**

*Input.* Pointer to data of the tensor described by the `xDesc` descriptor.

**yDesc**

*Input.* Handle to a previously initialized tensor descriptor.

**y**

*Output.* Pointer to data of the tensor described by the `yDesc` descriptor.
reserveSpace

Output. Pointer to user-allocated GPU memory used by this function. It is expected that the contents of reserveSpace does not change between cudnnDropoutForward() and cudnnDropoutBackward() calls.

reserveSpaceSizeInBytes

Input. Specifies the size in bytes of the provided memory for the reserve space.

Returns

CUDNN_STATUS_SUCCESS

The call was successful.

CUDNN_STATUS_NOT_SUPPORTED

The function does not support the provided configuration.

CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- The number of elements of input tensor and output tensors differ.
- The datatype of the input tensor and output tensors differs.
- The strides of the input tensor and output tensors differ and in-place operation is used (meaning, x and y pointers are equal).
- The provided reserveSpaceSizeInBytes is less than the value returned by cudnnDropoutGetReserveSpaceSize().
- cudnnSetDropoutDescriptor() has not been called on dropoutDesc with the non-NULL states argument.

CUDNN_STATUS_EXECUTION_FAILED

The function failed to launch on the GPU.

3.2.35. cudnnDropoutGetReserveSpaceSize()

cudnnStatus_t cudnnDropoutGetReserveSpaceSize(
    cudnnTensorDescriptor_t xDesc,
    size_t *sizeInBytes)

This function is used to query the amount of reserve needed to run dropout with the input dimensions given by xDesc. The same reserve space is expected to be passed to cudnnDropoutForward() and cudnnDropoutBackward(), and its contents is expected to remain unchanged between cudnnDropoutForward() and cudnnDropoutBackward() calls.

Parameters

xDesc

Input. Handle to a previously initialized tensor descriptor, describing input to a dropout operation.
sizeInBytes

*Output.* Amount of GPU memory needed as reserve space to be able to run dropout with an input tensor descriptor specified by xDesc.

**Returns**

**CUDNN_STATUS_SUCCESS**

The query was successful.

### 3.2.36. cudnnDropoutGetStatesSize()

```c
cudnnStatus_t cudnnDropoutGetStatesSize(
    cudnnHandle_t       handle,
    size_t             *sizeInBytes)
```

This function is used to query the amount of space required to store the states of the random number generators used by `cudnnDropoutForward()` function.

**Parameters**

**handle**

*Input.* Handle to a previously created cuDNN context.

**sizeInBytes**

*Output.* Amount of GPU memory needed to store random generator states.

**Returns**

**CUDNN_STATUS_SUCCESS**

The query was successful.

### 3.2.37. cudnnGetActivationDescriptor()

```c
cudnnStatus_t cudnnGetActivationDescriptor(
    const cudnnActivationDescriptor_t   activationDesc,
    cudnnActivationMode_t              *mode,
    cudnnNanPropagation_t              *reluNanOpt,
    double                             *coef)
```

This function queries a previously initialized generic activation descriptor object.

**Parameters**

**activationDesc**

*Input.* Handle to a previously created activation descriptor.

**mode**

*Output.* Enumerant to specify the activation mode.
reluNanOpt

Output. Enumerant to specify the NaN propagation mode.

coeff

Output. Floating point number to specify the clipping threshold when the activation mode is set to CUDNN_ACTIVATION_CLIPPED_RELU or to specify the alpha coefficient when the activation mode is set to CUDNN_ACTIVATION_ELU.

Returns

CUDNN_STATUS_SUCCESS

The object was queried successfully.

3.2.38. cudnnGetAlgorithmDescriptor()

This function has been deprecated in cuDNN 8.0.

```
cudnnStatus_t cudnnGetAlgorithmDescriptor(  
    const cudnnAlgorithmDescriptor_t algoDesc,  
    cudnnAlgorithm_t* algorithm)
```

This function queries a previously initialized generic algorithm descriptor object.

Parameters

algorithmDesc

Input. Handle to a previously created algorithm descriptor.

algorithm

Input. Struct to specify the algorithm.

Returns

CUDNN_STATUS_SUCCESS

The object was queried successfully.

3.2.39. cudnnGetAlgorithmPerformance()

This function has been deprecated in cuDNN 8.0.

```
cudnnStatus_t cudnnGetAlgorithmPerformance(  
    const cudnnAlgorithmPerformance_t algoPerf,  
    cudnnAlgorithmDescriptor_t* algoDesc,  
    cudnnStatus_t* status,  
    float* time,  
    size_t* memory)
```

This function queries a previously initialized generic algorithm performance object.
Parameters

**algoPerf**

*Input/Output.* Handle to a previously created algorithm performance object.

**algoDesc**

*Output.* The algorithm descriptor which the performance results describe.

**status**

*Output.* The cuDNN status returned from running the `algoDesc` algorithm.

**timecoef**

*Output.* The GPU time spent running the `algoDesc` algorithm.

**memory**

*Output.* The GPU memory needed to run the `algoDesc` algorithm.

Returns

**CUDNN_STATUS_SUCCESS**

The object was queried successfully.

### 3.2.40. `cudnnGetAlgorithmSpaceSize()`

This function has been deprecated in cuDNN 8.0.

```c
void cudnnGetAlgorithmSpaceSize(
    cudnnHandle_t handle,
    cudnnAlgorithmDescriptor_t algoDesc,
    size_t* algoSpaceSizeInBytes)
```

This function queries for the amount of host memory needed to call `cudnnSaveAlgorithm()`, much like the “get workspace size” function query for the amount of device memory needed.

Parameters

**handle**

*Input.* Handle to a previously created cuDNN context.

**algoDesc**

*Input.* A previously created algorithm descriptor.

**algoSpaceSizeInBytes**

*Output.* Amount of host memory needed as a workspace to be able to save the metadata from the specified `algoDesc`.
Returns

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of the arguments is NULL.

### 3.2.41. `cudnnGetCallback()`

```c
cudnnStatus_t cudnnGetCallback(
    unsigned            mask,
    void                **udata,
    cudnnCallback_t     fptr)
```

This function queries the internal states of cuDNN error reporting functionality.

**Parameters**

- **`mask`**

  *Output*. Pointer to the address where the current internal error reporting message bit mask will be outputted.

- **`udata`**

  *Output*. Pointer to the address where the current internally stored udata address will be stored.

- **`fptr`**

  *Output*. Pointer to the address where the current internally stored callback function pointer will be stored. When the built-in default callback function is used, NULL will be outputted.

**Returns**

- **CUDNN_STATUS_SUCCESS**

  The function launched successfully.

- **CUDNN_STATUS_BAD_PARAM**

  If any of the input parameters are NULL.

### 3.2.42. `cudnnGetCudartVersion()`

```c
size_t cudnnGetCudartVersion()
```

The same version of a given cuDNN library can be compiled against different NVIDIA® CUDA® Toolkit™ versions. This routine returns the CUDA Toolkit version that the currently used cuDNN library has been compiled against.
3.2.43. **cudnnGetDropoutDescriptor()**

```c
CUDNN_STATUS_T cudnnGetDropoutDescriptor(
    cudnnDropoutDescriptor_t dropoutDesc,
    cudnnHandle_t handle,
    float *dropout,
    void **states,
    unsigned long long *seed)
```

This function queries the fields of a previously initialized dropout descriptor.

**Parameters**

- **dropoutDesc**
- **handle**
  - *Input*. Handle to a previously created cuDNN context.
- **dropout**
  - *Output*. The probability with which the value from input is set to 0 during the dropout layer.
- **states**
  - *Output*. Pointer to user-allocated GPU memory that holds random number generator states.
- **seed**
  - *Output*. Seed used to initialize random number generator states.

**Returns**

- **CUDNN_STATUS_SUCCESS**
  - The call was successful.
- **CUDNN_STATUS_BAD_PARAM**
  - One or more of the arguments was an invalid pointer.

3.2.44. **cudnnGetErrorString()**

```c
const char * cudnnGetErrorString(cudnnStatus_t status)
```

This function converts the cuDNN status code to a NULL terminated [ASCIIZ] static string. For example, when the input argument is **CUDNN_STATUS_SUCCESS**, the returned string is **CUDNN_STATUS_SUCCESS**. When an invalid status value is passed to the function, the returned string is **CUDNN_UNKNOWN_STATUS**.

**Parameters**

- **status**
  - *Input*. cuDNN enumerant status code.
Returns

Pointer to a static, NULL terminated string with the status name.

3.2.45. *cudnnGetFilter4dDescriptor()*

```c
#include <cudnn.h>

cudnnStatus_t cudnnGetFilter4dDescriptor(
    const cudnnFilterDescriptor_t     filterDesc,
    cudnnDataType_t            *dataType,
    cudnnTensorFormat_t        *format,
    int                        *k,
    int                        *c,
    int                        *h,
    int                        *w)
```

This function queries the parameters of the previously initialized filter descriptor object.

Parameters

**filterDesc**

*Input*. Handle to a previously created filter descriptor.

**datatype**

*Output*. Data type.

**format**

*Output*. Type of format.

**k**

*Output*. Number of output feature maps.

**c**

*Output*. Number of input feature maps.

**h**

*Output*. Height of each filter.

**w**

*Output*. Width of each filter.

Returns

**CUDNN_STATUS_SUCCESS**

The object was set successfully.

3.2.46. *cudnnGetFilterNdDescriptor()*

```c
#include <cudnn.h>

cudnnStatus_t cudnnGetFilterNdDescriptor(
    const cudnnFilterDescriptor_t   filterDesc,
    int                             nbDimsRequested,
    cudnnDataType_t                *dataType,
    cudnnTensorFormat_t            *format,
    int                            *k,
    int                            *c,
    int                            *h,
    int                            *w)
```
This function queries a previously initialized filter descriptor object.

**Parameters**

**wDesc**
- *Input*. Handle to a previously initialized filter descriptor.

**nbDimsRequested**
- *Input*. Dimension of the expected filter descriptor. It is also the minimum size of the arrays `filterDimA` in order to be able to hold the results.

**datatype**
- *Output*. Data type.

**format**
- *Output*. Type of format.

**nbDims**
- *Output*. Actual dimension of the filter.

**filterDimA**
- *Output*. Array of dimension of at least `nbDimsRequested` that will be filled with the filter parameters from the provided filter descriptor.

**Returns**

- **CUDNN_STATUS_SUCCESS**
  - The object was set successfully.

- **CUDNN_STATUS_BAD_PARAM**
  - The parameter `nbDimsRequested` is negative.

### 3.2.47. cudnnGetFilterSizeInBytes()

```c
typedef cudnnclass status_t;
cudnnStatus_t cudnnGetFilterSizeInBytes(const cudnnFilterDescriptor_t filterDesc, size_t *size);
```

This function returns the size of the filter tensor in memory with respect to the given descriptor. It can be used to know the amount of GPU memory to be allocated to hold that filter tensor.

**Parameters**

**filterDesc**
- *Input*. handle to a previously initialized filter descriptor.
size

*Output.* size in bytes needed to hold the tensor in GPU memory.

**Returns**

**CUDNN_STATUS_SUCCESS**

FilterDesc is valid.

**CUDNN_STATUS_BAD_PARAM**

FilterDesc is invalid.

### 3.2.48. `cudnnGetLRNDescriptor()`

```c
void cudnnGetLRNDescriptor(  
    cudnnLRNDescriptor_t normDesc,  
    unsigned *lrnN,  
    double *lrnAlpha,  
    double *lrnBeta,  
    double *lrnK)
```

This function retrieves values stored in the previously initialized LRN descriptor object.

**Parameters**

**normDesc**

*Output.* Handle to a previously created LRN descriptor.

**lrnN, lrnAlpha, lrnBeta, lrnK**

*Output.* Pointers to receive values of parameters stored in the descriptor object. See `cudnnSetLRNDescriptor()` for more details. Any of these pointers can be `NULL` (no value is returned for the corresponding parameter).

**Returns**

**CUDNN_STATUS_SUCCESS**

Function completed successfully.

### 3.2.49. `cudnnGetOpTensorDescriptor()`

```c
void cudnnGetOpTensorDescriptor(  
    const cudnnOpTensorDescriptor_t opTensorDesc,  
    cudnnOpTensorOp_t *opTensorOp,  
    cudnnDataType_t *opTensorCompType,  
    cudnnNanPropagation_t *opTensorNanOpt)
```

This function returns the configuration of the passed tensor pointwise math descriptor.
Parameters

\textbf{opTensorDesc}

\textit{Input}. Tensor pointwise math descriptor passed to get the configuration from.

\textbf{opTensorOp}

\textit{Output}. Pointer to the tensor pointwise math operation type, associated with this tensor pointwise math descriptor.

\textbf{opTensorCompType}

\textit{Output}. Pointer to the cuDNN data-type associated with this tensor pointwise math descriptor.

\textbf{opTensorNanOpt}

\textit{Output}. Pointer to the NAN propagation option associated with this tensor pointwise math descriptor.

Returns

\textbf{CUDNN\_STATUS\_SUCCESS}

The function returned successfully.

\textbf{CUDNN\_STATUS\_BAD\_PARAM}

Input tensor pointwise math descriptor passed is invalid.

3.2.50. \texttt{cudnnGetPooling2dDescriptor()}

\begin{verbatim}
  cudnnStatus_t cudnnGetPooling2dDescriptor(
      const cudnnPoolingDescriptor_t          poolingDesc,
      cudnnPoolingMode_t                     *mode,
      cudnnNanPropagation_t                 *maxpoolingNanOpt,
      int                                    *windowHeight,
      int                                    *windowWidth,
      int                                    *verticalPadding,
      int                                    *horizontalPadding,
      int                                    *verticalStride,
      int                                    *horizontalStride)
  
This function queries a previously created 2D pooling descriptor object.

Parameters

\textbf{poolingDesc}

\textit{Input}. Handle to a previously created pooling descriptor.

\textbf{mode}

\textit{Output}. Enumerant to specify the pooling mode.

\textbf{maxpoolingNanOpt}

\textit{Output}. Enumerant to specify the Nan propagation mode.
windowHeight
   Output. Height of the pooling window.

windowWidth
   Output. Width of the pooling window.

verticalPadding
   Output. Size of vertical padding.

horizontalPadding
   Output. Size of horizontal padding.

verticalStride
   Output. Pooling vertical stride.

horizontalStride
   Output. Pooling horizontal stride.

Returns

CUDNN_STATUS_SUCCESS
   The object was set successfully.

3.2.51. cudnnGetPooling2dForwardOutputDim()
cudnnStatus_t cudnnGetPooling2dForwardOutputDim(
   const cudnnPoolingDescriptor_t poolingDesc,
   const cudnnTensorDescriptor_t inputDesc,
   int *outN,
   int *outC,
   int *outH,
   int *outW)

This function provides the output dimensions of a tensor after 2d pooling has been applied. Each dimension \( h \) and \( w \) of the output images is computed as follows:

\[
\text{outputDim} = 1 + \frac{(\text{inputDim} + 2\text{padding} - \text{windowDim})}{\text{poolingStride}};
\]

Parameters

poolingDesc
   Input. Handle to a previously initialized pooling descriptor.

inputDesc
   Input. Handle to the previously initialized input tensor descriptor.

N
   Output. Number of images in the output.
C

Output. Number of channels in the output.

H

Output. Height of images in the output.

W

Output. Width of images in the output.

Returns

CUDNN_STATUS_SUCCESS

The function launched successfully.

CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- poolingDesc has not been initialized.
- poolingDesc or inputDesc has an invalid number of dimensions (2 and 4 respectively are required).

3.2.52. cudnnGetPoolingNdDescriptor()

cudnnStatus_t cudnnGetPoolingNdDescriptor(
    const cudnnPoolingDescriptor_t poolingDesc,
    int nbDimsRequested,
    cudnnPoolingMode_t *mode,
    cudnnNanPropagation_t *maxpoolingNanOpt,
    int *nbDims,
    int *windowDimA[],
    int *paddingA[],
    int *strideA[])

This function queries a previously initialized generic pooling descriptor object.

Parameters

poolingDesc

Input. Handle to a previously created pooling descriptor.

nbDimsRequested

Input. Dimension of the expected pooling descriptor. It is also the minimum size of the arrays windowDimA, paddingA, and strideA in order to be able to hold the results.

mode

Output. Enumerant to specify the pooling mode.

maxpoolingNanOpt

Input. Enumerant to specify the Nan propagation mode.
nbDims

*Output.* Actual dimension of the pooling descriptor.

windowDimA

*Output.* Array of dimension of at least nbDimsRequested that will be filled with the window parameters from the provided pooling descriptor.

paddingA

*Output.* Array of dimension of at least nbDimsRequested that will be filled with the padding parameters from the provided pooling descriptor.

strideA

*Output.* Array of dimension at least nbDimsRequested that will be filled with the stride parameters from the provided pooling descriptor.

Returns

**CUDNN_STATUS_SUCCESS**

The object was queried successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The parameter nbDimsRequested is greater than CUDNN_DIM_MAX.

### 3.2.53. cudnnGetPoolingNdForwardOutputDim()

```c
const cudnnPoolingDescriptor_t poolingDesc,
const cudnnTensorDescriptor_t inputDesc,
int nbDims,
int outDimA[])
```

This function provides the output dimensions of a tensor after Nd pooling has been applied. Each dimension of the \((nbDims-2)\)-D images of the output tensor is computed as follows:

```plaintext
outputDim = 1 + (inputDim + 2*padding - windowDim)/poolingStride;
```

Parameters

poolingDesc

*Input.* Handle to a previously initialized pooling descriptor.

inputDesc

*Input.* Handle to the previously initialized input tensor descriptor.

nbDims

*Input.* Number of dimensions in which pooling is to be applied.

outDimA

*Output.* Array of nbDims output dimensions.
Returns

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- poolingDesc has not been initialized.
- The value of nbDims is inconsistent with the dimensionality of poolingDesc and inputDesc.

### 3.2.54. **`cudnnGetProperty()`**

```c
void cudnnGetProperty(     
    libraryPropertyType     type,     
    int                    *value)
```

This function writes a specific part of the cuDNN library version number into the provided host storage.

#### Parameters

**type**

*Input*. Enumerant type that instructs the function to report the numerical value of the cuDNN major version, minor version, or the patch level.

**value**

*Output*. Host pointer where the version information should be written.

#### Returns

**CUDNN_STATUS_INVALID_VALUE**

Invalid value of the `type` argument.

**CUDNN_STATUS_SUCCESS**

Version information was stored successfully at the provided address.

### 3.2.55. **`cudnnGetReduceTensorDescriptor()`**

```c
void cudnnGetReduceTensorDescriptor(     
    const cudnnReduceTensorDescriptor_t reduceTensorDesc,     
    cudnnReduceTensorOp_t          *reduceTensorOp,     
    cudnnDataType_t               *reduceTensorCompType,     
    cudnnNanPropagation_t         *reduceTensorNanOpt,     
    cudnnReduceTensorIndices_t    *reduceTensorIndices,     
    cudnnIndicesType_t            *reduceTensorIndicesType)
```

This function queries a previously initialized reduce tensor descriptor object.
Parameters

reduceTensorDesc
  Input. Pointer to a previously initialized reduce tensor descriptor object.

reduceTensorOp
  Output. Enumerant to specify the reduce tensor operation.

reduceTensorCompType
  Output. Enumerant to specify the computation datatype of the reduction.

reduceTensorNanOpt
  Input. Enumerant to specify the Nan propagation mode.

reduceTensorIndices
  Output. Enumerant to specify the reduced tensor indices.

reduceTensorIndicesType
  Output. Enumerant to specify the reduce tensor indices type.

Returns

CU_DNN_STATUS_SUCCESS
  The object was queried successfully.

CU_DNN_STATUS_BAD_PARAM
  reduceTensorDesc is NULL.

3.2.56. cudnnGetReductionIndicesSize()

cudnnStatus_t cudnnGetReductionIndicesSize(
  cudnnHandle_t handle,
  const cudnnReduceTensorDescriptor_t reduceDesc,
  const cudnnTensorDescriptor_t aDesc,
  const cudnnTensorDescriptor_t cDesc,
  size_t *sizeInBytes)

This is a helper function to return the minimum size of the index space to be passed to the reduction given the input and output tensors.

Parameters

handle
  Input. Handle to a previously created cuDNN library descriptor.

reduceDesc
  Input. Pointer to a previously initialized reduce tensor descriptor object.
aDesc

*Input*. Pointer to the input tensor descriptor.

cDesc

*Input*. Pointer to the output tensor descriptor.

sizeInBytes

*Output*. Minimum size of the index space to be passed to the reduction.

Returns

**CUDNN_STATUS_SUCCESS**

The index space size is returned successfully.

### 3.2.57. cudnnGetReductionWorkspaceSize()

```c

cudnnStatus_t cudnnGetReductionWorkspaceSize(
    cudnnHandle_t                       handle,
    const cudnnReduceTensorDescriptor_t reduceDesc,
    const cudnnTensorDescriptor_t       aDesc,
    const cudnnTensorDescriptor_t       cDesc,
    size_t                              *sizeInBytes)
```

This is a helper function to return the minimum size of the workspace to be passed to the reduction given the input and output tensors.

Parameters

**handle**

*Input*. Handle to a previously created cuDNN library descriptor.

**reduceDesc**

*Input*. Pointer to a previously initialized reduce tensor descriptor object.

**aDesc**

*Input*. Pointer to the input tensor descriptor.

**cDesc**

*Input*. Pointer to the output tensor descriptor.

**sizeInBytes**

*Output*. Minimum size of the index space to be passed to the reduction.

Returns

**CUDNN_STATUS_SUCCESS**

The workspace size is returned successfully.
3.2.58. **cudnnGetStream()**

cudnnStatus_t cudnnGetStream(
    cudnnHandle_t handle,
    cudaStream_t *streamId)

This function retrieves the user CUDA stream programmed in the cuDNN handle. When the user’s CUDA stream is not set in the cuDNN handle, this function reports the null-stream.

**Parameters**

*handle*

*Input*. Pointer to the cuDNN handle.

*streamID*

*Output*. Pointer where the current CUDA stream from the cuDNN handle should be stored.

**Returns**

**CUDNN_STATUS_BAD_PARAM**

Invalid (NULL) handle.

**CUDNN_STATUS_SUCCESS**

The stream identifier was retrieved successfully.

3.2.59. **cudnnGetTensor4dDescriptor()**

cudnnStatus_t cudnnGetTensor4dDescriptor(
    const cudnnTensorDescriptor_t tensorDesc,
    cudnnDataType_t *dataType,
    int *n,
    int *c,
    int *h,
    int *w,
    int *nStride,
    int *cStride,
    int *hStride,
    int *wStride)

This function queries the parameters of the previously initialized tensor4D descriptor object.

**Parameters**

*tensorDesc*

*Input*. Handle to a previously initialized tensor descriptor.

*datatype*

*Output*. Data type.

*n*

*Output*. Number of images.
c

*Output*. Number of feature maps per image.

h

*Output*. Height of each feature map.

w

*Output*. Width of each feature map.

nStride

*Output*. Stride between two consecutive images.

cStride

*Output*. Stride between two consecutive feature maps.

hStride

*Output*. Stride between two consecutive rows.

wStride

*Output*. Stride between two consecutive columns.

Returns

**CUDNN_STATUS_SUCCESS**

The operation succeeded.

### 3.2.60. `cudnnGetTensorNdDescriptor()`

cudnnStatus_t cudnnGetTensorNdDescriptor(
    const cudnnTensorDescriptor_t   tensorDesc,
    int                             nbDimsRequested,
    cudnnDataType_t                *dataType,
    int                             nbDims,
    int                             dimA[],
    int                             strideA[])

This function retrieves values stored in a previously initialized tensor descriptor object.

Parameters

tensorDesc

*Input*. Handle to a previously initialized tensor descriptor.

nbDimsRequested

*Input*. Number of dimensions to extract from a given tensor descriptor. It is also the minimum size of the arrays dimA and strideA. If this number is greater than the resulting nbDims[0], only nbDims[0] dimensions will be returned.

datatype

*Output*. Data type.
nbDims

*Output.* Actual number of dimensions of the tensor will be returned in nbDims[0].

dimA

*Output.* Array of dimensions of at least nbDimsRequested that will be filled with the
dimensions from the provided tensor descriptor.

strideA

*Input.* Array of dimension of at least nbDimsRequested that will be filled with the strides
from the provided tensor descriptor.

Returns

**CUDNN_STATUS_SUCCESS**

The results were returned successfully.

**CUDNN_STATUS_BAD_PARAM**

Either tensorDesc or nbDims pointer is NULL.

### 3.2.61. *cudnnGetTensorSizeInBytes()*

```c
const cudnnTensorDescriptor_t   tensorDesc,
size_t                         *size)
```

This function returns the size of the tensor in memory in respect to the given descriptor. This
function can be used to know the amount of GPU memory to be allocated to hold that tensor.

Parameters

tensorDesc

*Input.* Handle to a previously initialized tensor descriptor.

size

*Output.* Size in bytes needed to hold the tensor in GPU memory.

Returns

**CUDNN_STATUS_SUCCESS**

The results were returned successfully.

### 3.2.62. *cudnnGetTensorTransformDescriptor()*

```c

cudnnStatus_t cudnnGetTensorTransformDescriptor(
cudnnTensorTransformDescriptor_t transformDesc,
uint32_t nbDimsRequested,
cudnnTensorFormat_t *destFormat,
int32_t padBeforeA[],
int32_t padAfterA[],
uint32_t foldA[],
```
This function returns the values stored in a previously initialized tensor transform descriptor.

**Parameters**

- **transformDesc**
  - *Input*. A previously initialized tensor transform descriptor.

- **nbDimsRequested**
  - *Input*. The number of dimensions to consider. For more information, see the [Tensor Descriptor](https://developer.nvidia.com/cudnn) section in the *cuDNN Developer Guide*.

- **destFormat**
  - *Output*. The transform format that will be returned.

- **padBeforeA[]**
  - *Output*. An array filled with the amount of padding to add before each dimension. The dimension of this `padBeforeA[]` parameter is equal to `nbDimsRequested`.

- **padAfterA[]**
  - *Output*. An array filled with the amount of padding to add after each dimension. The dimension of this `padBeforeA[]` parameter is equal to `nbDimsRequested`.

- **foldA[]**
  - *Output*. An array that was filled with the folding parameters for each spatial dimension. The dimension of this `foldA[]` array is `nbDimsRequested-2`.

- **direction**
  - *Output*. The setting that selects folding or unfolding. For more information, see [cudnnFoldingDirection_t](https://developer.nvidia.com/cudnn).

**Returns**

- **CUDNN_STATUS_SUCCESS**
  - The results were obtained successfully.

- **CUDNN_STATUS_BAD_PARAM**
  - If `transformDesc` is `NULL` or if `nbDimsRequested` is less than 3 or greater than `CUDNN_DIM_MAX`.

### 3.2.63. cudnnGetVersion()

```c
size_t cudnnGetVersion()
```

This function returns the version number of the cuDNN library. It returns the `CUDNN_VERSION` defined present in the `cudnn.h` header file. Starting with release R2, the routine can be used to identify dynamically the current cuDNN library used by the application. The defined `CUDNN_VERSION` can be used to have the same application linked against different cuDNN versions using conditional compilation statements.

### 3.2.64. cudnnInitTransformDest()

```c
cudnnStatus_t cudnnInitTransformDest(
    const cudnnTensorTransformDescriptor_t transformDesc,
    const cudnnTensorDescriptor_t srcDesc,
    ...)  
```
cudnnTensorDescriptor_t destDesc,
size_t *destSizeInBytes);

This function initializes and returns a destination tensor descriptor destDesc for tensor transform operations. The initialization is done with the desired parameters described in the transform descriptor cudnnTensorDescriptor_t.

Note: The returned tensor descriptor will be packed.

Parameters

transformDesc
   Input. Handle to a previously initialized tensor transform descriptor.

srcDesc
   Input. Handle to a previously initialized tensor descriptor.

destDesc
   Output. Handle of the tensor descriptor that will be initialized and returned.

destSizeInBytes
   Output. A pointer to hold the size, in bytes, of the new tensor.

Returns

CUDNN_STATUS_SUCCESS
   The tensor descriptor was initialized successfully.

CUDNN_STATUS_BAD_PARAM
   If either srcDesc or destDesc is NULL, or if the tensor descriptor’s nbDims is incorrect. For more information, see the Tensor Descriptor section in the cuDNN Developer Guide.

CUDNN_STATUS_NOT_SUPPORTED
   If the provided configuration is not 4D.

CUDNN_STATUS_EXECUTION_FAILED
   Function failed to launch on the GPU.

3.2.65. cudnnLRNCrossChannelForward()

cudnnStatus_t cudnnLRNCrossChannelForward(
    cudnnHandle_t                     handle,
    cudnnLRNDescriptor_t             normDesc,
    cudnnLRNMode_t                   lrnMode,
    const void                      *alpha,
    const cudnnTensorDescriptor_t    xDesc,
    const void                      *x,
    const void                      *beta,
    const cudnnTensorDescriptor_t    yDesc,
    void                            *y)

This function performs the forward LRN layer computation.

Note: Supported formats are: positive-strided, NCHW and NHWC for 4D x and y, and only NCDHW DHW-packed for 5D (for both x and y). Only non-overlapping 4D and 5D tensors are supported. NCHW layout is preferred for performance.
Parameters

**handle**

*Input*. Handle to a previously created cuDNN library descriptor.

**normDesc**

*Input*. Handle to a previously initialized LRN parameter descriptor.

**lrnMode**

*Input*. LRN layer mode of operation. Currently only CUDNN_LRN_CROSS_CHANNEL_DIM1 is implemented. Normalization is performed along the tensor’s dimA[1].

**alpha, beta**

*Input*. Pointers to scaling factors (in host memory) used to blend the layer output value with prior value in the destination tensor as follows:

\[
\text{dstValue} = \alpha[0] \times \text{resultValue} + \beta[0] \times \text{priorDstValue}
\]

For more information, see Scaling Parameters in the cuDNN Developer Guide.

**xDesc, yDesc**

*Input*. Tensor descriptor objects for the input and output tensors.

**x**

*Input*. Input tensor data pointer in device memory.

**y**

*Output*. Output tensor data pointer in device memory.

Returns

**CUDNN_STATUS_SUCCESS**

The computation was performed successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- One of the tensor pointers x, y is NULL.
- Number of input tensor dimensions is 2 or less.
- LRN descriptor parameters are outside of their valid ranges.
- One of the tensor parameters is 5D but is not in NCDHW DHW-packed format.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration. See the following for some examples of non-supported configurations:

- Any of the input tensor datatypes is not the same as any of the output tensor datatype.
- x and y tensor dimensions mismatch.
ANY TENSOR PARAMETERS STRIDES ARE NEGATIVE.

### 3.2.66. `cudnnNormalizationForwardInference()`

cudnnStatus_t

cudnnNormalizationForwardInference(cudnnHandle_t handle,
cudnnNormMode_t mode,
cudnnNormOps_t normOps,
cudnnNormAlgo_t algo,
const void *alpha,
const void *beta,
const cudnnTensorDescriptor_t xDesc,
const void *x,
const cudnnTensorDescriptor_t normScaleBiasDesc,
const void *normScale,
const void *normBias,
const cudnnTensorDescriptor_t normMeanVarDesc,
const void *estimatedMean,
const void *estimatedVariance,
const cudnnTensorDescriptor_t zDesc,
const void *z,
const cudnnActivationDescriptor_t activationDesc,
const cudnnTensorDescriptor_t yDesc,
void *y,
double epsilon,
int groupCnt);

This function performs the forward normalization layer computation for the inference phase. Per-channel normalization layer is based on the paper *Batch Normalization: Accelerating Deep Network Training by Reducing Internal Covariate Shift*, S. Ioffe, C. Szegedy, 2015.

**Note:**

- Only 4D and 5D tensors are supported.
- The input transformation performed by this function is defined as:
  
  \[ y = \beta y + \alpha \left[ \text{normBias} + \left( \text{normScale} \times \frac{x - \text{estimatedMean}}{\sqrt{\epsilon + \text{estimatedVariance}}} \right) \right] \]

- The `epsilon` value has to be the same during training, backpropagation, and inference.
- For the training phase, use `cudnnNormalizationForwardTraining()`.
- Higher performance can be obtained when HW-packed tensors are used for all of `x` and `y`.

**Parameters**

**handle**

*Input*. Handle to a previously created cuDNN library descriptor. For more information, see `cudnnHandle_t`.

**mode**

*Input*. Mode of operation (per-channel or per-activation). For more information, see `cudnnNormMode_t`.

**normOps**

*Input*. Mode of post-operative. Currently, CUDNN_NORM_OPS_NORM_ACTIVATION and CUDNN_NORM_OPS_NORM_ADD_ACTIVATION are not supported.
algo

*Input. Algorithm to be performed. For more information, see cudnnNormAlgo_t.*

alpha, beta

*Inputs. Pointers to scaling factors [in host memory] used to blend the layer output value with prior value in the destination tensor as follows:

\[ \text{dstValue} = \text{alpha}[0]*\text{resultValue} + \text{beta}[0]*\text{priorDstValue} \]

For more information, see Scaling Parameters in the cuDNN Developer Guide.

xDesc, yDesc

*Input. Handles to the previously initialized tensor descriptors.

*x

*Input. Data pointer to GPU memory associated with the tensor descriptor xDesc, for the layer’s x input data.

*y

*Output. Data pointer to GPU memory associated with the tensor descriptor yDesc, for the y output of the normalization layer.

zDesc, *z

*Input. Tensor descriptors and pointers in device memory for residual addition to the result of the normalization operation, prior to the activation. zDesc and *z are optional and are only used when normOps is CUDNN_NORM_OPS_NORM_ADD_ACTIVATION, otherwise users may pass NULL. When in use, z should have exactly the same dimension as x and the final output y. For more information, see cudnnTensorDescriptor_t.

Since normOps is only supported for CUDNN_NORM_OPS_NORM, we can set these to NULL for now.

normScaleBiasDesc, normScale, normBias

*Inputs. Tensor descriptors and pointers in device memory for the normalization scale and bias parameters [in the original paper bias is referred to as beta and scale as gamma].

normMeanVarDesc, estimatedMean, estimatedVariance

*Inputs. Mean and variance tensors and their tensor descriptors. The estimatedMean and estimatedVariance inputs, accumulated during the training phase from the cudnnNormalizationForwardTraining call, should be passed as inputs here.

activationDesc

*Input. Descriptor for the activation operation. When the normOps input is set to either CUDNN_NORM_OPS_NORM_ACTIVATION or CUDNN_NORM_OPS_NORM_ADD_ACTIVATION then this activation is used, otherwise the user may pass NULL. Since normOps is only supported for CUDNN_NORM_OPS_NORM, we can set these to NULL for now.
epsilon

*Input.* Epsilon value used in the normalization formula. Its value should be equal to or greater than zero.

**groutCnt**

*Input.* Only support 1 for now.

**Returns**

**CUDNN_STATUS_SUCCESS**

The computation was performed successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- One of the pointers alpha, beta, x, y, normScale, normBias, estimatedMean, and estimatedInvVariance is NULL.
- The number of xDesc or yDesc tensor descriptor dimensions is not within the range of [4,5] (only 4D and 5D tensors are supported).
- normScaleBiasDesc and normMeanVarDesc dimensions are not 1xCx1x1 for 4D and 1xCx1x1x1 for 5D for per-channel, and are not 1xCxHxW for 4D and 1xCxDxHxW for 5D for per-activation mode.
- epsilon value is less than zero.
- Dimensions or data types mismatch for xDesc and yDesc.

**CUDNN_STATUS_NOT_SUPPORTED**

A compute or data type other than FLOAT was chosen, or an unknown algorithm type was chosen.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

### 3.2.67. cudnnOpsInferVersionCheck()

cudnnStatus_t cudnnOpsInferVersionCheck(void)

This function is the first of a series of corresponding functions that check for consistent library versions among DLL files for different modules.

**Returns**

**CUDNN_STATUS_SUCCESS**

The version of this DLL file is consistent with cuDNN DLLs on which it depends.
CUDNN_STATUS_VERSION_MISMATCH

The version of this DLL file does not match that of a cuDNN DLLs on which it depends.

3.2.68. cudnnOpTensor()

cudnnStatus_t cudnnOpTensor(
    cudnnHandle_t handle,
    const cudnnOpTensorDescriptor_t opTensorDesc,
    const void *alpha1,
    const cudnnTensorDescriptor_t aDesc,
    const void *A,
    const void *alpha2,
    const cudnnTensorDescriptor_t bDesc,
    const void *B,
    const void *beta,
    const cudnnTensorDescriptor_t cDesc,
    void *C)

This function implements the equation $C = \text{op}(\text{alpha1}[0] \cdot A, \text{alpha2}[0] \cdot B) + \text{beta}[0] \cdot C$, given the tensors $A$, $B$, and $C$ and the scaling factors $\text{alpha1}$, $\text{alpha2}$, and $\text{beta}$. The op to use is indicated by the descriptor cudnnOpTensorDescriptor_t, meaning, the type of opTensorDesc. Currently-supported ops are listed by the cudnnOpTensorOp_t enum.

The following restrictions on the input and destination tensors apply:

- Each dimension of the input tensor $A$ must match the corresponding dimension of the destination tensor $C$, and each dimension of the input tensor $B$ must match the corresponding dimension of the destination tensor $C$ or must be equal to 1. In the latter case, the same value from the input tensor $B$ for those dimensions will be used to blend into the $C$ tensor.

- The data types of the input tensors $A$ and $B$, and the destination tensor $C$, must satisfy Table 6.

Table 6. Supported Datatypes

<table>
<thead>
<tr>
<th>opTensorCompType in opTensorDesc</th>
<th>A</th>
<th>B</th>
<th>C (destination)</th>
</tr>
</thead>
<tbody>
<tr>
<td>FLOAT</td>
<td>FLOAT</td>
<td>FLOAT</td>
<td>FLOAT</td>
</tr>
<tr>
<td>FLOAT</td>
<td>INT8</td>
<td>INT8</td>
<td>FLOAT</td>
</tr>
<tr>
<td>FLOAT</td>
<td>HALF</td>
<td>HALF</td>
<td>FLOAT</td>
</tr>
<tr>
<td>DOUBLE</td>
<td>DOUBLE</td>
<td>DOUBLE</td>
<td>DOUBLE</td>
</tr>
<tr>
<td>FLOAT</td>
<td>FLOAT</td>
<td>FLOAT</td>
<td>FLOAT</td>
</tr>
<tr>
<td>FLOAT</td>
<td>HALF</td>
<td>HALF</td>
<td>HALF</td>
</tr>
<tr>
<td>FLOAT</td>
<td>INT8</td>
<td>INT8</td>
<td>INT8</td>
</tr>
<tr>
<td>FLOAT</td>
<td>FLOAT</td>
<td>FLOAT</td>
<td>INT8</td>
</tr>
</tbody>
</table>

Note: All tensor formats up to dimension five (5) are supported. This routine does not support tensor formats beyond these dimensions.
Parameters

handle

*Input.* Handle to a previously created cuDNN context.

opTensorDesc

*Input.* Handle to a previously initialized op tensor descriptor.

alpha1, alpha2, beta

*Input.* Pointers to scaling factors (in host memory) used to blend the source value with prior value in the destination tensor as follows:

\[
\text{dstValue} = \text{alpha}[0] \ast \text{resultValue} + \text{beta}[0] \ast \text{priorDstValue}
\]

For more information, see *Scaling Parameters* in the *cuDNN Developer Guide*.

aDesc, bDesc, cDesc

*Input.* Handle to a previously initialized tensor descriptor.

A, B

*Input.* Pointer to data of the tensors described by the aDesc and bDesc descriptors, respectively.

C

*Input/Output.* Pointer to data of the tensor described by the cDesc descriptor.

Returns

**CUDNN_STATUS_SUCCESS**

The function executed successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration. See the following for some examples of non-supported configurations:

- The dimensions of the bias tensor and the output tensor dimensions are above 5.
- opTensorCompType is not set as stated above.

**CUDNN_STATUS_BAD_PARAM**

The data type of the destination tensor C is unrecognized, or the restrictions on the input and destination tensors, stated above, are not met.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

### 3.2.69. cudnnPoolingForward()

cudnnStatus_t cudnnPoolingForward(
    cudnnHandle_t            handle,
    ...)
This function computes pooling of input values (meaning, the maximum or average of several adjacent values) to produce an output with smaller height and/or width.

**Note:**

- All tensor formats are supported, best performance is expected when using HW-packed tensors. Only 2 and 3 spatial dimensions are allowed.
- The dimensions of the output tensor $y_{Desc}$ can be smaller or bigger than the dimensions advised by the routine `cudnnGetPooling2dForwardOutputDim()` or `cudnnGetPoolingNdForwardOutputDim()`.

**Parameters**

**handle**

*Input.* Handle to a previously created cuDNN context.

**poolingDesc**

*Input.* Handle to a previously initialized pooling descriptor.

**alpha, beta**

*Input.* Pointers to scaling factors (in host memory) used to blend the computation result with prior value in the output layer as follows:

$$dstValue = alpha[0]*resultValue + beta[0]*priorDstValue$$

For more information, see [Scaling Parameters](https://developer.nvidia.com/cudnn) in the cuDNN Developer Guide.

**xDesc**

*Input.* Handle to the previously initialized input tensor descriptor. Must be of type `FLOAT`, `DOUBLE`, `HALF` or `INT8`. For more information, see `cudnnDataType_t`.

**x**

*Input.* Data pointer to GPU memory associated with the tensor descriptor xDesc.

**yDesc**

*Input.* Handle to the previously initialized output tensor descriptor. Must be of type `FLOAT`, `DOUBLE`, `HALF` or `INT8`. For more information, see `cudnnDataType_t`.

**y**

*Output.* Data pointer to GPU memory associated with the output tensor descriptor yDesc.
Returns

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The dimensions \( n \), \( c \) of the input tensor and output tensors differ.
- The data type of the input tensor and output tensors differs.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

### 3.2.70. `cudnnQueryRuntimeError()`

```c
#include <cudnn.h>

cudnnStatus_t cudnnQueryRuntimeError(
    cudnnHandle_t            handle,
    cudnnStatus_t           *rstatus,
    cudnnErrQueryMode_t      mode,
    cudnnRuntimeTag_t       *tag)
```

CuDNN library functions perform extensive input argument checking before launching GPU kernels. The last step is to verify that the GPU kernel actually started. When a kernel fails to start, **CUDNN_STATUS_EXECUTION_FAILED** is returned by the corresponding API call. Typically, after a GPU kernel starts, no runtime checks are performed by the kernel itself - numerical results are simply written to output buffers.

When the **CUDNN_BATCHNORM_SPATIAL_PERSISTENT** mode is selected in `cudnnBatchNormalizationForwardTraining()` or `cudnnBatchNormalizationBackward()`, the algorithm may encounter numerical overflows where **CUDNN_BATCHNORM_SPATIAL** performs just fine albeit at a slower speed. The user can invoke `cudnnQueryRuntimeError()` to make sure numerical overflows did not occur during the kernel execution. Those issues are reported by the kernel that performs computations.

`cudnnQueryRuntimeError()` can be used in polling and blocking software control flows. There are two polling modes (**CUDNN_ERRQUERY_RAWCODE** and **CUDNN_ERRQUERY_NONBLOCKING**) and one blocking mode **CUDNN_ERRQUERY_BLOCKING**.

**CUDNN_ERRQUERY_RAWCODE** reads the error storage location regardless of the kernel completion status. The kernel might not even start and the error storage (allocated per cuDNN handle) might be used by an earlier call.

**CUDNN_ERRQUERY_NONBLOCKING** checks if all tasks in the user stream are completed. The `cudnnQueryRuntimeError()` function will return immediately and report **CUDNN_STATUS_RUNTIME_IN_PROGRESS** in `rstatus` if some tasks in the user stream are pending. Otherwise, the function will copy the remote kernel error code to `rstatus`. 
In the blocking mode (CUDNN_ERRQUERY_BLOCKING), the function waits for all tasks to drain in the user stream before reporting the remote kernel error code. The blocking flavor can be further adjusted by calling cudaSetDeviceFlags with the cudaDeviceScheduleSpin, cudaDeviceScheduleYield, or cudaDeviceScheduleBlockingSync flag.

CUDNN_ERRQUERY_NONBLOCKING and CUDNN_ERRQUERY_BLOCKING modes should not be used when the user stream is changed in the cuDNN handle, meaning, cudnnSetStream() is invoked between functions that report runtime kernel errors and the cudnnQueryRuntimeError() function.

The remote error status reported in rstatus can be set to: CUDNN_STATUS_SUCCESS, CUDNN_STATUS_RUNTIME_IN_PROGRESS, or CUDNN_STATUS_RUNTIME_FP_OVERFLOW. The remote kernel error is automatically cleared by cudnnQueryRuntimeError().

Note: The cudnnQueryRuntimeError() function should be used in conjunction with cudnnBatchNormalizationForwardTraining() and cudnnBatchNormalizationBackward() when the cudnnBatchNormMode_t argument is CUDNN_BATCHNORM_SPATIAL_PERSISTENT.

Parameters

handle

  Input. Handle to a previously created cuDNN context.

rstatus

  Output. Pointer to the user’s error code storage.

mode

  Input. Remote error query mode.

tag

  Input/Output. Currently, this argument should be NULL.

Returns

CUDNN_STATUS_SUCCESS

  No errors detected (rstatus holds a valid value).

CUDNN_STATUS_BAD_PARAM

  Invalid input argument.

CUDNN_STATUS_INTERNAL_ERROR

  A stream blocking synchronization or a non-blocking stream query failed.

CUDNN_STATUS_MAPPING_ERROR

  The device cannot access zero-copy memory to report kernel errors.

3.2.71. cudnnReduceTensor() 

cudnnStatus_t cudnnReduceTensor()

cuDNN API Reference
This function reduces tensor \( A \) by implementing the equation \( C = \alpha \times \text{reduce op} (A) + \beta \times C \), given tensors \( A \) and \( C \) and scaling factors \( \alpha \) and \( \beta \). The reduction op to use is indicated by the descriptor \( \text{reduceTensorDesc} \). Currently-supported ops are listed by the \( \text{cudnnReduceTensorOp_t} \) enum.

Each dimension of the output tensor \( C \) must match the corresponding dimension of the input tensor \( A \) or must be equal to 1. The dimensions equal to 1 indicate the dimensions of \( A \) to be reduced.

The implementation will generate indices for the min and max ops only, as indicated by the \( \text{cudnnReduceTensorIndices_t} \) enum of the \( \text{reduceTensorDesc} \). Requesting indices for the other reduction ops results in an error. The data type of the indices is indicated by the \( \text{cudnnIndicesType_t} \) enum; currently only the 32-bit (unsigned int) type is supported.

The indices returned by the implementation are not absolute indices but relative to the dimensions being reduced. The indices are also flattened, meaning, not coordinate tuples.

The data types of the tensors \( A \) and \( C \) must match if of type double. In this case, \( \alpha \) and \( \beta \) and the computation enum of \( \text{reduceTensorDesc} \) are all assumed to be of type double.

The \( \text{HALF} \) and \( \text{INT8} \) data types may be mixed with the \( \text{FLOAT} \) data types. In these cases, the computation enum of \( \text{reduceTensorDesc} \) is required to be of type \( \text{FLOAT} \).

Note:
Up to dimension 8, all tensor formats are supported. Beyond those dimensions, this routine is not supported.

Parameters

\( \text{handle} \)

Input. Handle to a previously created cuDNN context.

\( \text{reduceTensorDesc} \)

Input. Handle to a previously initialized reduce tensor descriptor.

\( \text{indices} \)

Output. Handle to a previously allocated space for writing indices.

\( \text{indicesSizeInBytes} \)

Input. Size of the above previously allocated space.
workspace

*Input.* Handle to a previously allocated space for the reduction implementation.

workspaceSizeInBytes

*Input.* Size of the above previously allocated space.

alpha, beta

*Input.* Pointers to scaling factors [in host memory] used to blend the source value with prior value in the destination tensor as follows:

\[
\text{dstValue} = \alpha[0] \times \text{resultValue} + \beta[0] \times \text{priorDstValue}
\]

For more information, see [Scaling Parameters](#) in the cuDNN Developer Guide.

aDesc, cDesc

*Input.* Handle to a previously initialized tensor descriptor.

A

*Input.* Pointer to data of the tensor described by the aDesc descriptor.

C

*Input/Output.* Pointer to data of the tensor described by the cDesc descriptor.

Returns

**CUDNN_STATUS_SUCCESS**

The function executed successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration. See the following for some examples of non-supported configurations:

- The dimensions of the input tensor and the output tensor are above 8.
- reduceTensorCompType is not set as stated above.

**CUDNN_STATUS_BAD_PARAM**

The corresponding dimensions of the input and output tensors all match, or the conditions in the above paragraphs are unmet.

**CUDNN_INVALID_VALUE**

The allocations for the indices or workspace are insufficient.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

### 3.2.72. cudnnRestoreAlgorithm()

This function has been deprecated in cuDNN 8.0.
This function reads algorithm metadata from the host memory space provided by the user in algoSpace, allowing the user to use the results of RNN finds from previous cuDNN sessions.

Parameters

**handle**

*Input.* Handle to a previously created cuDNN context.

**algoDesc**

*Input.* A previously created algorithm descriptor.

**algoSpace**

*Input.* Pointer to the host memory to be read.

**algoSpaceSizeInBytes**

*Input.* Amount of host memory needed as a workspace to be able to hold the metadata from the specified algoDesc.

Returns

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The metadata is from a different cuDNN version.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions is met:

- One of the arguments is NULL.
- The metadata is corrupted.

### 3.2.73. cudnnRestoreDropoutDescriptor()

cudnnStatus_t cudnnRestoreDropoutDescriptor(
    cudnnDropoutDescriptor_t dropoutDesc,
    cudnnHandle_t handle,
    float dropout,
    void *states,
    size_t stateSizeInBytes,
    unsigned long long seed)

This function restores a dropout descriptor to a previously saved-off state.
Parameters

**dropoutDesc**

*Input/Output.* Previously created dropout descriptor.

**handle**

*Input.* Handle to a previously created cuDNN context.

**dropout**

*Input.* Probability with which the value from an input tensor is set to 0 when performing dropout.

**states**

*Input.* Pointer to GPU memory that holds random number generator states initialized by a prior call to **cudnnSetDropoutDescriptor**.

**stateSizeInBytes**

*Input.* Size in bytes of buffer holding random number generator states.

**seed**

*Input.* Seed used in prior call to **cudnnSetDropoutDescriptor** that initialized states buffer. Using a different seed from this has no effect. A change of seed, and subsequent update to random number generator states can be achieved by calling **cudnnSetDropoutDescriptor**.

Returns

- **CUDNN_STATUS_SUCCESS**
  The call was successful.
- **CUDNN_STATUS_INVALID_VALUE**
  States buffer size (as indicated in stateSizeInBytes) is too small.

3.2.74. **cudnnSaveAlgorithm()**

This function has been deprecated in cuDNN 8.0.

```c
void cudnnSaveAlgorithm(
    cudnnHandle_t    handle,
    cudnnAlgorithmDescriptor_t algoDesc,
    void*            algoSpace,
    size_t           algoSpaceSizeInBytes)
```

This function writes algorithm metadata into the host memory space provided by the user in algoSpace, allowing the user to preserve the results of RNN finds after cuDNN exits.

Parameters

**handle**

*Input.* Handle to a previously created cuDNN context.
algoDesc

*Input.* A previously created algorithm descriptor.

algoSpace

*Input.* Pointer to the host memory to be written.

algoSpaceSizeInBytes

*Input.* Amount of host memory needed as a workspace to be able to save the metadata from the specified algoDesc.

Returns

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions is met:

- One of the arguments is NULL.
- algoSpaceSizeInBytes is too small.

### 3.2.75. `cudnnScaleTensor()`

```c
void cudnnScaleTensor(
    cudnnHandle_t handle,
    const cudnnTensorDescriptor_t yDesc,
    void *y, 
    const void *alpha)
```

This function scales all the elements of a tensor by a given factor.

Parameters

**handle**

*Input.* Handle to a previously created cuDNN context.

**yDesc**

*Input.* Handle to a previously initialized tensor descriptor.

**y**

*Input/Output.* Pointer to data of the tensor described by the `yDesc` descriptor.

**alpha**

*Input.* Pointer in the host memory to a single value that all elements of the tensor will be scaled with. For more information, see Scaling Parameters in the *cuDNN Developer Guide*. 
Returns

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

One of the provided pointers is nil.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

3.2.76. **cudnnSetActivationDescriptor()**

```c
void cudnnSetActivationDescriptor(
  cudnnActivationDescriptor_t         activationDesc,
  cudnnActivationMode_t               mode,
  cudnnNanPropagation_t               reluNanOpt,
  double                              coef)
```

This function initializes a previously created generic activation descriptor object.

Parameters

**activationDesc**

*Input/Output.* Handle to a previously created pooling descriptor.

**mode**

*Input.* Enumerant to specify the activation mode.

**reluNanOpt**

*Input.* Enumerant to specify the NaN propagation mode.

**coef**

*Input.* Floating point number. When the activation mode (see `cudnnActivationMode_t`) is set to `CUDNN_ACTIVATION_CLIPPED_RELU`, this input specifies the clipping threshold; and when the activation mode is set to `CUDNN_ACTIVATION_RELU`, this input specifies the upper bound.

Returns

**CUDNN_STATUS_SUCCESS**

The object was set successfully.

**CUDNN_STATUS_BAD_PARAM**

`mode` or `reluNanOpt` has an invalid enumerant value.
3.2.77. **cudnnSetAlgorithmDescriptor()**

This function has been deprecated in cuDNN 8.0.

```c
  cudnnStatus_t cudnnSetAlgorithmDescriptor(
    cudnnAlgorithmDescriptor_t      algorithmDesc,
    cudnnAlgorithm_t                algorithm)
```

This function initializes a previously created generic algorithm descriptor object.

**Parameters**

`algorithmDesc`

*Input/Output.* Handle to a previously created algorithm descriptor.

`algorithm`

*Input.* Struct to specify the algorithm.

**Returns**

`CUDNN_STATUS_SUCCESS`

The object was set successfully.

3.2.78. **cudnnSetAlgorithmPerformance()**

This function has been deprecated in cuDNN 8.0.

```c
  cudnnStatus_t cudnnSetAlgorithmPerformance(
    cudnnAlgorithmPerformance_t     algoPerf,
    cudnnAlgorithmDescriptor_t      algoDesc,
    cudnnStatus_t                   status,
    float                          time,
    size_t                         memory)
```

This function initializes a previously created generic algorithm performance object.

**Parameters**

`algoPerf`

*Input/Output.* Handle to a previously created algorithm performance object.

`algoDesc`

*Input.* The algorithm descriptor which the performance results describe.

`status`

*Input.* The cuDNN status returned from running the `algoDesc` algorithm.

`time`

*Input.* The GPU time spent running the `algoDesc` algorithm.
3.2.79. **cudnnSetCallback()**

This function sets the internal states of cuDNN error reporting functionality.

### Parameters

- **mask**
  
  **Input.** An unsigned integer. The four least significant bits (LSBs) of this unsigned integer are used for switching on and off the different levels of error reporting messages. This applies for both the default callbacks, and for the customized callbacks. The bit position is in correspondence with the enum of `cudnnSeverity_t`. The user may utilize the predefined macros `CUDNN_SEV_ERROR_EN`, `CUDNN_SEV_WARNING_EN`, and `CUDNN_SEV_INFO_EN` to form the bit mask. When a bit is set to 1, the corresponding message channel is enabled.

  For example, when bit 3 is set to 1, the API logging is enabled. Currently, only the log output of level `CUDNN_SEV_INFO` is functional; the others are not yet implemented. When used for turning on and off the logging with the default callback, the user may pass `NULL` to `udata` and `fp` in. In addition, the environment variable `CUDNN_LOGDEST_DBG` must be set. For more information, see the [Backward compatibility and deprecation policy](#) section in the *cuDNN Developer Guide*.

  - **CUDNN_SEV_INFO_EN** = 0b1000 (functional).
  - **CUDNN_SEV_ERROR_EN** = 0b0010 (not yet functional).
  - **CUDNN_SEV_WARNING_EN** = 0b0100 (not yet functional).

  The output of `CUDNN_SEV_FATAL` is always enabled and cannot be disabled.

- **udata**
  
  **Input.** A pointer provided by the user. This pointer will be passed to the user’s custom logging callback function. The data it points to will not be read, nor be changed by cuDNN. This pointer may be used in many ways, such as in a mutex or in a communication socket for the user’s callback function for logging. If the user is utilizing the default callback

### Returns

- **CUDNN_STATUS_SUCCESS**
  
  The object was set successfully.

- **CUDNN_STATUS_BAD_PARAM**
  
  `mode` or `reluNanOpt` has an invalid enumerate value.
function, or doesn’t want to use this input in the customized callback function, they may pass in NULL.

\textit{fpstr}

\textit{Input}. A pointer to a user-supplied callback function. When NULL is passed to this pointer, then cuDNN switches back to the built-in default callback function. The user-supplied callback function prototype must be similar to the following (also defined in the header file):

\begin{verbatim}
void customizedLoggingCallback (cudnnSeverity_t sev, void *udata, const cudnnDebug_t *dbg, const char *msg);
\end{verbatim}

\begin{itemize}
  \item The structure \texttt{cudnnDebug\_t} is defined in the header file. It provides the metadata, such as time, time since start, stream ID, process and thread ID, that the user may choose to print or store in their customized callback.
  \item The variable \texttt{msg} is the logging message generated by cuDNN. Each line of this message is terminated by \texttt{\0}, and the end of the message is terminated by \texttt{\0\0}. Users may select what is necessary to show in the log, and may reformat the string.
\end{itemize}

\textbf{Returns}

\texttt{CUDNN\_STATUS\_SUCCESS}

The function launched successfully.

\subsection{3.2.80. \texttt{cudnnSetDropoutDescriptor()}}

\begin{verbatim}
cudnnStatus_t cudnnSetDropoutDescriptor(
    cudnnDropoutDescriptor_t dropoutDesc,
    cudnnHandle_t handle,
    float dropout,
    void *states,
    size_t stateSizeInBytes,
    unsigned long long seed)
\end{verbatim}

This function initializes a previously created dropout descriptor object. If the \texttt{states} argument is equal to \texttt{NULL}, then the random number generator states won’t be initialized, and only the dropout value will be set. No other function should be writing to the memory pointed at by the \texttt{states} argument while this function is running. The user is expected not to change the memory pointed at by \texttt{states} for the duration of the computation.

\textbf{Parameters}

\textbf{dropoutDesc}

\textit{Input/Output}. Previously created dropout descriptor object.

\textbf{handle}

\textit{Input}. Handle to a previously created cuDNN context.

\textbf{dropout}

\textit{Input}. The probability with which the value from input is set to zero during the dropout layer.
states

Output. Pointer to user-allocated GPU memory that will hold random number generator states.

stateSizeInBytes

Input. Specifies the size in bytes of the provided memory for the states.

seed

Input. Seed used to initialize random number generator states.

Returns

CUDA_STATUS_SUCCESS

The call was successful.

CUDA_STATUS_INVALID_VALUE

sizeInBytes is less than the value returned by cudnnDropoutGetStatesSize().

CUDA_STATUS_EXECUTION_FAILED

The function failed to launch on the GPU.

3.2.81. cudnnSetFilter4dDescriptor()

cudnnStatus_t cudnnSetFilter4dDescriptor(
        cudnnFilterDescriptor_t    filterDesc,
        cudnnDataType_t            dataType,
        cudnnTensorFormat_t        format,
        int                        k,
        int                        c,
        int                        h,
        int                        w)

This function initializes a previously created filter descriptor object into a 4D filter. The layout of the filters must be contiguous in memory.

Tensor format CUDNN_TENSOR_NHWC has limited support in cudnnConvolutionForward[], cudnnConvolutionBackwardData[], and cudnnConvolutionBackwardFilter[].

Parameters

filterDesc

Input/Output. Handle to a previously created filter descriptor.

datatype

Input. Data type.

format

Input. Type of the filter layout format. If this input is set to CUDNN_TENSOR_NCHW, which is one of the enumerant values allowed by cudnnTensorFormat_t descriptor, then the layout of the filter is in the form of KCRS, where:
K represents the number of output feature maps

C is the number of input feature maps

R is the number of rows per filter

S is the number of columns per filter

If this input is set to CUDNN_TENSOR_NHWC, then the layout of the filter is in the form of KRSC.

For more information, see cudnnTensorFormat_t.

\[ k \]

**Input.** Number of output feature maps.

\[ c \]

**Input.** Number of input feature maps.

\[ h \]

**Input.** Height of each filter.

\[ w \]

**Input.** Width of each filter.

**Returns**

**CUDNN_STATUS_SUCCESS**

The object was set successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of the parameters k, c, h, w is negative or dataType or format has an invalid enumerant value.

### 3.2.82. cudnnSetFilterNdDescriptor()

```c

cudnnStatus_t cudnnSetFilterNdDescriptor(
    cudnnFilterDescriptor_t filterDesc,
    cudnnDataType_t         dataType,
    cudnnTensorFormat_t     format,
    int                     nbDims,
    const int               filterDimA[])
```

This function initializes a previously created filter descriptor object. The layout of the filters must be contiguous in memory.

The tensor format CUDNN_TENSOR_NHWC has limited support in cudnnConvolutionForward(), cudnnConvolutionBackwardData(), and cudnnConvolutionBackwardFilter().

**Parameters**

**filterDesc**

**Input/Output.** Handle to a previously created filter descriptor.
datatype

Input. Data type.

format

Input. Type of the filter layout format. If this input is set to CUDNN_TENSOR_NCHW, which is one of the enumerant values allowed by cudnnTensorFormat_t descriptor, then the layout of the filter is as follows:

- For N=4, a 4D filter descriptor, the filter layout is in the form of $KCRS$:
  - $K$ represents the number of output feature maps
  - $C$ is the number of input feature maps
  - $R$ is the number of rows per filter
  - $S$ is the number of columns per filter
- For N=3, a 3D filter descriptor, the number $S$ (number of columns per filter) is omitted.
- For N=5 and greater, the layout of the higher dimensions immediately follows RS.

On the other hand, if this input is set to CUDNN_TENSOR_NHWC, then the layout of the filter is as follows:

- For N=4, a 4D filter descriptor, the filter layout is in the form of $KRSC$.
- For N=3, a 3D filter descriptor, the number $S$ (number of columns per filter) is omitted and the layout of $C$ immediately follows $R$.
- For N=5 and greater, the layout of the higher dimensions are inserted between $S$ and $C$.

For more information, see cudnnTensorFormat_t.

nbDims

Input. Dimension of the filter.

filterDimA

Input. Array of dimension nbDims containing the size of the filter for each dimension.

Returns

CUDNN_STATUS_SUCCESS

The object was set successfully.

CUDNN_STATUS_BAD_PARAM

At least one of the elements of the array filterDimA is negative or dataType or format has an invalid enumerant value.

CUDNN_STATUS_NOT_SUPPORTED

The parameter nbDims exceeds CUDNN_DIM_MAX.
### 3.2.83. `cudnnSetLRNDescriptor()`

```c
#include <cudnn.h>

cudnnStatus_t cudnnSetLRNDescriptor(cudnnLRNDescriptor_t normDesc, 
                                      unsigned lrnN, 
                                      double lrnAlpha, 
                                      double lrnBeta, 
                                      double lrnK)
```

This function initializes a previously created LRN descriptor object.

### Parameters

**normDesc**

*Output.* Handle to a previously created LRN descriptor.

**lrnN**

*Input.* Normalization window width in elements. The LRN layer uses a window `[center-lookBehind, center+lookAhead]`, where `lookBehind = floor((lrnN-1)/2)`, `lookAhead = lrnN-lookBehind-1`. So for `n=10`, the window is `[k-4...k...k+5]` with a total of 10 samples. For the DivisiveNormalization layer, the window has the same extents as above in all spatial dimensions (`dimA[2], dimA[3], dimA[4]`). By default, `lrnN` is set to 5 in `cudnnCreateLRNDescriptor()`.

**lrnAlpha**

*Input.* Value of the alpha variance scaling parameter in the normalization formula. Inside the library code, this value is divided by the window width for LRN and by `(window width) ^ spatialDimensions` for DivisiveNormalization. By default, this value is set to `1e-4` in `cudnnCreateLRNDescriptor()`.

**lrnBeta**

*Input.* Value of the beta power parameter in the normalization formula. By default, this value is set to 0.75 in `cudnnCreateLRNDescriptor()`.

**lrnK**

*Input.* Value of the $k$ parameter in the normalization formula. By default, this value is set to `2.0`.

### Returns

**CUDNN_STATUS_SUCCESS**

The object was set successfully.
**CUDNN_STATUS_BAD_PARAM**

One of the input parameters was out of valid range as described above.

### 3.2.84. **cudnnSetOpTensorDescriptor()**

```c
cudnnStatus_t cudnnSetOpTensorDescriptor(
    cudnnOpTensorDescriptor_t   opTensorDesc,
    cudnnOpTensorOp_t           opTensorOp,
    cudnnDataType_t             opTensorCompType,
    cudnnNanPropagation_t       opTensorNanOpt)
```

This function initializes a tensor pointwise math descriptor.

**Parameters**

- **opTensorDesc**
  - *Output.* Pointer to the structure holding the description of the tensor pointwise math descriptor.

- **opTensorOp**
  - *Input.* Tensor pointwise math operation for this tensor pointwise math descriptor.

- **opTensorCompType**
  - *Input.* Computation datatype for this tensor pointwise math descriptor.

- **opTensorNanOpt**
  - *Input.* NAN propagation policy.

**Returns**

- **CUDNN_STATUS_SUCCESS**
  - The function returned successfully.

- **CUDNN_STATUS_BAD_PARAM**
  - At least one of the input parameters passed is invalid.

### 3.2.85. **cudnnSetPooling2dDescriptor()**

```c
cudnnStatus_t cudnnSetPooling2dDescriptor(
    cudnnPoolingDescriptor_t    poolingDesc,
    cudnnPoolingMode_t          mode,
    cudnnNanPropagation_t       maxpoolingNanOpt,
    int                         windowHeight,
    int                         windowWidth,
    int                         verticalPadding,
    int                         horizontalPadding,
    int                         verticalStride,
    int                         horizontalStride)
```

This function initializes a previously created generic pooling descriptor object into a 2D description.
Parameters

poolingDesc

Input/Output. Handle to a previously created pooling descriptor.

mode

Input. Enumerant to specify the pooling mode.

maxpoolingNanOpt

Input. Enumerant to specify the Nan propagation mode.

windowHeight

Input. Height of the pooling window.

windowWidth

Input. Width of the pooling window.

verticalPadding

Input. Size of vertical padding.

horizontalPadding

Input. Size of horizontal padding

verticalStride

Input. Pooling vertical stride.

horizontalStride

Input. Pooling horizontal stride.

Returns

CUDNN_STATUS_SUCCESS

The object was set successfully.

CUDNN_STATUS_BAD_PARAM

At least one of the parameters windowHeight, windowWidth, verticalStride, horizontalStride is negative or mode or maxpoolingNanOpt has an invalid enumerate value.

3.2.86. cudnnSetPoolingNdDescriptor()

cudnnStatus_t cudnnSetPoolingNdDescriptor(
    cudnnPoolingDescriptor_t poolingDesc,
    const cudnnPoolingMode_t mode,
    const cudnnNanPropagation_t maxpoolingNanOpt,
    int nbDims,
    const int windowDimA[],
    const int paddingA[],
    const int strideA[])

This function initializes a previously created generic pooling descriptor object.

**Parameters**

**poolingDesc**
- **Input/Output.** Handle to a previously created pooling descriptor.

**mode**
- **Input.** Enumerant to specify the pooling mode.

**maxpoolingNanOpt**
- **Input.** Enumerant to specify the Nan propagation mode.

**nbDims**
- **Input.** Dimension of the pooling operation. Must be greater than zero.

**windowDimA**
- **Input.** Array of dimension `nbDims` containing the window size for each dimension. The value of array elements must be greater than zero.

**paddingA**
- **Input.** Array of dimension `nbDims` containing the padding size for each dimension. Negative padding is allowed.

**strideA**
- **Input.** Array of dimension `nbDims` containing the striding size for each dimension. The value of array elements must be greater than zero (meaning, negative striding size is not allowed).

**Returns**

**CUDNN_STATUS_SUCCESS**
- The object was initialized successfully.

**CUDNN_STATUS_NOT_SUPPORTED**
- If `(nbDims > CUDNN_DIM_MAX-2)`.

**CUDNN_STATUS_BAD_PARAM**
- Either `nbDims`, or at least one of the elements of the arrays `windowDimA` or `strideA` is negative, or `mode` or `maxpoolingNanOpt` has an invalid enumerate value.

### 3.2.87. cudnnSetReduceTensorDescriptor()®

```c
typedef cudnnStatus_t cudnnSetReduceTensorDescriptor( 
    cudnnReduceTensorDescriptor_t reduceTensorDesc,
    cudnnReduceTensorOp_t reduceTensorOp,
    cudnnDataType_t reduceTensorCompType,
    cudnnNanPropagation_t reduceTensorNanOpt,
    cudnnReduceTensorIndices_t reduceTensorIndices,
    cudnnIndicesType_t reduceTensorIndicesType)
```
This function initializes a previously created reduce tensor descriptor object.

**Parameters**

- **reduceTensorDesc**
  
  *Input/Output.* Handle to a previously created reduce tensor descriptor.

- **reduceTensorOp**
  
  *Input.* Enumerant to specify the reduce tensor operation.

- **reduceTensorCompType**
  
  *Input.* Enumerant to specify the computation datatype of the reduction.

- **reduceTensorNanOpt**
  
  *Input.* Enumerant to specify the Nan propagation mode.

- **reduceTensorIndices**
  
  *Input.* Enumerant to specify the reduced tensor indices.

- **reduceTensorIndicesType**
  
  *Input.* Enumerant to specify the reduce tensor indices type.

**Returns**

- **CUDNN_STATUS_SUCCESS**
  
  The object was set successfully.

- **CUDNN_STATUS_BAD_PARAM**
  
  `reduceTensorDesc` is NULL (`reduceTensorOp`, `reduceTensorCompType`, `reduceTensorNanOpt`, `reduceTensorIndices` or `reduceTensorIndicesType` has an invalid enumerant value).

### 3.2.88. cudnnSetSpatialTransformerNdDescriptor()

cudnnStatus_t cudnnSetSpatialTransformerNdDescriptor(
    cudnnSpatialTransformerDescriptor_t stDesc,
    cudnnSamplerType_t samplerType,
    cudnnDataType_t dataType,
    const int nbDims,
    const int dimA[])

This function initializes a previously created generic spatial transformer descriptor object.

**Parameters**

- **stDesc**
  
  *Input/Output.* Previously created spatial transformer descriptor object.

- **samplerType**
  
  *Input.* Enumerant to specify the sampler type.
**dataType**

*Input.* Data type.

**nbDims**

*Input.* Dimension of the transformed tensor.

**dimA**

*Input.* Array of dimension nbDims containing the size of the transformed tensor for every dimension.

**Returns**

**CUDNN_STATUS_SUCCESS**

The call was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- Either stDesc or dimA is NULL.
- Either dataType or samplerType has an invalid enumerant value.

### 3.2.89. **cudnnSetStream()**

```c
cudnnStatus_t cudnnSetStream(  
cudnnHandle_t handle,  
cudaStream_t streamId)
```

This function sets the user’s CUDA stream in the cuDNN handle. The new stream will be used to launch cuDNN GPU kernels or to synchronize to this stream when cuDNN kernels are launched in the internal streams. If the cuDNN library stream is not set, all kernels use the default (NULL) stream. Setting the user stream in the cuDNN handle guarantees the issue-order execution of cuDNN calls and other GPU kernels launched in the same stream.

**Parameters**

**handle**

*Input.* Pointer to the cuDNN handle.

**streamID**

*Input.* New CUDA stream to be written to the cuDNN handle.

**Returns**

**CUDNN_STATUS_BAD_PARAM**

Invalid (NULL) handle.

**CUDNN_STATUS_MAPPING_ERROR**

Mismatch between the user stream and the cuDNN handle context.
CUDNN_STATUS_SUCCESS

The new stream was set successfully.

3.2.90. cudnnSetTensor()

cudnnStatus_t cudnnSetTensor(
    cudnnHandle_t                   handle,
    const cudnnTensorDescriptor_t   yDesc,
    void                           *y,
    const void                     *valuePtr)

This function sets all the elements of a tensor to a given value.

Parameters

handle

*Input*. Handle to a previously created cuDNN context.

yDesc

*Input*. Handle to a previously initialized tensor descriptor.

y

*Input/Output*. Pointer to data of the tensor described by the yDesc descriptor.

valuePtr

*Input*. Pointer in host memory to a single value. All elements of the y tensor will be set to value[0]. The data type of the element in value[0] has to match the data type of tensor y.

Returns

CUDNN_STATUS_SUCCESS

The function launched successfully.

CUDNN_STATUS_NOT_SUPPORTED

The function does not support the provided configuration.

CUDNN_STATUS_BAD_PARAM

One of the provided pointers is nil.

CUDNN_STATUS_EXECUTION_FAILED

The function failed to launch on the GPU.

3.2.91. cudnnSetTensor4dDescriptor()

cudnnStatus_t cudnnSetTensor4dDescriptor(
    cudnnTensorDescriptor_t tensorDesc,
    cudnnTensorFormat_t     format,
    cudnnDataType_t         dataType,
    int                     n,
    int                     c,
    int                     h,
    int                     w)
This function initializes a previously created generic tensor descriptor object into a 4D tensor. The strides of the four dimensions are inferred from the format parameter and set in such a way that the data is contiguous in memory with no padding between dimensions.

**Note:** The total size of a tensor including the potential padding between dimensions is limited to 2 Giga-elements of type `datatype`.

### Parameters

- **`tensorDesc`**
  - *Input/Output*. Handle to a previously created tensor descriptor.

- **`format`**
  - *Input*. Type of format.

- **`datatype`**
  - *Input*. Data type.

- **`n`**
  - *Input*. Number of images.

- **`c`**
  - *Input*. Number of feature maps per image.

- **`h`**
  - *Input*. Height of each feature map.

- **`w`**
  - *Input*. Width of each feature map.

### Returns

- **`CUDNN_STATUS_SUCCESS`**
  - The object was set successfully.

- **`CUDNN_STATUS_BAD_PARAM`**
  - At least one of the parameters `n`, `c`, `h`, `w` was negative or `format` has an invalid enumerant value or `dataType` has an invalid enumerant value.

- **`CUDNN_STATUS_NOT_SUPPORTED`**
  - The total size of the tensor descriptor exceeds the maximum limit of 2 Giga-elements.

### 3.2.92. `cudnnSetTensor4dDescriptorEx()`

```
cudnnStatus_t cudnnSetTensor4dDescriptorEx(
    cudnnTensorDescriptor_t tensorDesc,
    cudnnDataType_t       dataType,
    int                   n,
    int                   c,

    cudnnSetTensor4dDescriptorExEx() cudnnSetTensor4dDescriptorExEx( 
```
This function initializes a previously created generic tensor descriptor object into a 4D tensor, similarly to `cudnnSetTensor4dDescriptor()` but with the strides explicitly passed as parameters. This can be used to lay out the 4D tensor in any order or simply to define gaps between dimensions.

**Parameters**

- **tensorDesc**
  - *Input/Output*. Handle to a previously created tensor descriptor.

- **datatype**
  - *Input*. Data type.

- **n**
  - *Input*. Number of images.

- **c**
  - *Input*. Number of feature maps per image.

- **h**
  - *Input*. Height of each feature map.

- **w**
  - *Input*. Width of each feature map.

- **nStride**
  - *Input*. Stride between two consecutive images.

- **cStride**
  - *Input*. Stride between two consecutive feature maps.

- **hStride**
  - *Input*. Stride between two consecutive rows.

- **wStride**
  - *Input*. Stride between two consecutive columns.
Returns

**CUDNN_STATUS_SUCCESS**

The object was set successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of the parameters \( n, c, h, w \) or \( nStride, cStride, hStride, wStride \) is negative or \( \text{dataType} \) has an invalid enumerant value.

**CUDNN_STATUS_NOT_SUPPORTED**

The total size of the tensor descriptor exceeds the maximum limit of 2 Giga-elements.

3.2.93. **cudnnSetTensorNdDescriptor()**

```c
cudnnStatus_t cudnnSetTensorNdDescriptor(
    cudnnTensorDescriptor_t tensorDesc,
    cudnnDataType_t         dataType,
    int                     nbDims,
    const int               dimA[],
    const int               strideA[])
```

This function initializes a previously created generic tensor descriptor object.

**Note:** The total size of a tensor including the potential padding between dimensions is limited to 2 Giga-elements of type \( \text{dataType} \). Tensors are restricted to having at least 4 dimensions, and at most \( \text{CUDNN_DIM_MAX} \) dimensions (defined in `cudnn.h`). When working with lower dimensional data, it is recommended that the user create a 4D tensor, and set the size along unused dimensions to 1.

**Parameters**

- **tensorDesc**
  
  *Input/Output.* Handle to a previously created tensor descriptor.

- **datatype**
  
  *Input.* Data type.

- **nbDims**
  
  *Input.* Dimension of the tensor.

**Note:** Do not use 2 dimensions. Due to historical reasons, the minimum number of dimensions in the filter descriptor is three. For more information, see `cudnnGetRNNLinLayerBiasParams()`.

- **dimA**
  
  *Input.* Array of dimension \( \text{nbDims} \) that contain the size of the tensor for every dimension. The size along unused dimensions should be set to 1. By convention, the ordering of
dimensions in the array follows the format - \([N, C, D, H, W]\), with \(W\) occupying the smallest index in the array.

**strideA**

*Input.* Array of dimension \(nbDims\) that contain the stride of the tensor for every dimension. By convention, the ordering of the strides in the array follows the format - \([N\text{stride}, C\text{stride}, D\text{stride}, H\text{stride}, W\text{stride}]\), with \(W\text{stride}\) occupying the smallest index in the array.

**Returns**

**CUDNN_STATUS_SUCCESS**

The object was set successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of the elements of the array \(dimA\) was negative or zero, or \(dataType\) has an invalid enumerant value.

**CUDNN_STATUS_NOT_SUPPORTED**

The parameter \(nbDims\) is outside the range \([4, \text{CUDNN}_\text{DIM}_\text{MAX}]\), or the total size of the tensor descriptor exceeds the maximum limit of 2 Giga-elements.

### 3.2.94. `cudnnSetTensorNdDescriptorEx()`

```c

```cudnnStatus_t cudnnSetTensorNdDescriptorEx(
    cudnnTensorDescriptor_t tensorDesc,
    cudnnTensorFormat_t     format,
    cudnnDataType_t         dataType,
    int                     nbDims,
    const int               dimA[])
```

This function initializes an n-D tensor descriptor.

**Parameters**

**tensorDesc**

*Output.* Pointer to the tensor descriptor struct to be initialized.

**format**

*Input.* Tensor format.

**dataType**

*Input.* Tensor data type.
**nbDims**

*Input.* Dimension of the tensor.

**Note:** Do not use 2 dimensions. Due to historical reasons, the minimum number of dimensions in the filter descriptor is three. For more information, see `cudnnGetRNNLinLayerBiasParams()`.

**dimA**

*Input.* Array containing the size of each dimension.

**Returns**

**CUDNN_STATUS_SUCCESS**

The function was successful.

**CUDNN_STATUS_BAD_PARAM**

Tensor descriptor was not allocated properly; or input parameters are not set correctly.

**CUDNN_STATUS_NOT_SUPPORTED**

Dimension size requested is larger than maximum dimension size supported.

### 3.2.95. `cudnnSetTensorTransformDescriptor()`

cudnnStatus_t cudnnSetTensorTransformDescriptor(
    cudnnTensorTransformDescriptor_t transformDesc,
    const uint32_t nbDims,
    const cudnnTensorFormat_t destFormat,
    const int32_t padBeforeA[],
    const int32_t padAfterA[],
    const uint32_t foldA[],
    const cudnnFoldingDirection_t direction);

This function initializes a tensor transform descriptor that was previously created using the `cudnnCreateTensorTransformDescriptor[]` function.

**Parameters**

**transformDesc**

*Output.* The tensor transform descriptor to be initialized.

**nbDims**

*Input.* The dimensionality of the transform operands. Must be greater than 2. For more information, see the Tensor Descriptor section from the cuDNN Developer Guide.

**destFormat**

*Input.* The desired destination format.
padBeforeA[]

*Input.* An array that contains the amount of padding that should be added before each dimension. Set to *NULL* for no padding.

padAfterA[]

*Input.* An array that contains the amount of padding that should be added after each dimension. Set to *NULL* for no padding.

foldA[]

*Input.* An array that contains the folding parameters for each spatial dimension (dimensions 2 and up). Set to *NULL* for no folding.

direction

*Input.* Selects folding or unfolding. This input has no effect when folding parameters are all <= 1. For more information, see [cudnnFoldingDirection_t](#).

Returns

**CUDNN_STATUS_SUCCESS**

The function was launched successfully.

**CUDNN_STATUS_BAD_PARAM**

The parameter `transformDesc` is *NULL*, or if `direction` is invalid, or `nbDims` is <= 2.

**CUDNN_STATUS_NOT_SUPPORTED**

If the dimension size requested is larger than maximum dimension size supported (meaning, one of the `nbDims` is larger than `CUDNN_DIM_MAX`), or if `destFormat` is something other than `NCHW` or `NHWC`.

### 3.2.96. `cudnnSoftmaxForward()`

```c
cudnnStatus_t cudnnSoftmaxForward(
    cudnnHandle_t                    handle,
    cudnnSoftmaxAlgorithm_t          algorithm,
    cudnnSoftmaxMode_t               mode,
    const void                      *alpha,
    const cudnnTensorDescriptor_t    xDesc,
    const void                      *x,
    const void                      *beta,
    const cudnnTensorDescriptor_t    yDesc,
    void                            *y)
```

This routine computes the softmax function.

**Note:** All tensor formats are supported for all modes and algorithms with 4 and 5D tensors. Performance is expected to be highest with NCHW fully-packed tensors. For more than 5 dimensions tensors must be packed in their spatial dimensions.
Parameters

handle

Input. Handle to a previously created cuDNN context.

algorithm

Input. Enumerant to specify the softmax algorithm.

mode

Input. Enumerant to specify the softmax mode.

alpha, beta

Input. Pointers to scaling factors [in host memory] used to blend the computation result with prior value in the output layer as follows:

\[
\text{dstValue} = \alpha[0] \times \text{result} + \beta[0] \times \text{priorDstValue}
\]

For more information, see the Scaling Parameters section in the cuDNN Developer Guide.

xDesc

Input. Handle to the previously initialized input tensor descriptor.

x

Input. Data pointer to GPU memory associated with the tensor descriptor xDesc.

yDesc

Input. Handle to the previously initialized output tensor descriptor.

y

Output. Data pointer to GPU memory associated with the output tensor descriptor yDesc.

Returns

CUDNN_STATUS_SUCCESS

The function launched successfully.

CUDNN_STATUS_NOT_SUPPORTED

The function does not support the provided configuration.

CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- The dimensions \( n, c, h, w \) of the input tensor and output tensors differ.
- The datatype of the input tensor and output tensors differ.
- The parameters algorithm or mode have an invalid enumerant value.

CUDNN_STATUS_EXECUTION_FAILED

The function failed to launch on the GPU.
3.2.97. **cudnnSpatialTfGridGeneratorForward()**

```c
    cudnnStatus_t cudnnSpatialTfGridGeneratorForward(
        cudnnHandle_t                               handle,
        const cudnnSpatialTransformerDescriptor_t   stDesc,
        const void                                 *theta,
        void                                       *grid)
```

This function generates a grid of coordinates in the input tensor corresponding to each pixel from the output tensor.

**Note:** Only 2d transformation is supported.

**Parameters**

- **handle**
  
  *Input.* Handle to a previously created cuDNN context.

- **stDesc**
  
  *Input.* Previously created spatial transformer descriptor object.

- **theta**
  
  *Input.* Affine transformation matrix. It should be of size \( n \times 2 \times 3 \) for a 2d transformation, where \( n \) is the number of images specified in \( stDesc \).

- **grid**
  
  *Output.* A grid of coordinates. It is of size \( n \times h \times w \times 2 \) for a 2d transformation, where \( n, h, w \) is specified in \( stDesc \). In the 4th dimension, the first coordinate is \( x \), and the second coordinate is \( y \).

**Returns**

- **CUDNN_STATUS_SUCCESS**
  
  The call was successful.

- **CUDNN_STATUS_BAD_PARAM**
  
  At least one of the following conditions are met:
  
  - handle is NULL.
  - One of the parameters grid or theta is NULL.

- **CUDNN_STATUS_NOT_SUPPORTED**
  
  The function does not support the provided configuration. See the following for some examples of non-supported configurations:
  
  - The dimension of the transformed tensor specified in \( stDesc \) > 4.
CUDNN_STATUS_EXECUTION_FAILED

The function failed to launch on the GPU.

3.2.98. **cudnnSpatialTfSamplerForward()**

```c
void cudnnSpatialTfSamplerForward(
    cudnnHandle_t                              handle,
    const cudnnSpatialTransformerDescriptor_t  stDesc,
    const void                                *alpha,
    const cudnnTensorDescriptor_t              xDesc,
    const void                                *x,
    const void                                *grid,
    const void                                *beta,
    cudnnTensorDescriptor_t                    yDesc,
    void                                      *y)
```

This function performs a sampler operation and generates the output tensor using the grid given by the grid generator.

**Note:** Only 2d transformation is supported.

**Parameters**

**handle**

*Input.* Handle to a previously created cuDNN context.

**stDesc**

*Input.* Previously created spatial transformer descriptor object.

**alpha, beta**

*Input.* Pointers to scaling factors (in host memory) used to blend the source value with prior value in the destination tensor as follows:

\[
\text{dstValue} = \alpha[0] \times \text{srcValue} + \beta[0] \times \text{priorDstValue}
\]

For more information, see the [Scaling Parameters](#) section in the cuDNN Developer Guide.

**xDesc**

*Input.* Handle to the previously initialized input tensor descriptor.

**x**

*Input.* Data pointer to GPU memory associated with the tensor descriptor `xDesc`.

**grid**

*Input.* A grid of coordinates generated by `cudnnSpatialTfGridGeneratorForward()`.

**yDesc**

*Input.* Handle to the previously initialized output tensor descriptor.

**y**

*Output.* Data pointer to GPU memory associated with the output tensor descriptor `yDesc`. 
Returns

**CUDNN_STATUS_SUCCESS**

The call was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- handle is NULL.
- One of the parameters x, y or grid is NULL.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration. See the following for some examples of non-supported configurations:

- The dimension of transformed tensor > 4.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

### 3.2.99. `cudnnTransformFilter()`

```c

cudnnStatus_t cudnnTransformTensorEx(
    cudnnHandle_t handle,
    const cudnnTensorTransformDescriptor_t transDesc,
    const void *alpha,
    const cudnnFilterDescriptor_t srcDesc,
    const void *srcData,
    const void *beta,
    const cudnnFilterDescriptor_t destDesc,
    void *destData);
```

This function converts the filter between different formats, data types, or dimensions based on the described transformation. It can be used to convert a filter with an unsupported layout format to a filter with a supported layout format.

This function copies the scaled data from the input filter srcDesc to the output tensor destDesc with a different layout. If the filter descriptors of srcDesc and destDesc have different dimensions, they must be consistent with folding and padding amount and order specified in transDesc.

The srcDesc and destDesc tensors must not overlap in any way (meaning, tensors cannot be transformed in place).

**Note:** When performing a folding transform or a zero-padding transform, the scaling factors [alpha, beta] should be set to [1, 0]. However, unfolding transforms support any [alpha, beta] values. This function is thread safe.
Parameters

**handle**

*Input*. Handle to a previously created cuDNN context. For more information, see `cudnnHandle_t`.

**transDesc**

*Input*. A descriptor containing the details of the requested filter transformation. For more information, see `cudnnTensorTransformDescriptor_t`.

**alpha, beta**

*Input*. Pointers, in the host memory, to the scaling factors used to scale the data in the input tensor `srcDesc`. `beta` is used to scale the destination tensor, while `alpha` is used to scale the source tensor. For more information, see the *Scaling Parameters* section in the cuDNN Developer Guide.

The beta scaling value is not honored in the folding and zero-padding cases. Unfolding supports any `{alpha, beta}`.

**srcDesc, destDesc**

*Input*. Handles to the previously initiated filter descriptors. `srcDesc` and `destDesc` must not overlap. For more information, see `cudnnTensorDescriptor_t`.

**srcData, destData**

*Input*. Pointers, in the host memory, to the data of the tensor described by `srcDesc` and `destDesc` respectively.

Returns

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_BAD_PARAM**

A parameter is uninitialized or initialized incorrectly, or the number of dimensions is different between `srcDesc` and `destDesc`.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration. Also, in the folding and padding paths, any value other than `A=1` and `B=0` will result in a CUDNN_STATUS_NOT_SUPPORTED.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

### 3.2.100. `cudnnTransformTensor()`

cudnnStatus_t cudnnTransformTensor(
    cudnnHandle_t handle,
    /* other parameters */
);
This function copies the scaled data from one tensor to another tensor with a different layout. Those descriptors need to have the same dimensions but not necessarily the same strides. The input and output tensors must not overlap in any way (meaning, tensors cannot be transformed in place). This function can be used to convert a tensor with an unsupported format to a supported one.

**Parameters**

**handle**

*Input.* Handle to a previously created cuDNN context.

**alpha, beta**

*Input.* Pointers to scaling factors (in host memory) used to blend the source value with prior value in the destination tensor as follows:

\[
dstValue = alpha[0] \times srcValue + beta[0] \times priorDstValue
\]

For more information, see the [Scaling Parameters](#) section in the *cuDNN Developer Guide*.

**xDesc**

*Input.* Handle to a previously initialized tensor descriptor. For more information, see [cudnnTensorDescriptor_t](#).

**x**

*Input.* Pointer to data of the tensor described by the xDesc descriptor.

**yDesc**

*Input.* Handle to a previously initialized tensor descriptor. For more information, see [cudnnTensorDescriptor_t](#).

**y**

*Output.* Pointer to data of the tensor described by the yDesc descriptor.

**Returns**

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

The dimensions \( n, c, h, w \) or the `dataType` of the two tensor descriptors are different.
CUDNN_STATUS_EXECUTION_FAILED

The function failed to launch on the GPU.

3.2.101. cudnnTransformTensorEx()

cudnnStatus_t cudnnTransformTensorEx(
    cudnnHandle_t handle,
    const cudnnTensorTransformDescriptor_t transDesc,
    const void *alpha,
    const cudnnTensorDescriptor_t srcDesc,
    const void *srcData,
    const void *beta,
    const cudnnTensorDescriptor_t destDesc,
    void *destData);

This function converts the tensor layouts between different formats. It can be used to convert a tensor with an unsupported layout format to a tensor with a supported layout format.

This function copies the scaled data from the input tensor srcDesc to the output tensor destDesc with a different layout. The tensor descriptors of srcDesc and destDesc should have the same dimensions but need not have the same strides.

The srcDesc and destDesc tensors must not overlap in any way (meaning, tensors cannot be transformed in place).

Note: When performing a folding transform or a zero-padding transform, the scaling factors (alpha, beta) should be set to (1, 0). However, unfolding transforms support any (alpha, beta) values. This function is thread safe.

Parameters

handle

Input. Handle to a previously created cuDNN context. For more information, see cudnnHandle_t.

transDesc

Input. A descriptor containing the details of the requested tensor transformation. For more information, see cudnnTensorTransformDescriptor_t.

alpha, beta

Input. Pointers, in the host memory, to the scaling factors used to scale the data in the input tensor srcDesc. beta is used to scale the destination tensor, while alpha is used to scale the source tensor. For more information, see the Scaling Parameters section in the cuDNN Developer Guide.

The beta scaling value is not honored in the folding and zero-padding cases. Unfolding supports any (alpha, beta).
**srcDesc, destDesc**

*Input.* Handles to the previously initiated tensor descriptors. `srcDesc` and `destDesc` must not overlap. For more information, see `cudnnTensorDescriptor_t`.

**srcData, destData**

*Input.* Pointers, in the host memory, to the data of the tensor described by `srcDesc` and `destDesc` respectively.

**Returns**

**CUDNN_STATUS_SUCCESS**

The function was launched successfully.

**CUDNN_STATUS_BAD_PARAM**

A parameter is uninitialized or initialized incorrectly, or the number of dimensions is different between `srcDesc` and `destDesc`.

**CUDNN_STATUS_NOT_SUPPORTED**

Function does not support the provided configuration. Also, in the folding and padding paths, any value other than `A=1` and `B=0` will result in a CUDNN_STATUS_NOT_SUPPORTED.

**CUDNN_STATUS_EXECUTION_FAILED**

Function failed to launch on the GPU.
4.1. API Functions

4.1.1. cudnnActivationBackward()

```c
void cudnnActivationBackward(
    cudnnHandle_t                    handle,
    cudnnActivationDescriptor_t      activationDesc,
    const void                      *alpha,
    const cudnnTensorDescriptor_t    yDesc,
    const void                      *y,
    const cudnnTensorDescriptor_t    dyDesc,
    const void                      *dy,
    const cudnnTensorDescriptor_t    xDesc,
    const void                      *x,
    const void                      *beta,
    const cudnnTensorDescriptor_t    dxDesc,
    void                            *dx)
```

This routine computes the gradient of a neuron activation function.

**Note:**
- In-place operation is allowed for this routine; meaning `dy` and `dx` pointers may be equal. However, this requires the corresponding tensor descriptors to be identical [particularly, the strides of the input and output must match for an in-place operation to be allowed].
- All tensor formats are supported for 4 and 5 dimensions, however, the best performance is obtained when the strides of `yDesc` and `xDesc` are equal and HW-packed. For more than 5 dimensions the tensors must have their spatial dimensions packed.

**Parameters**

**handle**

*Input.* Handle to a previously created cuDNN context. For more information, see `cudnnHandle_t`. 
activationDesc

*Input.* Activation descriptor. See [cudnnActivationDescriptor_t](#).

**alpha, beta**

*Input.* Pointers to scaling factors (in host memory) used to blend the computation result with prior value in the output layer as follows:

\[
dstValue = alpha[0]*result + beta[0]*priorDstValue
\]

For more information, see [Scaling Parameters](#) in the [cuDNN Developer Guide](#).

**yDesc**

*Input.* Handle to the previously initialized input tensor descriptor. For more information, see [cudnnTensorDescriptor_t](#).

**y**

*Input.* Data pointer to GPU memory associated with the tensor descriptor yDesc.

**dyDesc**

*Input.* Handle to the previously initialized input differential tensor descriptor.

**dy**

*Input.* Data pointer to GPU memory associated with the tensor descriptor dyDesc.

**xDesc**

*Input.* Handle to the previously initialized output tensor descriptor.

**x**

*Input.* Data pointer to GPU memory associated with the output tensor descriptor xDesc.

**dxDesc**

*Input.* Handle to the previously initialized output differential tensor descriptor.

**dx**

*Output.* Data pointer to GPU memory associated with the output tensor descriptor dxDesc.

**Returns**

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The strides nStride, cStride, hStride, wStride of the input differential tensor and output differential tensor differ and in-place operation is used.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration. See the following for some examples of non-supported configurations:
The dimensions \(n, c, h, w\) of the input tensor and output tensor differ.

- The datatype of the input tensor and output tensor differs.
- The strides \(n\text{Stride}, c\text{Stride}, h\text{Stride}, w\text{Stride}\) of the input tensor and the input differential tensor differ.
- The strides \(n\text{Stride}, c\text{Stride}, h\text{Stride}, w\text{Stride}\) of the output tensor and the output differential tensor differ.

**CUDNN\_STATUS\_EXECUTION\_FAILED**

The function failed to launch on the GPU.

### 4.1.2. cudnnBatchNormalizationBackward()

```c
void cudnnBatchNormalizationBackward(
    cudnnHandle_t handle,
    cudnnBatchNormMode_t mode,
    const void *alphaDataDiff,
    const void *betaDataDiff,
    const void *alphaParamDiff,
    const void *betaParamDiff,
    const cudnnTensorDescriptor_t xDesc,
    const void *x,
    const cudnnTensorDescriptor_t dyDesc,
    const void *dy,
    const cudnnTensorDescriptor_t dxDesc,
    void *dx,
    const cudnnTensorDescriptor_t bnScaleBiasDiffDesc,
    const void *bnScale,
    void *resultBnScaleDiff,
    void *resultBnBiasDiff,
    double epsilon,
    const void *savedMean,
    const void *savedInvVariance)
```

This function performs the backward batch normalization layer computation. This layer is based on the paper *Batch Normalization: Accelerating Deep Network Training by Reducing Internal Covariate Shift*, S. Ioffe, C. Szegedy, 2015.

**Note:**

- Only 4D and 5D tensors are supported.
- The \(\epsilon\) value has to be the same during training, backpropagation, and inference.
- Higher performance can be obtained when HW-packed tensors are used for all of \(x, dy, dx\).

For more information, see cudnnDeriveBNTensorDescriptor() for the secondary tensor descriptor generation for the parameters used in this function.

**Parameters**

**handle**

*Input*. Handle to a previously created cuDNN library descriptor. For more information, see cudnnHandle_t.
mode

*Input*. Mode of operation (spatial or per-activation). For more information, see cudnnBatchNormMode_t.

**alphaDataDiff**, **betaDataDiff**

*Inputs*. Pointers to scaling factors (in host memory) used to blend the gradient output $dx$ with a prior value in the destination tensor as follows:

$$dstValue = alphaDataDiff[0] \times resultValue + betaDataDiff[0] \times priorDstValue$$

For more information, see Scaling Parameters in the cuDNN Developer Guide.

**alphaParamDiff**, **betaParamDiff**

*Inputs*. Pointers to scaling factors (in host memory) used to blend the gradient outputs resultBnScaleDiff and resultBnBiasDiff with prior values in the destination tensor as follows:

$$dstValue = alphaParamDiff[0] \times resultValue + betaParamDiff[0] \times priorDstValue$$

For more information, see Scaling Parameters.

**xDesc**, **dxDesc**, **dyDesc**

*Inputs*. Handles to the previously initialized tensor descriptors.

**x**

*Input*. Data pointer to GPU memory associated with the tensor descriptor $xDesc$, for the layer’s $x$ data.

**dy**

*Inputs*. Data pointer to GPU memory associated with the tensor descriptor $dyDesc$, for the backpropagated differential $dy$ input.

**dx**

*Inputs*. Data pointer to GPU memory associated with the tensor descriptor $dxDesc$, for the resulting differential output with respect to $x$.

**bnScaleBiasDiffDesc**

*Input*. Shared tensor descriptor for the following five tensors: $bnScale$, resultBnScaleDiff, resultBnBiasDiff, savedMean, savedInvVariance. The dimensions for this tensor descriptor are dependent on normalization mode. For more information, see cudnnDeriveBNTensorDescriptor().

Note: The data type of this tensor descriptor must be float for FP16 and FP32 input tensors, and double for FP64 input tensors.
**bnScale**

*Input*. Pointer in the device memory for the batch normalization scale parameter [in the original paper the quantity scale is referred to as gamma].

*Note: The bnBias parameter is not needed for this layer’s computation.*

**resultBnScaleDiff, resultBnBiasDiff**

*Outputs*. Pointers in device memory for the resulting scale and bias differentials computed by this routine. Note that these scale and bias gradients are weight gradients specific to this batch normalization operation, and by definition are not backpropagated.

**epsilon**

*Input*. Epsilon value used in batch normalization formula. Its value should be equal to or greater than the value defined for CUDNN_BN_MIN_EPSILON in cudnn.h. The same epsilon value should be used in forward and backward functions.

**savedMean, savedInvVariance**

*Inputs*. Optional cache parameters containing saved intermediate results that were computed during the forward pass. For this to work correctly, the layer’s x and bnScale data have to remain unchanged until this backward function is called.

*Note: Both these parameters can be NULL but only at the same time. It is recommended to use this cache since the memory overhead is relatively small.*

**Supported configurations**

This function supports the following combinations of data types for various descriptors.

<table>
<thead>
<tr>
<th>Data Type Configurations</th>
<th>xDesc</th>
<th>bnScaleBiasMean</th>
<th>alphaDataDiff, betaDataDiff, alphaParamDiff, betaParamDiff</th>
<th>dyDesc</th>
<th>dxDesc</th>
</tr>
</thead>
<tbody>
<tr>
<td>PSEUDO_HALF_CONFIG</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_HALF</td>
</tr>
<tr>
<td>FLOAT_CONFIG</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
</tr>
<tr>
<td>DOUBLE_CONFIG</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
</tr>
</tbody>
</table>

**Returns**

**CUDNN_STATUS_SUCCESS**

The computation was performed successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.
CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- Any of the pointers `alpha`, `beta`, `x`, `dy`, `dx`, `bnScale`, `resultBnScaleDiff`, `resultBnBiasDiff` is NULL.
- The number of `xDesc` or `yDesc` or `dxDesc` tensor descriptor dimensions is not within the range of [4, 5] (only 4D and 5D tensors are supported).
- `bnScaleBiasDiffDesc` dimensions are not 1xCx1x1 for 4D and 1xCx1x1x1 for 5D for spatial, and are not 1xCxHxW for 4D and 1xCxDxHxW for 5D for per-activation mode.
- Exactly one of `savedMean`, `savedInvVariance` pointers is NULL.
- `epsilon` value is less than `CUDNN_BN_MIN_EPSILON`.
- Dimensions or data types mismatch for any pair of `xDesc`, `dyDesc`, `dxDesc`.

4.1.3. cudnnBatchNormalizationBackwardEx()

cudnnStatus_t cudnnBatchNormalizationBackwardEx (   cudnnHandle_t                       handle,   cudnnBatchNormMode_t                mode,   cudnnBatchNormOps_t                 bnOps,   const void                          *alphaDataDiff,   const void                          *betaDataDiff,   const void                          *alphaParamDiff,   const void                          *betaParamDiff,   const cudnnTensorDescriptor_t       xDesc,   const void                          *xData,   const cudnnTensorDescriptor_t       yDesc,   const void                          *yData,   const cudnnTensorDescriptor_t       dyDesc,   const void                          *dyData,   const cudnnTensorDescriptor_t       dzDesc,   void                                *dzData,   const cudnnTensorDescriptor_t       dxDesc,   void                                *dxData,   const cudnnTensorDescriptor_t       dbnScaleBiasDesc,   const void                          *bnScaleData,   const void                          *bnBiasData,   void                                *dbnScaleData,   void                                *dbnBiasData,   double                              epsilon,   const void                          *savedMean,   const void                          *savedInvVariance,   const cudnnActivationDescriptor_t   activationDesc,   void                                *workspace,   size_t                              workSpaceSizeInBytes,   void                                *reserveSpace,   size_t                              reserveSpaceSizeInBytes);

This function is an extension of the cudnnBatchNormalizationBackward() for performing the backward batch normalization layer computation with a fast NHWC semi-persistent kernel. This API will trigger the new semi-persistent NHWC kernel when the following conditions are true:

- All tensors, namely, `x`, `y`, `dz`, `dy`, `dx` must be NHWC-fully packed, and must be of the type `CUDNN_DATA_HALF`.
- The tensor C dimension should be a multiple of 4.
The input parameter `mode` must be set to `CUDNN_BATCHNORM_SPATIAL_PERSISTENT`.

- `workspace` is not NULL.
- `workSpaceSizeInBytes` is equal or larger than the amount required by `cudnnGetBatchNormalizationBackwardExWorkSpaceSize()`.
- `reserveSpaceSizeInBytes` is equal or larger than the amount required by `cudnnGetBatchNormalizationTrainingExReserveSpaceSize()`.
- The content in `reserveSpace` stored by `cudnnBatchNormalizationForwardTrainingEx()` must be preserved.

If `workspace` is NULL and `workSpaceSizeInBytes` of zero is passed in, this API will function exactly like the non-extended function `cudnnBatchNormalizationBackward`. This `workspace` is not required to be clean. Moreover, the `workspace` does not have to remain unchanged between the forward and backward pass, as it is not used for passing any information.

This extended function can accept a `*workspace` pointer to the GPU workspace, and `workSpaceSizeInBytes`, the size of the workspace, from the user.

The `bnOps` input can be used to set this function to perform either only the batch normalization, or batch normalization followed by activation, or batch normalization followed by element-wise addition and then activation.

Only 4D and 5D tensors are supported. The `epsilon` value has to be the same during the training, the backpropagation, and the inference.

When the tensor layout is NCHW, higher performance can be obtained when HW-packed tensors are used for `x`, `dy`, `dx`.

**Parameters**

**handle**

*Input*. Handle to a previously created cuDNN library descriptor. For more information, see `cudnnHandle_t`.

**mode**

*Input*. Mode of operation [spatial or per-activation]. For more information, see `cudnnBatchNormMode_t`.

**bnOps**

*Input*. Mode of operation. Currently, `CUDNN_BATCHNORM_OPS_BN_ACTIVATION` and `CUDNN_BATCHNORM_OPS_BN_ADD_ACTIVATION` are only supported in the NHWC layout. For more information, see `cudnnBatchNormOps_t`. This input can be used to set this function to perform either only the batch normalization, or batch normalization followed by activation, or batch normalization followed by element-wise addition and then activation.

**alphaDataDiff, *betaDataDiff**

*Inputs*. Pointers to scaling factors [in host memory] used to blend the gradient output `dx` with a prior value in the destination tensor as follows:

```
dstValue = alpha[0]*resultValue + beta[0]*priorDstValue
```
For more information, see Scaling Parameters in the cuDNN Developer Guide.

**alphaParamDiff**, *betaParamDiff*

*Inputs.* Pointers to scaling factors (in host memory) used to blend the gradient outputs dBnScaleData and dBnBiasData with prior values in the destination tensor as follows:

dstValue = alpha[0]*resultValue + beta[0]*priorDstValue

For more information, see Scaling Parameters in the cuDNN Developer Guide.

**xDesc, *x, yDesc, *yData, dyDesc, *dyData**

*Inputs.* Tensor descriptors and pointers in the device memory for the layer’s x data, backpropagated gradient input dy, the original forward output y data. yDesc and yData are not needed if bnOps is set to CUDNN_BATCHNORM_OPS_BN, users may pass NULL. For more information, see cudnnTensorDescriptor_t.

**dzDesc, *dzData, dxDesc, *dxData**

*Outputs.* Tensor descriptors and pointers in the device memory for the computed gradient output dz, and dx. dzDesc and *dzData are not needed when bnOps is CUDNN_BATCHNORM_OPS_BN or CUDNN_BATCHNORM_OPS_BN_ACTIVATION, users may pass NULL. For more information, see cudnnTensorDescriptor_t.

**dBnScaleBiasDesc**

*Input.* Shared tensor descriptor for the following six tensors: bnScaleData, bnBiasData, dBnScaleData, dBnBiasData, savedMean, and savedInvVariance. For more information, see cudnnDeriveBNTensorDescriptor().

The dimensions for this tensor descriptor are dependent on normalization mode.

Note: The data type of this tensor descriptor must be float for FP16 and FP32 input tensors and double for FP64 input tensors.

For more information, see cudnnTensorDescriptor_t.

***bnScaleData**

*Input.* Pointer in the device memory for the batch normalization scale parameter (in the original paper the quantity scale is referred to as gamma).

***bnBiasData**

*Input.* Pointers in the device memory for the batch normalization bias parameter (in the original paper bias is referred to as beta). This parameter is used only when activation should be performed.

**dBnScaleData, dBnBiasData**

*Inputs.* Pointers in the device memory for the gradients of bnScaleData and bnBiasData, respectively.

**epsilon**

*Input.* Epsilon value used in batch normalization formula. Its value should be equal to or greater than the value defined for CUDNN_BN_MIN_EPSILON in cudnn.h. The same epsilon value should be used in forward and backward functions.
*savedMean, *savedInvVariance

**Inputs.** Optional cache parameters containing saved intermediate results computed during the forward pass. For this to work correctly, the layer's \( x \) and \( bnScaleData, bnBiasData \) data has to remain unchanged until this backward function is called. Note that both these parameters can be `NULL` but only at the same time. It is recommended to use this cache since the memory overhead is relatively small.

**activationDesc**

*Input.** Descriptor for the activation operation. When the `bnOps` input is set to either `CUDNN_BATCHNORM_OPS_BN_ACTIVATION` or `CUDNN_BATCHNORM_OPS_BN_ADD_ACTIVATION` then this activation is used, otherwise user may pass `NULL`.

**workspace**

*Input.* Pointer to the GPU workspace. If `workspace` is `NULL` and `workSpaceSizeInBytes` of zero is passed in, then this API will function exactly like the non-extended function `cudnnBatchNormalizationBackward()`,

**workSpaceSizeInBytes**

*Input.* The size of the workspace. It must be large enough to trigger the fast NHWC semi-persistent kernel by this function.

*reserveSpace*

*Input.* Pointer to the GPU workspace for the `reserveSpace`.

**reserveSpaceSizeInBytes**

*Input.* The size of the `reserveSpace`. It must be equal or larger than the amount required by `cudnnGetBatchNormalizationTrainingExReserveSpaceSize()`.

**Supported configurations**

This function supports the following combinations of data types for various descriptors.

**Table 8. Supported configurations**

<table>
<thead>
<tr>
<th>Data Type Configurations</th>
<th>xDesc, yDesc</th>
<th>dBnScaleBiasDesc</th>
<th>alphaDataDiff, betaDataDiff, alphaParamDiff</th>
<th>betaParamDiff</th>
<th>dxDesc</th>
</tr>
</thead>
<tbody>
<tr>
<td>PSEUDO_HALF_CONFIG</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_HALF</td>
<td></td>
</tr>
<tr>
<td>FLOAT_CONFIG</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td></td>
</tr>
<tr>
<td>DOUBLE_CONFIG</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
<td></td>
</tr>
</tbody>
</table>

**Returns**

**CUDNN_STATUS_SUCCESS**

The computation was performed successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.
CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- Any of the pointers alphaDataDiff, betaDataDiff, alphaParamDiff, betaParamDiff, x, dy, dx, bnScale, resultBnScaleDiff, resultBnBiasDiff is NULL.
- The number of xDesc or yDesc or dxDesc tensor descriptor dimensions is not within the range of [4, 5] (only 4D and 5D tensors are supported).
- dBnScaleBiasDesc dimensions not 1xCx1x1 for 4D and 1xCx1x1x1 for 5D for spatial, and are not 1xCxHxW for 4D and 1xCxDxHxW for 5D for per-activation mode.
- Exactly one of savedMean, savedInvVariance pointers is NULL.
- epsilon value is less than CUDNN_BN_MIN_EPSILON.
- Dimensions or data types mismatch for any pair of xDesc, dyDesc, dxDesc.

4.1.4. cudnnBatchNormalizationForwardTraining()

cudnnStatus_t cudnnBatchNormalizationForwardTraining(
    cudnnHandle_t                    handle,
    cudnnBatchNormMode_t             mode,
    const void                      *alpha,
    const void                      *beta,
    const cudnnTensorDescriptor_t    xDesc,
    const void                      *x,
    const cudnnTensorDescriptor_t    yDesc,
    void                            *y,
    const cudnnTensorDescriptor_t    bnScaleBiasMeanVarDesc,
    const void                      *bnScale,
    const void                      *bnBias,
    double                           exponentialAverageFactor,
    void                            *resultRunningMean,
    void                            *resultRunningVariance,
    double                           epsilon,
    void                            *resultSaveMean,
    void                            *resultSaveInvVariance)

This function performs the forward batch normalization layer computation for the training phase. This layer is based on the paper *Batch Normalization: Accelerating Deep Network Training by Reducing Internal Covariate Shift*, S. Ioffe, C. Szegedy, 2015.

Note:

- Only 4D and 5D tensors are supported.
- The epsilon value has to be the same during training, backpropagation, and inference.
- For the inference phase, use cudnnBatchNormalizationForwardInference.
- Higher performance can be obtained when HW-packed tensors are used for both x and y.

See cudnnDeriveBNTensorDescriptor() for the secondary tensor descriptor generation for the parameters used in this function.
Parameters

**handle**

Handle to a previously created cuDNN library descriptor. For more information, see `cudnnHandle_t`.

**mode**

Mode of operation (spatial or per-activation). For more information, see `cudnnBatchNormMode_t`.

**alpha, beta**

*Inputs*. Pointers to scaling factors (in host memory) used to blend the layer output value with prior value in the destination tensor as follows:

\[
\text{dstValue} = \alpha[0] \times \text{resultValue} + \beta[0] \times \text{priorDstValue}
\]

For more information, see Scaling Parameters in the cuDNN Developer Guide.

**xDesc, yDesc**

Tensor descriptors and pointers in device memory for the layer’s x and y data. For more information, see `cudnnTensorDescriptor_t`.

*x*

*Input*. Data pointer to GPU memory associated with the tensor descriptor xDesc, for the layer’s x input data.

*y*

*Input*. Data pointer to GPU memory associated with the tensor descriptor yDesc, for the y output of the batch normalization layer.

**bnScaleBiasMeanVarDesc**

Shared tensor descriptor desc for the secondary tensor that was derived by `cudnnDeriveBNTensorDescriptor[]`. The dimensions for this tensor descriptor are dependent on the normalization mode.

**bnScale, bnBias**

*Inputs*. Pointers in device memory for the batch normalization scale and bias parameters [in the original paper bias is referred to as beta and scale as gamma]. Note that bnBias parameter can replace the previous layer’s bias parameter for improved efficiency.

**exponentialAverageFactor**

*Input*. Factor used in the moving average computation as follows:

\[
\text{runningMean} = \text{runningMean} \times (1-\text{factor}) + \text{newMean} \times \text{factor}
\]

Use a factor=1/(1+n) at N-th call to the function to get Cumulative Moving Average (CMA) behavior such that:

\[
\text{CMA}[n] = (x[1]+...+x[n])/n
\]

This is proved below:

\[
\text{CMA}[n+1] = ((n+1) \times \text{CMA}[n]-\text{CMA}[n])/(n+1) + x[n+1]/(n+1)
\]
\[
\text{resultRunningMean} = \text{CMA}[n] \times (1 - \frac{1}{n+1}) + \text{x}[n+1] \times \frac{1}{n+1} \\
\text{resultRunningVariance} = \text{CMA}[n] \times (1 - \text{factor}) + \text{x}[n+1] \times \text{factor}
\]

**resultRunningMean, resultRunningVariance**

*Inputs/Outputs.* Running mean and variance tensors (these have the same descriptor as the bias and scale). Both of these pointers can be NULL but only at the same time. The value stored in resultRunningVariance (or passed as an input in inference mode) is the sample variance and is the moving average of \(\text{variance}[x]\) where the variance is computed either over batch or spatial+batch dimensions depending on the mode. If these pointers are not NULL, the tensors should be initialized to some reasonable values or to 0.

**epsilon**

*Input.* Epsilon value used in the batch normalization formula. Its value should be equal to or greater than the value defined for CUDNN_BN_MIN_EPSILON in cudnn.h. The same epsilon value should be used in forward and backward functions.

**resultSaveMean, resultSaveInvVariance**

*Outputs.* Optional cache to save intermediate results computed during the forward pass. These buffers can be used to speed up the backward pass when supplied to the cudnnBatchNormalizationBackward() function. The intermediate results stored in resultSaveMean and resultSaveInvVariance buffers should not be used directly by the user. Depending on the batch normalization mode, the results stored in resultSaveInvVariance may vary. For the cache to work correctly, the input layer data must remain unchanged until the backward function is called. Note that both parameters can be NULL but only at the same time. In such a case, intermediate statistics will not be saved, and cudnnBatchNormalizationBackward() will have to re-compute them. It is recommended to use this cache as the memory overhead is relatively small because these tensors have a much lower product of dimensions than the data tensors.

**Supported configurations**

This function supports the following combinations of data types for various descriptors.

**Table 9. Supported configurations**

<table>
<thead>
<tr>
<th>Data Type Configurations</th>
<th>xDesc</th>
<th>bnScaleBiasMean</th>
<th>alpha, beta</th>
<th>yDesc</th>
</tr>
</thead>
<tbody>
<tr>
<td>PSEUDO_HALF_CONFIG</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_HALF</td>
</tr>
<tr>
<td>FLOAT_CONFIG</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
</tr>
<tr>
<td>DOUBLE_CONFIG</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
</tr>
</tbody>
</table>

**Returns**

**CUDNN_STATUS_SUCCESS**

The computation was performed successfully.
CUDNN_STATUS_NOT_SUPPORTED

The function does not support the provided configuration.

CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- One of the pointers alpha, beta, x, y, bnScale, bnBias is NULL.
- The number of xDesc or yDesc tensor descriptor dimensions is not within the range of [4, 5] (only 4D and 5D tensors are supported).
- bnScaleBiasMeanVarDesc dimensions are not 1xCx1x1 for 4D and 1xCx1x1x1 for 5D for spatial, and are not 1xCxHxW for 4D and 1xCxDxHxW for 5D for per-activation mode.
- Exactly one of resultSaveMean, resultSaveInvVariance pointers are NULL.
- Exactly one of resultRunningMean, resultRunningInvVariance pointers are NULL.
- epsilon value is less than CUDNN_BN_MIN_EPSILON.
- Dimensions or data types mismatch for xDesc, yDesc.

4.1.5. cudnnBatchNormalizationForwardTrainingEx()

cudnnStatus_t cudnnBatchNormalizationForwardTrainingEx(
    cudnnHandle_t handle,
    cudnnBatchNormMode_t mode,
    cudnnBatchNormOps_t bnOps,
    const void *alpha,
    const void *beta,
    const cudnnTensorDescriptor_t xDesc,
    const void *xData,
    const cudnnTensorDescriptor_t zDesc,
    const void *zData,
    const cudnnTensorDescriptor_t yDesc,
    void *yData,
    const cudnnTensorDescriptor_t bnScaleBiasMeanVarDesc,
    const void *bnScaleData,
    const void *bnBiasData,
    double exponentialAverageFactor,
    void *resultRunningMeanData,
    void *resultRunningVarianceData,
    double epsilon,
    void *saveMean,
    void *saveInvVariance,
    const cudnnActivationDescriptor_t activationDesc,
    void *workspace,
    size_t workSpaceSizeInBytes
    void *reserveSpace
    size_t reserveSpaceSizeInBytes);

This function is an extension of the cudnnBatchNormalizationForwardTraining() for performing the forward batch normalization layer computation.

This API will trigger the new semi-persistent NHWC kernel when the following conditions are true:

- All tensors, namely, x, y, dz, dy, dx must be NHWC-fully packed and must be of the type CUDNN_DATA_HALF.
- The tensor C dimension should be a multiple of 4.
The input parameter `mode` must be set to `CUDNN_BATCHNORM_SPATIAL_PERSISTENT`.

- `workspace` is not NULL.
- `workSpaceSizeInBytes` is equal or larger than the amount required by `cudnnGetBatchNormalizationForwardTrainingExWorkspaceSize()`.
- `reserveSpaceSizeInBytes` is equal or larger than the amount required by `cudnnGetBatchNormalizationTrainingExReserveSpaceSize()`.
- The content in `reserveSpace` stored by `cudnnBatchNormalizationForwardTrainingEx()` must be preserved.

If `workspace` is NULL and `workSpaceSizeInBytes` of zero is passed in, this API will function exactly like the non-extended function `cudnnBatchNormalizationForwardTraining()`. This workspace is not required to be clean. Moreover, the workspace does not have to remain unchanged between the forward and backward pass, as it is not used for passing any information.

This extended function can accept a `workspace` pointer to the GPU workspace, and `workSpaceSizeInBytes`, the size of the workspace, from the user.

The `bnOps` input can be used to set this function to perform either only the batch normalization, or batch normalization followed by activation, or batch normalization followed by element-wise addition and then activation.

Only 4D and 5D tensors are supported. The `epsilon` value has to be the same during the training, the backpropagation, and the inference.

When the tensor layout is NCHW, higher performance can be obtained when HW-packed tensors are used for \( x, dy, dx \).

**Parameters**

**handle**

Handle to a previously created cuDNN library descriptor. For more information, see `cudnnHandle_t`.

**mode**

Mode of operation (spatial or per-activation). For more information, see `cudnnBatchNormMode_t`.

**bnOps**

Input. Mode of operation for the fast NHWC kernel. See `cudnnBatchNormOps_t`. This input can be used to set this function to perform either only the batch normalization, or batch normalization followed by activation, or batch normalization followed by element-wise addition and then activation.

**\*alpha, \*beta**

Inputs. Pointers to scaling factors (in host memory) used to blend the layer output value with prior value in the destination tensor as follows:

\[
    \text{dstValue} = \alpha[0] \times \text{resultValue} + \beta[0] \times \text{priorDstValue}
\]

For more information, see Scaling Parameters in the cuDNN Developer Guide.
Tensor descriptors and pointers in device memory for the layer’s input \( x \) and output \( y \), and for the optional \( z \) tensor input for residual addition to the result of the batch normalization operation, prior to the activation. The optional \( zDesc \) and \(*zData\) descriptors are only used when \( bnOps \) is \( \text{CUDNN\_BATCHNORM\_OPS\_BN\_ADD\_ACTIVATION} \), otherwise users may pass NULL. When in use, \( z \) should have exactly the same dimension as \( x \) and the final output \( y \). For more information, see \texttt{cudnnTensorDescriptor}.

**bnScaleBiasMeanVarDesc**

Shared tensor descriptor \( desc \) for the secondary tensor that was derived by \texttt{cudnnDeriveBNTensorDescriptor}. The dimensions for this tensor descriptor are dependent on the normalization mode.

**\*bnScaleData, \*bnBiasData**

*Inputs.* Pointers in device memory for the batch normalization scale and bias parameters (in the original paper, bias is referred to as beta and scale as gamma). Note that \( \*bnBiasData \) parameter can replace the previous layer’s bias parameter for improved efficiency.

**exponentialAverageFactor**

*Input.* Factor used in the moving average computation as follows:

\[
\text{runningMean} = \text{runningMean} \times (1 - \text{factor}) + \text{newMean} \times \text{factor}
\]

Use a \( \text{factor}=1/(1+n) \) at \( N \)-th call to the function to get Cumulative Moving Average (CMA) behavior such that:

\[
\text{CMA}[n] = (x[1]+...+x[n])/n
\]

This is proved below:

**Writing**

\[
\begin{align*}
\text{CMA}[n+1] &= (n \times \text{CMA}[n] + x[n+1])/(n+1) \\
&= (n \times \text{CMA}[n] - \text{CMA}[n])/(n+1) + x[n+1]/(n+1) \\
&= \text{CMA}[n] \times (1 - 1/(n+1)) + x[n+1]/(n+1) \\
&= \text{CMA}[n] \times (1 - \text{factor}) + x[n+1] \times \text{factor}
\end{align*}
\]

**\*resultRunningMeanData, \*resultRunningVarianceData**

*Inputs/Outputs.* Pointers to the running mean and running variance data. Both these pointers can be NULL but only at the same time. The value stored in \( \*resultRunningVarianceData \) (or passed as an input in inference mode) is the sample variance and is the moving average of \( \text{variance}[x] \) where the variance is computed either over batch or spatial+batch dimensions depending on the mode. If these pointers are not NULL, the tensors should be initialized to some reasonable values or to 0.

**epsilon**

*Input.* Epsilon value used in the batch normalization formula. Its value should be equal to or greater than the value defined for \( \text{CUDNN\_BN\_MIN\_EPSILON} \) in \texttt{cudnn.h}. The same \( \text{epsilon} \) value should be used in forward and backward functions.

**\*saveMean, \*saveInvVariance**

*Outputs.* Optional cache parameters containing saved intermediate results computed during the forward pass. For this to work correctly, the layer’s \( x \) and \( \*bnScaleData, \*bnBiasData \) data has to remain unchanged until this backward function is called. Note that...
both these parameters can be NULL but only at the same time. It is recommended to use this cache since the memory overhead is relatively small.

**activationDesc**

*Input.* The tensor descriptor for the activation operation. When the `bnOps` input is set to either `CUDNN_BATCHNORM_OPS_BN_ACTIVATION` or `CUDNN_BATCHNORM_OPS_BN_ADD_ACTIVATION` then this activation is used, otherwise user may pass NULL.

**workspace, workSpaceSizeInBytes**

*Inputs.* `workspace` is a pointer to the GPU workspace, and `workSpaceSizeInBytes` is the size of the workspace. When `workspace` is not NULL and `workSpaceSizeInBytes` is large enough, and the tensor layout is NHWC and the data type configuration is supported, then this function will trigger a new semi-persistent NHWC kernel for batch normalization. The workspace is not required to be clean. Also, the workspace does not need to remain unchanged between the forward and backward passes.

**reserveSpace**

*Input.* Pointer to the GPU workspace for the `reserveSpace`.

**reserveSpaceSizeInBytes**

*Input.* The size of the `reserveSpace`. Must be equal or larger than the amount required by `cudnnGetBatchNormalizationTrainingExReserveSpaceSize()`.

### Supported configurations

This function supports the following combinations of data types for various descriptors.

<table>
<thead>
<tr>
<th>Data Type Configurations</th>
<th>xDesc</th>
<th>bnScaleBiasMean, alpha, beta</th>
<th>zDesc</th>
<th>yDesc</th>
</tr>
</thead>
<tbody>
<tr>
<td>PSEUDO_HALF_CONFIG</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_HALF</td>
</tr>
<tr>
<td>FLOAT_CONFIG</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
</tr>
<tr>
<td>DOUBLE_CONFIG</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
</tr>
</tbody>
</table>

### Returns

**CUDNN_STATUS_SUCCESS**

The computation was performed successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- One of the pointers `alpha`, `beta`, `x`, `y`, `bnScaleData`, `bnBiasData` is NULL.
The number of xDesc or yDesc tensor descriptor dimensions is not within the [4, 5] range (only 4D and 5D tensors are supported).

bnScaleBiasMeanVarDesc dimensions are not 1xCx1x1 for 4D and 1xCx1x1x1 for 5D for spatial, and are not 1xCxHxW for 4D and 1xCxDxHxW for 5D for per-activation mode.

Exactly one of saveMean, saveInvVariance pointers are NULL.

Exactly one of resultRunningMeanData, resultRunningInvVarianceData pointers are NULL.

epsilon value is less than CUDNN_BN_MIN_EPSILON.

Dimensions or data types mismatch for xDesc, yDesc.

4.1.6. **cudnnDivisiveNormalizationBackward()**

cudnnStatus_t cudnnDivisiveNormalizationBackward(
    cudnnHandle_t                    handle,
    cudnnLRNDescriptor_t             normDesc,
    cudnnDivNormMode_t               mode,
    const void                      *alpha,
    const cudnnTensorDescriptor_t    xDesc,
    const void                      *x,
    const void                      *means,
    *dy,
    *temp,
    *temp2,
    *beta,
    const void                      *dxDesc,
    void                            *dx,
    void                            *dMeans)

This function performs the backward DivisiveNormalization layer computation.

**Note:** Supported tensor formats are NCHW for 4D and NCDHW for 5D with any non-overlapping non-negative strides. Only 4D and 5D tensors are supported.

**Parameters**

**handle**

*Input.* Handle to a previously created cuDNN library descriptor.

**normDesc**

*Input.* Handle to a previously initialized LRN parameter descriptor (this descriptor is used for both LRN and DivisiveNormalization layers).

**mode**

*Input.* DivisiveNormalization layer mode of operation. Currently only CUDNN_DIVNORM_PRECOMPUTED_MEANS is implemented. Normalization is performed using the means input tensor that is expected to be precomputed by the user.
**alpha, beta**

*Input.* Pointers to scaling factors (in host memory) used to blend the layer output value with prior value in the destination tensor as follows:

\[ \text{dstValue} = \alpha[0]*\text{resultValue} + \beta[0]*\text{priorDstValue} \]

For more information, see [Scaling Parameters](#) in the [cuDNN Developer Guide](#).

**xDesc, x, means**

*Input.* Tensor descriptor and pointers in device memory for the layer’s x and means data. Note that the means tensor is expected to be precomputed by the user. It can also contain any valid values (not required to be actual means, and can be for instance a result of a convolution with a Gaussian kernel).

**dy**

*Input.* Tensor pointer in device memory for the layer’s dy cumulative loss differential data (error backpropagation).

**temp, temp2**

*Workspace.* Temporary tensors in device memory. These are used for computing intermediate values during the backward pass. These tensors do not have to be preserved from forward to backward pass. Both use xDesc as a descriptor.

**dxDesc**

*Input.* Tensor descriptor for dx and dMeans.

**dx, dMeans**

*Output.* Tensor pointers (in device memory) for the layers resulting cumulative gradients dx and dMeans (dLoss/dx and dLoss/dMeans). Both share the same descriptor.

**Returns**

**CUDNN_STATUS_SUCCESS**

The computation was performed successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- One of the tensor pointers x, dx, temp, temp2, dy is NULL.
- Number of any of the input or output tensor dimensions is not within the [4, 5] range.
- Either alpha or beta pointer is NULL.
- A mismatch in dimensions between xDesc and dxDesc.
- LRN descriptor parameters are outside of their valid ranges.
- Any of the tensor strides is negative.
CUDNN_STATUS_UNSUPPORTED

The function does not support the provided configuration, for example, any of the input and output tensor strides mismatch (for the same dimension) is a non-supported configuration.

4.1.7. cudnnDropoutBackward()

cudnnStatus_t cudnnDropoutBackward(
    cudnnHandle_t                   handle,
    const cudnnDropoutDescriptor_t  dropoutDesc,
    const cudnnTensorDescriptor_t   dydesc,
    const void                     *dy,
    const cudnnTensorDescriptor_t   dxdesc,
    void                           *dx,
    void                           *reserveSpace,
    size_t                          reserveSpaceSizeInBytes)

This function performs backward dropout operation over dy returning results in dx. If during forward dropout operation value from x was propagated to y then during backward operation value from dy will be propagated to dx, otherwise, dx value will be set to 0.

Note: Better performance is obtained for fully packed tensors.

Parameters

handle

Input. Handle to a previously created cuDNN context.

dropoutDesc

Input. Previously created dropout descriptor object.

dyDesc

Input. Handle to a previously initialized tensor descriptor.

dy

Input. Pointer to data of the tensor described by the dyDesc descriptor.

dxDesc

Input. Handle to a previously initialized tensor descriptor.

dx

Output. Pointer to data of the tensor described by the dxDesc descriptor.

reserveSpace

Input. Pointer to user-allocated GPU memory used by this function. It is expected that reserveSpace was populated during a call to cudnnDropoutForward and has not been changed.

reserveSpaceSizeInBytes

Input. Specifies the size in bytes of the provided memory for the reserve space.
Returns

CUDNN_STATUS_SUCCESS
The call was successful.

CUDNN_STATUS_NOT_SUPPORTED
The function does not support the provided configuration.

CUDNN_STATUS_BAD_PARAM
At least one of the following conditions are met:

- The number of elements of input tensor and output tensors differ.
- The datatype of the input tensor and output tensors differs.
- The strides of the input tensor and output tensors differ and in-place operation is used (i.e., x and y pointers are equal).
- The provided reserveSpaceSizeInBytes is less then the value returned by cudnnDropoutGetReserveSpaceSize.
- cudnnSetDropoutDescriptor has not been called on dropoutDesc with the non-NULL states argument.

CUDNN_STATUS_EXECUTION_FAILED
The function failed to launch on the GPU.

4.1.8. cudnnGetBatchNormalizationBackwardExWorkspaceSize()

cudnnStatus_t cudnnGetBatchNormalizationBackwardExWorkspaceSize(
    cudnnHandle_t                       handle,
    cudnnBatchNormMode_t                mode,
    cudnnBatchNormOps_t                 bnOps,
    const cudnnTensorDescriptor_t       xDesc,
    const cudnnTensorDescriptor_t       yDesc,
    const cudnnTensorDescriptor_t       dyDesc,
    const cudnnTensorDescriptor_t       dzDesc,
    const cudnnTensorDescriptor_t       dxDesc,
    const cudnnTensorDescriptor_t       dBnScaleBiasDesc,
    const cudnnActivationDescriptor_t   activationDesc,
    size_t                              *sizeInBytes);

This function returns the amount of GPU memory workspace the user should allocate to be able to call cudnnGetBatchNormalizationBackwardExWorkspaceSize() function for the specified bnOps input setting. The workspace allocated will then be passed to the function cudnnGetBatchNormalizationBackwardExWorkspaceSize().

Parameters

handle

Input. Handle to a previously created cuDNN library descriptor. For more information, see cudnnHandle_t.
mode

*Input*. Mode of operation (spatial or per-activation). For more information, see [cudnnBatchNormMode_t](#).

bnOps

*Input*. Mode of operation for the fast NHWC kernel. For more information, see [cudnnBatchNormOps_t](#). This input can be used to set this function to perform either only the batch normalization, or batch normalization followed by activation, or batch normalization followed by element-wise addition and then activation.

xDesc, yDesc, dyDesc, dzDesc, dxDesc

Tensor descriptors and pointers in the device memory for the layer’s x data, back propagated differential dy (inputs), the optional y input data, the optional dz output, and the dx output, which is the resulting differential with respect to x. For more information, see [cudnnTensorDescriptor_t](#).

dBnScaleBiasDesc

*Input*. Shared tensor descriptor for the following six tensors: bnScaleData, bnBiasData, dBnScaleData, dBnBiasData, savedMean, and savedInvVariance. This is the shared tensor descriptor desc for the secondary tensor that was derived by [cudnnDeriveBNTensorDescriptor()](#). The dimensions for this tensor descriptor are dependent on normalization mode. Note that the data type of this tensor descriptor must be float for FP16 and FP32 input tensors, and double for FP64 input tensors.

activationDesc

*Input*. Descriptor for the activation operation. When the bnOps input is set to either CUDNN_BATCHNORM_OPS_BN_ACTIVATION or CUDNN_BATCHNORM_OPS_BN_ADD_ACTIVATION, then this activation is used, otherwise user may pass NULL.

*sizeInBytes*

*Output*. Amount of GPU memory required for the workspace, as determined by this function, to be able to execute the [cudnnGetBatchNormalizationForwardTrainingExWorkspaceSize()](#) function with the specified bnOps input setting.

**Returns**

**CUDNN_STATUS_SUCCESS**

The computation was performed successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- Number of xDesc, yDesc or dxDesc tensor descriptor dimensions is not within the range of [4, 5] (only 4D and 5D tensors are supported).
- dBnScaleBiasDesc dimensions not 1xCx1x1 for 4D and 1xCx1x1x1 for 5D for spatial, and are not 1xCxHxW for 4D and 1xCxDxHxW for 5D for per-activation mode.
- Dimensions or data types mismatch for any pair of xDesc, dyDesc, dxDesc.

### 4.1.9. `cudnnGetBatchNormalizationForwardTrainingExWorkspaceSize()`

```c
    cudnnGetBatchNormalizationForwardTrainingExWorkspaceSize(
        cudnnHandle_t                           handle,
        cudnnBatchNormMode_t                    mode,
        cudnnBatchNormOps_t                     bnOps,
        const cudnnTensorDescriptor_t           xDesc,
        const cudnnTensorDescriptor_t           zDesc,
        const cudnnTensorDescriptor_t           yDesc,
        const cudnnTensorDescriptor_t           bnScaleBiasMeanVarDesc,
        const cudnnActivationDescriptor_t       activationDesc,
        size_t                                  *sizeInBytes);
```

This function returns the amount of GPU memory workspace the user should allocate to be able to call `cudnnGetBatchNormalizationForwardTrainingExWorkspaceSize()` function for the specified `bnOps` input setting. The workspace allocated should then be passed by the user to the function `cudnnGetBatchNormalizationForwardTrainingExWorkspaceSize()`.

#### Parameters

- **handle**
  
  *Input*. Handle to a previously created cuDNN library descriptor. For more information, see `cudnnHandle_t`.

- **mode**
  
  *Input*. Mode of operation [spatial or per-activation]. For more information, see `cudnnBatchNormMode_t`.

- **bnOps**
  
  *Input*. Mode of operation for the fast NHWC kernel. For more information, see `cudnnBatchNormOps_t`. This input can be used to set this function to perform either only the batch normalization, or batch normalization followed by activation, or batch normalization followed by element-wise addition and then activation.

- **xDesc, zDesc, yDesc**
  
  Tensor descriptors and pointers in the device memory for the layer’s x data, the optional z input data, and the y output. `zDesc` is only needed when `bnOps` is `CUDNN_BATCHNORM_OPS_BN_ADD_ACTIVATION`, otherwise the user may pass NULL. For more information, see `cudnnTensorDescriptor_t`.

- **bnScaleBiasMeanVarDesc**
  
  *Input*. Shared tensor descriptor for the following six tensors: `bnScaleData`, `bnBiasData`, `dBnScaleData`, `dBnBiasData`, `savedMean`, and `savedInvVariance`. This is the shared tensor descriptor desc for the secondary tensor that was derived by `cudnnDeriveBNTensorDescriptor[]`. The dimensions for this tensor descriptor are...
dependent on normalization mode. Note that the data type of this tensor descriptor must be float for FP16 and FP32 input tensors, and double for FP64 input tensors.

**activationDesc**

*Input.* Descriptor for the activation operation. When the `bnOps` input is set to either `CUDNN_BATCHNORM_OPS_BN_ACTIVATION` or `CUDNN BATCHNORM_OPS_BN_ADD_ACTIVATION` then this activation is used, otherwise the user may pass `NULL`.

**sizeInBytes**

*Output.* Amount of GPU memory required for the workspace, as determined by this function, to be able to execute the `cudnnGetBatchNormalizationForwardTrainingExWorkspaceSize()` function with the specified `bnOps` input setting.

**Returns**

- **CUDNN_STATUS_SUCCESS**
  
  The computation was performed successfully.

- **CUDNN_STATUS_NOT_SUPPORTED**
  
  The function does not support the provided configuration.

- **CUDNN_STATUS_BAD_PARAM**
  
  At least one of the following conditions are met:
  
  - Number of `xDesc`, `yDesc` or `dxDesc` tensor descriptor dimensions is not within the range of [4, 5] (only 4D and 5D tensors are supported).
  - `dBNScaleBiasDesc` dimensions not 1xCx1x1 for 4D and 1xCx1x1x1 for 5D for spatial, and are not 1xCxHxW for 4D and 1xCxDxHxW for 5D for per-activation mode.
  - Dimensions or data types mismatch for `xDesc`, `yDesc`.

### 4.1.10. `cudnnGetBatchNormalizationTrainingExReserveSpaceSize()`

```c
int cudnnGetBatchNormalizationTrainingExReserveSpaceSize(
    cudnnHandle_t                       handle,
    cudnnBatchNormMode_t                mode,
    cudnnBatchNormOps_t                 bnOps,
    const cudnnActivationDescriptor_t   activationDesc,
    const cudnnTensorDescriptor_t       xDesc,
    size_t                              *sizeInBytes);
```

This function returns the amount of reserve GPU memory workspace the user should allocate for the batch normalization operation, for the specified `bnOps` input setting. In contrast to the workspace, the reserved space should be preserved between the forward and backward calls, and the data should not be altered.
Parameters

**handle**

*Input.* Handle to a previously created cuDNN library descriptor. For more information, see *[cudnnHandle_t]*.

**mode**

*Input.* Mode of operation [spatial or per-activation]. For more information, see *[cudnnBatchNormMode_t]*.

**bnOps**

*Input.* Mode of operation for the fast NHWC kernel. For more information, see *[cudnnBatchNormOps_t]*. This input can be used to set this function to perform either only the batch normalization, or batch normalization followed by activation, or batch normalization followed by element-wise addition and then activation.

**xDesc**

Tensor descriptors for the layer’s x data. For more information, see *[cudnnTensorDescriptor_t]*.

**activationDesc**

*Input.* Descriptor for the activation operation. When the bnOps input is set to either CUDNN_BATCHNORM_OPS_BN_ACTIVATION or CUDNN_BATCHNORM_OPS_BN_ADD_ACTIVATION then this activation is used, otherwise user may pass NULL.

**sizeInBytes**

*Output.* Amount of GPU memory reserved.

Returns

**CUDNN_STATUS_SUCCESS**

The computation was performed successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The xDesc tensor descriptor dimension is not within the [4, 5] range (only 4D and 5D tensors are supported).

### 4.1.11. **cudnnGetNormalizationBackwardWorkspaceSize()**

cudnnStatus_t

cudnnGetNormalizationBackwardWorkspaceSize(cudnnHandle_t handle,
               cudnnNormMode_t mode,
               cudnnNormOps_t normOps,
               cudnnNormAlgo_t algo,
               const cudnnTensorDescriptor_t xDesc,
               ...
This function returns the amount of GPU memory workspace the user should allocate to be able to call `cudnnNormalizationBackward()` function for the specified `normOps` and `algo` input setting. The workspace allocated will then be passed to the function `cudnnNormalizationBackward()`.

**Parameters**

**handle**

*Input*. Handle to a previously created cuDNN library descriptor. For more information, see `cudnnHandle_t`.

**mode**

*Input*. Mode of operation (per-channel or per-activation). For more information, see `cudnnNormMode_t`.

**normOps**

*Input*. Mode of post-operative. Currently CUDNN_NORM_OPS_NORM_ACTIVATION and CUDNN_NORM_OPS_NORM_ADD_ACTIVATION are only supported in the NHWC layout. For more information, see `cudnnNormOps_t`. This input can be used to set this function to perform either only the normalization, or normalization followed by activation, or normalization followed by element-wise addition and then activation.

**algo**

*Input*. Algorithm to be performed. For more information, see `cudnnNormAlgo_t`.

**xDesc, yDesc, dyDesc, dzDesc, dxDesc**

Tensor descriptors and pointers in the device memory for the layer’s x data, back propagated differential dy (inputs), the optional y input data, the optional dz output, and the dx output, which is the resulting differential with respect to x. For more information, see `cudnnTensorDescriptor_t`.

**dNormScaleBiasDesc**

*Input*. Shared tensor descriptor for the following four tensors: normScaleData, normBiasData, dNormScaleData, dNormBiasData. The dimensions for this tensor descriptor are dependent on normalization mode. Note that the data type of this tensor descriptor must be float for FP16 and FP32 input tensors, and double for FP64 input tensors.
**activationDesc**

*Input.* Descriptor for the activation operation. When the `normOps` input is set to either `CUDNN_NORM_OPS_NORM_ACTIVATION` or `CUDNN_NORM_OPS_NORM_ADD_ACTIVATION`, then this activation is used, otherwise the user may pass NULL.

**normMeanVarDesc**

*Input.* Shared tensor descriptor for the following tensors: `savedMean` and `savedInvVariance`. The dimensions for this tensor descriptor are dependent on normalization mode. Note that the data type of this tensor descriptor must be float for FP16 and FP32 input tensors, and double for FP64 input tensors.

**sizeInBytes**

*Output.* Amount of GPU memory required for the workspace, as determined by this function, to be able to execute the `cudnnGetNormalizationForwardTrainingWorkspaceSize()` function with the specified `normOps` input setting.

**groutCnt**

*Input.* Only support 1 for now.

**Returns**

**CUDNN_STATUS_SUCCESS**

The computation was performed successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- Number of `xDesc`, `yDesc` or `dxDesc` tensor descriptor dimensions is not within the range of [4,5] (only 4D and 5D tensors are supported).
- `dNormScaleBiasDesc` dimensions not `1xCx1x1` for 4D and `1xCx1x1x1` for 5D for per-channel, and are not `1xCxHxW` for 4D and `1xCxDxHxW` for 5D for per-activation mode.
- Dimensions or data types mismatch for any pair of `xDesc`, `dyDesc`, `dxDesc`.

### 4.1.12. `cudnnGetNormalizationForwardTrainingWorkspaceSize()`

cudnnStatus_t cudnnGetNormalizationForwardTrainingWorkspaceSize(cudnnHandle_t handle, cudnnNormMode_t mode, cudnnNormOps_t normOps, cudnnNormAlgo_t algo, const cudnnTensorDescriptor_t xDesc, const cudnnTensorDescriptor_t zDesc, const cudnnTensorDescriptor_t yDesc, const cudnnTensorDescriptor_t normScaleBiasDesc, ...
This function returns the amount of GPU memory workspace the user should allocate to be able to call `cudnnNormalizationForwardTraining()` function for the specified `normOps` and `algo` input setting. The workspace allocated should then be passed by the user to the function `cudnnNormalizationForwardTraining()`.

### Parameters

**handle**

*Input*. Handle to a previously created cuDNN library descriptor. For more information, see `cudnnHandle_t`.

**mode**

*Input*. Mode of operation (per-channel or per-activation). For more information, see `cudnnNormMode_t`.

**normOps**

*Input*. Mode of post-operative. Currently `CUDNN_NORM_OPS_NORM_ACTIVATION` and `CUDNN_NORM_OPS_NORM_ADD_ACTIVATION` are only supported in the NHWC layout. For more information, see `cudnnNormOps_t`. This input can be used to set this function to perform either only the normalization, or normalization followed by activation, or normalization followed by element-wise addition and then activation.

**algo**

*Input*. Algorithm to be performed. For more information, see `cudnnNormAlgo_t`.

**xDesc, zDesc, yDesc**

Tensor descriptors and pointers in the device memory for the layer’s `x` data, the optional `z` input data, and the `y` output. `zDesc` is only needed when `normOps` is `CUDNN_NORM_OPS_NORM_ADD_ACTIVATION`, otherwise the user may pass NULL. For more information, see `cudnnTensorDescriptor_t`.

**normScaleBiasDesc**

*Input*. Shared tensor descriptor for the following tensors: `normScaleData` and `normBiasData`. The dimensions for this tensor descriptor are dependent on normalization mode. Note that the data type of this tensor descriptor must be float for FP16 and FP32 input tensors, and double for FP64 input tensors.

**activationDesc**

*Input*. Descriptor for the activation operation. When the `normOps` input is set to either `CUDNN_NORM_OPS_NORM_ACTIVATION` or `CUDNN_NORM_OPS_NORM_ADD_ACTIVATION`, then this activation is used, otherwise the user may pass NULL.
**normMeanVarDesc**

*Input.* Shared tensor descriptor for the following tensors: `savedMean` and `savedInvVariance`. The dimensions for this tensor descriptor are dependent on normalization mode. Note that the data type of this tensor descriptor must be float for FP16 and FP32 input tensors, and double for FP64 input tensors.

*sizeInBytes*

*Output.* Amount of GPU memory required for the workspace, as determined by this function, to be able to execute the `cudnnGetNormalizationForwardTrainingWorkspaceSize()` function with the specified `normOps` input setting.

**groutCnt**

*Input.* Only support 1 for now.

**Returns**

**CUDNN_STATUS_SUCCESS**

The computation was performed successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- Number of xDesc, yDesc or zDesc tensor descriptor dimensions is not within the range of [4,5] (only 4D and 5D tensors are supported).
- `normScaleBiasDesc` dimensions not 1xCx1x1 for 4D and 1xCx1x1x1 for 5D for per-channel, and are not 1xCxHxW for 4D and 1xCxDxHxW for 5D for per-activation mode.
- Dimensions or data types mismatch for xDesc, yDesc.

### 4.1.13. `cudnnGetNormalizationTrainingReserveSpaceSize()`

```c
typedef cudnnStatus_t cudnnGetNormalizationTrainingReserveSpaceSize(cudnnHandle_t handle, cudnnNormMode_t mode, cudnnNormOps_t normOps, cudnnNormAlgo_t algo, const cudnnActivationDescriptor_t activationDesc, const cudnnTensorDescriptor_t xDesc, size_t *sizeInBytes, int groupCnt);
```

This function returns the amount of reserve GPU memory workspace the user should allocate for the normalization operation, for the specified `normOps` input setting. In contrast to the workspace, the reserved space should be preserved between the forward and backward calls, and the data should not be altered.
Parameters

handle

*Input*. Handle to a previously created cuDNN library descriptor. For more information, see `cudnnHandle_t`.

mode

*Input*. Mode of operation (per-channel or per-activation). For more information, see `cudnnNormMode_t`.

normOps

*Input*. Mode of post-operative. Currently `CUDNN_NORM_OPS_NORM_ACTIVATION` and `CUDNN_NORM_OPS_NORM_ADD_ACTIVATION` are only supported in the NHWC layout. For more information, see `cudnnNormOps_t`. This input can be used to set this function to perform either only the normalization, or normalization followed by activation, or normalization followed by element-wise addition and then activation.

algo

*Input*. Algorithm to be performed. For more information, see `cudnnNormAlgo_t`.

xDesc

Tensor descriptors for the layer’s x data. For more information, see `cudnnTensorDescriptor_t`.

activationDesc

*Input*. Descriptor for the activation operation. When the normOps input is set to either `CUDNN_NORM_OPS_NORM_ACTIVATION` or `CUDNN_NORM_OPS_NORM_ADD_ACTIVATION` then this activation is used, otherwise the user may pass NULL.

*sizeInBytes*

*Output*. Amount of GPU memory reserved.

groutCnt

*Input*. Only support 1 for now.

Returns

`CUDNN_STATUS_SUCCESS`

The computation was performed successfully.

`CUDNN_STATUS_NOT_SUPPORTED`

The function does not support the provided configuration.

`CUDNN_STATUS_BAD_PARAM`

At least one of the following conditions are met:
The xDesc tensor descriptor dimension is not within the [4,5] range (only 4D and 5D tensors are supported).

### 4.1.14. cudnnLRNCrossChannelBackward()

```c
#include <cudnn.h>

typedef cudnnStatus_t cudnnLRNCrossChannelBackward(
    cudnnHandle_t                    handle,
    cudnnLRNDescriptor_t             normDesc,
    cudnnLRNMode_t                   lrnMode,
    const void                      *alpha,
    const cudnnTensorDescriptor_t    yDesc,
    const void                      *y,
    const cudnnTensorDescriptor_t    dyDesc,
    const void                      *dy,
    const cudnnTensorDescriptor_t    xDesc,
    const void                      *x,
    const void                      *beta,
    const cudnnTensorDescriptor_t    dxDesc,
    void                            *dx
);
```

This function performs the backward LRN layer computation.

**Note:** Supported formats are: positive-strided, NCHW and NHWC for 4D x and y, and only NCDHW DHW-packed for 5D (for both x and y). Only non-overlapping 4D and 5D tensors are supported. NCHW layout is preferred for performance.

#### Parameters

- **handle**
  
  Input. Handle to a previously created cuDNN library descriptor.

- **normDesc**
  
  Input. Handle to a previously initialized LRN parameter descriptor.

- **lrnMode**
  
  Input. LRN layer mode of operation. Currently, only CUDNN_LRN_CROSS_CHANNEL_DIM1 is implemented. Normalization is performed along the tensor’s dimA[1].

- **alpha, beta**
  
  Input. Pointers to scaling factors (in host memory) used to blend the layer output value with prior value in the destination tensor as follows:
  
  \[
  dstValue = alpha[0]*resultValue + beta[0]*priorDstValue
  \]

  For more information, see Scaling Parameters in the cuDNN Developer Guide.

- **yDesc, y**
  
  Input. Tensor descriptor and pointer in device memory for the layer’s y data.

- **dyDesc, dy**
  
  Input. Tensor descriptor and pointer in device memory for the layer’s input cumulative loss differential data dy (including error backpropagation).
xDesc, x

Input. Tensor descriptor and pointer in device memory for the layer’s x data. Note that these values are not modified during backpropagation.

dxDesc, dx

Output. Tensor descriptor and pointer in device memory for the layer’s resulting cumulative loss differential data dx (including error backpropagation).

Returns

CUDNN_STATUS_SUCCESS

The computation was performed successfully.

CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- One of the tensor pointers x, y is NULL.
- Number of input tensor dimensions is 2 or less.
- LRN descriptor parameters are outside of their valid ranges.
- One of the tensor parameters is 5D but is not in NCDHW DHW-packed format.

CUDNN_STATUS_NOT_SUPPORTED

The function does not support the provided configuration. See the following for some examples of non-supported configurations:

- Any of the input tensor datatypes is not the same as any of the output tensor datatype.
- Any pairwise tensor dimensions mismatch for x, y, dx, dy.
- Any tensor parameters strides are negative.

4.1.15. cudnnNormalizationBackward()

cudnnStatus_t

cudnnNormalizationBackward(cudnnHandle_t handle,  
cudnnNormMode_t mode,  
cudnnNormOps_t normOps,  
cudnnNormAlgo_t algo,  
const void *alphaDataDiff,  
const void *betaDataDiff,  
const void *alphaParamDiff,  
const void *betaParamDiff,  
const cudnnTensorDescriptor_t xDesc,  
const void *xData,  
const cudnnTensorDescriptor_t yDesc,  
const void *yData,  
const cudnnTensorDescriptor_t dyDesc,  
const void *dyData,  
const cudnnTensorDescriptor_t dzDesc,  
void *dzData,  
const cudnnTensorDescriptor_t dxDesc,  
void *dxData,  
const cudnnTensorDescriptor_t dNormScaleBiasDesc,  
const void *normScaleData,
This function performs backward normalization layer computation that is specified by mode. Per-channel normalization layer is based on the paper *Batch Normalization: Accelerating Deep Network Training by Reducing Internal Covariate Shift*, S. Ioffe, C. Szegedy, 2015.

**Note:** Only 4D and 5D tensors are supported.

The `epsilon` value has to be the same during training, backpropagation, and inference. This workspace is not required to be clean. Moreover, the workspace does not have to remain unchanged between the forward and backward pass, as it is not used for passing any information.

This function can accept a `*workspace` pointer to the GPU workspace, and `workSpaceSizeInBytes`, the size of the workspace, from the user.

The `normOps` input can be used to set this function to perform either only the normalization, or normalization followed by activation, or normalization followed by element-wise addition and then activation.

When the tensor layout is NCHW, higher performance can be obtained when HW-packed tensors are used for `x`, `dy`, `dx`.

Higher performance for `CUDNN_NORM_PER_CHANNEL` mode can be obtained when the following conditions are true:

- All tensors, namely, `x`, `y`, `dz`, `dy`, and `dx` must be NHWC-fully packed, and must be of the type `CUDNN_DATA_HALF`.
- The tensor `C` dimension should be a multiple of 4.
- The input parameter `mode` must be set to `CUDNN_NORM_PER_CHANNEL`.
- The input parameter `algo` must be set to `CUDNN_NORM_ALGO_PERSIST`.
- `workspace` is not `NULL`.
- `workSpaceSizeInBytes` is equal or larger than the amount required by `cudnnGetNormalizationBackwardWorkspaceSize[]`.
- `reserveSpaceSizeInBytes` is equal or larger than the amount required by `cudnnGetNormalizationTrainingReserveSpaceSize[]`.
- The content in `reserveSpace` stored by `cudnnNormalizationForwardTraining[]` must be preserved.
Parameters

**handle**

*Input.* Handle to a previously created cuDNN library descriptor. For more information, see `cudnnHandle_t`.

**mode**

*Input.* Mode of operation (per-channel or per-activation). For more information, see `cudnnNormMode_t`.

**normOps**

*Input.* Mode of post-operative. Currently `CUDNN_NORM_OPS_NORM_ACTIVATION` and `CUDNN_NORM_OPS_NORM_ADD_ACTIVATION` are only supported in the NHWC layout. For more information, see `cudnnNormOps_t`. This input can be used to set this function to perform either only the normalization, or normalization followed by activation, or normalization followed by element-wise addition and then activation.

**algo**

*Input.* Algorithm to be performed. For more information, see `cudnnNormAlgo_t`.

**alphaDataDiff, betaDataDiff**

*Inputs.* Pointers to scaling factors (in host memory) used to blend the gradient output `dx` with a prior value in the destination tensor as follows:

\[
\text{dstValue} = \alpha[0] \times \text{resultValue} + \beta[0] \times \text{priorDstValue}
\]

For more information, see *Scaling Parameters* in the *cuDNN Developer Guide*.

**alphaParamDiff, betaParamDiff**

*Inputs.* Pointers to scaling factors (in host memory) used to blend the gradient outputs `dNormScaleData` and `dNormBiasData` with prior values in the destination tensor as follows:

\[
\text{dstValue} = \alpha[0] \times \text{resultValue} + \beta[0] \times \text{priorDstValue}
\]

For more information, see *Scaling Parameters* in the *cuDNN Developer Guide*.

**xDesc, *xData, yDesc, *yData, dyDesc, *dyData**

*Inputs.* Tensor descriptors and pointers in the device memory for the layer’s `x data`, backpropagated gradient input `dy`, the original forward output `y data`. `yDesc` and `yData` are not needed if `normOps` is set to `CUDNN_NORM_OPS_NORM`, users may pass NULL. For more information, see `cudnnTensorDescriptor_t`.

**dzDesc, *dzData, dxDesc, *dxData**

*Outputs.* Tensor descriptors and pointers in the device memory for the computed gradient output `dz` and `dx`. `dzDesc` and `*dzData` is not needed when `normOps` is `CUDNN_NORM_OPS_NORM` or `CUDNN_NORM_OPS_NORM_ACTIVATION`, users may pass NULL. For more information, see `cudnnTensorDescriptor_t`.
**dNormScaleBiasDesc**

*Input.* Shared tensor descriptor for the following six tensors: normScaleData, normBiasData, dNormScaleData, and dNormBiasData. The dimensions for this tensor descriptor are dependent on normalization mode.

Note: The data type of this tensor descriptor must be float for FP16 and FP32 input tensors and double for FP64 input tensors.

For more information, see cudnnTensorDescriptor_t.

**normScaleData**

*Input.* Pointer in the device memory for the normalization scale parameter (in the original paper the quantity scale is referred to as gamma).

**normBiasData**

*Input.* Pointers in the device memory for the normalization bias parameter (in the original paper bias is referred to as beta). This parameter is used only when activation should be performed.

**dNormScaleData, dNormBiasData**

*Inputs.* Pointers in the device memory for the gradients of normScaleData and normBiasData, respectively.

**epsilon**

*Input.* Epsilon value used in normalization formula. Its value should be equal to or greater than zero. The same epsilon value should be used in forward and backward functions.

**normMeanVarDesc**

*Input.* Shared tensor descriptor for the following tensors: savedMean and savedInvVariance. The dimensions for this tensor descriptor are dependent on normalization mode.

Note: The data type of this tensor descriptor must be float for FP16 and FP32 input tensors and double for FP64 input tensors.

For more information, see cudnnTensorDescriptor_t.

**savedMean, savedInvVariance**

*Inputs.* Optional cache parameters containing saved intermediate results computed during the forward pass. For this to work correctly, the layer's x and normScaleData, normBiasData data has to remain unchanged until this backward function is called. Note that both these parameters can be NULL but only at the same time. It is recommended to use this cache since the memory overhead is relatively small.
**activationDesc**

*Input.* Descriptor for the activation operation. When the `normOps` input is set to either `CUDNN_NORM_OPS_NORM_ACTIVATION` or `CUDNN_NORM_OPS_NORM_ADD_ACTIVATION` then this activation is used, otherwise the user may pass NULL.

**workspace**

*Input.* Pointer to the GPU workspace.

**workSpaceSizeInBytes**

*Input.* The size of the workspace. It must be large enough to trigger the fast NHWC semi-persistent kernel by this function.

**reserveSpace**

*Input.* Pointer to the GPU workspace for the `reserveSpace`.

**reserveSpaceSizeInBytes**

*Input.* The size of the `reserveSpace`. It must be equal or larger than the amount required by `cudnnGetNormalizationTrainingReserveSpaceSize()`. 

**groutCnt**

*Input.* Only support 1 for now.

**Returns**

**CUDNN_STATUS_SUCCESS**

The computation was performed successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- Any of the pointers `alphaDataDiff`, `betaDataDiff`, `alphaParamDiff`, `betaParamDiff`, `xData`, `dyData`, `dxData`, `normScaleData`, `dNormScaleData`, and `dNormBiasData` is NULL.
- The number of `xDesc` or `yDesc` or `dxDesc` tensor descriptor dimensions is not within the range of [4,5] (only 4D and 5D tensors are supported).
- `dNormScaleBiasDesc` dimensions not 1xCx1x1 for 4D and 1xCx1x1x1 for 5D for per-channel, and are not 1xCxHxW for 4D and 1xCxDxHxW for 5D for per-activation mode.
- Exactly one of `savedMean`, `savedInvVariance` pointers is NULL.
- `epsilon` value is less than zero.
- Dimensions or data types mismatch for any pair of `xDesc`, `dyDesc`, `dxDesc`, `dNormScaleBiasDesc`, and `normMeanVarDesc`. 
4.1.16. **cudnnNormalizationForwardTraining()**

```c
const void *alpha,
const void *beta,
const cudnnTensorDescriptor_t xDesc,
const void *xData,
const cudnnTensorDescriptor_t normScaleBiasDesc,
const void *normScale,
const void *normBias,
double exponentialAverageFactor,
const cudnnTensorDescriptor_t normMeanVarDesc,
void *resultRunningMean,
void *resultRunningVariance,
double epsilon,
void *resultSaveMean,
void *resultSaveInvVariance,
void *activationDesc,
const cudnnTensorDescriptor_t zDesc,
void *zData,
const cudnnTensorDescriptor_t yDesc,
void *yData,
void *workspace,
size_t workSpaceSizeInBytes,
void *reserveSpace,
size_t reserveSpaceSizeInBytes,
int groupCnt);
```

This function performs the forward normalization layer computation for the training phase. Depending on mode, different normalization operations will be performed. Per-channel layer is based on the paper [Batch Normalization: Accelerating Deep Network Training by Reducing Internal Covariate Shift, S. Ioffe, C. Szegedy, 2015](https://arxiv.org/abs/1502.03167).

**Note:**
- Only 4D and 5D tensors are supported.
- The `epsilon` value has to be the same during training, back propagation, and inference.
- For the inference phase, use `cudnnNormalizationForwardInference()`.  
- Higher performance can be obtained when HW-packed tensors are used for both x and y.

This API will trigger the new semi-persistent NHWC kernel when the following conditions are true:
- All tensors, namely, xData, yData must be NHWC-fully packed and must be of the type `CUDNN_DATA_HALF`.
- The tensor C dimension should be a multiple of 4.
- The input parameter mode must be set to `CUDNN_NORM_PER_CHANNEL`.
- The input parameter algo must be set to `CUDNN_NORM_ALGO_PERSIST`.
- `workspace` is not `NULL`.
- `workSpaceSizeInBytes` is equal or larger than the amount required by `cudnnGetNormalizationForwardTrainingWorkspaceSize()`.
- `reserveSpaceSizeInBytes` is equal or larger than the amount required by `cudnnGetNormalizationTrainingReserveSpaceSize()`.
- The content in `reserveSpace` stored by `cudnnNormalizationForwardTraining()` must be preserved.

This workspace is not required to be clean. Moreover, the workspace does not have to remain unchanged between the forward and backward pass, as it is not used for passing any information. This extended function can accept a `workspace` pointer to the GPU workspace, and `workSpaceSizeInBytes`, the size of the workspace, from the user.

The `normOps` input can be used to set this function to perform either only the normalization, or normalization followed by activation, or normalization followed by element-wise addition and then activation.

Only 4D and 5D tensors are supported. The `epsilon` value has to be the same during the training, the backpropagation, and the inference.

When the tensor layout is NCHW, higher performance can be obtained when HW-packed tensors are used for `xData`, `yData`.

### Parameters

**handle**

*Input.* Handle to a previously created cuDNN library descriptor. For more information, see `cudnnHandle_t`.

**mode**

*Input.* Mode of operation (per-channel or per-activation). For more information, see `cudnnNormMode_t`.

**normOps**

*Input.* Mode of post-operative. Currently `CUDNN_NORM_OPS_NORM_ACTIVATION` and `CUDNN_NORM_OPS_NORM_ADD_ACTIVATION` are only supported in the NHWC layout. For more information, see `cudnnNormOps_t`. This input can be used to set this function to perform either only the normalization, or normalization followed by activation, or normalization followed by element-wise addition and then activation.

**algo**

*Input.* Algorithm to be performed. For more information, see `cudnnNormAlgo_t`.

**alpha, beta**

*Inputs.* Pointers to scaling factors (in host memory) used to blend the layer output value with prior value in the destination tensor as follows: $dstValue = alpha[0]\cdot resultValue + beta[0]\cdot priorDstValue$

For more information, see Scaling Parameters in the cuDNN Developer Guide.

**xDesc, yDesc**

*Input.* Handles to the previously initialized tensor descriptors.
**xData**

*Input.* Data pointer to GPU memory associated with the tensor descriptor xDesc, for the layer’s x input data.

**yData**

*Output.* Data pointer to GPU memory associated with the tensor descriptor yDesc, for the y output of the normalization layer.

zDesc, *zData*

*Input.* Tensor descriptors and pointers in device memory for residual addition to the result of the normalization operation, prior to the activation. zDesc and *zData are optional and are only used when normOps is CUDNN_NORM_OPS_NORM_ADD_ACTIVATION, otherwise the user may pass NULL. When in use, z should have exactly the same dimension as xData and the final output yData. For more information, see cudnnTensorDescriptor_t.

normScaleBiasDesc, normScale, normBias

*Inputs.* Tensor descriptors and pointers in device memory for the normalization scale and bias parameters (in the original paper bias is referred to as beta and scale as gamma). The dimensions for the tensor descriptor are dependent on the normalization mode.

**exponentialAverageFactor**

*Input.* Factor used in the moving average computation as follows:

$$
\text{runningMean} = \text{runningMean} \times (1-\text{factor}) + \text{newMean} \times \text{factor}
$$

Use a factor $= \frac{1}{1+n}$ at $N$-th call to the function to get Cumulative Moving Average (CMA) behavior such that:

$$
\text{CMA}[n] = \frac{(x[1]+...+x[n])}{n}
$$

This is proved below:

Writing

$$
\text{CMA}[n+1] = \frac{(n \times \text{CMA}[n]+x[n+1])}{n+1}
$$

$= \frac{(n+1) \times \text{CMA}[n]-\text{CMA}[n]}{n+1} + x[n+1]/(n+1)$

$= \text{CMA}[n] \times (\frac{1}{n+1}) + x[n+1] \times \text{factor}$

normMeanVarDesc

*Inputs.* Tensor descriptor used for following tensors: resultRunningMean, resultRunningVariance, resultSaveMean, resultSaveInvVariance.

*resultRunningMean, *resultRunningVariance*

*Inputs/Outputs.* Pointers to the running mean and running variance data. Both these pointers can be NULL but only at the same time. The value stored in resultRunningVariance (or passed as an input in inference mode) is the sample variance and is the moving average of variance[x] where the variance is computed either over batch or spatial+batch dimensions depending on the mode. If these pointers are not NULL, the tensors should be initialized to some reasonable values or to 0.
epsilon

Input. Epsilon value used in the normalization formula. Its value should be equal to or greater than zero.

*resultSaveMean, *resultSaveInvVariance

Outputs. Optional cache parameters containing saved intermediate results computed during the forward pass. For this to work correctly, the layer's $x$ and $\text{normScale}$, $\text{normBias}$ data has to remain unchanged until this backward function is called. Note that both these parameters can be NULL but only at the same time. It is recommended to use this cache since the memory overhead is relatively small.

activationDesc

Input. The tensor descriptor for the activation operation. When the $\text{normOps}$ input is set to either CUDNN_NORM_OPS_NORM_ACTIVATION or CUDNN_NORM_OPS_NORM_ADD_ACTIVATION then this activation is used, otherwise the user may pass NULL.

*workspace, workSpaceSizeInBytes

Inputs. *workspace is a pointer to the GPU workspace, and workSpaceSizeInBytes is the size of the workspace. When *workspace is not NULL and *workSpaceSizeInBytes is large enough, and the tensor layout is NHWC and the data type configuration is supported, then this function will trigger a semi-persistent NHWC kernel for normalization. The workspace is not required to be clean. Also, the workspace does not need to remain unchanged between the forward and backward passes.

*reserveSpace

Input. Pointer to the GPU workspace for the reserveSpace.

reserveSpaceSizeInBytes

Input. The size of the reserveSpace. Must be equal or larger than the amount required by cudnnGetNormalizationTrainingReserveSpaceSize()i.

groutCnt

Input. Only support 1 for now.

Returns

CUDNN_STATUS_SUCCESS

The computation was performed successfully.

CUDNN_STATUS_NOT_SUPPORTED

The function does not support the provided configuration.

CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- One of the pointers alpha, beta, xData, yData, normScale, and normBias is NULL.
- The number of `xDesc` or `yDesc` tensor descriptor dimensions is not within the \([4,5]\) range (only 4D and 5D tensors are supported).
- `normScaleBiasDesc` dimensions are not \(1\times\text{C}\times1\times1\) for 4D and \(1\times\text{C}\times1\times1\times1\) for 5D for per-channel mode, and are not \(1\times\text{C}\times\text{H}\times\text{W}\) for 4D and \(1\times\text{C}\times\text{D}\times\text{H}\times\text{W}\) for 5D for per-activation mode.
- Exactly one of `resultSaveMean`, `resultSaveInvVariance` pointers are NULL.
- Exactly one of `resultRunningMean`, `resultRunningInvVariance` pointers are NULL.
- `epsilon` value is less than zero.
- Dimensions or data types mismatch for `xDesc`, `yDesc`.

### 4.1.17. cudnnOpsTrainVersionCheck()

```c
cudnnStatus_t cudnnOpsTrainVersionCheck(void)
```

This function checks whether the version of the OpsTrain subset of the library is consistent with the other sub-libraries.

**Returns**

- **CUDNN_STATUS_SUCCESS**
  - The version is consistent with other sub-libraries.
- **CUDNN_STATUS_VERSION_MISMATCH**
  - The version of OpsTrain is not consistent with other sub-libraries. Users should check the installation and make sure all sub-component versions are consistent.

### 4.1.18. cudnnPoolingBackward()

```c
cudnnStatus_t cudnnPoolingBackward(
    cudnnHandle_t                      handle,
    const cudnnPoolingDescriptor_t     poolingDesc,
    const void                         *alpha,
    const cudnnTensorDescriptor_t      yDesc,
    const void                         *y,
    const cudnnTensorDescriptor_t      dyDesc,
    const void                         *dy,
    const cudnnTensorDescriptor_t      xDesc,
    const void                         *xData,
    const void                         *beta,
    const cudnnTensorDescriptor_t      dxDesc,
    void                               *dx)
```

This function computes the gradient of a pooling operation.

As of cuDNN version 6.0, a deterministic algorithm is implemented for max backwards pooling. This algorithm can be chosen via the pooling mode enum of `poolingDesc`. The deterministic algorithm has been measured to be up to 50% slower than the legacy max backwards pooling algorithm, or up to 20% faster, depending upon the use case.

*Note: All tensor formats are supported, best performance is expected when using HW-packed tensors. Only 2 and 3 spatial dimensions are allowed.*
Parameters

handle

*Input*. Handle to a previously created cuDNN context.

poolingDesc

*Input*. Handle to the previously initialized pooling descriptor.

alpha, beta

*Input*. Pointers to scaling factors (in host memory) used to blend the computation result with prior value in the output layer as follows:

\[
\text{dstValue} = \alpha[0] \times \text{resultValue} + \beta[0] \times \text{priorDstValue}
\]

For more information, see Scaling Parameters in the cuDNN Developer Guide.

yDesc

*Input*. Handle to the previously initialized input tensor descriptor.

y

*Input*. Data pointer to GPU memory associated with the tensor descriptor yDesc.

dyDesc

*Input*. Handle to the previously initialized input differential tensor descriptor.

dy

*Input*. Data pointer to GPU memory associated with the tensor descriptor dyData.

xDesc

*Input*. Handle to the previously initialized output tensor descriptor.

x

*Input*. Data pointer to GPU memory associated with the output tensor descriptor xDesc.

dxDesc

*Input*. Handle to the previously initialized output differential tensor descriptor.

dx

*Output*. Data pointer to GPU memory associated with the output tensor descriptor dxDesc.

Returns

CUDNN_STATUS_SUCCESS

The function launched successfully.

CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- The dimensions \(n, c, h, w\) of the yDesc and dyDesc tensors differ.
The strides nStride, cStride, hStride, wStride of the yDesc and dyDesc tensors differ.

- The dimensions n, c, h, w of the dxDesc and dxDesc tensors differ.
- The strides nStride, cStride, hStride, wStride of the xDesc and dxDesc tensors differ.
- The datatype of the four tensors differ.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration. See the following for some examples of non-supported configurations:

- The wStride of input tensor or output tensor is not 1.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

### 4.1.19. `cudnnSoftmaxBackward()`

```c
void cudnnSoftmaxBackward(cuDNNHandle_t handle, cudnnSoftmaxAlgorithm_t algorithm, cudnnSoftmaxMode_t mode, const float *alpha, const cudnnTensorDescriptor_t yDesc, const void *yData, const cudnnTensorDescriptor_t dyDesc, const void *dy, const void *beta, const cudnnTensorDescriptor_t dxDesc, void *dx)
```

This routine computes the gradient of the softmax function.

**Note:**

- In-place operation is allowed for this routine; meaning, dy and dx pointers may be equal. However, this requires dyDesc and dxDesc descriptors to be identical (particularly, the strides of the input and output must match for in-place operation to be allowed).
- All tensor formats are supported for all modes and algorithms with 4 and 5D tensors. Performance is expected to be highest with NCHW fully-packed tensors. For more than 5 dimensions tensors must be packed in their spatial dimensions.

**Parameters**

- **handle**
  
  `Input`. Handle to a previously created cuDNN context.

- **algorithm**
  
  `Input`. Enumerator to specify the softmax algorithm.
mode
   Input. Enumerant to specify the softmax mode.

alpha, beta
   Input. Pointers to scaling factors (in host memory) used to blend the computation result with prior value in the output layer as follows:
   \[
   \text{dstValue} = \alpha[0] \cdot \text{result} + \beta[0] \cdot \text{priorDstValue}
   \]
   For more information, see the Scaling Parameters section in the cuDNN Developer Guide.

yDesc
   Input. Handle to the previously initialized input tensor descriptor.

y
   Input. Data pointer to GPU memory associated with the tensor descriptor yDesc.

dyDesc
   Input. Handle to the previously initialized input differential tensor descriptor.

dy
   Input. Data pointer to GPU memory associated with the tensor descriptor dyData.

dxDesc
   Input. Handle to the previously initialized output differential tensor descriptor.

dx
   Output. Data pointer to GPU memory associated with the output tensor descriptor dxDesc.

Returns

CUDNN_STATUS_SUCCESS
   The function launched successfully.

CUDNN_STATUS_NOT_SUPPORTED
   The function does not support the provided configuration.

CUDNN_STATUS_BAD_PARAM
   At least one of the following conditions are met:
   ▶ The dimensions n, c, h, w of the yDesc, dyDesc and dxDesc tensors differ.
   ▶ The strides nStride, cStride, hStride, wStride of the yDesc and dyDesc tensors differ.
   ▶ The datatype of the three tensors differs.

CUDNN_STATUS_EXECUTION_FAILED
   The function failed to launch on the GPU.
4.1.20. cudnnSpatialTfGridGeneratorBackward()

cudnnStatus_t cudnnSpatialTfGridGeneratorBackward(
    cudnnHandle_t                               handle,
    const cudnnSpatialTransformerDescriptor_t   stDesc,
    const void                                 *dgrid,
    void                                       *dtheta)

This function computes the gradient of a grid generation operation.

Note: Only 2d transformation is supported.

Parameters

handle

Input. Handle to a previously created cuDNN context.

stDesc

Input. Previously created spatial transformer descriptor object.

dgrid

Input. Data pointer to GPU memory contains the input differential data.

dtheta

Output. Data pointer to GPU memory contains the output differential data.

Returns

CUDNN_STATUS_SUCCESS

The call was successful.

CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- handle is NULL.
- One of the parameters dgrid or dtheta is NULL.

CUDNN_STATUS_NOT_SUPPORTED

The function does not support the provided configuration. See the following for some examples of non-supported configurations:

- The dimension of the transformed tensor specified in stDesc > 4.

CUDNN_STATUS_EXECUTION_FAILED

The function failed to launch on the GPU.
4.1.21. cudnnSpatialTfSamplerBackward()

This function computes the gradient of a sampling operation.

Note: Only 2d transformation is supported.

Parameters

handle

*Input*. Handle to a previously created cuDNN context.

stDesc

*Input*. Previously created spatial transformer descriptor object.

alpha, beta

*Input*. Pointers to scaling factors (in host memory) used to blend the source value with prior value in the destination tensor as follows:

dstValue = alpha[0]*srcValue + beta[0]*priorDstValue

For more information, see the Scaling Parameters section in the cuDNN Developer Guide.

xDesc

*Input*. Handle to the previously initialized input tensor descriptor.

x

*Input*. Data pointer to GPU memory associated with the tensor descriptor xDesc.

dxDesc

*Input*. Handle to the previously initialized output differential tensor descriptor.

dx

*Output*. Data pointer to GPU memory associated with the output tensor descriptor dxDesc.
alphaDgrid, betaDgrid

**Input.** Pointers to scaling factors (in host memory) used to blend the gradient outputs dgrid with prior value in the destination pointer as follows:

\[
\text{dstValue} = \alpha[0] \times \text{srcValue} + \beta[0] \times \text{priorDstValue}
\]

For more information, see the Scaling Parameters section in the cuDNN Developer Guide.

dyDesc

**Input.** Handle to the previously initialized input differential tensor descriptor.

dy

**Input.** Data pointer to GPU memory associated with the tensor descriptor dyDesc.

grid

**Input.** A grid of coordinates generated by cudnnSpatialTfGridGeneratorForward().

dgrid

**Output.** Data pointer to GPU memory contains the output differential data.

**Returns**

**CUDNN_STATUS_SUCCESS**

The call was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- handle is NULL.
- One of the parameters x, dx, y, dy, grid, dgrid is NULL.
- The dimension of dy differs from those specified in stDesc.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration. See the following for some examples of non-supported configurations:

- The dimension of transformed tensor > 4.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.
5.1. Data Type References

5.1.1. Pointer To Opaque Struct Types

5.1.1.1. cudnnConvolutionDescriptor_t

cudnnConvolutionDescriptor_t is a pointer to an opaque structure holding the description of a convolution operation. cudnnCreateConvolutionDescriptor() is used to create one instance, and cudnnSetConvolutionNdDescriptor() or cudnnSetConvolution2dDescriptor() must be used to initialize this instance.

5.1.2. Struct Types

5.1.2.1. cudnnConvolutionBwdDataAlgoPerf_t

cudnnConvolutionBwdDataAlgoPerf_t is a structure containing performance results returned by cudnnFindConvolutionBackwardDataAlgorithm() or heuristic results returned by cudnnGetConvolutionBackwardDataAlgorithm_v7().

Data Members

cudnnConvolutionBwdDataAlgo_t algo

The algorithm runs to obtain the associated performance metrics.

cudnnStatus_t status

If any error occurs during the workspace allocation or timing of cudnnConvolutionBackwardData[], this status will represent that error. Otherwise, this status will be the return status of cudnnConvolutionBackwardData[].
- **CUDNN_STATUS_ALLOC_FAILED** if any error occurred during workspace allocation or if the provided workspace is insufficient.
- **CUDNN_STATUS_INTERNAL_ERROR** if any error occurred during timing calculations or workspace deallocation.
- Otherwise, this will be the return status of `cudnnConvolutionBackwardData()`.

**float time**

The execution time of `cudnnConvolutionBackwardData()` (in milliseconds).

**size_t memory**

The workspace size (in bytes).

**cudnnDeterminism_t determinism**

The determinism of the algorithm.

**cudnnMathType_t mathType**

The math type provided to the algorithm.

**int reserved[3]**

Reserved space for future properties.

### 5.1.2.2. `cudnnConvolutionFwdAlgoPerf_t`

`cudnnConvolutionFwdAlgoPerf_t` is a structure containing performance results returned by `cudnnFindConvolutionForwardAlgorithm()` or heuristic results returned by `cudnnGetConvolutionForwardAlgorithm_v7()`.

**Data Members**

- **cudnnConvolutionFwdAlgo_t algo**
  
  The algorithm runs to obtain the associated performance metrics.

- **cudnnStatus_t status**
  
  If any error occurs during the workspace allocation or timing of `cudnnConvolutionForward()`, this status will represent that error. Otherwise, this status will be the return status of `cudnnConvolutionForward()`.
  
  - **CUDNN_STATUS_ALLOC_FAILED** if any error occurred during workspace allocation or if the provided workspace is insufficient.
  
  - **CUDNN_STATUS_INTERNAL_ERROR** if any error occurred during timing calculations or workspace deallocation.
  
  - Otherwise, this will be the return status of `cudnnConvolutionForward()`.

- **float time**
  
  The execution time of `cudnnConvolutionForward()` (in milliseconds).
size_t memory

The workspace size (in bytes).

cudnnDeterminism_t determinism

The determinism of the algorithm.

cudnnMathType_t mathType

The math type provided to the algorithm.

int reserved[3]

Reserved space for future properties.

5.1.3. Enumeration Types

5.1.3.1. cudnnBackendAttributeName_t

cudnnBackendAttributeName_t is an enumerated type that indicates the backend descriptor attributes that can be set or get via cudnnBackendSetAttribute() and cudnnBackendGetAttribute() functions. The backend descriptor to which an attribute belongs is identified by the prefix of the attribute name.

typedef enum {
    CUDNN_ATTR_POINTWISE_MODE = 0,
    CUDNN_ATTR_POINTWISE_MATH_PREC = 1,
    CUDNN_ATTR_POINTWISE_NAN_PROPAGATION = 2,
    CUDNN_ATTR_POINTWISE_RELU_LOWER_CLIP = 3,
    CUDNN_ATTR_POINTWISE_RELU_UPPER_CLIP = 4,
    CUDNN_ATTR_CONVOLUTION_COMP_TYPE = 100,
    CUDNN_ATTR_CONVOLUTION_CONV_MODE = 101,
    CUDNN_ATTR_CONVOLUTION_DILATIONS = 102,
    CUDNN_ATTR_CONVOLUTION_FILTER_STRIDES = 103,
    CUDNN_ATTR_CONVOLUTION_POST_PADDINGS = 104,
    CUDNN_ATTR_CONVOLUTION_PRE_PADDINGS = 105,
    CUDNN_ATTR_CONVOLUTION_SPATIAL_DIMS = 106,
    CUDNN_ATTR_ENGINEHEUR_MODE = 200,
    CUDNN_ATTR_ENGINEHEUR_OPERATION_GRAPH = 201,
    CUDNN_ATTR_ENGINEHEUR_RESULTS = 202,
    CUDNN_ATTR_ENGINECFG_ENGINE = 300,
    CUDNN_ATTR_ENGINECFG_INTERMEDIATE_INFO = 301,
    CUDNN_ATTR_ENGINECFG_KNOB_CHOICES = 302,
    CUDNN_ATTR_EXECUTION_PLAN_HANDLE = 400,
    CUDNN_ATTR_EXECUTION_PLAN_ENGINE_CONFIG = 401,
    CUDNN_ATTR_EXECUTION_PLAN_WORKSPACE_SIZE = 402,
    CUDNN_ATTR_EXECUTION_PLAN_COMPUTED_INTERMEDIATE_UIDS = 403,
    CUDNN_ATTR_EXECUTION_PLAN_RUN_ONLY_INTERMEDIATE_UIDS = 404,
    CUDNN_ATTR_INTERMEDIATE_INFO_UNIQUE_ID = 500,
    CUDNN_ATTR_INTERMEDIATE_INFO_SIZE = 501,
    CUDNN_ATTR_INTERMEDIATE_INFO_DEPENDENT_DATA_UIDS = 502,
    CUDNN_ATTR_INTERMEDIATE_INFO_DEPENDENT_ATTRIBUTES = 503,
    CUDNN_ATTR_KNOB_CHOICE_KNOB_TYPE = 600,
    CUDNN_ATTR_KNOB_CHOICE_KNOB_VALUE = 601,
    CUDNN_ATTR_OPERATION_CONVOLUTION_FORWARD_ALPHA = 700,
} cudnnBackendAttributeName_t;
### cudnnBackendAttributeName_t

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<th>Attribute Name</th>
<th>Value</th>
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<td>CUDNN_ATTR_TENSOR_VECTORIZED_DIMENSION</td>
<td>905</td>
</tr>
<tr>
<td>CUDNN_ATTR_TENSOR_UNIQUE_ID</td>
<td>906</td>
</tr>
<tr>
<td>CUDNN_ATTR_TENSOR_IS_VIRTUAL</td>
<td>907</td>
</tr>
<tr>
<td>CUDNN_ATTR_VARIANT_PACK_UNIQUE_IDS</td>
<td>1000</td>
</tr>
<tr>
<td>CUDNN_ATTR_VARIANT_PACK_DATA_POINTERS</td>
<td>1001</td>
</tr>
<tr>
<td>CUDNN_ATTR_VARIANT_PACK_INTERMEDIATES</td>
<td>1002</td>
</tr>
<tr>
<td>CUDNN_ATTR_VARIANT_PACK_WORKSPACE</td>
<td>1003</td>
</tr>
<tr>
<td>CUDNN_ATTR_LAYOUT_INFO_TENSOR_UID</td>
<td>1100</td>
</tr>
<tr>
<td>CUDNN_ATTR_LAYOUT_INFO_TYPES</td>
<td>1101</td>
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<tr>
<td>CUDNN_ATTR_KNOB_INFO_TYPE</td>
<td>1200</td>
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<tr>
<td>CUDNN_ATTR_KNOB_INFO_MAXIMUM_VALUE</td>
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<tr>
<td>CUDNN_ATTR_KNOB_INFO_MINIMUM_VALUE</td>
<td>1202</td>
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<tr>
<td>CUDNN_ATTR_KNOB_INFO_STRIDE</td>
<td>1203</td>
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<tr>
<td>CUDNN_ATTR_ENGINE_OPERATION_GRAPH</td>
<td>1300</td>
</tr>
<tr>
<td>CUDNN_ATTR_ENGINE_GLOBAL_INDEX</td>
<td>1301</td>
</tr>
<tr>
<td>CUDNN_ATTR_ENGINE_KNOB_INFO</td>
<td>1302</td>
</tr>
<tr>
<td>CUDNN_ATTR_ENGINE_NUMERICAL_NOTE</td>
<td>1303</td>
</tr>
<tr>
<td>CUDNN_ATTR_ENGINE_LAYOUT_INFO</td>
<td>1304</td>
</tr>
</tbody>
</table>

#### 5.1.3.2. cudnnBackendAttributeType_t
cudnnBackendAttributeType_t is an enumerated type that indicates type of backend descriptor attributes that can be set and get via cudnnBackendSetAttribute() and cudnnBackendGetAttribute() functions.

typedef enum {
    CUDNN_TYPE_HANDLE = 0,
    CUDNN_TYPE_DATA_TYPE,
    CUDNN_TYPE_BOOLEAN,
    CUDNN_TYPE_INT64,
    CUDNN_TYPE_FLOAT,
    CUDNN_TYPE_DOUBLE,
    CUDNN_TYPE_VOID_PTR,
    CUDNN_TYPE_CONVOLUTION_MODE,
    CUDNN_TYPE_HEUR_MODE,
    CUDNN_TYPE_KNOB_TYPE,
    CUDNN_TYPE_NAN_PROPAGATION,
    CUDNN_TYPE_NUMERICAL_NOTE,
    CUDNN_TYPE_LAYOUT_TYPE,
    CUDNN_TYPE_ATTRIB_NAME,
    CUDNN_TYPE_POINTWISE_MODE,
    CUDNN_TYPE_BACKEND_DESCRIPTOR,
    CUDNN_TYPE_GENSTATS_MODE
} cudnnBackendAttributeType_t;

5.1.3.3. cudnnBackendDescriptorType_t

cudnnBackendDescriptor_t is an enumerated type that indicates type of backend descriptors. Users create a backend descriptor of a particular type by passing a value from this enumerate to cudnnBackendCreateDescriptor() function.

typedef enum {
    CUDNN_BACKEND_POINTWISE_DESCRIPTOR = 0,
    CUDNN_BACKEND_CONVOLUTION_DESCRIPTOR,
    CUDNN_BACKEND_ENGINE_DESCRIPTOR,
    CUDNN_BACKEND_ENGINECFG_DESCRIPTOR,
    CUDNN_BACKEND_ENGINEHEUR_DESCRIPTOR,
    CUDNN_BACKEND_EXECUTION_PLAN_DESCRIPTOR,
    CUDNN_BACKEND_INTERMEDIATE_INFO_DESCRIPTOR,
    CUDNN_BACKEND_KNOB_CHOICE_DESCRIPTOR,
    CUDNN_BACKEND_KNOB_INFO_DESCRIPTOR,
    CUDNN_BACKEND_LAYOUT_INFO_DESCRIPTOR,
    CUDNN_BACKEND_OPERATION_CONVOLUTION_FORWARD_DESCRIPTOR,
    CUDNN_BACKEND_OPERATION_CONVOLUTION_BACKWARD_FILTER_DESCRIPTOR,
    CUDNN_BACKEND_OPERATION_CONVOLUTION_BACKWARD_DATA_DESCRIPTOR,
    CUDNN_BACKEND_OPERATION_POINTWISE_DESCRIPTOR,
    CUDNN_BACKEND_OPERATION_GENSTATS_DESCRIPTOR,
    CUDNN_BACKEND_OPERATIONGRAPH_DESCRIPTOR,
    CUDNN_BACKEND_VARIANT_PACK_DESCRIPTOR,
    CUDNN_BACKEND_TENSOR_DESCRIPTOR
} cudnnBackendDescriptorType_t;

5.1.3.4. cudnnBackendHeurMode_t

cudnnBackendHeurMode_t is an enumerated type that indicates the operation mode of a CUDNN_BACKEND_ENGINE_HEUR_DESCRIPTOR.

typedef enum {
    CUDNN_HEUR_MODE_INSTANT = 0
}

5.1.3.5. cudnnBackendKnobType_t
cudnnBackendKnobType_t is an enumerated type that indicates the type of performance knobs. Performance knobs are runtime settings to an engine that will affect its performance. Users can query for an array of performance knobs and their valid value range from a cudnn_BACKEND_ENGINE_DESCRIPTOR using cudnnBackendGetAttribute() function. Users can set the choice for each knob using the cudnnBackendSetAttribute() function with a cudnn_BACKEND_KNOB_CHOICE_DESCRIPTOR descriptor.

typedef enum {
    CUDNN_KNOB_TYPE_SPLIT_K = 0,
    CUDNN_KNOB_TYPE_SWIZZLE = 1,
    CUDNN_KNOB_TYPE_TILE_SIZE = 2,
    CUDNN_KNOB_TYPE_USE_TEX = 3,
    CUDNN_KNOB_TYPE_EDGE = 4,
    CUDNN_KNOB_TYPE_KBLOCK = 5,
    CUDNN_KNOB_TYPE_LDG = 6,
    CUDNN_KNOB_TYPE_LDG = 7,
    CUDNN_KNOB_TYPE_CHUNK_K = 8,
    CUDNN_KNOB_TYPE_SPLIT_H = 9,
    CUDNN_KNOB_TYPE_WINO_TILE = 10,
    CUDNN_KNOB_TYPE_MULTIPLY = 11,
    CUDNN_KNOB_TYPE_SPLIT_K_BUF = 12,
    CUDNN_KNOB_TYPE_TILEK = 13,
    CUDNN_KNOB_TYPE_STAGES = 14,
    CUDNN_KNOB_TYPE_REDUCTION_MODE = 15,
    CUDNN_KNOB_TYPE_CTA_SPLIT_K_MODE = 16,
    CUDNN_KNOB_TYPE_SPLIT_K_SLC = 17,
    CUDNN_KNOB_TYPEIDX_MODE = 18,
    CUDNN_KNOB_TYPE_SLCED = 19,
    CUDNN_KNOB_TYPE_SPLIT_RS = 20,
    CUDNN_KNOB_TYPE_SINGLEBUFFER = 21,
    CUDNN_KNOB_TYPE_LDG = 22,
    CUDNN_KNOB_TYPE_SPEC_FILT = 23,
    CUDNN_KNOB_TYPE_COUNTS = 24,
} cudnnBackendKnobType_t;

5.1.3.6. cudnnBackendLayoutType_t

cudnnBackendLayoutType_t is an enumerated type that indicates queryable layout requirements of an engine. Users can query for layout requirements from a cudnn_BACKEND_ENGINE_DESC descriptor using cudnnBackendGetAttribute() function.

typedef enum {
    CUDNN_LAYOUT_TYPE_PREFERRED_NCHW = 0,
    CUDNN_LAYOUT_TYPE_PREFERRED_NHWC = 1,
    CUDNN_LAYOUT_TYPE_PREFERRED_PAD4CK = 2,
    CUDNN_LAYOUT_TYPE_PREFERRED_PAD8CK = 3,
    CUDNN_LAYOUT_TYPE_COUNT = 4,
} cudnnBackendLayoutType_t;

5.1.3.7. cudnnBackendNumericalNote_t

cudnnBackendNumericalNote_t is an enumerated type that indicates queryable numerical properties of an engine. Users can query for an array of numerical notes from an cudnn_BACKEND_ENGINE_DESC using cudnnBackendGetAttribute() function.

typedef enum {
    CUDNN_NUMERIC NOTE_TENSOR_CORE = 0,
    CUDNN_NUMERIC NOTE_DOWN_CONVERT_INPUTS,
    CUDNN_NUMERIC NOTE_REDUCED_PRECISION_REDUCTION,
    CUDNN_NUMERIC NOTE_FFT,
    CUDNN_NUMERIC NOTE_NONDETERMINISTIC,
    CUDNN_NUMERIC NOTE_WINOGRAD,
    CUDNN_NUMERIC NOTE_COUNT
}
5.1.3.8. **cudnnConvolutionBwdDataAlgo_t**

*cudnnConvolutionBwdDataAlgo_t* is an enumerated type that exposes the different algorithms available to execute the backward data convolution operation.

**Values**

**CUDNN_CONVOLUTION_BWD_DATA_ALGO_0**

This algorithm expresses the convolution as a sum of matrix products without actually explicitly forming the matrix that holds the input tensor data. The sum is done using the atomic add operation, thus the results are non-deterministic.

**CUDNN_CONVOLUTION_BWD_DATA_ALGO_1**

This algorithm expresses the convolution as a matrix product without actually explicitly forming the matrix that holds the input tensor data. The results are deterministic.

**CUDNN_CONVOLUTION_BWD_DATA_ALGO_FFT**

This algorithm uses a Fast-Fourier Transform approach to compute the convolution. A significant memory workspace is needed to store intermediate results. The results are deterministic.

**CUDNN_CONVOLUTION_BWD_DATA_ALGO_FFT_TILING**

This algorithm uses the Fast-Fourier Transform approach but splits the inputs into tiles. A significant memory workspace is needed to store intermediate results but less than **CUDNN_CONVOLUTION_BWD_DATA_ALGO_FFT** for large size images. The results are deterministic.

**CUDNN_CONVOLUTION_BWD_DATA_ALGO_WINOGRAD**

This algorithm uses the Winograd Transform approach to compute the convolution. A reasonably sized workspace is needed to store intermediate results. The results are deterministic.

**CUDNN_CONVOLUTION_BWD_DATA_ALGO_WINOGRAD_NONFUSED**

This algorithm uses the Winograd Transform approach to compute the convolution. A significant workspace may be needed to store intermediate results. The results are deterministic.

5.1.3.9. **cudnnConvolutionBwdFilterAlgo_t**

*cudnnConvolutionBwdFilterAlgo_t* is an enumerated type that exposes the different algorithms available to execute the backward filter convolution operation.
Values

**CUDNN_CONVOLUTION_BWD_FILTER_ALGO_0**

This algorithm expresses the convolution as a sum of matrix products without actually explicitly forming the matrix that holds the input tensor data. The sum is done using the atomic add operation, thus the results are non-deterministic.

**CUDNN_CONVOLUTION_BWD_FILTER_ALGO_1**

This algorithm expresses the convolution as a matrix product without actually explicitly forming the matrix that holds the input tensor data. The results are deterministic.

**CUDNN_CONVOLUTION_BWD_FILTER_ALGO_FFT**

This algorithm uses the Fast-Fourier Transform approach to compute the convolution. A significant workspace is needed to store intermediate results. The results are deterministic.

**CUDNN_CONVOLUTION_BWD_FILTER_ALGO_3**

This algorithm is similar to **CUDNN_CONVOLUTION_BWD_FILTER_ALGO_0** but uses some small workspace to precompute some indices. The results are also non-deterministic.

**CUDNN_CONVOLUTION_BWD_FILTER_WINOGRAD_NONFUSED**

This algorithm uses the Winograd Transform approach to compute the convolution. A significant workspace may be needed to store intermediate results. The results are deterministic.

**CUDNN_CONVOLUTION_BWD_FILTER_ALGO_FFT_TILING**

This algorithm uses the Fast-Fourier Transform approach to compute the convolution but splits the input tensor into tiles. A significant workspace may be needed to store intermediate results. The results are deterministic.

5.1.3.10. **cudnnConvolutionFwdAlgo_t**

`cudnnConvolutionFwdAlgo_t` is an enumerated type that exposes the different algorithms available to execute the forward convolution operation.

Values

**CUDNN_CONVOLUTION_FWD_ALGO_IMPLICIT_GEMM**

This algorithm expresses the convolution as a matrix product without actually explicitly forming the matrix that holds the input tensor data.

**CUDNN_CONVOLUTION_FWD_ALGO_IMPLICIT_PRECOMP_GEMM**

This algorithm expresses convolution as a matrix product without actually explicitly forming the matrix that holds the input tensor data, but still needs some memory workspace to precompute some indices in order to facilitate the implicit construction of the matrix that holds the input tensor data.
CUDNN_CONVOLUTION_FWD_ALGO_GEMM

This algorithm expresses the convolution as an explicit matrix product. A significant memory workspace is needed to store the matrix that holds the input tensor data.

CUDNN_CONVOLUTION_FWD_ALGO_DIRECT

This algorithm expresses the convolution as a direct convolution (for example, without implicitly or explicitly doing a matrix multiplication).

CUDNN_CONVOLUTION_FWD_ALGO_FFT

This algorithm uses the Fast-Fourier Transform approach to compute the convolution. A significant memory workspace is needed to store intermediate results.

CUDNN_CONVOLUTION_FWD_ALGO_FFT_TILING

This algorithm uses the Fast-Fourier Transform approach but splits the inputs into tiles. A significant memory workspace is needed to store intermediate results but less than CUDNN_CONVOLUTION_FWD_ALGO_FFT for large size images.

CUDNN_CONVOLUTION_FWD_ALGO_WINograd

This algorithm uses the Winograd Transform approach to compute the convolution. A reasonably sized workspace is needed to store intermediate results.

CUDNN_CONVOLUTION_FWD_ALGO_WINograd_NONFUSED

This algorithm uses the Winograd Transform approach to compute the convolution. A significant workspace may be needed to store intermediate results.

5.1.3.11. cudnnConvolutionMode_t

cudnnConvolutionMode_t is an enumerated type used by cudnnSetConvolution2dDescriptor() to configure a convolution descriptor. The filter used for the convolution can be applied in two different ways, corresponding mathematically to a convolution or to a cross-correlation. (A cross-correlation is equivalent to a convolution with its filter rotated by 180 degrees.)

Values

CUDNN_CONVOLUTION

In this mode, a convolution operation will be done when applying the filter to the images.

CUDNN_CROSS_CORRELATION

In this mode, a cross-correlation operation will be done when applying the filter to the images.

5.1.3.12. cudnnGenStatsMode_t

cudnnGenStatsMode_t is an enumerated type to indicate the statistics mode in the backend statistics generation operation.
Values

CUDNN_GENSTATS_SUM_SQSUM

In this mode, the sum and sum of squares of the input tensor along the specified dimensions are computed and written out. The reduction dimensions currently supported are limited per channel, however additional support may be added upon request.

5.1.3.13. cudnnPointwiseMode_t

cudnnPointwiseMode_t is an enumerated type to indicate the intended pointwise math operation in the backend pointwise operation descriptor.

Values

CUDNN_POINTWISE_ADD

In this mode, a pointwise add between two tensors is computed.

CUDNN_POINTWISE_MUL

In this mode, a pointwise multiplication between two tensors is computed.

CUDNN_POINTWISE_MIN

In this mode, a pointwise minimum is taken between two tensors.

CUDNN_POINTWISE_MAX

In this mode, a pointwise max is taken between two tensors.

CUDNN_POINTWISE_SQRT

In this mode, a pointwise square root of the input tensor is computed.

CUDNN_POINTWISE_IDENTITY_FWD

In this mode, an identity activation (pointwise value copy) is performed.

CUDNN_POINTWISE_RELU_FWD

In this mode, a pointwise ReLu activation is computed.

CUDNN_POINTWISE_TANH_FWD

In this mode, a pointwise tanh activation is computed.

CUDNN_POINTWISE_SIGMOID_FWD

In this mode, a pointwise sigmoid activation is computed.

CUDNN_POINTWISE_ELＵ_FWD

In this mode, a pointwise Exponential Linear Unit activation is computed.

5.1.3.14. cudnnReorderType_t

typedef enum {
    CUDNN_DEFAULT_REORDER = 0,
    // other values
cudnnReorderType_t is an enumerated type to set the convolution reordering type. The reordering type can be set by `cudnnSetConvolutionReorderType()` and its status can be read by `cudnnGetConvolutionReorderType()`.

### 5.1.4. Data Types Found In `cudnn_backend.h`

#### 5.1.4.1. `cudnnBackendDescriptor_t`

`cudnnBackendDescriptor_t` is a typedef void pointer to one of many opaque descriptor structures. The type of structure that it points to is determined by the argument when allocating the memory for the opaque structure using `cudnnBackendCreateDescriptor()`. Attributes of a descriptor can be set using `cudnnBackendSetAttribute()`. After all required attributes of a descriptor are set, the descriptor can be finalized by `cudnnBackendFinalizeDescriptor()`. From a finalized descriptor, one can query its queryable attributes using `cudnnBackendGetAttribute()`. Finally, the memory allocated for a descriptor can be freed using `cudnnBackendDestroyDescriptor()`.

### 5.2. API Functions

#### 5.2.1. `cudnnBackendCreateDescriptor()`

```c

cudnnStatus_t cudnnBackendCreateDescriptor(cudnnBackendDescriptorType_t descriptorType, cudnnBackendDescriptor_t *descriptor)
```

This function allocates memory:

- in the descriptor for a given descriptor type
- at the location pointed by the descriptor

**Note:** The void * is a pointer to the `cudnnBackend_t`.

**Parameters**

- `descriptorType`
  - *Input*. One among the enumerated `cudnnBackendDescriptorType_t`.

- `descriptor`
  - *Input*. Pointer to an instance of `cudnnBackendDescriptor_t` to be created.

**Returns**

- `CUDNN_STATUS_SUCCESS`
  - The creation was successful.
**CUDNN_STATUS_NOT_SUPPORTED**

Creating a descriptor of a given type is not supported.

**CUDNN_STATUS_ALLOC_FAILED**

The memory allocation failed.

### 5.2.2. **cudnnBackendDestroyDescriptor()**

cudnnStatus_t cudnnBackendDestroyDescriptor(cudnnBackendDescriptor_t descriptor)

This function destroys instances of `cudnnBackendDescriptor_t` that were previously created using `cudnnBackendCreateDescriptor()`.

**Parameters**

descriptor

*Input.* Instance of `cudnnBackendDescriptor_t` previously created by `cudnnBackendCreateDescriptor()`.

**Returns**

**CUDNN_STATUS_SUCCESS**

The memory was destroyed successfully.

**CUDNN_STATUS_ALLOC_FAILED**

The destruction of memory failed.

**Undefined Behavior**

The descriptor was altered between the Create and Destroy Descriptor.

**Undefined**

The value pointed by the descriptor will be Undefined after the memory is free and done.

### 5.2.3. **cudnnBackendExecute()**

cudnnStatus_t cudnnBackendExecute(cudnnHandle_t handle, cudnnBackendDescriptor_t executionPlan, cudnnBackendDescriptor_t varianPack)

This function executes:

- the given Engine Configuration Plan on the VariantPack
- the finalized ExecutionPlan on the data

The data and the working space are encapsulated in the VariantPack.

**Parameters**

executionPlan

*Input.* Pointer to the cuDNN handle to be destroyed.
variantPack

*Input*. Pointer to the finalized `VariantPack` consisting of:

- Data pointer for each non-virtual pointer of the operation set in the execution plan.
- Pointer to user-allocated workspace in global memory at least as large as the size queried from `CUDNN_BACKEND_`.

**Returns**

**CUDNN_STATUS_SUCCESS**

The `ExecutionPlan` was executed successfully.

**CUDNN_STATUS_BAD_PARAM**

An incorrect or inconsistent value is encountered. Some examples:

- A required data pointer is invalid.

**CUDNN_STATUS_INTERNAL_ERROR**

Some internal errors were encountered.

**CUDNN_STATUS_EXECUTION_FAILED**

An error was encountered executing the plan with the variant pack.

### 5.2.4. `cudnnBackendFinalize()`

```c
int cudnnBackendFinalize(cudnnBackendDescriptor descriptor)
```

This function finalizes the memory pointed to by the `descriptor`. The type of finalization is done depending on the `descriptorType` argument with which the `descriptor` was created using `cudnnBackendCreate()` or initialized using `cudnnBackendInitialize()`.

`cudnnBackendFinalize()` also checks all the attributes set between the create/initialization and finalize phase. If successful, `cudnnBackendFinalize()` returns `CUDNN_STATUS_SUCCESS` and the finalized state of the `descriptor` is set to `true`. In this state, setting attributes using `cudnnBackendSetAttribute()` is not allowed. Getting attributes using `cudnnBackendGetAttribute()` is only allowed when the finalized state of the `descriptor` is `true`.

**Parameters**

`descriptor`

*Input*. Instance of `cudnnBackendDescriptor_t` to finalize.

**Returns**

**CUDNN_STATUS_SUCCESS**

The `descriptor` was finalized successfully.
**CUDNN_STATUS_BAD_PARAM**

Invalid descriptor attribute values or combination thereof is encountered.

**CUDNN_STATUS_NOT_SUPPORTED**

Descriptor attribute values or combinations therefore not supported by the current version of cuDNN is encountered.

**CUDNN_STATUS_INTERNAL_ERROR**

Some internal errors are encountered.

### 5.2.5. cudnnBackendGetAttribute()

cudnnStatus_t cudnnBackendGetAttribute(
  cudnnBackendDescriptor_t descriptor,
  cudnnBackendAttributeName_t attributeName,
  cudnnBackendAttributeType_t attributeType,
  int64_t requestedElementCount,
  int64_t *elementCount,
  void *arrayOfElements);

This function retrieves the value(s) of an attribute of a descriptor. attributeName is the name of the attribute whose value is requested. The attributeType is the type of attribute. requestedElementCount is the number of elements to be potentially retrieved. The number of elements for the requested attribute is stored in elementCount. The retrieved values are stored in arrayOfElements. When the attribute is expected to have a single value, arrayOfElements can be pointer to the output value. This function will return CUDNN_STATUS_NOT_INITIALIZED if the descriptor was already successfully finalized.

**Parameters**

**descriptor**

*Input*. Instance of **cudnnBackendDescriptor_t** whose attribute the user wants to retrieve.

**attributeName**

*Input*. The name of the attribute being get from the on the descriptor.

**attributeType**

*Input*. The type of attribute.

**requestedElementCount**

*Input*. Number of elements to output to arrayOfElements.

**elementCount**

*Input*. Output pointer for the number of elements the descriptor attribute has. Note that cudnnBackendGetAttribute() will only write the least of this and requestedElementCount elements to arrayOfElements.

**arrayOfElements**

*Input*. Output pointer to element of attribute type.
Returns

**CUDNN_STATUS_SUCCESS**

The `attributeName` was given to the `descriptor` successfully.

**CUDNN_STATUS_BAD_PARAM**

One or more invalid or inconsistent argument values was encountered. Some examples:

- `attributeName` is not a valid attribute for the `descriptor`.
- `attributeType` is not one of the valid types for the attribute.

**CUDNN_STATUS_NOT_INITIALIZED**

The `descriptor` has not been successfully finalized using `cudnnBackendFinalize()`.

### 5.2.6. `cudnnBackendInitialize()`

```c
extern "C" {
cudnnStatus_t cudnnBackendInitialize(cudnnBackendDescriptor_t descriptor,
cudnnBackendDescriptorType_t descriptorType, size_t sizeInBytes)
```  

This function repurposes a pre-allocated memory pointed to by a `descriptor` of size `sizeInBytes` to a backend `descriptor` of type `descriptorType`. The necessary size for a `descriptor` type can be acquired by calling the function `cudnnBackendGetSizeOf()`. The finalized state of the `descriptor` is set to `false`.

**Parameters**

- **descriptor**
  
  *Input*. Instance of `cudnnBackendDescriptor_t` to be initialized.

- **descriptorType**
  
  *Input*. Enumerated value for the type of cuDNN backend `descriptor`.

- **sizeInBytes**
  
  *Input*. Size of memory pointed to by `descriptor`.

**Returns**

**CUDNN_STATUS_SUCCESS**

The memory was initialized successfully.

**CUDNN_STATUS_BAD_PARAM**

An invalid or inconsistent argument value is encountered. For example:

- `descriptor` is a `nullptr`
- `sizeInBytes` is less than the size required by the `descriptor` type
5.2.7. **cudnnBackendSetAttribute()**

```c
typedef enum cudnnBackendAttributeName_t {
    CUDNN_BACKEND_NAME
} cudnnBackendAttributeName_t;

typedef enum cudnnBackendAttributeType_t {
    CUDNN_ATTRIBUTE_TYPE
} cudnnBackendAttributeType_t;

cudnnStatus_t cudnnBackendSetAttribute(
    cudnnBackendDescriptor_t descriptor,
    cudnnBackendAttributeName_t attributeName,
    cudnnBackendAttributeType_t attributeType,
    int64_t elementCount,
    void *arrayOfElements);
```

This function sets an attribute of a descriptor to value[s] provided as a pointer. `descriptor` is the descriptor to be set. `attributeName` is the name of the attribute to be set. `attributeType` is the type of attribute. The value to which the attribute is set, is pointed by `arrayOfElements`. The number of elements is given by `elementCount`. This function will return `CUDNN_STATUS_NOT_INITIALIZED` if the descriptor is already successfully finalized using `cudnnBackendFinalize`.

**Parameters**

- `descriptor`
  
  *Input.* Instance of `cudnnBackendDescriptor_t` whose attribute is being set.

- `attributeName`
  
  *Input.* The name of the attribute being set on the descriptor.

- `attributeType`
  
  *Input.* The type of attribute.

- `elementCount`
  
  *Input.* Number of elements being set.

- `arrayOfElements`
  
  *Input.* The starting location for an array from where to read the values from.

**Returns**

- `CUDNN_STATUS_SUCCESS`
  
  The `attributeName` was set to the descriptor.

- `CUDNN_STATUS_NOT_INITIALIZED`
  
  The backend descriptor pointed to by `descriptor` is already in finalized state.

- `CUDNN_STATUS_BAD_PARAM`
  
  The function is called with arguments that correspond to invalid values. Some possible causes are:

  - `attributeName` is not a settable attribute of `descriptor`.
  - `attributeType` is incorrect for this `attributeName`.
  - `elementCount` value is unexpected.
  - `arrayOfElements` contains values invalid for the `attributeType`.
CUDNN_STATUS_NOT_SUPPORTED

The value(s) to which the attributes are being set is not supported by the current version of cuDNN.

5.2.8. cudnnConvolutionBackwardData()

cudnnStatus_t cudnnConvolutionBackwardData(
    cudnnHandle_t                       handle,
    const void                         *alpha,
    const cudnnFilterDescriptor_t       wDesc,
    const void                         *w,
    const cudnnTensorDescriptor_t       dyDesc,
    const void                         *dy,
    const cudnnConvolutionDescriptor_t  convDesc,
    cudnnConvolutionBwdDataAlgo_t       algo,
    void                               *workSpace,
    size_t                              workSpaceSizeInBytes,
    const void                         *beta,
    const cudnnTensorDescriptor_t       dxDesc,
    void                               *dx)

This function computes the convolution data gradient of the tensor \(dy\), where \(y\) is the output of the forward convolution in cudnnConvolutionForward(). It uses the specified \(\text{algo}\), and returns the results in the output tensor \(dx\). Scaling factors \(\alpha\) and \(\beta\) can be used to scale the computed result or accumulate with the current \(dx\).

Parameters

handle

*Input. Handle to a previously created cuDNN context. For more information, see cudnnHandle_t.*

alpha, beta

*Input. Pointers to scaling factors (in host memory) used to blend the computation result with prior value in the output layer as follows:

\[
\text{dstValue} = \alpha[0]\times\text{result} + \beta[0]\times\text{priorDstValue}
\]

For more information, see *Scaling Parameters* in the cuDNN Developer Guide.*

wDesc

*Input. Handle to a previously initialized filter descriptor. For more information, see cudnnFilterDescriptor_t.*

w

*Input. Data pointer to GPU memory associated with the filter descriptor wDesc.*

dyDesc

*Input. Handle to the previously initialized input differential tensor descriptor. For more information, see cudnnTensorDescriptor_t.*
dy

*Input.* Data pointer to GPU memory associated with the input differential tensor descriptor dyDesc.

convDesc

*Input.* Previously initialized convolution descriptor. For more information, see cudnnConvolutionDescriptor_t.

algo

*Input.* Enumerant that specifies which backward data convolution algorithm should be used to compute the results. For more information, see cudnnConvolutionBwdDataAlgo_t.

workSpace

*Input.* Data pointer to GPU memory to a workspace needed to be able to execute the specified algorithm. If no workspace is needed for a particular algorithm, that pointer can be nil.

workSpaceSizeInBytes

*Input.* Specifies the size in bytes of the provided workSpace.

dxDesc

*Input.* Handle to the previously initialized output tensor descriptor.

dx

*Input/Output.* Data pointer to GPU memory associated with the output tensor descriptor dxDesc that carries the result.

**Supported configurations**

This function supports the following combinations of data types for wDesc, dyDesc, convDesc, and dxDesc.

<table>
<thead>
<tr>
<th>Data Type Configurations</th>
<th>wDesc, dyDesc and dxDesc Data Type</th>
<th>convDesc Data Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>TRUE_HALF_CONFIG [only supported on architectures with true FP16 support, meaning, compute capability 5.3 and later]</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_HALF</td>
</tr>
<tr>
<td>PSEUDO_HALF_CONFIG</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_FLOAT</td>
</tr>
<tr>
<td>FLOAT_CONFIG</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
</tr>
<tr>
<td>DOUBLE_CONFIG</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
</tr>
</tbody>
</table>
Supported algorithms

**Note:** Specifying a separate algorithm can cause changes in performance, support and computation determinism. See the following for a list of algorithm options, and their respective supported parameters and deterministic behavior.

The table below shows the list of the supported 2D and 3D convolutions. The 2D convolutions are described first, followed by the 3D convolutions.

For the following terms, the short-form versions shown in the parentheses are used in the table below, for brevity:

- `CUDNN_CONVOLUTION_BWD_DATA_ALGO_0` (_ALGO_0_)
- `CUDNN_CONVOLUTION_BWD_DATA_ALGO_1` (_ALGO_1_)
- `CUDNN_CONVOLUTION_BWD_DATA_ALGO_FFT` (_FFT_)
- `CUDNN_CONVOLUTION_BWD_DATA_ALGO_FFT_TILING` (_FFT_TILING_)
- `CUDNN_CONVOLUTION_BWD_DATA_ALGO_WINOGRAD` (_WINOGRAD_)
- `CUDNN_CONVOLUTION_BWD_DATA_ALGO_WINOGRAD_NONFUSED` (_WINOGRAD_NONFUSED_)
- `CUDNN_TENSOR_NCHW` (_NCHW_)
- `CUDNN_TENSOR_NHWC` (_NHWC_)
- `CUDNN_TENSOR_NCHW_VECT_C` (_NCHW_VECT_C_)

Table 11. For 2D convolutions: wDesc: _NHWC_

<table>
<thead>
<tr>
<th>Filter descriptor wDesc: <em>NHWC</em> (see cudnnTensorFormat_t)</th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Algo Name</td>
<td>Deterministic (Yes or No)</td>
<td>Tensor Formats Supported for dyDesc</td>
<td>Tensor Formats Supported for dxDesc</td>
</tr>
<tr>
<td><em>ALGO_0</em></td>
<td>NHWC HWC-packed</td>
<td>NHWC HWC-packed</td>
<td>TRUE_HALF_CONFIG</td>
</tr>
<tr>
<td><em>ALGO_1</em></td>
<td></td>
<td></td>
<td>PSEUDO_HALF_CONFIG</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>FLOAT_CONFIG</td>
</tr>
</tbody>
</table>
Table 12. For 2D convolutions: \( w_{\text{Desc}}: \_NCHW \)

<table>
<thead>
<tr>
<th>Filter descriptor: ( w_{\text{Desc}}: _NCHW ).</th>
<th>Algo Name</th>
<th>Deterministic (Yes or No)</th>
<th>Tensor Formats Supported for ( dy_{\text{Desc}} )</th>
<th>Tensor Formats Supported for ( dx_{\text{Desc}} )</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td>_ALGO_0</td>
<td>No</td>
<td>NCHW CHW-packed</td>
<td>All except ( _{\text{NCHN Vect}} _C ), ( _{\text{NCHN Vect}} _C )</td>
<td>TRUE_HALF_CONFIG, PSEUDO_HALF_CONFIG, FLOAT_CONFIG, DOUBLE_CONFIG</td>
<td>Dilation: greater than 0 for all dimensions ( conv_{\text{Desc}} ) Group Count Support: Greater than 0</td>
<td></td>
</tr>
<tr>
<td>_ALGO_1</td>
<td>Yes</td>
<td>NCHW CHW-packed</td>
<td>All except ( _{\text{NCHN Vect}} _C ), ( _{\text{NCHN Vect}} _C )</td>
<td>TRUE_HALF_CONFIG, PSEUDO_HALF_CONFIG, FLOAT_CONFIG, DOUBLE_CONFIG</td>
<td>Dilation: greater than 0 for all dimensions ( conv_{\text{Desc}} ) Group Count Support: Greater than 0</td>
<td></td>
</tr>
<tr>
<td>_FFT</td>
<td>Yes</td>
<td>NCHW CHW-packed</td>
<td>NCHW HW-packed</td>
<td>PSEUDO_HALF_CONFIG, FLOAT_CONFIG</td>
<td>Dilation: 1 for all dimensions ( conv_{\text{Desc}} ) Group Count Support: Greater than 0 ( dx_{\text{Desc}} ) feature map height + 2 ( \times ) ( conv_{\text{Desc}} ) zero-padding height must equal 256 or less ( dx_{\text{Desc}} ) feature map width + 2 ( \times ) ( conv_{\text{Desc}} ) zero-padding</td>
<td></td>
</tr>
</tbody>
</table>
**Filter descriptor** \( w_{\text{Desc}}: \_\text{NCHW} \).

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>Deterministic (Yes or No)</th>
<th>Tensor Formats Supported for dyDesc</th>
<th>Tensor Formats Supported for dxDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td><em>FFT_TILING</em></td>
<td>Yes</td>
<td>NCHW CHW-packed</td>
<td>NCHW HW-packed</td>
<td>PSEUDO_HALF_CONFIG, FLOAT_CONFIG, DOUBLE_CONFIG is also supported when the task can be handled by 1D FFT, meaning, one of the filter dimensions, width or height is 1.</td>
<td>( \text{Dilation: 1 for all dimensions} )</td>
</tr>
</tbody>
</table>

- \( \text{convDesc} \) vertical and horizontal filter stride must equal 1.
- \( w_{\text{Desc}} \) filter height must be greater than \( \text{convDesc} \) zero-padding height.
- \( w_{\text{Desc}} \) filter width must be greater than \( \text{convDesc} \) zero-padding width.
- \( \text{convDesc} \) Group Count Support: Greater than 0.

When neither of \( w_{\text{Desc}} \) filter dimension is 1, the filter width and height must not be larger than 32.

When either of \( w_{\text{Desc}} \) filter
Filter descriptor \texttt{wDesc: _NCHW.}

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>Deterministic (Yes or No)</th>
<th>Tensor Formats Supported for dyDesc</th>
<th>Tensor Formats Supported for dxDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td>_WINOGRAD</td>
<td>Yes</td>
<td>NCHW CHW-packed</td>
<td>All except _NCHW_VECT_C, FLOAT_CONFIG</td>
<td>PSEUDO_HALF_CONFIG</td>
<td>Dilation: 1 for all dimensions convDesc Group Count Support: Greater than 0</td>
</tr>
</tbody>
</table>

- dimension is 1, the largest filter dimension should not exceed 256
- \texttt{convDesc} vertical and horizontal filter stride must equal 1 when either the filter width or filter height is 1, otherwise, the stride can be 1 or 2
- \texttt{wDesc} filter height must be greater than \texttt{convDesc} zero-padding height
- \texttt{wDesc} filter width must be greater than \texttt{convDesc} zero-padding width
**Filter descriptor** \( w_{\text{Desc}}: \_\text{NCHW} \).

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>Deterministic (Yes or No)</th>
<th>Tensor Formats Supported for ( dy_{\text{Desc}} )</th>
<th>Tensor Formats Supported for ( dx_{\text{Desc}} )</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td><em>WINOGRAD_NONFUSED</em></td>
<td>Yes</td>
<td>NCHW CHW-packed</td>
<td>All except _\text{NCHW_VECT_C}</td>
<td>TRUE_HALF_CONFIG</td>
<td>Dilation: ( 1 ) for all dimensions</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>PSEUDO_HALF_CONFIG</td>
<td>convDesc vertical and horizontal filter stride must equal 1</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>FLOAT_CONFIG</td>
<td>( w_{\text{Desc}} ) filter height must be 3</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>( w_{\text{Desc}} ) filter width must be 3</td>
</tr>
</tbody>
</table>

**Important notes:**
- \( w_{\text{Desc}} \) filter height must be 3.
- \( w_{\text{Desc}} \) filter width must be 3.
- If \( w_{\text{Desc}} \) filter \( (height, width) \) is \( (5,5) \) then the data type config TRUE\_HALF\_CONFIG is not supported.
### Table 13. For 3D convolutions: $wDesc: \_NCHW$ 

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>Deterministic [Yes or No]</th>
<th>$dyDesc$ Tensor Formats Supported</th>
<th>$dxDesc$ Tensor Formats Supported</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td>_ALGO_0</td>
<td>Yes</td>
<td>NCDHW CDHW-packed</td>
<td>All except $_NCDHW_VECT_C$ CDHW-packed</td>
<td>PSEUDO_HALF_CONFIG FLOAT_CONFIG DOUBLE_CONFIG</td>
<td>dilation: greater than 0 for all dimensions convDesc Group Count Support: Greater than 0</td>
</tr>
<tr>
<td>_ALGO_1</td>
<td>Yes</td>
<td>NCDHW CDHW-packed</td>
<td>NCDHW CDHW-packed</td>
<td>TRUE_HALF_CONFIG PSEUDO_HALF_CONFIG FLOAT_CONFIG DOUBLE_CONFIG</td>
<td>dilation: 1 for all dimensions convDesc Group Count Support: Greater than 0</td>
</tr>
<tr>
<td>_FFT_TILING</td>
<td>Yes</td>
<td>NCDHW CDHW-packed</td>
<td>NCDHW DHW-packed</td>
<td>PSEUDO_HALF_CONFIG FLOAT_CONFIG DOUBLE_CONFIG</td>
<td>dilation: 1 for all dimensions convDesc Group Count Support: Greater than 0 $wDesc$ filter height must equal 16 or less $wDesc$ filter width must equal 16 or less $wDesc$ filter depth must equal 16 or less</td>
</tr>
</tbody>
</table>
Filter descriptor wDesc: _NCHW.

<table>
<thead>
<tr>
<th>Algo Name (3D Convolutions)</th>
<th>Deterministic (Yes or No)</th>
<th>Tensor Formats Supported for dyDesc</th>
<th>Tensor Formats Supported for dxDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td>_ALGO_1</td>
<td>Yes</td>
<td>NDHWC</td>
<td>NDHWC</td>
<td>TRUE_HALF_CONFIG</td>
<td>Dilatation: Greater than 0 for all dimensions</td>
</tr>
</tbody>
</table>
Filter descriptor \texttt{wDesc: \_NHWC}

<table>
<thead>
<tr>
<th>Algo Name (3D Convolutions)</th>
<th>Deterministic (Yes or No)</th>
<th>Tensor Formats Supported for dyDesc</th>
<th>Tensor Formats Supported for dxDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
</table>

Returns

\textbf{CUDNN\_STATUS\_SUCCESS}

The operation was launched successfully.

\textbf{CUDNN\_STATUS\_BAD\_PARAM}

At least one of the following conditions are met:

- At least one of the following is NULL: handle, dyDesc, wDesc, convDesc, dxDesc, dy, w, dx, alpha, beta
- wDesc and dyDesc have a non-matching number of dimensions
- wDesc and dxDesc have a non-matching number of dimensions
- wDesc has fewer than three number of dimensions
- wDesc, dxDesc, and dyDesc have a non-matching data type.
- wDesc and dxDesc have a non-matching number of input feature maps per image (or group in case of grouped convolutions).
- dyDesc spatial sizes do not match with the expected size as determined by \texttt{cudnnGetConvolutionNdForwardOutputDim}

\textbf{CUDNN\_STATUS\_NOT\_SUPPORTED}

At least one of the following conditions are met:

- dyDesc or dxDesc have a negative tensor striding
- dyDesc, wDesc or dxDesc has a number of dimensions that is not 4 or 5
- The chosen algo does not support the parameters provided; see above for an exhaustive list of parameters that support each algo
- dyDesc or wDesc indicate an output channel count that isn’t a multiple of group count (if group count has been set in convDesc).

\textbf{CUDNN\_STATUS\_MAPPING\_ERROR}

An error occurs during the texture binding of the filter data or the input differential tensor data
5.2.9. cudnnConvolutionBiasActivationForward()

```c

cudnnStatus_t cudnnConvolutionBiasActivationForward(
    cudnnHandle_t                        handle,
    const void                           *alpha1,
    const cudnnTensorDescriptor_t        xDesc,
    const void                           *x,
    const cudnnFilterDescriptor_t        wDesc,
    const void                           *w,
    const cudnnConvolutionDescriptor_t   convDesc,
    cudnnConvolutionFwdAlgo_t            algo,
    void                                 *workSpace,
    size_t                               workSpaceSizeInBytes,
    const void                           *alpha2,
    const cudnnTensorDescriptor_t        zDesc,
    const void                           *z,
    const cudnnTensorDescriptor_t        biasDesc,
    const void                           *bias,
    const cudnnActivationDescriptor_t    activationDesc,
    const cudnnTensorDescriptor_t        yDesc,
    void                                 *y)
```

This function applies a bias and then an activation to the convolutions or cross-correlations of `cudnnConvolutionForward()`, returning results in `y`. The full computation follows the equation

\[ y = \text{act} \left( \alpha_1 \times \text{conv}(x) + \alpha_2 \times z + \text{bias} \right) \]

**Parameters**

**handle**

*Input.* Handle to a previously created cuDNN context. For more information, see `cudnnHandle_t`.  

---

**Note:**

- The routine `cudnnGetConvolution2dForwardOutputDim[]` or `cudnnGetConvolutionNdForwardOutputDim[]` can be used to determine the proper dimensions of the output tensor descriptor `yDesc` with respect to `xDesc`, `convDesc`, and `wDesc`.  
- Only the CUDNN_CONVOLUTION_FWD_ALGO_IMPLICIT_PRECOMP_GEMM algo is enabled with CUDNN_ACTIVATION_IDENTITY. In other words, in the `cudnnActivationDescriptor_t` structure of the input activationDesc, if the mode of the `cudnnActivationMode_t` field is set to the enum value CUDNN_ACTIVATION_IDENTITY, then the input `cudnnConvolutionFwdAlgo_t` of this function `cudnnConvolutionBiasActivationForward()` must be set to the enum value CUDNN_CONVOLUTION_FWD_ALGO_IMPLICIT_PRECOMP_GEMM. For more information, see `cudnnSetActivationDescriptor[]`.  
- Device pointer `z` and `y` may be pointing to the same buffer, however, `x` cannot point to the same buffer as `z` or `y`. 
alpha1, alpha2

*Input*. Pointers to scaling factors (in host memory) used to blend the computation result of convolution with z and bias as follows:

\[
y = \text{act} \left( \alpha_1 \ast \text{conv}(x) + \alpha_2 \ast z + \text{bias} \right)
\]

For more information, see *Scaling Parameters* in the *cuDNN Developer Guide*.

xDesc

*Input*. Handle to a previously initialized tensor descriptor. For more information, see `cudnnTensorDescriptor_t`.

x

*Input*. Data pointer to GPU memory associated with the tensor descriptor xDesc.

wDesc

*Input*. Handle to a previously initialized filter descriptor. For more information, see `cudnnFilterDescriptor_t`.

w

*Input*. Data pointer to GPU memory associated with the filter descriptor wDesc.

convDesc

*Input*. Previously initialized convolution descriptor. For more information, see `cudnnConvolutionDescriptor_t`.

algo

*Input*. Enumerant that specifies which convolution algorithm should be used to compute the results. For more information, see `cudnnConvolutionFwdAlgo_t`.

workSpace

*Input*. Data pointer to GPU memory to a workspace needed to be able to execute the specified algorithm. If no workspace is needed for a particular algorithm, that pointer can be nil.

workSpaceSizeInBytes

*Input*. Specifies the size in bytes of the provided workSpace.

zDesc

*Input*. Handle to a previously initialized tensor descriptor.

z

*Input*. Data pointer to GPU memory associated with the tensor descriptor zDesc.

biasDesc

*Input*. Handle to a previously initialized tensor descriptor.

bias

*Input*. Data pointer to GPU memory associated with the tensor descriptor biasDesc.
activationDesc

Input. Handle to a previously initialized activation descriptor. For more information, see cudnnActivationDescriptor_t.

yDesc

Input. Handle to a previously initialized tensor descriptor.

y

Input/Output. Data pointer to GPU memory associated with the tensor descriptor yDesc that carries the result of the convolution.

For the convolution step, this function supports the specific combinations of data types for xDesc, wDesc, convDesc, and yDesc as listed in the documentation of cudnnConvolutionForward(). The following table specifies the supported combinations of data types for x, y, z, bias, and alpha1/alpha2.

Table 15. Supported combinations of data types \( \{X = \text{CUDNN\_DATA}\} \)

<table>
<thead>
<tr>
<th>x</th>
<th>w</th>
<th>convDesc</th>
<th>y and z</th>
<th>bias</th>
<th>alpha1/alpha2</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_DOUBLE</td>
<td>X_DOUBLE</td>
<td>X_DOUBLE</td>
<td>X_DOUBLE</td>
<td>X_DOUBLE</td>
<td>X_DOUBLE</td>
</tr>
<tr>
<td>X_FLOAT</td>
<td>X_FLOAT</td>
<td>X_FLOAT</td>
<td>X_FLOAT</td>
<td>X_FLOAT</td>
<td>X_FLOAT</td>
</tr>
<tr>
<td>X_HALF</td>
<td>X_HALF</td>
<td>X_FLOAT</td>
<td>X_HALF</td>
<td>X_HALF</td>
<td>X_FLOAT</td>
</tr>
<tr>
<td>X_INT8</td>
<td>X_INT8</td>
<td>X_INT32</td>
<td>X_INT8</td>
<td>X_FLOAT</td>
<td>X_FLOAT</td>
</tr>
<tr>
<td>X_INT8\times4</td>
<td>X_INT8\times4</td>
<td>X_INT32</td>
<td>X_INT8</td>
<td>X_FLOAT</td>
<td>X_FLOAT</td>
</tr>
<tr>
<td>X_INT8\times4</td>
<td>X_INT8\times4</td>
<td>X_INT32</td>
<td>X_INT8</td>
<td>X_FLOAT</td>
<td>X_FLOAT</td>
</tr>
<tr>
<td>X_UINT8</td>
<td>X_INT8</td>
<td>X_INT32</td>
<td>X_INT8</td>
<td>X_FLOAT</td>
<td>X_FLOAT</td>
</tr>
<tr>
<td>X_UINT8\times4</td>
<td>X_INT8\times4</td>
<td>X_INT32</td>
<td>X_INT8</td>
<td>X_FLOAT</td>
<td>X_FLOAT</td>
</tr>
<tr>
<td>X_INT8\times32</td>
<td>X_INT8\times32</td>
<td>X_INT32</td>
<td>X_INT8\times32</td>
<td>X_FLOAT</td>
<td>X_FLOAT</td>
</tr>
</tbody>
</table>

Returns

In addition to the error values listed by the documentation of cudnnConvolutionForward(), the possible error values returned by this function and their meanings are listed below.

CUDNN\_STATUS\_SUCCESS

The operation was launched successfully.
**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- At least one of the following is NULL: handle, xDesc, wDesc, convDesc, yDesc, zDesc, biasDesc, activationDesc, xData, wData, yData, zData, bias, alpha1, alpha2.
- The number of dimensions of xDesc, wDesc, yDesc, zDesc is not equal to the array length of convDesc + 2.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration. Some examples of non-supported configurations are as follows:

- The mode of activationDesc is neither CUDNN_ACTIVATION_RELU or CUDNN_ACTIVATION_IDENTITY.
- The reluNanOpt of activationDesc is not CUDNN_NOT_PROPAGATE_NAN.
- The second stride of biasDesc is not equal to one.
- The first dimension of biasDesc is not equal to one.
- The second dimension of biasDesc and the first dimension of filterDesc are not equal.
- The data type of biasDesc does not correspond to the data type of yDesc as listed in the above data types table.
- zDesc and destDesc do not match.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

### 5.2.10. cudnnConvolutionForward()

```c
#include <cudnn.h>

typedef cudnnStatus_t cudnnConvolutionForward(
    cudnnHandle_t handle,
const void *alpha,
const cudnnTensorDescriptor_t xDesc,
const void *x,
const cudnnFilterDescriptor_t wDesc,
const void *w,
const cudnnConvolutionDescriptor_t convDesc,
void *workSpace,
size_t workSpaceSizeInBytes,
const void *beta,
const cudnnTensorDescriptor_t yDesc,
void *y);
```

This function executes convolutions or cross-correlations over x using filters specified with w, returning results in y. Scaling factors alpha and beta can be used to scale the input tensor and the output tensor respectively.

**Note:** The routine `cudnnGetConvolution2dForwardOutputDim()` or `cudnnGetConvolutionNdForwardOutputDim()` can be used to determine the proper dimensions of the output tensor descriptor yDesc with respect to xDesc, convDesc, and wDesc.
Parameters

**handle**

*Input.* Handle to a previously created cuDNN context. For more information, see `cudnnHandle_t`.

**alpha, beta**

*Input.* Pointers to scaling factors [in host memory] used to blend the computation result with prior value in the output layer as follows:

\[ \text{dstValue} = \alpha[0] \times \text{result} + \beta[0] \times \text{priorDstValue} \]

For more information, see Scaling Parameters in the cuDNN Developer Guide.

**xDesc**

*Input.* Handle to a previously initialized tensor descriptor. For more information, see `cudnnTensorDescriptor_t`.

**x**

*Input.* Data pointer to GPU memory associated with the tensor descriptor `xDesc`.

**wDesc**

*Input.* Handle to a previously initialized filter descriptor. For more information, see `cudnnFilterDescriptor_t`.

**w**

*Input.* Data pointer to GPU memory associated with the filter descriptor `wDesc`.

**convDesc**

*Input.* Previously initialized convolution descriptor. For more information, see `cudnnConvolutionDescriptor_t`.

**algo**

*Input.* Enumerant that specifies which convolution algorithm should be used to compute the results. For more information, see `cudnnConvolutionFwdAlgo_t`.

**workSpace**

*Input.* Data pointer to GPU memory to a workspace needed to be able to execute the specified algorithm. If no workspace is needed for a particular algorithm, that pointer can be nil.

**workSpaceSizeInBytes**

*Input.* Specifies the size in bytes of the provided `workSpace`.

**yDesc**

*Input.* Handle to a previously initialized tensor descriptor.
**Input/Output.** Data pointer to GPU memory associated with the tensor descriptor `yDesc` that carries the result of the convolution.

**Supported configurations**

This function supports the following combinations of data types for `xDesc`, `wDesc`, `convDesc`, and `yDesc`.

**Table 16. Supported configurations**

<table>
<thead>
<tr>
<th>Data Type Configurations</th>
<th>xDesc and wDesc</th>
<th>convDesc</th>
<th>yDesc</th>
</tr>
</thead>
<tbody>
<tr>
<td>TRUE_HALF_CONFIG</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_HALF</td>
</tr>
<tr>
<td>(only supported on architectures with true FP16 support, meaning, compute capability 5.3 and later)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>PSEUDO_HALF_CONFIG</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_HALF</td>
</tr>
<tr>
<td>FLOAT_CONFIG</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
</tr>
<tr>
<td>DOUBLE_CONFIG</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
</tr>
<tr>
<td>INT8_CONFIG</td>
<td>CUDNN_DATA_INT8</td>
<td>CUDNN_DATA_INT32</td>
<td>CUDNN_DATA_INT8</td>
</tr>
<tr>
<td>(only supported on architectures with DP4A support, meaning, compute capability 6.1 and later)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>INT8_EXT_CONFIG</td>
<td>CUDNN_DATA_INT8</td>
<td>CUDNN_DATA_INT32</td>
<td>CUDNN_DATA_FLOAT</td>
</tr>
<tr>
<td>(only supported on architectures with DP4A support, meaning, compute capability 6.1 and later)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>INT8x4_CONFIG</td>
<td>CUDNN_DATA_INT8x4</td>
<td>CUDNN_DATA_INT32</td>
<td>CUDNN_DATA_INT8x4</td>
</tr>
<tr>
<td>(only supported on architectures with DP4A support,</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Data Type Configurations</td>
<td>xDesc and wDesc</td>
<td>convDesc</td>
<td>yDesc</td>
</tr>
<tr>
<td>--------------------------</td>
<td>-----------------</td>
<td>----------</td>
<td>-------</td>
</tr>
<tr>
<td>INT8x4_EXT_CONFIG</td>
<td>CUDNN_DATA_INT8x4</td>
<td>CUDNN_DATA_INT32</td>
<td>CUDNN_DATA_FLOAT</td>
</tr>
<tr>
<td>UINT8x4_CONFIG</td>
<td>CUDNN_DATA_UINT8x4</td>
<td>CUDNN_DATA_INT32</td>
<td>CUDNN_DATA_UINT8x4</td>
</tr>
<tr>
<td>INT8x32_CONFIG</td>
<td>CUDNN_DATA_INT8x32</td>
<td>CUDNN_DATA_INT32</td>
<td>CUDNN_DATA_INT8x32</td>
</tr>
</tbody>
</table>

Supported algorithms

**Note:** For this function, all algorithms perform deterministic computations. Specifying a separate algorithm can cause changes in performance and support.

The table below shows the list of the supported 2D and 3D convolutions. The 2D convolutions are described first, followed by the 3D convolutions.
For the following terms, the short-form versions shown in the parenthesis are used in the table below, for brevity:

- CUDNN_CONVOLUTION_FWD_ALGO_IMPLICIT_GEMM (\_IMPLICIT_GEMM)
- CUDNN_CONVOLUTION_FWD_ALGO_IMPLICIT_PRECOMP_GEMM (\_IMPLICIT_PRECOMP_GEMM)
- CUDNN_CONVOLUTION_FWD_ALGO_GEMM (\_GEMM)
- CUDNN_CONVOLUTION_FWD_ALGO_DIRECT (\_DIRECT)
- CUDNN_CONVOLUTION_FWD_ALGO_FFT (\_FFT)
- CUDNN_CONVOLUTION_FWD_ALGO_FFT_TILING (\_FFT_TILING)
- CUDNN_CONVOLUTION_FWD_ALGO_WINOGRAD (\_WINOGRAD)
- CUDNN_CONVOLUTION_FWD_ALGO_WINOGRAD_NONFUSED (\_WINOGRAD_NONFUSED)
- CUDNN_TENSOR_NCHW (\_NCHW)
- CUDNN_TENSOR_NHWC (\_NHWC)
- CUDNN_TENSOR_NCHW_VECT_C (\_NCHW_VECT_C)

Table 17. For 2D convolutions: wDesc: \_NCHW

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>Tensor Formats Supported for xDesc</th>
<th>Tensor Formats Supported for yDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td>_IMPLICIT_GEMM</td>
<td>All except _NCHW_VECT_C.</td>
<td>All except _NCHW_VECT_C.</td>
<td>TRUE_HALF_CONFIG</td>
<td>Dilation: Greater than 0 for all dimensions</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>PSEUDO_HALF_CONFIG</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>FLOAT_CONFIG</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>DOUBLE_CONFIG</td>
<td></td>
</tr>
<tr>
<td>_IMPLICIT_PRECOMP_GEMM</td>
<td>All except _NCHW_VECT_C.</td>
<td>All except _NCHW_VECT_C.</td>
<td>TRUE_HALF_CONFIG</td>
<td>Dilation: 1 for all dimensions</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>PSEUDO_HALF_CONFIG</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>FLOAT_CONFIG</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>DOUBLE_CONFIG</td>
<td></td>
</tr>
<tr>
<td>_GEMM</td>
<td>All except _NCHW_VECT_C.</td>
<td>All except _NCHW_VECT_C.</td>
<td>PSEUDO_HALF_CONFIG</td>
<td>Dilation: 1 for all dimensions</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>FLOAT_CONFIG</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>DOUBLE_CONFIG</td>
<td></td>
</tr>
<tr>
<td>_FFT</td>
<td>NCHW HW-packed</td>
<td>NCHW HW-packed</td>
<td>PSEUDO_HALF_CONFIG</td>
<td>Dilation: 1 for all dimensions</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>FLOAT_CONFIG</td>
<td></td>
</tr>
</tbody>
</table>
Filter descriptor wDesc: _NCHW (see cudnnTensorFormat_t)

convDesc Group count support: Greater than 0, for all algos.

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>Tensor Formats Supported for xDesc</th>
<th>Tensor Formats Supported for yDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

_FFT_TILING

<p>| | | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
</table>

**Important**

- xDesc feature map height + 2 * convDesc zero-padding height must equal 256 or less
- xDesc feature map width + 2 * convDesc zero-padding width must equal 256 or less
- convDesc vertical and horizontal filter stride must equal 1
- wDesc filter height must be greater than convDesc zero-padding height
- wDesc filter width must be greater than convDesc zero-padding width

- _FFT_TILING_ is also supported when the task can be handled by 1D FFT, meaning, one of the filter dimensions
- When neither of wDesc filter dimension is 1, the filter width and height must not be larger than 32
Filter descriptor `wDesc: _NCHW` (see `cudnnTensorFormat_t`)

**convDesc** Group count support: Greater than 0, for all algs.

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>Tensor Formats Supported for <code>xDesc</code></th>
<th>Tensor Formats Supported for <code>yDesc</code></th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td><em>WINOGRAD</em></td>
<td>All except <em>NCHW_VECT</em></td>
<td>All except <em>NCHW_VECT</em></td>
<td>PSEUDO_HALF_CONFIG</td>
<td>Dilation: 1 for all dimensions</td>
</tr>
</tbody>
</table>

- **Dimensions, width or height is 1.**
- **When either of `wDesc` filter dimension is 1, the largest filter dimension should not exceed 256.**
- **convDesc vertical and horizontal filter stride must equal 1 when either the filter width or filter height is 1, otherwise the stride can be a 1 or 2.**
- **`wDesc` filter height must be greater than `convDesc` zero-padding height.**
- **`wDesc` filter width must be greater than `convDesc` zero-padding width.**
- **`wDesc` filter height must be 3.**
Filter descriptor \texttt{wDesc: _NCHW} [see \texttt{cudnnTensorFormat_t}]

\texttt{convDesc} Group count support: Greater than 0, for all algs.

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>Tensor Formats Supported for \texttt{xDesc}</th>
<th>Tensor Formats Supported for \texttt{yDesc}</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td>_WINOGRAD_NONFUSED</td>
<td></td>
<td></td>
<td>TRUE_HALF_CONFIG</td>
<td>Dilation: 1 for all dimensions</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>PSEUDO_HALF_CONFIG</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>FLOAT_CONFIG</td>
<td>convDesc vertical and horizontal filter stride must equal 1</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>wDesc filter (height, width) must be (3,3) or (5,5)</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>If wDesc filter (height, width) is (5,5), then data type config TRUE_HALF_CONFIG is not supported.</td>
<td></td>
</tr>
<tr>
<td>_DIRECT</td>
<td>Currently not implemented in cuDNN.</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 18. For 2D convolutions: \texttt{wDesc: _NCHWC}

Filter descriptor \texttt{wDesc: _NCHWC}

\texttt{convDesc} Group count support: Greater than 0.

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>\texttt{xDesc}</th>
<th>\texttt{yDesc}</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td>_IMPLICIT_GEMM</td>
<td>_NCHW_VECT_C</td>
<td>_NCHW_VECT_C</td>
<td>INT8_X4_CONFIG</td>
<td>Dilation: 1 for all dimensions</td>
</tr>
<tr>
<td>_IMPLICIT_PRECOMP_GEMM</td>
<td></td>
<td></td>
<td>UINT8_X4_CONFIG</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>INT8_X4_EXT_CONFIG</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>UINT8_X4_EXT_CONFIG</td>
<td></td>
</tr>
</tbody>
</table>
Filter descriptor \texttt{wDesc: \_NCHWC}

\texttt{convDesc} Group count support: Greater than 0.

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>xDesc</th>
<th>yDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td>_IMPLICIT_PRECOMP_GEMM</td>
<td>_NCHW_VECTOR_C</td>
<td>_NCHW_VECTOR_C</td>
<td>INT8x32_CONFIG</td>
<td>Dilation: 1 for all dimensions</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Requires compute capability 7.2 or above.</td>
</tr>
</tbody>
</table>

Table 19. For 2D convolutions: \texttt{wDesc: \_NHWC}

Filter descriptor \texttt{wDesc: \_NHWC}

\texttt{convDesc} Group count support: Greater than 0.

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>xDesc</th>
<th>yDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td>_IMPLICIT_GMM</td>
<td>NHWC fully-packed</td>
<td>NHWC fully-packed</td>
<td>INT8_CONFIG</td>
<td>Dilation: 1 for all dimensions</td>
</tr>
<tr>
<td>_IMPLICIT_PRECOMP_GEMM</td>
<td></td>
<td></td>
<td>INT8_EXT_CONFIG</td>
<td>Input and output feature maps must be a multiple of 4.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>UINT8_CONFIG</td>
<td>Output features maps can be non-multiple in the case of</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>UINT8_EXT_CONFIG</td>
<td>INT8_EXT_CONFIG or UINT8_EXT_CONFIG.</td>
</tr>
<tr>
<td>_IMPLICIT_GMM</td>
<td>NHWC HWC-packed.</td>
<td>NHWC HWC-packed.</td>
<td>TRUE_HALF_CONFIG</td>
<td></td>
</tr>
<tr>
<td>_IMPLICIT_PRECOMP_GEMM</td>
<td></td>
<td></td>
<td>PSEUDO_HALF_CONFIG</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>FLOAT_CONFIG</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>DOUBLE_CONFIG</td>
<td></td>
</tr>
</tbody>
</table>
Table 20. For 3D convolutions: \texttt{wDesc: NCHW}

**Filter descriptor wDesc: NCHW**

\texttt{convDesc} Group count support: Greater than 0, for all algos.

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>xDesc</th>
<th>yDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td>_IMPLICIT_GEMM</td>
<td>All except _NCHW_VECT_C.</td>
<td>All except _NCHW_VECT_C.</td>
<td>PSEUDO_HALF_CONFIG, FLOAT_CONFIG, DOUBLE_CONFIG</td>
<td>Dilation: Greater than 0 for all dimensions</td>
</tr>
<tr>
<td>_IMPLICIT_PRECOMP_GEMM</td>
<td></td>
<td></td>
<td></td>
<td>Dilation: Greater than 0 for all dimensions</td>
</tr>
<tr>
<td>_FFT_TILING</td>
<td>NCDHW DHW-packed</td>
<td>NCDHW DHW-packed</td>
<td></td>
<td>Dilation: 1 for all dimensions</td>
</tr>
</tbody>
</table>

\texttt{wDesc} filter height must equal 16 or less
\texttt{wDesc} filter width must equal 16 or less
\texttt{wDesc} filter depth must equal 16 or less
\texttt{convDesc} must have all filter strides equal to 1
\texttt{wDesc} filter height must be greater than \texttt{convDesc} zero-padding height
\texttt{wDesc} filter width must be greater than \texttt{convDesc} zero-padding width
\texttt{wDesc} filter depth must be greater
Filter descriptor wDesc: _NCHW

convDesc Group count support: Greater than 0, for all algos.

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>xDesc</th>
<th>yDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>zero-padding width</td>
</tr>
</tbody>
</table>

Table 21. For 3D convolutions: wDesc: _NHWC

Filter descriptor wDesc: _NHWC

convDesc Group count support: Greater than 0, for all algos.

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>xDesc</th>
<th>yDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td>_IMPLICIT_PRECOMP_GEMM</td>
<td>NHWC</td>
<td>NDHWC</td>
<td>PSEUDO_HALF_CONFIG</td>
<td>Dilation: Greater than 0 for all dimensions</td>
</tr>
<tr>
<td></td>
<td>DHWC-packed</td>
<td>DHWC-packed</td>
<td>FLOAT_CONFIG</td>
<td></td>
</tr>
</tbody>
</table>

Note: Tensors can be converted to and from CUDNN_TENSOR_NCHW_VECT_C with cudnnTransformTensor().

Returns

CUDNN_STATUS_SUCCESS
The operation was launched successfully.

CUDNN_STATUS_BAD_PARAM
At least one of the following conditions are met:

- At least one of the following is NULL: handle, xDesc, wDesc, convDesc, yDesc, xData, w, yData, alpha, beta
- xDesc and yDesc have a non-matching number of dimensions
- xDesc and wDesc have a non-matching number of dimensions
- xDesc has fewer than three number of dimensions
- xDesc’s number of dimensions is not equal to convDesc array length + 2
- xDesc and wDesc have a non-matching number of input feature maps per image (or group in case of grouped convolutions)
- yDesc or wDesc indicate an output channel count that isn’t a multiple of group count (if group count has been set in convDesc).
- xDesc, wDesc, and yDesc have a non-matching data type
- For some spatial dimension, wDesc has a spatial size that is larger than the input spatial size (including zero-padding size)

**CUDNN_STATUS_NOT_SUPPORTED**

At least one of the following conditions are met:
- xDesc or yDesc have negative tensor striding
- xDesc, wDesc, or yDesc has a number of dimensions that is not 4 or 5
- yDesc spatial sizes do not match with the expected size as determined by cudnnGetConvolutionNdForwardOutputDim()
- The chosen algo does not support the parameters provided; see above for an exhaustive list of parameters supported for each algo

**CUDNN_STATUS_MAPPING_ERROR**

An error occurred during the texture binding of the filter data.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

### 5.2.11. **cudnnCreateConvolutionDescriptor()**

```
cudnnStatus_t cudnnCreateConvolutionDescriptor(
    cudnnConvolutionDescriptor_t *convDesc)
```

This function creates a convolution descriptor object by allocating the memory needed to hold its opaque structure. For more information, see _cudnnConvolutionDescriptor_.

**Returns**

**CUDNN_STATUS_SUCCESS**

The object was created successfully.

**CUDNN_STATUS_ALLOC_FAILED**

The resources could not be allocated.

### 5.2.12. **cudnnDestroyConvolutionDescriptor()**

```
cudnnStatus_t cudnnDestroyConvolutionDescriptor(
    cudnnConvolutionDescriptor_t convDesc)
```

This function destroys a previously created convolution descriptor object.

**Returns**

**CUDNN_STATUS_SUCCESS**

The descriptor was destroyed successfully.
5.2.13. **cudnnFindConvolutionBackwardDataAlgorithm()**

This function attempts all algorithms available for `cudnnConvolutionBackwardData()`. It will attempt both the provided `convDesc` mathType and `CUDNN_DEFAULT_MATH` (assuming the two differ).

**Note:** Algorithms without the `CUDNN_TENSOR_OP_MATH` availability will only be tried with `CUDNN_DEFAULT_MATH`, and returned as such.

Memory is allocated via `cudaMalloc()`. The performance metrics are returned in the user-allocated array of `cudnnConvolutionBwdDataAlgoPerf_t`. These metrics are written in a sorted fashion where the first element has the lowest compute time. The total number of resulting algorithms can be queried through the API `cudnnGetConvolutionBackwardDataAlgorithmMaxCount()`.

**Parameters**

- **handle**
  
  *Input*. Handle to a previously created cuDNN context.

- **wDesc**
  
  *Input*. Handle to a previously initialized filter descriptor.

- **dyDesc**
  
  *Input*. Handle to the previously initialized input differential tensor descriptor.

- **convDesc**
  
  *Input*. Previously initialized convolution descriptor.

- **dxDesc**
  
  *Input*. Handle to the previously initialized output tensor descriptor.

- **requestedAlgoCount**
  
  *Input*. The maximum number of elements to be stored in `perfResults`. 
returnedAlgoCount  
*Output.* The number of output elements stored in `perfResults`.

`perfResults`  
*Output.* A user-allocated array to store performance metrics sorted ascending by compute time.

**Returns**

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- `handle` is not allocated properly.
- `wDesc`, `dyDesc`, or `dxDesc` is not allocated properly.
- `wDesc`, `dyDesc`, or `dxDesc` has fewer than 1 dimension.
- Either `returnedCount` or `perfResults` is nil.
- `requestedCount` is less than 1.

**CUDNN_STATUS_ALLOC_FAILED**

This function was unable to allocate memory to store sample input, filters and output.

**CUDNN_STATUS_INTERNAL_ERROR**

At least one of the following conditions are met:

- The function was unable to allocate necessary timing objects.
- The function was unable to deallocate necessary timing objects.
- The function was unable to deallocate sample input, filters and output.

### 5.2.14. `cudnnFindConvolutionBackwardDataAlgorithmEx()`

```c
@cudnnStatus_t cudnnFindConvolutionBackwardDataAlgorithmEx(
    cudnnHandle_t handle,
    const cudnnFilterDescriptor_t wDesc,
    const void *w,
    const cudnnTensorDescriptor_t dyDesc,
    const void *dy,
    const cudnnConvolutionDescriptor_t convDesc,
    const cudnnTensorDescriptor_t dxDesc,
    void *dx,
    const int requestedAlgoCount,
    int *returnedAlgoCount,
    cudnnConvolutionBwdDataAlgoPerf_t *perfResults,
    void *workSpace,
    size_t workSpaceSizeInBytes)
```
This function attempts all algorithms available for cudnnConvolutionBackwardData(). It will attempt both the provided convDesc mathType and CUDNN_DEFAULT_MATH (assuming the two differ).

**Note:** Algorithms without the CUDNN_TENSOR_OP_MATH availability will only be tried with CUDNN_DEFAULT_MATH, and returned as such.

Memory is allocated via cudaMalloc(). The performance metrics are returned in the user-allocated array of cudnnConvolutionBwdDataAlgoPerf_t. These metrics are written in a sorted fashion where the first element has the lowest compute time. The total number of resulting algorithms can be queried through the API cudnnGetConvolutionBackwardDataAlgorithmMaxCount().

**Note:** This function is host blocking.

### Parameters

**handle**

*Input.* Handle to a previously created cuDNN context.

**wDesc**

*Input.* Handle to a previously initialized filter descriptor.

**w**

*Input.* Data pointer to GPU memory associated with the filter descriptor wDesc.

**dyDesc**

*Input.* Handle to the previously initialized input differential tensor descriptor.

**dy**

*Input.* Data pointer to GPU memory associated with the filter descriptor dyDesc.

**convDesc**

*Input.* Previously initialized convolution descriptor.

**dxDesc**

*Input.* Handle to the previously initialized output tensor descriptor.

** dxDesc**

*Input/Output.* Data pointer to GPU memory associated with the tensor descriptor dxDesc. The content of this tensor will be overwritten with arbitrary values.

**requestedAlgoCount**

*Input.* The maximum number of elements to be stored in perfResults.

**returnedAlgoCount**

*Output.* The number of output elements stored in perfResults.
perfResults

*Output.* A user-allocated array to store performance metrics sorted ascending by compute time.

workSpace

*Input.* Data pointer to GPU memory is a necessary workspace for some algorithms. The size of this workspace will determine the availability of algorithms. A nil pointer is considered a workSpace of 0 bytes.

workSpaceSizeInBytes

*Input.* Specifies the size in bytes of the provided workSpace.

Returns

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- handle is not allocated properly.
- wDesc, dyDesc, or dxDesc is not allocated properly.
- wDesc, dyDesc, or dxDesc has fewer than 1 dimension.
- w, dy, or dx is nil.
- Either returnedCount or perfResults is nil.
- requestedCount is less than 1.

**CUDNN_STATUS_INTERNAL_ERROR**

At least one of the following conditions are met:

- The function was unable to allocate necessary timing objects.
- The function was unable to deallocate necessary timing objects.
- The function was unable to deallocate sample input, filters and output.

5.2.15. **cudnnFindConvolutionForwardAlgorithm()**

cudnnStatus_t cudnnFindConvolutionForwardAlgorithm(
    cudnnHandle_t                      handle,
    const cudnnTensorDescriptor_t      xDesc,
    const cudnnFilterDescriptor_t      wDesc,
    const cudnnConvolutionDescriptor_t convDesc,
    const cudnnTensorDescriptor_t      yDesc,
    const int                          requestedAlgoCount,
    int *returnedAlgoCount,
    cudnnConvolutionFwdAlgoPerf_t     *perfResults)
This function attempts all algorithms available for `cudnnConvolutionForward()`. It will attempt both the provided `convDesc` `mathType` and `CUDNN_DEFAULT_MATH` (assuming the two differ).

Note: Algorithms without the `CUDNN_TENSOR_OP_MATH` availability will only be tried with `CUDNN_DEFAULT_MATH`, and returned as such.

Memory is allocated via `cudaMalloc()`. The performance metrics are returned in the user-allocated array of `cudnnConvolutionFwdAlgoPerf_t`. These metrics are written in a sorted fashion where the first element has the lowest compute time. The total number of resulting algorithms can be queried through the API `cudnnGetConvolutionForwardAlgorithmMaxCount()`.

Note:
- This function is host blocking.
- It is recommended to run this function prior to allocating layer data; doing otherwise may needlessly inhibit some algorithm options due to resource usage.

Parameters

`handle`

*Input.* Handle to a previously created cuDNN context.

`xDesc`

*Input.* Handle to the previously initialized input tensor descriptor.

`wDesc`

*Input.* Handle to a previously initialized filter descriptor.

`convDesc`

*Input.* Previously initialized convolution descriptor.

`yDesc`

*Input.* Handle to the previously initialized output tensor descriptor.

`requestedAlgoCount`

*Input.* The maximum number of elements to be stored in `perfResults`.

`returnedAlgoCount`

*Output.* The number of output elements stored in `perfResults`.

`perfResults`

*Output.* A user-allocated array to store performance metrics sorted ascending by compute time.
Returns

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- handle is not allocated properly.
- xDesc, wDesc, or yDesc are not allocated properly.
- xDesc, wDesc, or yDesc has fewer than 1 dimension.
- Either returnedCount or perfResults is nil.
- requestedCount is less than 1.

**CUDNN_STATUS_ALLOC_FAILED**

This function was unable to allocate memory to store sample input, filters and output.

**CUDNN_STATUS_INTERNAL_ERROR**

At least one of the following conditions are met:

- The function was unable to allocate necessary timing objects.
- The function was unable to deallocate necessary timing objects.
- The function was unable to deallocate sample input, filters and output.

### 5.2.16. cudnnFindConvolutionForwardAlgorithmEx() (cudnnStatus_t)

```c
void cudnnStatus_t cudnnFindConvolutionForwardAlgorithmEx(
    cudnnHandle_t                      handle,
    const cudnnTensorDescriptor_t      xDesc,
    const void                        *x,
    const cudnnFilterDescriptor_t      wDesc,
    const void                        *w,
    const cudnnConvolutionDescriptor_t convDesc,
    const cudnnTensorDescriptor_t      yDesc,
    void                              *y,
    const int                          requestedAlgoCount,
    int                                *returnedAlgoCount,
    cudnnConvolutionFwdAlgoPerf_t     *perfResults,
    void                              *workSpace,
    size_t                             workSpaceSizeInBytes)
```

This function attempts all algorithms available for `cudnnConvolutionForward()`. It will attempt both the provided convDesc `mathType` and CUDNN_DEFAULT_MATH (assuming the two differ).

> **Note:** Algorithms without the CUDNN_TENSOR_OP_MATH availability will only be tried with CUDNN_DEFAULT_MATH, and returned as such.

Memory is allocated via `cudaMalloc()`. The performance metrics are returned in the user-allocated array of `cudnnConvolutionFwdAlgoPerf_t`. These metrics are written in a sorted fashion where the first element has the lowest compute
time. The total number of resulting algorithms can be queried through the API `cudnnGetConvolutionForwardAlgorithmMaxCount()`.

Note: This function is host blocking.

Parameters

**handle**

*Input*. Handle to a previously created cuDNN context.

**xDesc**

*Input*. Handle to the previously initialized input tensor descriptor.

**x**

*Input*. Data pointer to GPU memory associated with the tensor descriptor `xDesc`.

**wDesc**

*Input*. Handle to a previously initialized filter descriptor.

**w**

*Input*. Data pointer to GPU memory associated with the filter descriptor `wDesc`.

**convDesc**

*Input*. Previously initialized convolution descriptor.

**yDesc**

*Input*. Handle to the previously initialized output tensor descriptor.

**y**

*Input/Output*. Data pointer to GPU memory associated with the tensor descriptor `yDesc`. The content of this tensor will be overwritten with arbitrary values.

**requestedAlgoCount**

*Input*. The maximum number of elements to be stored in `perfResults`.

**returnedAlgoCount**

*Output*. The number of output elements stored in `perfResults`.

**perfResults**

*Output*. A user-allocated array to store performance metrics sorted ascending by compute time.

**workSpace**

*Input*. Data pointer to GPU memory is a necessary workspace for some algorithms. The size of this workspace will determine the availability of algorithms. A nil pointer is considered a `workSpace` of 0 bytes.
workSpaceSizeInBytes

*Input.* Specifies the size in bytes of the provided `workSpace`.

**Returns**

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- handle is not allocated properly.
- xDesc, wDesc, or yDesc are not allocated properly.
- xDesc, wDesc, or yDesc has fewer than 1 dimension.
- x, w, or y is nil.
- Either `returnedCount` or `perfResults` is nil.
- `requestedCount` is less than 1.

**CUDNN_STATUS_INTERNAL_ERROR**

At least one of the following conditions are met:

- The function was unable to allocate necessary timing objects.
- The function was unable to deallocate necessary timing objects.
- The function was unable to deallocate sample input, filters and output.

### 5.2.17. cudnnGetConvolution2dDescriptor()

```c

cudnnStatus_t cudnnGetConvolution2dDescriptor(

    const cudnnConvolutionDescriptor_t  convDesc,
    int                                *pad_h,
    int                                *pad_w,
    int                                *u,
    int                                *v,
    int                                *dilation_h,
    int                                *dilation_w,
    cudnnConvolutionMode_t             *mode,
    cudnnDataType_t                    *computeType)

```

This function queries a previously initialized 2D convolution descriptor object.

**Parameters**

**convDesc**

*Input/Output.* Handle to a previously created convolution descriptor.

**pad_h**

*Output.* Zero-padding height: number of rows of zeros implicitly concatenated onto the top and onto the bottom of input images.
pad_w

Output. Zero-padding width: number of columns of zeros implicitly concatenated onto the left and onto the right of input images.

u

Output. Vertical filter stride.

v

Output. Horizontal filter stride.

dilation_h

Output. Filter height dilation.

dilation_w

Output. Filter width dilation.

mode

Output. Convolution mode.

computeType

Output. Compute precision.

Returns

CUDNN_STATUS_SUCCESS

The operation was successful.

CUDNN_STATUS_BAD_PARAM

The parameter convDesc is nil.

5.2.18. cudnnGetConvolution2dForwardOutputDim()

This function returns the dimensions of the resulting 4D tensor of a 2D convolution, given the convolution descriptor, the input tensor descriptor and the filter descriptor. This function can help to setup the output tensor and allocate the proper amount of memory prior to launch the actual convolution.

Each dimension h and w of the output images is computed as follows:

```
outputDim = 1 + (inputDim + 2*pad - (((filterDim-1)*dilation)+1)) / convolutionStride;
```
Note: The dimensions provided by this routine must be strictly respected when calling `cudnnConvolutionForward()` or `cudnnConvolutionBackwardBias()`. Providing a smaller or larger output tensor is not supported by the convolution routines.

**Parameters**

`convDesc`

*Input*. Handle to a previously created convolution descriptor.

`inputTensorDesc`

*Input*. Handle to a previously initialized tensor descriptor.

`filterDesc`

*Input*. Handle to a previously initialized filter descriptor.

`n`

*Output*. Number of output images.

`c`

*Output*. Number of output feature maps per image.

`h`

*Output*. Height of each output feature map.

`w`

*Output*. Width of each output feature map.

**Returns**

**CUDNN_STATUS_BAD_PARAM**

One or more of the descriptors has not been created correctly or there is a mismatch between the feature maps of `inputTensorDesc` and `filterDesc`.

**CUDNN_STATUS_SUCCESS**

The object was set successfully.

### 5.2.19. `cudnnGetConvolutionBackwardDataAlgorithmMaxCount()`

```
cudnnStatus_t cudnnGetConvolutionBackwardDataAlgorithmMaxCount(
    cudnnHandle_t       handle,
int                 *count)
```

This function returns the maximum number of algorithms which can be returned from `cudnnFindConvolutionBackwardDataAlgorithm()` and `cudnnGetConvolutionForwardAlgorithm_v7()`. This is the sum of all algorithms plus the sum of all algorithms with Tensor Core operations supported for the current device.
Parameters

**handle**

*Input.* Handle to a previously created cuDNN context.

**count**

*Output.* The resulting maximum number of algorithms.

Returns

**CUDNN_STATUS_SUCCESS**

The function was successful.

**CUDNN_STATUS_BAD_PARAM**

The provided handle is not allocated properly.

5.2.20. **cudnnGetConvolutionBackwardDataAlgorithm_v7()**

```c
const cudnnFilterDescriptor_t wDesc,
const cudnnTensorDescriptor_t dyDesc,
const cudnnConvolutionDescriptor_t convDesc,
const int requestedAlgoCount,
int *returnedAlgoCount,
cudnnConvolutionBwdDataAlgoPerf_t *perfResults)
```

This function serves as a heuristic for obtaining the best suited algorithm for `cudnnConvolutionBackwardData()` for the given layer specifications. This function will return all algorithms (including CUDNN_TENSOR_OP_MATH and CUDNN_DEFAULT_MATH versions of algorithms where CUDNN_TENSOR_OP_MATH may be available) sorted by expected (based on internal heuristic) relative performance with the fastest being index 0 of `perfResults`. For an exhaustive search for the fastest algorithm, use `cudnnFindConvolutionBackwardDataAlgorithm()`. The total number of resulting algorithms can be queried through the `returnedAlgoCount` variable.

Parameters

**handle**

*Input.* Handle to a previously created cuDNN context.

**wDesc**

*Input.* Handle to a previously initialized filter descriptor.

**dyDesc**

*Input.* Handle to the previously initialized input differential tensor descriptor.

**convDesc**

*Input.* Previously initialized convolution descriptor.
dxDesc

*Input*. Handle to the previously initialized output tensor descriptor.

requestedAlgoCount

*Input*. The maximum number of elements to be stored in `perfResults`.

returnedAlgoCount

*Output*. The number of output elements stored in `perfResults`.

perfResults

*Output*. A user-allocated array to store performance metrics sorted ascending by compute time.

**Returns**

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- One of the parameters `handle`, `wDesc`, `dyDesc`, `convDesc`, `dxDesc`, `perfResults`, `returnedAlgoCount` is NULL.
- The numbers of feature maps of the input tensor and output tensor differ.
- The `dataType` of the two tensor descriptors or the filters are different.
- `requestedAlgoCount` is less than or equal to 0.

### 5.2.21. `cudnnGetConvolutionBackwardDataWorkspaceSize()`

```c
cudnnStatus_t cudnnGetConvolutionBackwardDataWorkspaceSize(
    cudnnHandle_t                       handle,
    const cudnnFilterDescriptor_t       wDesc,
    const cudnnTensorDescriptor_t       dyDesc,
    const cudnnConvolutionDescriptor_t  convDesc,
    const cudnnTensorDescriptor_t       dxDesc,
    cudnnConvolutionBwdDataAlgo_t       algo,
    size_t                             *sizeInBytes)
```

This function returns the amount of GPU memory workspace the user needs to allocate to be able to call `cudnnConvolutionBackwardData()` with the specified algorithm. The workspace allocated will then be passed to the routine `cudnnConvolutionBackwardData()`. The specified algorithm can be the result of the call to `cudnnGetConvolutionBackwardDataAlgorithm_v7()` or can be chosen arbitrarily by the user. Note that not every algorithm is available for every configuration of the input tensor and/or every configuration of the convolution descriptor.

**Parameters**

*handle*

*Input*. Handle to a previously created cuDNN context.
wDesc

*Input.* Handle to a previously initialized filter descriptor.

dyDesc

*Input.* Handle to the previously initialized input differential tensor descriptor.

convDesc

*Input.* Previously initialized convolution descriptor.

dxDesc

*Input.* Handle to the previously initialized output tensor descriptor.

algo

*Input.* Enumerant that specifies the chosen convolution algorithm.

sizeInBytes

*Output.* Amount of GPU memory needed as workspace to be able to execute a forward convolution with the specified algo.

Returns

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The numbers of feature maps of the input tensor and output tensor differ.
- The `dataType` of the two tensor descriptors or the filter are different.

**CUDNN_STATUS_NOT_SUPPORTED**

The combination of the tensor descriptors, filter descriptor and convolution descriptor is not supported for the specified algorithm.

### 5.2.22. cudnnGetConvolutionForwardAlgorithmMaxCount()

```c
void cudnnGetConvolutionForwardAlgorithmMaxCount(
    cudnnHandle_t handle,
    int *count)
```

This function returns the maximum number of algorithms which can be returned from `cudnnFindConvolutionForwardAlgorithm[]` and `cudnnGetConvolutionForwardAlgorithm_v7[]`. This is the sum of all algorithms plus the sum of all algorithms with Tensor Core operations supported for the current device.

**Parameters**

**handle**

*Input.* Handle to a previously created cuDNN context.
count

*Output*. The resulting maximum number of algorithms.

**Returns**

**CUDNN_STATUS_SUCCESS**

The function was successful.

**CUDNN_STATUS_BAD_PARAM**

The provided handle is not allocated properly.

### 5.2.23. `cudnnGetConvolutionForwardAlgorithm_v7()`

```c
#include <cudnn.h>

__attribute__((visibility("default"))) _GLIBCXX_FORCE_CXX11 _NOSUPPRESS_WARNING

cudnnStatus_t cudnnGetConvolutionForwardAlgorithm_v7(
    cudnnHandle_t                       handle,
    const cudnnTensorDescriptor_t       xDesc,
    const cudnnFilterDescriptor_t       wDesc,
    const cudnnConvolutionDescriptor_t  convDesc,
    const cudnnTensorDescriptor_t       yDesc,
    const int                           requestedAlgoCount,
    int                                *returnedAlgoCount,
    cudnnConvolutionFwdAlgoPerf_t      *perfResults)
```

This function serves as a heuristic for obtaining the best suited algorithm for `cudnnConvolutionForward()` for the given layer specifications. This function will return all algorithms (including `CUDNN_TENSOR_OP_MATH` and `CUDNN_DEFAULT_MATH` versions of algorithms where `CUDNN_TENSOR_OP_MATH` may be available) sorted by expected (based on internal heuristic) relative performance with the fastest being index 0 of `perfResults`. For an exhaustive search for the fastest algorithm, use `cudnnFindConvolutionForwardAlgorithm()`. The total number of resulting algorithms can be queried through the `returnedAlgoCount` variable.

**Parameters**

**handle**

*Input*. Handle to a previously created cuDNN context.

**xDesc**

*Input*. Handle to the previously initialized input tensor descriptor.

**wDesc**

*Input*. Handle to a previously initialized convolution filter descriptor.

**convDesc**

*Input*. Previously initialized convolution descriptor.

**yDesc**

*Input*. Handle to the previously initialized output tensor descriptor.

**requestedAlgoCount**

*Input*. The maximum number of elements to be stored in `perfResults`.

```c
#include <cudnn.h>

__attribute__((visibility("default"))) _GLIBCXX_FORCE_CXX11 _NOSUPPRESS_WARNING

cudnnStatus_t cudnnGetConvolutionForwardAlgorithm_v7(
    cudnnHandle_t                       handle,
    const cudnnTensorDescriptor_t       xDesc,
    const cudnnFilterDescriptor_t       wDesc,
    const cudnnConvolutionDescriptor_t  convDesc,
    const cudnnTensorDescriptor_t       yDesc,
    const int                           requestedAlgoCount,
    int                                *returnedAlgoCount,
    cudnnConvolutionFwdAlgoPerf_t      *perfResults)
```
**returnedAlgoCount**

*Output.* The number of output elements stored in `perfResults`.

**perfResults**

*Output.* A user-allocated array to store performance metrics sorted ascending by compute time.

**Returns**

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- One of the parameters `handle`, `xDesc`, `wDesc`, `convDesc`, `yDesc`, `perfResults`, `returnedAlgoCount` is `NULL`.
- Either `yDesc` or `wDesc` have different dimensions from `xDesc`.
- The data types of tensors `xDesc`, `yDesc` or `wDesc` are not all the same.
- The number of feature maps in `xDesc` and `wDesc` differs.
- The tensor `xDesc` has a dimension smaller than 3.
- `requestedAlgoCount` is less than or equal to 0.

### 5.2.24. cudnnGetConvolutionForwardWorkspaceSize()

```c
extern "C" cudnnStatus_t cudnnGetConvolutionForwardWorkspaceSize(
    cudnnHandle_t handle,
    const cudnnTensorDescriptor_t xDesc,
    const cudnnFilterDescriptor_t wDesc,
    const cudnnConvolutionDescriptor_t convDesc,
    const cudnnTensorDescriptor_t yDesc,
    cudnnConvolutionFwdAlgo_t algo,
    size_t *sizeInBytes)
```

This function returns the amount of GPU memory workspace the user needs to allocate to be able to call `cudnnConvolutionForward()` with the specified algorithm. The workspace allocated will then be passed to the routine `cudnnConvolutionForward()`. The specified algorithm can be the result of the call to `cudnnGetConvolutionForwardAlgorithm_v7()` or can be chosen arbitrarily by the user. Note that not every algorithm is available for every configuration of the input tensor and/or every configuration of the convolution descriptor.

**Parameters**

**handle**

*Input.* Handle to a previously created cuDNN context.

**xDesc**

*Input.* Handle to the previously initialized `x` tensor descriptor.
wDesc

Input. Handle to a previously initialized filter descriptor.

covDesc

Input. Previously initialized convolution descriptor.

yDesc

Input. Handle to the previously initialized y tensor descriptor.

algo

Input. Enumerant that specifies the chosen convolution algorithm.

sizeInBytes

Output. Amount of GPU memory needed as workspace to be able to execute a forward convolution with the specified algo.

Returns

CUDNN_STATUS_SUCCESS

The query was successful.

CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- One of the parameters handle, xDesc, wDesc, convDesc, yDesc is NULL.
- The tensor yDesc or wDesc are not of the same dimension as xDesc.
- The tensor xDesc, yDesc or wDesc are not of the same data type.
- The numbers of feature maps of the tensor xDesc and wDesc differ.
- The tensor xDesc has a dimension smaller than 3.

CUDNN_STATUS_NOT_SUPPORTED

The combination of the tensor descriptors, filter descriptor and convolution descriptor is not supported for the specified algorithm.

5.2.25. cudnnGetConvolutionGroupCount()

cudnnStatus_t cudnnGetConvolutionGroupCount(
    cudnnConvolutionDescriptor_t convDesc,  
    int *groupCount)

This function returns the group count specified in the given convolution descriptor.

Returns

CUDNN_STATUS_SUCCESS

The group count was returned successfully.
CUDNN_STATUS_BAD_PARAM

An invalid convolution descriptor was provided.

5.2.26. cudnnGetConvolutionMathType()
cudnnStatus_t cudnnGetConvolutionMathType(
    cudnnConvolutionDescriptor_t convDesc,
    cudnnMathType_t *mathType)

This function returns the math type specified in a given convolution descriptor.

Returns

CUDNN_STATUS_SUCCESS

The math type was returned successfully.

CUDNN_STATUS_BAD_PARAM

An invalid convolution descriptor was provided.

5.2.27. cudnnGetConvolutionNdDescriptor()
cudnnStatus_t cudnnGetConvolutionNdDescriptor(
    const cudnnConvolutionDescriptor_t convDesc,
    int arrayLengthRequested,
    int *arrayLength,
    int padA[],
    int filterStrideA[],
    int dilationA[],
    cudnnConvolutionMode_t *mode,
    cudnnDataType_t *dataType)

This function queries a previously initialized convolution descriptor object.

Parameters

convDesc

Input/Output. Handle to a previously created convolution descriptor.

arrayLengthRequested

Input. Dimension of the expected convolution descriptor. It is also the minimum size of the arrays padA, filterStrideA, and dilationA in order to be able to hold the results

arrayLength

Output. Actual dimension of the convolution descriptor.

padA

Output. Array of dimension of at least arrayLengthRequested that will be filled with the padding parameters from the provided convolution descriptor.

filterStrideA

Output. Array of dimension of at least arrayLengthRequested that will be filled with the filter stride from the provided convolution descriptor.
dilationA

Output. Array of dimension of at least `arrayLengthRequested` that will be filled with the
dilation parameters from the provided convolution descriptor.

mode

Output. Convolution mode of the provided descriptor.

datatype

Output. Datatype of the provided descriptor.

Returns

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The descriptor `convDesc` is nil.
- The `arrayLengthRequest` is negative.

**CUDNN_STATUS_NOT_SUPPORTED**

The `arrayLengthRequested` is greater than `CUDNN_DIM_MAX-2`.

5.2.28. **cudnnGetConvolutionNdForwardOutputDim()**

cudnnStatus_t cudnnGetConvolutionNdForwardOutputDim(
    const cudnnConvolutionDescriptor_t convDesc,
    const cudnnTensorDescriptor_t inputTensorDesc,
    const cudnnFilterDescriptor_t filterDesc,
    int nbDims,
    int *outputDimA[])

This function returns the dimensions of the resulting n-D tensor of a `nbDims-2`-D convolution,
given the convolution descriptor, the input tensor descriptor and the filter descriptor. This
function can help to setup the output tensor and allocate the proper amount of memory prior
to launch the actual convolution.

Each dimension of the `(nbDims-2)`-D images of the output tensor is computed as follows:

\[
\text{outputDim} = 1 + (\text{inputDim} + 2\times\text{pad} - (((\text{filterDim}-1)\times\text{dilation})+1)) / \text{convolutionStride};
\]

- **Note:** The dimensions provided by this routine must be strictly respected when calling
  `cudnnConvolutionForward()` or `cudnnConvolutionBackwardBias()`. Providing a smaller or larger
  output tensor is not supported by the convolution routines.
Parameters

**convDesc**

*Input.* Handle to a previously created convolution descriptor.

**inputTensorDesc**

*Input.* Handle to a previously initialized tensor descriptor.

**filterDesc**

*Input.* Handle to a previously initialized filter descriptor.

**nbDims**

*Input.* Dimension of the output tensor.

**tensorOutputDimA**

*Output.* Array of dimensions `nbDims` that contains on exit of this routine the sizes of the output tensor.

Returns

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- One of the parameters `convDesc`, `inputTensorDesc`, and `filterDesc` is nil.
- The dimension of the filter descriptor `filterDesc` is different from the dimension of input tensor descriptor `inputTensorDesc`.
- The dimension of the convolution descriptor is different from the dimension of input tensor descriptor `inputTensorDesc-2`.
- The features map of the filter descriptor `filterDesc` is different from the one of input tensor descriptor `inputTensorDesc`.
- The size of the dilated filter `filterDesc` is larger than the padded sizes of the input tensor.
- The dimension `nbDims` of the output array is negative or greater than the dimension of input tensor descriptor `inputTensorDesc`.

**CUDNN_STATUS_SUCCESS**

The routine exited successfully.

5.2.29. **cudnnGetConvolutionReorderType()**

cudnnStatus_t cudnnGetConvolutionReorderType(
    cudnnConvolutionDescriptor_t convDesc,
    cudnnReorderType_t *reorderType);

This function retrieves the convolution reorder type from the given convolution descriptor.
Parameters

**convDesc**
*Input.* The convolution descriptor from which the reorder type should be retrieved.

**reorderType**
*Output.* The retrieved reorder type. For more information, see cudnnReorderType_t.

Returns

**CUDNN_STATUS_BAD_PARAM**
One of the inputs to this function is not valid.

**CUDNN_STATUS_SUCCESS**
The reorder type is retrieved successfully.

5.2.30. **cudnnGetFoldedConvBackwardDataDescriptors()**

```c
const cudnnStatus_t cudnnGetFoldedConvBackwardDataDescriptors(
    const cudnnHandle_t handle,
    const cudnnFilterDescriptor_t filterDesc,
    const cudnnTensorDescriptor_t diffDesc,
    const cudnnConvolutionDescriptor_t convDesc,
    const cudnnTensorDescriptor_t gradDesc,
    const cudnnTensorFormat_t transformFormat,
    cudnnFilterDescriptor_t foldedFilterDesc,
    cudnnTensorDescriptor_t paddedDiffDesc,
    cudnnConvolutionDescriptor_t foldedConvDesc,
    cudnnTensorDescriptor_t foldedGradDesc,
    cudnnConvolutionDescriptor_t filterFoldTransDesc,
    cudnnTensorTransformDescriptor_t diffPadTransDesc,
    cudnnTensorTransformDescriptor_t gradFoldTransDesc,
    cudnnTensorTransformDescriptor_t gradUnfoldTransDesc);
```

This function calculates folding descriptors for backward data gradient. It takes as input the data descriptors along with convolution descriptor and computes the folded data descriptors and the folding transform descriptors. These can then be used to do the actual folding transform.

Parameters

**handle**
*Input.* Handle to a previously created cuDNN context.

**filterDesc**
*Input.* Filter descriptor before folding.

**diffDesc**
*Input.* Diff descriptor before folding.
convDesc

*Input.* Convolution descriptor before folding.

gradDesc

*Input.* Gradient descriptor before folding.

transformFormat

*Input.* Transform format for folding.

foldedFilterDesc

*Output.* Folded filter descriptor.

paddedDiffDesc

*Output.* Padded Diff descriptor.

foldedConvDesc

*Output.* Folded convolution descriptor.

foldedGradDesc

*Output.* Folded gradient descriptor.

filterFoldTransDesc

*Output.* Folding transform descriptor for filter.

diffPadTransDesc

*Output.* Folding transform descriptor for Desc.

gradFoldTransDesc

*Output.* Folding transform descriptor for gradient.

gradUnfoldTransDesc

*Output.* Unfolding transform descriptor for folded gradient.

Returns

**CUDNN_STATUS_SUCCESS**

Folded descriptors were computed successfully.

**CUDNN_STATUS_BAD_PARAM**

If any of the input parameters is `NULL` or if the input tensor has more than 4 dimensions.

**CUDNN_STATUS_EXECUTION_FAILED**

Computing the folded descriptors failed.

5.2.31. **cudnnIm2Col()**

```c

cudnnStatus_t cudnnIm2Col(
    cudnnHandle_t    handle,
    cudnnTensorDescriptor_t srcDesc,
    const void*       srcData,
);
```
This function constructs the A matrix necessary to perform a forward pass of GEMM convolution. This A matrix has a height of batch\_size*y\_height*y\_width and width of input\_channels*filter\_height*filter\_width, where:

- batch\_size is xDesc first dimension
- y\_height/y\_width are computed from cudnnGetConvolutionNdForwardOutputDim()
- input\_channels is xDesc second dimension
- filter\_height/filter\_width are wDesc third and fourth dimension

The A matrix is stored in format HW fully-packed in GPU memory.

Parameters

**handle**

*Input*. Handle to a previously created cuDNN context.

**srcDesc**

*Input*. Handle to a previously initialized tensor descriptor.

**srcData**

*Input*. Data pointer to GPU memory associated with the input tensor descriptor.

**filterDesc**

*Input*. Handle to a previously initialized filter descriptor.

**convDesc**

*Input*. Handle to a previously initialized convolution descriptor.

**colBuffer**

*Output*. Data pointer to GPU memory storing the output matrix.

Returns

CUDNN\_STATUS\_BAD\_PARAM

srcData or colBuffer is NULL.

CUDNN\_STATUS\_NOT\_SUPPORTED

Any of srcDesc, filterDesc, convDesc has dataType of CUDNN\_DATA\_INT8, CUDNN\_DATA\_INT8x4, CUDNN\_DATA\_INT8 or CUDNN\_DATA\_INT8x4 convDesc has groupCount larger than 1.

CUDNN\_STATUS\_EXECUTION\_FAILED

The CUDA kernel execution was unsuccessful.
5.2.32. **cudnnReorderFilterAndBias()**

```c
int cudnnReorderFilterAndBias(  
  cudnnHandle_t handle,  
  const cudnnFilterDescriptor_t filterDesc,  
  cudnnReorderType_t reorderType,  
  const void *filterData,  
  void *reorderedFilterData,  
  int reorderBias,  
  const void *biasData,  
  void *reorderedBiasData);
```

This function `cudnnReorderFilterAndBias()` reorders the filter and bias values. It can be used to enhance the inference time by separating the reordering operation from convolution.

For example, convolutions in a neural network of multiple layers can require reordering of kernels at every layer, which can take up a significant fraction of the total inference time. Using this function, the reordering can be done one time on the filter and bias data followed by the convolution operations at the multiple layers, thereby enhancing the inference time.

**Parameters**

- **filterDesc**
  
  *Input*. Descriptor for the kernel dataset.

- **reorderType**
  
  *Input*. Setting to either perform reordering or not. For more information, see `cudnnReorderType_t`.

- **filterData**
  
  *Input*. Pointer to the filter (kernel) data location in the device memory.

- **reorderedFilterData**
  
  *Input*. Pointer to the location in the device memory where the reordered filter data will be written to, by this function.

- **reorderBias**
  
  *Input*. If > 0, then reorders the bias data also. If <= 0 then does not perform reordering operations on the bias data.

- **biasData**
  
  *Input*. Pointer to the bias data location in the device memory.

- **reorderedBiasData**
  
  *Input*. Pointer to the location in the device memory where the reordered bias data will be written to, by this function.

**Returns**

- **CUDNN_STATUS_SUCCESS**
  
  Reordering was successful.
CUDNN_STATUS_EXECUTION_FAILED
Either the reordering of the filter data or of the bias data failed.

5.2.33. cudnnSetConvolution2dDescriptor()

This function initializes a previously created convolution descriptor object into a 2D correlation. This function assumes that the tensor and filter descriptors correspond to the forward convolution path and checks if their settings are valid. That same convolution descriptor can be reused in the backward path provided it corresponds to the same layer.

Parameters

convDesc
Input/Output. Handle to a previously created convolution descriptor.

pad_h
Input. Zero-padding height: number of rows of zeros implicitly concatenated onto the top and onto the bottom of input images.

pad_w
Input. Zero-padding width: number of columns of zeros implicitly concatenated onto the left and onto the right of input images.

u
Input. Vertical filter stride.

v
Input. Horizontal filter stride.

dilation_h
Input. Filter height dilation.

dilation_w
Input. Filter width dilation.

mode
Input. Selects between CUDNN_CONVOLUTION and CUDNN_CROSS_CORRELATION.

computeType
Input. Compute precision.
Returns

**CUDNN_STATUS_SUCCESS**

The object was set successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The descriptor `convDesc` is nil.
- One of the parameters `pad_h`, `pad_w` is strictly negative.
- One of the parameters `u`, `v` is negative or zero.
- One of the parameters `dilation_h`, `dilation_w` is negative or zero.
- The parameter `mode` has an invalid enumerant value.

### 5.2.34. cudnnSetConvolutionGroupCount()

cudnnStatus_t cudnnSetConvolutionGroupCount(
    cudnnConvolutionDescriptor_t convDesc,
    int groupCount)

This function allows the user to specify the number of groups to be used in the associated convolution.

Returns

**CUDNN_STATUS_SUCCESS**

The group count was set successfully.

**CUDNN_STATUS_BAD_PARAM**

An invalid convolution descriptor was provided.

### 5.2.35. cudnnSetConvolutionMathType()

cudnnStatus_t cudnnSetConvolutionMathType(
    cudnnConvolutionDescriptor_t convDesc,
    cudnnMathType_t mathType)

This function allows the user to specify whether or not the use of tensor op is permitted in the library routines associated with a given convolution descriptor.

Returns

**CUDNN_STATUS_SUCCESS**

The math type was set successfully.

**CUDNN_STATUS_BAD_PARAM**

Either an invalid convolution descriptor was provided or an invalid math type was specified.
5.2.36. cudnnSetConvolutionNdDescriptor()

cudnnStatus_t cudnnSetConvolutionNdDescriptor(
    cudnnConvolutionDescriptor_t    convDesc,
    int                             arrayLength,
    const int                       padA[],
    const int                       filterStrideA[],
    const int                       dilationA[],
    cudnnConvolutionMode_t          mode,
    cudnnDataType_t                 dataType)

This function initializes a previously created generic convolution descriptor object into a n-D correlation. That same convolution descriptor can be reused in the backward path provided it corresponds to the same layer. The convolution computation will be done in the specified dataType, which can be potentially different from the input/output tensors.

Parameters

convDesc

Input/Output. Handle to a previously created convolution descriptor.

arrayLength

Input. Dimension of the convolution.

padA

Input. Array of dimension arrayLength containing the zero-padding size for each dimension. For every dimension, the padding represents the number of extra zeros implicitly concatenated at the start and at the end of every element of that dimension.

filterStrideA

Input. Array of dimension arrayLength containing the filter stride for each dimension. For every dimension, the filter stride represents the number of elements to slide to reach the next start of the filtering window of the next point.

dilationA

Input. Array of dimension arrayLength containing the dilation factor for each dimension.

mode

Input. Selects between CUDNN_CONVOLUTION and CUDNN_CROSS_CORRELATION.

datatype

Input. Selects the data type in which the computation will be done.

Note: CUDNN_DATA_HALF in cudnnSetConvolutionNdDescriptor() with HALF_CONVOLUTION_BWD_FILTER is not recommended as it is known to not be useful for any practical use case for training and will be considered to be blocked in a future cuDNN release. The use of CUDNN_DATA_HALF for input tensors in cudnnSetTensorNdDescriptor() and CUDNN_DATA_FLOAT in cudnnSetConvolutionNdDescriptor() with HALF_CONVOLUTION_BWD_FILTER is...
recommended and is used with the automatic mixed precision (AMP) training in many well known deep learning frameworks.

Returns

**CUDNN_STATUS_SUCCESS**

The object was set successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The descriptor `convDesc` is nil.
- The `arrayLengthRequest` is negative.
- The enumerant `mode` has an invalid value.
- The enumerant `datatype` has an invalid value.
- One of the elements of `padA` is strictly negative.
- One of the elements of `strideA` is negative or zero.
- One of the elements of `dilationA` is negative or zero.

**CUDNN_STATUS_NOT_SUPPORTED**

At least one of the following conditions are met:

- The `arrayLengthRequest` is greater than `CUDNN_DIM_MAX`.

5.2.37. **cudnnSetConvolutionReorderType()**

cudnnStatus_t cudnnSetConvolutionReorderType(
  cudnnConvolutionDescriptor_t convDesc,
  cudnnReorderType_t reorderType);

This function sets the convolution reorder type for the given convolution descriptor.

Parameters

- `convDesc
  Input. The convolution descriptor for which the reorder type should be set.

- `reorderType
  Input. Set the reorder type to this value. For more information, see `cudnnReorderType_t`.

Returns

**CUDNN_STATUS_BAD_PARAM**

The reorder type supplied is not supported.

**CUDNN_STATUS_SUCCESS**

Reorder type is set successfully.
6.1. Data Type References

6.1.1. Pointer To Opaque Struct Types

6.1.1.1. cudnnFusedOpsConstParamPack_t

cudnnFusedOpsConstParamPack_t is a pointer to an opaque structure holding the description of the cudnnFusedOps constant parameters. Use the function cudnnCreateFusedOpsConstParamPack() to create one instance of this structure, and the function cudnnDestroyFusedOpsConstParamPack() to destroy a previously-created descriptor.

6.1.1.2. cudnnFusedOpsPlan_t

cudnnFusedOpsPlan_t is a pointer to an opaque structure holding the description of the cudnnFusedOpsPlan. This descriptor contains the plan information, including the problem type and size, which kernels should be run, and the internal workspace partition. Use the function cudnnCreateFusedOpsPlan() to create one instance of this structure, and the function cudnnDestroyFusedOpsPlan() to destroy a previously-created descriptor.

6.1.1.3. cudnnFusedOpsVariantParamPack_t

cudnnFusedOpsVariantParamPack_t is a pointer to an opaque structure holding the description of the cudnnFusedOps variant parameters. Use the function cudnnCreateFusedOpsVariantParamPack() to create one instance of this structure, and the function cudnnDestroyFusedOpsVariantParamPack() to destroy a previously-created descriptor.

6.1.2. Struct Types

6.1.2.1. cudnnConvolutionBwdFilterAlgoPerf_t
cudnnConvolutionBwdFilterAlgoPerf_t is a structure containing performance results returned by `cudnnFindConvolutionBackwardFilterAlgorithm()` or heuristic results returned by `cudnnGetConvolutionBackwardFilterAlgorithm_v7()`.

**Data Members**

- **cudnnConvolutionBwdFilterAlgo_t algo**
  The algorithm runs to obtain the associated performance metrics.

- **cudnnStatus_t status**
  If any error occurs during the workspace allocation or timing of `cudnnConvolutionBackwardFilter()`, this status will represent that error. Otherwise, this status will be the return status of `cudnnConvolutionBackwardFilter()`.
  - CUDNN_STATUS_ALLOC_FAILED if any error occurred during workspace allocation or if the provided workspace is insufficient.
  - CUDNN_STATUS_INTERNAL_ERROR if any error occurred during timing calculations or workspace deallocation.
  - Otherwise, this will be the return status of `cudnnConvolutionBackwardFilter()`.

- **float time**
  The execution time of `cudnnConvolutionBackwardFilter()` (in milliseconds).

- **size_t memory**
  The workspace size (in bytes).

- **cudnnDeterminism_t determinism**
  The determinism of the algorithm.

- **cudnnMathType_t mathType**
  The math type provided to the algorithm.

- **int reserved[3]**
  Reserved space for future properties.

### 6.1.3. Enumeration Types

#### 6.1.3.1. cudnnFusedOps_t

The `cudnnFusedOps_t` type is an enumerated type to select a specific sequence of computations to perform in the fused operations.

<table>
<thead>
<tr>
<th>Member</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CUDNN_FUSED_SCALE_BIAS_ACTIVATION_CONV_BNSTATS</td>
<td>One per-channel basis, performs these operations in this order: scale, add bias, activation, convolution, and generate batchnorm statistics.</td>
</tr>
<tr>
<td>Member</td>
<td>Description</td>
</tr>
<tr>
<td>--------</td>
<td>-------------</td>
</tr>
<tr>
<td>CUDNN_FUSED_SCALE_BIAS_ACTIVATION_WGRAD = 1</td>
<td>On a per-channel basis, performs these operations in this order: scale, add bias, activation, convolution backward weights, and generate batchnorm statistics.</td>
</tr>
</tbody>
</table>

**CUDNN_FUSED_SCALE_BIAS_ACTIVATION_WGRAD**

Output

\[
\begin{align*}
\text{dw} & \rightarrow \text{wgrad} \\
y_1 & \rightarrow \text{ReLU} \\
y_0 & \rightarrow \text{Scale & Bias} \\
y_1 &= \text{ReLU}(y_0) \\
y_0 &= \text{scale}(x)+\text{bias}
\end{align*}
\]

Input

\[
\begin{align*}
x & \rightarrow \text{equivalent scale} \\
x & \rightarrow \text{equivalent bias}
\end{align*}
\]

\[
\text{dy} \leftarrow \text{dw} \\
\]

- CUDNN_FUSED_BN_FINALIZE_STATISTICS_TRAINING = 2
  - Computes the equivalent scale and bias from \(y\text{Sum}, y\text{SqSum}\) and learned scale, bias.
  - Optionally update running statistics and generate saved stats.

- CUDNN_FUSED_BN_FINALIZE_STATISTICS_INFERENCE = 3
  - Computes the equivalent scale and bias from the learned running statistics and the learned scale, bias.

- CUDNN_FUSED_CONV_SCALE_BIAS_ADD_ACTIVATION = 4
  - On a per-channel basis, performs these operations in this order: convolution, scale, add bias, element-wise addition with another tensor, and activation.

- CUDNN_FUSED_SCALE_BIAS_ADD_ACTIVATION_GEN_BITMASK = 5
  - On a per-channel basis, performs these operations in this order: scale and bias on one tensor, scale, and bias on a second tensor, element-wise addition of these two tensors, and on the resulting tensor perform activation, and generate activation bit mask.

- CUDNN_FUSED_DACTIVATION_FORK_DBATCHNORM = 6
  - On a per-channel basis, performs these operations in this order: backward activation, fork [meaning, write out gradient for the residual branch], and backward batch norm.
6.1.3.2. **cudnnFusedOpsConstParamLabel_t**

The `cudnnFusedOpsConstParamLabel_t` is an enumerated type for the selection of the type of the `cudnnFusedOps` descriptor. For more information, see `cudnnSetFusedOpsConstParamPackAttribute()`.

```c
typedef enum {
    CUDNN_PARAM_XDESC                          = 0,
    CUDNN_PARAM_XDATA_PLACEHOLDER              = 1,
    CUDNN_PARAM_BN_MODE                        = 2,
    CUDNN_PARAM_BN_EQSCALEBIAS_DESC            = 3,
    CUDNN_PARAM_BN_EQSCALE_PLACEHOLDER         = 4,
    CUDNN_PARAM_BN_EQBIAS_PLACEHOLDER          = 5,
    CUDNN_PARAM_ACTIVATION_DESC                = 6,
    CUDNN_PARAM_CONV_DESC                      = 7,
    CUDNN_PARAM_WDESC                          = 8,
    CUDNN_PARAM_WDATA_PLACEHOLDER              = 9,
    CUDNN_PARAM_DWDESC                         = 10,
    CUDNN_PARAM_DWDATA_PLACEHOLDER             = 11,
    CUDNN_PARAM_YDESC                          = 12,
    CUDNN_PARAM_YDATA_PLACEHOLDER              = 13,
    CUDNN_PARAM_YDESC                          = 12,
    CUDNN_PARAM_DXDESC                         = 14,
    CUDNN_PARAM_DXDATA_PLACEHOLDER             = 15,
    CUDNN_PARAM_DWDESC                         = 16,
    CUDNN_PARAM_DWDATA_PLACEHOLDER             = 17,
    CUDNN_PARAM_BN_SCALEBIAS_MEANVAR_DESC      = 18,
    CUDNN_PARAM_BN_SCALE_PLACEHOLDER           = 19,
    CUDNN_PARAM_BN_BIAS_PLACEHOLDER            = 20,
    CUDNN_PARAM_BN_SAVED_MEAN_PLACEHOLDER      = 21,
    CUDNN_PARAM_BN_SAVED_INVSTD_PLACEHOLDER    = 22,
    CUDNN_PARAM_BN_RUNNING_MEAN_PLACEHOLDER    = 23,
    CUDNN_PARAM_BN_RUNNING_VAR_PLACEHOLDER     = 24,
    CUDNN_PARAM_BN_ZDESC                       = 25,
    CUDNN_PARAM_BN_ZDATA_PLACEHOLDER           = 26,
    CUDNN_PARAM_ACTIVATION_BITMASK_DESC        = 27,
    CUDNN_PARAM_ACTIVATION_BITMASK_PLACEHOLDER = 28,
    CUDNN_PARAM_DXDESC                         = 29,
    CUDNN_PARAM_DXDATA_PLACEHOLDER             = 30,
    CUDNN_PARAM_BN_DSCALE_PLACEHOLDER          = 31,
    CUDNN_PARAM_BN_DBIAS_PLACEHOLDER           = 32,
} cudnnFusedOpsConstParamLabel_t;
```

<table>
<thead>
<tr>
<th>Short-form used</th>
<th>Stands for</th>
</tr>
</thead>
<tbody>
<tr>
<td>Setter</td>
<td>cudnnSetFusedOpsConstParamPackAttribute()</td>
</tr>
<tr>
<td>Getter</td>
<td>cudnnGetFusedOpsConstParamPackAttribute()</td>
</tr>
<tr>
<td>X_PointerPlaceHolder_t</td>
<td>cudnnFusedOpsPointerPlaceHolder_t</td>
</tr>
<tr>
<td>X_prefix in the Attribute column</td>
<td>Stands for CUDNN_PARAM in the enumerator name</td>
</tr>
</tbody>
</table>
Table 22. **CUDNN_FUSED_SCALE_BIAS_ACTIVATION_CONV_BNSTATS**

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_XDESC</td>
<td>In the setter, the *param should be xDesc, a pointer to a previously initialized cudnnTensorDescriptor_t.</td>
<td>Tensor descriptor describing the size, layout, and datatype of the x (input) tensor.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_XDATA_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder_t.</td>
<td>Describes whether xData pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_BN_MODE</td>
<td>In the setter, the *param should be a pointer to a previously initialized cudnnBatchNormMode_t.</td>
<td>Describes the mode of operation for the scale, bias and the statistics. As of cuDNN 7.6.0, only CUDNN_BATCHNORM_SPATIAL and CUDNN_BATCHNORM_SPATIAL_PERSISTENT are supported, meaning, scale, bias, and statistics are all per-channel.</td>
<td>CUDNN_BATCHNORM_PER_ACTIVATION</td>
</tr>
<tr>
<td>X_BN_EQSCALEBIAS_DESC</td>
<td>In the setter, the *param should be a pointer to a previously initialized cudnnTensorDescriptor_t.</td>
<td>Tensor descriptor describing the size, layout, and datatype of the batchNorm equivalent scale and bias tensors. The shapes must match the mode specified in CUDNN_PARAM_BN_MODE. If set to NULL, both scale and bias operation will become a NOP.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_BN_EQSCALE_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder_t.</td>
<td>Describes whether batchnorm equivalent scale pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>Attribute</td>
<td>Expected Descriptor Type Passed in, in the Setter</td>
<td>Description</td>
<td>Default Value After Creation</td>
</tr>
<tr>
<td>----------------------------------------</td>
<td>------------------------------------------------------------------------------------------------------------------</td>
<td>--------------------------------------------------------------------------------------------------</td>
<td>-------------------------------</td>
</tr>
<tr>
<td>CUDNN_FUSED_SCALE_BIAS_ACTIVATION_CONV_BNSTATS</td>
<td>If set to CUDNN_PTR_NULL, then the scale operation becomes a NOP.</td>
<td></td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_BN_EQBIAS_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder.</td>
<td>Describes whether batchnorm equivalent bias pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_ACTIVATION_DESC</td>
<td>In the setter, the *param should be a pointer to a previously initialized cudnnActivationDescriptor.</td>
<td>Describes the activation operation.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_CONV_DESC</td>
<td>In the setter, the <em>param should be a pointer to a previously initialized cudnnConvolutionDescriptor_t</em>.</td>
<td>Describes the convolution operation.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_WDESC</td>
<td>In the setter, the <em>param should be a pointer to a previously initialized cudnnFilterDescriptor_t</em>.</td>
<td>Filter descriptor describing the size, layout and datatype of the ( w ) (filter) tensor.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_WDATA_PLACEHOLDER</td>
<td>In the setter, the <em>param should be a pointer to a previously initialized X_PointerPlaceHolder_t</em>.</td>
<td>Describes whether ( w ) (filter) tensor pointer in the VariantParamPack will be NULL, or if not,</td>
<td>CUDNN_PTR_NULL</td>
</tr>
</tbody>
</table>
For the attribute `CUDNN_FUSED_SCALE_BIAS_ACTIVATION_CONV_BNSTATS` in `cudnnFusedOp_t`

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_YDESC</td>
<td>In the setter, the <em>param should be a pointer to a previously initialized <code>cudnnTensorDescriptor_t</code>.</em></td>
<td>Tensor descriptor describing the size, layout and datatype of the y (output) tensor.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_YDATA_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized <code>X_PointerPlaceHolder</code></td>
<td>Describes whether y (output) tensor pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment.*</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_YSTATS_DESC</td>
<td>In the setter, the <em>param should be a pointer to a previously initialized <code>cudnnTensorDescriptor_t</code>.</em></td>
<td>Tensor descriptor describing the size, layout and datatype of the sum of y and sum of y square tensors. The shapes need to match the mode specified in <code>CUDNN_PARAM_BN_MODE</code>. If set to NULL, the y statistics generation operation will become a NOP.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_YSUM_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized <code>X_PointerPlaceHolder</code></td>
<td>Describes whether sum of y pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment.*. If set to CUDNN_PTR.NULL, the y statistics generation operation will become a NOP.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_YSQSUM_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized <code>X_PointerPlaceHolder</code></td>
<td>Describes whether sum of y square pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment.*.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
</tbody>
</table>
For the attribute **CUDNN_FUSED_SCALE_BIAS_ACTIVATION_CONV_BNSTATS** in **cudnnFusedOp_t**

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>If set to CUDNN_PTR_NULL, the statistics generation operation will become a NOP.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Note:**

- If the corresponding pointer placeholder in ConstParamPack is set to CUDNN_PTR_NULL, then the device pointer in the VariantParamPack needs to be NULL as well.
- If the corresponding pointer placeholder in ConstParamPack is set to CUDNN_PTR_ELEM_ALIGNED or CUDNN_PTR_16B_ALIGNED, then the device pointer in the VariantParamPack may not be NULL and need to be at least element-aligned or 16 bytes-aligned, respectively.

As of cuDNN 7.6.0, if the conditions in **Table 23** are met, then the fully fused fast path will be triggered. Otherwise, a slower partially fused path will be triggered.

**Table 23. Conditions for Fully Fused Fast Path (Forward)**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Condition</th>
</tr>
</thead>
<tbody>
<tr>
<td>Device compute capability</td>
<td>Need to be one of 7.0, 7.2 or 7.5.</td>
</tr>
<tr>
<td>CUDNN_PARAM_XDESC</td>
<td>Tensor is 4 dimensional</td>
</tr>
<tr>
<td>CUDNN_PARAM_XDATA_PLACEHOLDER</td>
<td>Datatype is CUDNN_DATA_HALF</td>
</tr>
<tr>
<td></td>
<td>Layout is NHWC fully packed</td>
</tr>
<tr>
<td></td>
<td>Alignment is CUDNN_PTR_16B_ALIGNED</td>
</tr>
<tr>
<td></td>
<td>Tensor’s C dimension is a multiple of 8.</td>
</tr>
<tr>
<td>CUDNN_PARAM_BN_EQSCALEBIAS_DESC</td>
<td>If either one of scale and bias operation is not turned into a NOP:</td>
</tr>
<tr>
<td>CUDNN_PARAM_BN_EQSCALE_PLACEHOLDER</td>
<td>Tensor is 4 dimensional with shape 1xCx1x1</td>
</tr>
<tr>
<td>CUDNN_PARAM_BN_EQBIAS_PLACEHOLDER</td>
<td>Datatype is CUDNN_DATA_HALF</td>
</tr>
<tr>
<td></td>
<td>Layout is fully packed</td>
</tr>
<tr>
<td></td>
<td>Alignment is CUDNN_PTR_16B_ALIGNED</td>
</tr>
<tr>
<td>CUDNN_PARAM_CONV_DESC</td>
<td>Convolution descriptor’s mode needs to be CUDNN_CROSS_CORRELATION.</td>
</tr>
<tr>
<td>CUDNN_PARAM_WDESC</td>
<td>Convolution descriptor’s dataType needs to be CUDNN_DATA_FLOAT.</td>
</tr>
<tr>
<td>CUDNN_PARAM_WDATA_PLACEHOLDER</td>
<td>Convolution descriptor’s dilationA is (1,1).</td>
</tr>
</tbody>
</table>
### Parameter Condition

- Convolution descriptor’s group count needs to be 1.
- Convolution descriptor’s mathType needs to be `CUDNN_TENSOR_OP_MATH` or `CUDNN_TENSOR_OP_MATH.AllowConversion`.
- Filter is in NHWC layout
- Filter’s data type is `CUDNN_DATA_HALF`
- Filter’s K dimension is a multiple of 32
- Filter size RxS is either 1x1 or 3x3
- If filter size RxS is 1x1, convolution descriptor’s padA needs to be (0,0) and filterStrideA needs to be (1,1).
- Filter’s alignment is `CUDNN_PTR_16B_ALIGNED`

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Condition</th>
</tr>
</thead>
<tbody>
<tr>
<td>CUDNN_PARAM_YDESC</td>
<td>Tensor is 4 dimensional</td>
</tr>
<tr>
<td>CUDNN_PARAM_YDATA_PLACEHOLDER</td>
<td>Datatype is <code>CUDNN_DATA_HALF</code></td>
</tr>
<tr>
<td></td>
<td>Layout is NHWC fully packed</td>
</tr>
<tr>
<td></td>
<td>Alignment is <code>CUDNN_PTR_16B_ALIGNED</code></td>
</tr>
<tr>
<td>CUDNN_PARAM_YSTATS_DESC</td>
<td>If the generate statistics operation is not turned into a NOP:</td>
</tr>
<tr>
<td>CUDNN_PARAM_YSUM_PLACEHOLDER</td>
<td>Tensor is 4 dimensional with shape 1xKx1x1</td>
</tr>
<tr>
<td>CUDNN_PARAM_YSQSUM_PLACEHOLDER</td>
<td>Datatype is <code>CUDNN_DATA_FLOAT</code></td>
</tr>
<tr>
<td></td>
<td>Layout is fully packed</td>
</tr>
<tr>
<td></td>
<td>Alignment is <code>CUDNN_PTR_16B_ALIGNED</code></td>
</tr>
</tbody>
</table>

### Table 24. CUDNN_FUSED_SCALE_BIAS_ACTIVATION_WGRAD

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_XDESC</td>
<td>In the setter, the *param should be xDesc, a pointer to a previously initialized cudnnTensorDescriptor_t.</td>
<td>Tensor descriptor describing the size, layout and datatype of the x (input) tensor</td>
<td>NULL</td>
</tr>
<tr>
<td>X_XDATA_PLACEHOLDER</td>
<td>In the setter, the <em>param should be a pointer to a previously initialized X_PointerPlaceHolder_t</em>.</td>
<td>Describes whether xData pointer in the VariantParamPack will be NULL, or if not,</td>
<td><code>CUDNN_PTR_NULL</code></td>
</tr>
</tbody>
</table>
### For the attribute CUDNN_FUSED_SCALE_BIAS_ACTIVATION_WGRAD in cudnnFusedOp_t

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_BN_MODE</td>
<td>In the setter, the <em>param should be a pointer to a previously initialized cudnnBatchNormMode_t</em>.</td>
<td>Describes the mode of operation for the scale, bias and the statistics.</td>
<td>CUDNN_BATCHNORM_PER_ACTIVATION</td>
</tr>
<tr>
<td></td>
<td></td>
<td>As of cuDNN 7.6.0, only CUDNN_BATCHNORM_SPATIAL and CUDNN_BATCHNORM_SPATIAL_PERSISTENT are supported, meaning, scale, bias, and statistics are all per-channel.</td>
<td></td>
</tr>
<tr>
<td>X_BN_EQSCALEBIAS_DESC</td>
<td>In the setter, the *param should be a pointer to a previously initialized cudnnTensorDescriptor_t.</td>
<td>Tensor descriptor describing the size, layout and datatype of the batchNorm equivalent scale and bias tensors. The shapes must match the mode specified in CUDNN_PARAM_BN_MODE. If set to NULL, both scale and bias operation will become a NOP.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_BN_EQSCALE_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder.</td>
<td>Describes whether batchnorm equivalent scale pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *. If set to CUDNN_PTR_NULL, then the scale operation becomes a NOP.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_BN_EQBIAS_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder.</td>
<td>Describes whether batchnorm equivalent bias pointer in the VariantParamPack will be NULL, or if not,</td>
<td>CUDNN_PTR_NULL</td>
</tr>
</tbody>
</table>
For the attribute **CUDNN_FUSED_SCALE_BIAS_ACTIVATION_WGRAD** in cudnnFusedOp_t

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>user promised pointer alignment *</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>If set to CUDNN_PTR_NULL, then the bias operation</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>becomes a NOP.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>X_ACTIVATION_DESC</td>
<td>In the setter, the <em>param should be a pointer to a previously initialized cudnnActivationDescriptor_t</em></td>
<td>Describes the activation operation. As of cuDNN 7.6.0, only activation mode of CUDNN_ACTIVATION_RELU and CUDNN_ACTIVATION_IDENTITY is supported. If set to NULL or if the activation mode is set to CUDNN_ACTIVATION_IDENTITY, then the activation in the op sequence becomes a NOP.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_CONV_DESC</td>
<td>In the setter, the <em>param should be a pointer to a previously initialized cudnnConvolutionDescriptor_t</em></td>
<td>Describes the convolution operation.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_DWDESC</td>
<td>In the setter, the <em>param should be a pointer to a previously initialized cudnnFilterDescriptor_t</em></td>
<td>Filter descriptor describing the size, layout and datatype of the dw [filter gradient output] tensor.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_DWDATA_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceholder</td>
<td>Describes whether dw [filter gradient output] tensor pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_DYDESC</td>
<td>In the setter, the <em>param should be a pointer to a previously initialized cudnnTensorDescriptor_t</em></td>
<td>Tensor descriptor describing the size, layout and datatype of the dy [gradient input] tensor.</td>
<td>NULL</td>
</tr>
</tbody>
</table>
### For the attribute CUDNN_FUSED_SCALE_BIAS_ACTIVATION_WGRAD in cudnnFusedOp_t

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_DYDATA_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X.PointerPlaceHolder</td>
<td>Describes whether dy (gradient input) tensor pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
</tbody>
</table>

**Note:**
- If the corresponding pointer placeholder in ConstParamPack is set to CUDNN_PTR_NULL, then the device pointer in the VariantParamPack needs to be NULL as well.
- If the corresponding pointer placeholder in ConstParamPack is set to CUDNN_PTR_ELEM_ALIGNED or CUDNN_PTR_16B_ALIGNED, then the device pointer in the VariantParamPack may not be NULL and needs to be at least element-aligned or 16 bytes-aligned, respectively.

As of cuDNN 7.6.0, if the conditions in Table 25 are met, then the fully fused fast path will be triggered. Otherwise a slower partially fused path will be triggered.

### Table 25. Conditions for Fully Fused Fast Path (Backward)

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Condition</th>
</tr>
</thead>
<tbody>
<tr>
<td>Device compute capability</td>
<td>Needs to be one of 7.0, 7.2 or 7.5.</td>
</tr>
<tr>
<td>CUDNN_PARAM_XDESC</td>
<td>Tensor is 4 dimensional</td>
</tr>
<tr>
<td>CUDNN_PARAM_XDATA_PLACEHOLDER</td>
<td>Datatype is CUDNN_DATA_HALF</td>
</tr>
<tr>
<td></td>
<td>Layout is NHWC fully packed</td>
</tr>
<tr>
<td></td>
<td>Alignment is CUDNN_PTR_16B_ALIGNED</td>
</tr>
<tr>
<td></td>
<td>Tensor’s C dimension is a multiple of 8.</td>
</tr>
<tr>
<td>CUDNN_PARAM_BN_EQSCALEBIAS_DESC</td>
<td>If either one of scale and bias operation is not turned into a NOP:</td>
</tr>
<tr>
<td>CUDNN_PARAM_BN_EQSCALE_PLACEHOLDER</td>
<td>Tensor is 4 dimensional with shape 1xCx1x1</td>
</tr>
<tr>
<td>CUDNN_PARAM_BN_EQBIAS_PLACEHOLDER</td>
<td>Datatype is CUDNN_DATA_HALF</td>
</tr>
<tr>
<td></td>
<td>Layout is fully packed</td>
</tr>
<tr>
<td></td>
<td>Alignment is CUDNN_PTR_16B_ALIGNED</td>
</tr>
<tr>
<td>CUDNN_PARAM_CONV_DESC</td>
<td>Convolution descriptor’s mode needs to be CUDNN_CROSS_CORRELATION.</td>
</tr>
<tr>
<td>CUDNN_PARAM_DWDESC</td>
<td>Convolution descriptor’s dataType needs to be CUDNN_DATA_FLOAT.</td>
</tr>
<tr>
<td>CUDNN_PARAM_DWDATA_PLACEHOLDER</td>
<td></td>
</tr>
</tbody>
</table>
### Parameter Condition

- Convolution descriptor’s `dilationA` is (1,1)
- Convolution descriptor’s group count needs to be 1.
- Convolution descriptor’s `mathType` needs to be `CUDNN_TENSOR_OP_MATH` or `CUDNN_TENSOR_OP_MATH_ALLOW_CONVERSION`.
- Filter gradient is in `NHWC` layout
- Filter gradient’s data type is `CUDNN_DATA_HALF`
- Filter gradient’s `k` dimension is a multiple of 32.
- Filter gradient size `RxS` is either 1x1 or 3x3
- If filter gradient size `RxS` is 1x1, convolution descriptor’s `padA` needs to be (0,0) and `filterStrideA` needs to be (1,1).
- Filter gradient’s alignment is `CUDNN_PTR_16B_ALIGNED`

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Condition</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>CUDNN_PARAM_DYDESC</code></td>
<td>Tensor is 4 dimensional</td>
</tr>
<tr>
<td><code>CUDNN_PARAM_DYDATA_PLACEHOLDER</code></td>
<td>Datatype is <code>CUDNN_DATA_HALF</code></td>
</tr>
<tr>
<td></td>
<td>Layout is <code>NHWC</code> fully packed</td>
</tr>
<tr>
<td></td>
<td>Alignment is <code>CUDNN_PTR_16B_ALIGNED</code></td>
</tr>
</tbody>
</table>

### Table 26. CUDNN_FUSED_BN_FINALIZE_STATISTICS_TRAINING

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>X_BN_MODE</code></td>
<td>In the setter, the <code>*param</code> should be a pointer to a previously initialized <code>cudnnBatchNormMode_t</code></td>
<td>Describes the mode of operation for the scale, bias and the statistics.</td>
<td><code>CUDNN_BATCHNORM_PER_ACTIVATION</code></td>
</tr>
<tr>
<td></td>
<td></td>
<td>As of cuDNN 7.6.0, only <code>CUDNN_BATCHNORM_SPATIAL</code> and <code>CUDNN_BATCHNORM_SPATIAL_PERSISTENT</code> are supported, meaning, scale, bias and statistics are all per-channel.</td>
<td></td>
</tr>
<tr>
<td><code>X_YSTATS_DESC</code></td>
<td>In the setter, the <code>*param</code> should describe the size,</td>
<td>Tensor descriptor describing the size,</td>
<td><code>NULL</code></td>
</tr>
<tr>
<td>Attribute</td>
<td>Expected Descriptor Type Passed in, in the Setter</td>
<td>Description</td>
<td>Default Value After Creation</td>
</tr>
<tr>
<td>-----------</td>
<td>--------------------------------------------------</td>
<td>-------------</td>
<td>-----------------------------</td>
</tr>
<tr>
<td>CUDNN_FUSED_BN_FINALIZE_STATISTICS_TRAINING</td>
<td>be a pointer to a previously initialized cudnnTensorDescriptor_t*</td>
<td>layout and datatype of the sum of y and sum of y square tensors. The shapes need to match the mode specified in CUDNN_PARAM_BN_MODE.</td>
<td></td>
</tr>
<tr>
<td>X_YSUM_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder_t.</td>
<td>Describes whether sum of y pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_YSQSUM_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder_t.</td>
<td>Describes whether sum of y square pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_BN_SCALEBIAS_MEANVAR_DESC</td>
<td>In the setter, the *param should be a pointer to a previously initialized cudnnTensorDescriptor_t.</td>
<td>A common tensor descriptor describing the size, layout and datatype of the batchNorm trained scale, bias and statistics tensors. The shapes need to match the mode specified in CUDNN_PARAM_BN_MODE (similar to the bnScaleBiasMeanVarDesc field in the cudnnBatchNormalization* API).</td>
<td>NULL</td>
</tr>
<tr>
<td>X_BN_SCALE_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder_t.</td>
<td>Describes whether the batchNorm trained scale pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *. If the output of BN_EQSCALE is not needed, then this is</td>
<td>CUDNN_PTR_NULL</td>
</tr>
</tbody>
</table>
For the attribute `CUDNN_FUSED_BN_FINALIZE_STATISTICS_TRAINING` in `cudnnFusedOp_t`

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
</table>
| X_BN_BIAS_PLACEHOLDER        | In the setter, the `*param` should be a pointer to a previously initialized `X_PointerPlaceHolder` | Describes whether the batchNorm trained bias pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *.
If neither output of `BN_EQSCALE` or `BN_EQBIAS` is needed, then this is not needed and may be NULL. | CUDNN_PTR_NULL                |
| X_BN_SAVED_MEAN_PLACEHOLDER  | In the setter, the `*param` should be a pointer to a previously initialized `X_PointerPlaceHolder` | Describes whether the batchNorm saved mean pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *.
If set to CUDNN_PTR_NULL, then the computation for this output becomes a NOP. | CUDNN_PTR_NULL                |
| X_BN_SAVED_INVSTD_PLACEHOLDER| In the setter, the `*param` should be a pointer to a previously initialized `X_PointerPlaceHolder` | Describes whether the batchNorm saved inverse standard deviation pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *.
If set to CUDNN_PTR_NULL, then the computation for this output becomes a NOP. | CUDNN_PTR_NULL                |
| X_BN_RUNNING_MEAN_PLACEHOLDER| In the setter, the `*param` should be a pointer to a previously initialized `X_PointerPlaceHolder` | Describes whether the batchNorm running mean pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *.
If set to CUDNN_PTR_NULL, then the computation for this output becomes a NOP. | CUDNN_PTR_NULL                |
<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td>CUDNN_FUSED_BN_FINALIZE_STATISTICS_TRAINING</td>
<td>previously initialized X_PointerPlaceHolder</td>
<td>user promised pointer alignment *. If set to CUDNN_PTR_NULL, then the computation for this output becomes a NOP.</td>
<td></td>
</tr>
<tr>
<td>X_BN_RUNNING_VAR_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder</td>
<td>Describes whether the batchNorm running variance pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *. If set to CUDNN_PTR_NULL, then the computation for this output becomes a NOP.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_BN_EQSCALEBIAS_DESC</td>
<td>In the setter, the *param should be a pointer to a previously initialized cudnnTensorDescriptor_t</td>
<td>Tensor descriptor describing the size, layout and datatype of the batchNorm equivalent scale and bias tensors. The shapes need to match the mode specified in CUDNN_PARAM_BN_MODE. If neither output of BN_EQSACLE or BN_EQBIAS is needed, then this is not needed and may be NULL.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_BN_EQSCALE_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder</td>
<td>Describes whether batchnorm equivalent scale pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *. If set to CUDNN_PTR_NULL, then the computation for</td>
<td>CUDNN_PTR_NULL</td>
</tr>
</tbody>
</table>
For the attribute **CUDNN_FUSED_BN_FINALIZE_STATISTICS_TRAINING** in `cudnnFusedOp_t`

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_BN_EQBIAS_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder.</td>
<td>Describes whether batchnorm equivalent bias pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *. If set to CUDNN_PTR_NULL, then the computation for this output becomes a NOP.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
</tbody>
</table>

Table 27. **CUDNN_FUSED_BN_FINALIZE_STATISTICS_INFERENC**

For the attribute **CUDNN_FUSED_BN_FINALIZE_STATISTICS_INFERENC** in `cudnnFusedOp_t`

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_BN_MODE</td>
<td>In the setter, the <em>param should be a pointer to a previously initialized cudnnBatchNormMode_t</em>.</td>
<td>Describes the mode of operation for the scale, bias and the statistics. As of cuDNN 7.6.0, only CUDNN_BATCHNORM_SPATIAL and CUDNN_BATCHNORM_SPATIAL_PERSISTENT are supported, meaning, scale, bias and statistics are all per-channel.</td>
<td>CUDNN_BATCHNORM_PER_ACTIVATION</td>
</tr>
<tr>
<td>X_BN_SCALEBIAS_MEANVAR_DESC</td>
<td>In the setter, the *param should be a pointer to a previously initialized cudnnTensorDescriptor_t.</td>
<td>A common tensor descriptor describing the size, layout and datatype of the batchNorm trained scale, bias and statistics tensors. The NULL is used to indicate that the tensor descriptor is not set.</td>
<td>NULL</td>
</tr>
</tbody>
</table>
For the attribute **CUDNN_FUSED_BN_FINALIZE_STATISTICS_INFERENC**E in **cudnnFusedOp_t**

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>shapes need to match the mode specified in CUDNN_PARAM_BN_MODE (similar to the bnScaleBiasMeanVarDesc field in the cudnnBatchNormalization API).</td>
<td></td>
</tr>
<tr>
<td>X_BN_SCALE_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder</td>
<td>Describes whether the batchNorm trained scale pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_BN_BIAS_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder</td>
<td>Describes whether the batchNorm trained bias pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_BN_RUNNING_MEAN_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder</td>
<td>Describes whether the batchNorm running mean pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_BN_RUNNING_VAR_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder</td>
<td>Describes whether the batchNorm running variance pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_BN_EQSCALEBIAS_DESC</td>
<td>In the setter, the *param should be a pointer to a previously initialized cudnnTensorDescriptor</td>
<td>Tensor descriptor describing the size, layout and datatype of the batchNorm equivalent scale and bias tensors. The shapes need to match the mode specified in CUDNN_PARAM_BN_MODE.</td>
<td>NULL</td>
</tr>
</tbody>
</table>
### Table 28. cudnnFusedOp_t

#### cudnnFusedConvolutionScaleBiasAddRelu

For the attribute **CUDNN_FUSED_CONVOLUTION_SCALE_BIAS_ADD_RELU** in cudnnFusedOp_t

This operation performs the following computation, where * denotes convolution operator:

\[ y = 1(w \times x) + 2z + b \]

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_XDESC</td>
<td>In the setter, the *param should be xDesc, a pointer to a previously initialized cudnnTensorDescriptor_t.</td>
<td>Tensor descriptor describing the size, layout and datatype of the x (input) tensor.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_XDATA_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder</td>
<td>Describes whether xData pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
</tbody>
</table>

**For the attribute CUDNN_FUSED_BN_FINALIZE_STATISTICS_INERENCE in cudnnFusedOp_t**

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_BN_EQSCALE_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder</td>
<td>Describes whether batchnorm equivalent scale pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *. If set to CUDNN_PTR_NULL, then the computation for this output becomes a NOP.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_BN_EQBIAS_PLACEHOLDER</td>
<td>In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder</td>
<td>Describes whether batchnorm equivalent bias pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *. If set to CUDNN_PTR_NULL, then the computation for this output becomes a NOP.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
</tbody>
</table>
For the attribute **CUDNN_FUSED_CONVOLUTION_SCALE_BIAS_ADD_RELU** in `cudnnFusedOp_t`

This operation performs the following computation, where * denotes convolution operator:

\[ y = (w \ast x) + 2z + b \]

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>X_CONV_DESC</strong></td>
<td>previously initialized <code>X_PointerPlaceHolder_t</code></td>
<td>user promised pointer alignment *</td>
<td>NULL</td>
</tr>
<tr>
<td></td>
<td>In the setter, the *param should be a pointer to a previously initialized</td>
<td>Describes the convolution operation.</td>
<td>NULL</td>
</tr>
<tr>
<td></td>
<td><code>cudnnConvolutionDescriptor_t</code></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>X_WDESC</strong></td>
<td>In the setter, the *param should be a pointer to a previously initialized</td>
<td>Filter descriptor describing the size, layout and datatype of the w (filter) tensor.</td>
<td>NULL</td>
</tr>
<tr>
<td></td>
<td><code>cudnnFilterDescriptor_t</code></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
| **X_WDATA_PLACEHOLDER**    | In the setter, the *param should be a pointer to a previously initialized              | Describes whether w (filter) tensor pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *.
|                            | `X_PointerPlaceHolder_t`                                                               |                                                                              | CUDNN_PTR_NULL               |
| **X_BN_EQSCALEBIAS_DESC**  | In the setter, the *param should be a pointer to a previously initialized              | Tensor descriptor describing the size, layout and datatype of the \( \alpha_1 \) scale and bias tensors. The tensor should have shape \([1,K,1,1]\), \( K \) is the number of output features. | NULL                         |
|                            | `cudnnTensorDescriptor_t`                                                              |                                                                              |                              |
| **X_BN_EQSCALE_PLACEHOLDER** | The setter, the *param should be a pointer to a previously initialized               | Describes whether batchnorm equivalent scale or \( \alpha_1 \) tensor pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *.
|                            | `X_PointerPlaceHolder_t`                                                               |                                                                              | CUDNN_PTR_NULL               |
|                            | If set to CUDNN_PTR_NULL, then \( \alpha_1 \) scaling becomes an NOP.                   |                                                                              |                              |
| **X_ZDESC**                | In the setter, the *param should be xDesc, a pointer to a                              | Tensor descriptor describing the size, layout and datatype of the z tensor.  | NULL                         |
|                            | `X_PointerPlaceHolder_t`                                                               |                                                                              |                              |
For the attribute **CUDNN_FUSED_CONVOLUTION_SCALE_BIAS_ADD_RELU** in `cudnnFusedOp_t`

This operation performs the following computation, where \( \ast \) denotes convolution operator:

\[
y = 1 \ast (w \ast x) + 2 \ z + b
\]

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>Description</th>
<th>Default Value After Creation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Previously initialized <code>cudnnTensorDescriptor_t</code></td>
<td>If unset, then ( z ) scale-add term becomes a NOP.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CUDNN_PARAM_ZDATA_PLACEHOLDER</td>
<td>In the setter, the ( \ast )param should be a pointer to a previously initialized ( \ast )X_PointerPlaceHolder( \ast )</td>
<td>Describes whether ( z ) tensor pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment ( \ast ). If set to CUDNN_PTR_NULL, then ( z ) scale-add term becomes a NOP.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>CUDNN_PARAM_BN_Z_EQSCALEBIAS_DESC</td>
<td>In the setter, the ( \ast )param should be a pointer to a previously initialized ( \ast )cudnnTensorDescriptor_t</td>
<td>Tensor descriptor describing the size, layout and datatype of the ( \alpha )( \ast ) tensor. If set to NULL then scaling for input ( z ) becomes a NOP.</td>
<td>NULLPTR</td>
</tr>
<tr>
<td>CUDNN_PARAM_BN_Z_EQSCALE_PLACEHOLDER</td>
<td>In the setter, the ( \ast )param should be a pointer to a previously initialized ( \ast )X_PointerPlaceHolder( \ast )</td>
<td>Describes whether batchnorm ( z )-equivalent scaling pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment ( \ast ). If set to CUDNN_PTR_NULL, then the scaling for input ( z ) becomes a NOP.</td>
<td>CUDNN_PTR_NULL</td>
</tr>
<tr>
<td>X_ACTIVATION_DESC</td>
<td>In the setter, the ( \ast )param should be a pointer to a previously initialized ( \ast )cudnnActivationDescriptor_t</td>
<td>Describes the activation operation. As of 7.6.0, only activation modes of CUDNN_ACTIVATION_RELU and CUDNN_ACTIVATION_IDENTITY are supported. If set to NULL or if the activation mode is set to</td>
<td>NULL</td>
</tr>
</tbody>
</table>
For the attribute `CUDNN_FUSED_CONVOLUTION_SCALE_BIAS_ADD_RELU` in `cudnnFusedOp_t`

This operation performs the following computation, where * denotes convolution operator:

\[ y = (w * x) + 2 \cdot z + b \]

### Attribute | Expected Descriptor Type Passed in, in the Setter | Description | Default Value After Creation
--- | --- | --- | ---
X_YDESC | In the setter, the *param should be a pointer to a previously initialized cudnnTensorDescriptor_t*. | Tensor descriptor describing the size, layout and datatype of the y (output) tensor. | NULL
X_YDATA_PLACEHOLDER | In the setter, the *param should be a pointer to a previously initialized X_PointerPlaceHolder_t. | Describes whether y (output) tensor pointer in the VariantParamPack will be NULL, or if not, user promised pointer alignment *. | CUDNN_PTR_NULL

### 6.1.3.3. cudnnFusedOpsPointerPlaceHolder_t

cudnnFusedOpsPointerPlaceHolder_t is an enumerated type used to select the alignment type of the cudnnFusedOps descriptor pointer.

<table>
<thead>
<tr>
<th>Member</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CUDNN_PTR_NULL = 0</td>
<td>Indicates that the pointer to the tensor in the variantPack will be NULL.</td>
</tr>
<tr>
<td>CUDNN_PTR_ELEM_ALIGNED = 1</td>
<td>Indicates that the pointer to the tensor in the variantPack will not be NULL, and will have element alignment.</td>
</tr>
<tr>
<td>CUDNN_PTR_16B_ALIGNED = 2</td>
<td>Indicates that the pointer to the tensor in the variantPack will not be NULL, and will have 16 byte alignment.</td>
</tr>
</tbody>
</table>

### 6.1.3.4. cudnnFusedOpsVariantParamLabel_t

The cudnnFusedOpsVariantParamLabel_t is an enumerated type that is used to set the buffer pointers. These buffer pointers can be changed in each iteration.

```c
typedef enum {
    CUDNN_PTR_XDATA = 0,
    CUDNN_PTR_EN_EQSCALE = 1,
    CUDNN_PTR_EN_EQBIAS = 2,
    CUDNN_PTR_WDATA = 3,
    CUDNN_PTR_DWDATA = 4,
    CUDNN_PTR_YDATA = 5,
    CUDNN_PTR_DYDATA = 6,
} cudnnFusedOpsVariantParamLabel_t;
```
Table 29. Legend For Tables in This Section

<table>
<thead>
<tr>
<th>Short-form used</th>
<th>Stands for</th>
</tr>
</thead>
<tbody>
<tr>
<td>Setter</td>
<td>cudnnSetFusedOpsVariantParamPackAttribute()</td>
</tr>
<tr>
<td>Getter</td>
<td>cudnnGetFusedOpsVariantParamPackAttribute()</td>
</tr>
</tbody>
</table>

X_ prefix in the Attribute key column stands for CUDNN_PTR_ or CUDNN_SCALAR_ in the enumerator name.

Table 30. CUDNN_FUSED_SCALE_BIAS_ACTIVATION_CONV_BNSTATS

For the attribute CUDNN_FUSED_SCALE_BIAS_ACTIVATION_CONV_BNSTATS in cudnnFusedOp_t

<table>
<thead>
<tr>
<th>Attribute key</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>I/O Type</th>
<th>Description</th>
<th>Default Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_XDATA</td>
<td>void *</td>
<td>input</td>
<td>Pointer to x (input) tensor on device, need to agree with previously set</td>
<td>NULL</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>CUDNN_PARAM_XDATA_PLACEHOLDER attribute *.</td>
<td></td>
</tr>
<tr>
<td>X_BN_EQSCALE</td>
<td>void *</td>
<td>input</td>
<td>Pointer to batchnorm equivalent scale tensor on device, need to</td>
<td>NULL</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>agree with previously set CUDNN_PARAM_BN_EQSCALE_PLACEHOLDER attribute *.</td>
<td></td>
</tr>
</tbody>
</table>
## For the attribute `CUDNN_FUSED_SCALE_BIAS_ACTIVATION_CONV_BNSTATS` in `cudnnFusedOp_t`

<table>
<thead>
<tr>
<th>Attribute key</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>I/O Type</th>
<th>Description</th>
<th>Default Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_BN_EQBIAS</td>
<td>void *</td>
<td>input</td>
<td>Pointer to batchnorm equivalent bias tensor on device, need to agree with previously set CUDNN_PARAM_BN_EQBIAS_PLACEHOLDER attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_WDATA</td>
<td>void *</td>
<td>input</td>
<td>Pointer to ( w ) (filter) tensor on device, need to agree with previously set CUDNN_PARAM_WDATA_PLACEHOLDER attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_YDATA</td>
<td>void *</td>
<td>output</td>
<td>Pointer to ( y ) (output) tensor on device, need to agree with previously set CUDNN_PARAM_YDATA_PLACEHOLDER attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_YSUM</td>
<td>void *</td>
<td>output</td>
<td>Pointer to sum of ( y ) tensor on device, need to agree with previously set CUDNN_PARAM_YSUM_PLACEHOLDER attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_YSQSUM</td>
<td>void *</td>
<td>output</td>
<td>Pointer to sum of ( y ) square tensor on device, need to agree with previously set CUDNN_PARAM_YSQSUM_PLACEHOLDER attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_WORKSPACE</td>
<td>void *</td>
<td>input</td>
<td>Pointer to user allocated workspace on device. Can be NULL if the workspace size requested is 0.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_SIZE_T_WORKSPACE_SIZE_inBytes</td>
<td>void *</td>
<td>input</td>
<td>Pointer to a size_t value in host memory describing the user allocated workspace size in bytes. The amount needs to be equal or larger than the amount requested in cudnnMakeFusedOpsPlan.</td>
<td>0</td>
</tr>
</tbody>
</table>

**Note:**
- If the corresponding pointer placeholder in `ConstParamPack` is set to CUDNN_PTR_NULL, then the device pointer in the `VariantParamPack` needs to be NULL as well.
If the corresponding pointer placeholder in `ConstParamPack` is set to `CUDNN_PTR_ELEMAligned` or `CUDNN_PTR_16B_Aligned`, then the device pointer in the `VariantParamPack` may not be NULL and needs to be at least element-aligned or 16 bytes-aligned, respectively.

<table>
<thead>
<tr>
<th>Attribute key</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>I/O Type</th>
<th>Description</th>
<th>Default Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_XDATA</td>
<td>void *</td>
<td>input</td>
<td>Pointer to $x$ (input) tensor on device, need to agree with previously set</td>
<td>NULL</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td><code>CUDNN_PARAM_XDATA_PLACEHOLDER</code> attribute *</td>
<td></td>
</tr>
<tr>
<td>X_BN_EQSCALE</td>
<td>void *</td>
<td>input</td>
<td>Pointer to batchnorm equivalent scale tensor on device, need to agree</td>
<td>NULL</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>with previously set <code>CUDNN_PARAM_BN_EQSCALE_PLACEHOLDER</code> attribute *</td>
<td></td>
</tr>
<tr>
<td>X_BN_EQBIAS</td>
<td>void *</td>
<td>input</td>
<td>Pointer to batchnorm equivalent bias tensor on device, need to agree</td>
<td>NULL</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>with previously set <code>CUDNN_PARAM_BN_EQBIAS_PLACEHOLDER</code> attribute *</td>
<td></td>
</tr>
<tr>
<td>X_DWDATA</td>
<td>void *</td>
<td>output</td>
<td>Pointer to $dw$ (filter gradient output) tensor on device, need to agree</td>
<td>NULL</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>with previously set <code>CUDNN_PARAM_WDATA_PLACEHOLDER</code> attribute *</td>
<td></td>
</tr>
<tr>
<td>X_DYDATA</td>
<td>void *</td>
<td>input</td>
<td>Pointer to $dy$ (gradient input) tensor on device, need to agree with</td>
<td>NULL</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>previously set <code>CUDNN_PARAM_YDATA_PLACEHOLDER</code> attribute *</td>
<td></td>
</tr>
<tr>
<td>X_WORKSPACE</td>
<td>void *</td>
<td>input</td>
<td>Pointer to user allocated workspace on device. Can be NULL if the workspace</td>
<td>NULL</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>size requested is 0.</td>
<td></td>
</tr>
<tr>
<td>X_SIZE_T_WORKSPACE_SIZE_IN_BYTES_t</td>
<td>void *</td>
<td>input</td>
<td>Pointer to a size_t value in host memory describing the</td>
<td>0</td>
</tr>
</tbody>
</table>
For the attribute `CUDNN_FUSED_SCALE_BIAS_ACTIVATION_WGRAD` in `cudnnFusedOp_t`

<table>
<thead>
<tr>
<th>Attribute key</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>I/O Type</th>
<th>Description</th>
<th>Default Value</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>user allocated workspace size in bytes. The amount needs to be equal or larger than the amount requested in <code>cudnnMakeFusedOpsPlan</code>.</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Note:
- If the corresponding pointer placeholder in `ConstParamPack` is set to `CUDNN_PTR_NULL`, then the device pointer in the `VariantParamPack` needs to be `NULL` as well.
- If the corresponding pointer placeholder in `ConstParamPack` is set to `CUDNN_PTR_ELEM_ALIGNED` or `CUDNN_PTR_16B_ALIGNED`, then the device pointer in the `VariantParamPack` may not be `NULL` and needs to be at least element-aligned or 16 bytes-aligned, respectively.

### Table 32. `CUDNN_FUSED_BN_FINALIZE_STATISTICS_TRAINING`

<table>
<thead>
<tr>
<th>Attribute key</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>I/O Type</th>
<th>Description</th>
<th>Default Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_YSUM</td>
<td>void *</td>
<td>input</td>
<td>Pointer to sum of $y$ tensor on device, need to agree with previously set <code>CUDNN_PARAM_YSUM_PLACEHOLDER</code> attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_YSQSUM</td>
<td>void *</td>
<td>input</td>
<td>Pointer to sum of $y$ square tensor on device, need to agree with previously set <code>CUDNN_PARAM_YSQSUM_PLACEHOLDER</code> attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_BN_SCALE</td>
<td>void *</td>
<td>input</td>
<td>Pointer to sum of $y$ square tensor on device, need to agree with previously set <code>CUDNN_PARAM_BN_SCALE_PLACEHOLDER</code> attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>Attribute key</td>
<td>Expected Descriptor Type Passed in, in the Setter</td>
<td>I/O Type</td>
<td>Description</td>
<td>Default Value</td>
</tr>
<tr>
<td>---------------</td>
<td>-----------------------------------------------</td>
<td>---------</td>
<td>-------------</td>
<td>--------------</td>
</tr>
<tr>
<td>X_BN_BIAS</td>
<td>void *</td>
<td>input</td>
<td>Pointer to sum of $y$ square tensor on device, need to agree with previously set CUDNN_PARAM_BN_BIAS_PLACEHOLDER attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_BN_SAVED_MEAN</td>
<td>void *</td>
<td>output</td>
<td>Pointer to sum of $y$ square tensor on device, need to agree with previously set CUDNN_PARAM_BN_SAVED_MEAN_PLACEHOLDER attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_BN_SAVED_INVSTD</td>
<td>void *</td>
<td>output</td>
<td>Pointer to sum of $y$ square tensor on device, need to agree with previously set CUDNN_PARAM_BN_SAVED_INVSTD_PLACEHOLDER attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_BN_RUNNING_MEAN</td>
<td>void *</td>
<td>input/output</td>
<td>Pointer to sum of $y$ square tensor on device, need to agree with previously set CUDNN_PARAM_BN_RUNNING_MEAN_PLACEHOLDER attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_BN_RUNNING_VAR</td>
<td>void *</td>
<td>input/output</td>
<td>Pointer to sum of $y$ square tensor on device, need to agree with previously set CUDNN_PARAM_BN_RUNNING_VAR_PLACEHOLDER attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_BN_EQSCALE</td>
<td>void *</td>
<td>output</td>
<td>Pointer to batchnorm equivalent scale tensor on device, need to agree with previously set CUDNN_PARAM_BN_EQSCALE_PLACEHOLDER attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_BN_EQBIAS</td>
<td>void *</td>
<td>output</td>
<td>Pointer to batchnorm equivalent bias tensor on device, need to agree with previously set CUDNN_PARAM_BN_EQBIAS_PLACEHOLDER attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_INT64_T_BN_ACCUMULATION_COUNT</td>
<td>int64_t *</td>
<td>input</td>
<td>Pointer to a scalar value in int64_t on host memory. This value should describe the number of tensor elements accumulated in the sum of $y$ and sum of $y$ square tensors.</td>
<td>0</td>
</tr>
</tbody>
</table>
For the attribute CUDNN_FUSED_BN_FINALIZE_STATISTICS_TRAINING in cudnnFusedOp_t

<table>
<thead>
<tr>
<th>Attribute key</th>
<th>Expected Description Type Passed in, in the Setter</th>
<th>I/O Type</th>
<th>Description</th>
<th>Default Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_DOUBLE_BN_EXP_AVG_FACTOR</td>
<td>double *</td>
<td>input</td>
<td>Pointer to a scalar value in double on host memory. Factor used in the moving average computation. See exponentialAverageFactor in cudnnBatchNormalization* APIs.</td>
<td>0.0</td>
</tr>
<tr>
<td>X_DOUBLE_BN_EPSILON</td>
<td>double *</td>
<td>input</td>
<td>Pointer to a scalar value in double on host memory. A conditioning constant used in the batch normalization formula. Its value should be equal to or greater than the value defined for CUDNN_BN_MIN_EPSILON in cudnn.h. See exponentialAverageFactor in cudnnBatchNormalization* APIs.</td>
<td>0.0</td>
</tr>
<tr>
<td>X_WORKSPACE</td>
<td>void *</td>
<td>input</td>
<td>Pointer to user allocated workspace on device. Can be NULL if the workspace size requested is 0.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_SIZE_T_WORKSPACE_SIZE_IN_BYTES</td>
<td>size_t *</td>
<td>input</td>
<td>Pointer to a size_t value in host memory describing the user allocated workspace</td>
<td>0</td>
</tr>
</tbody>
</table>
For the attribute CUDNN_FUSED_BN_FINALIZE_STATISTICS_TRAINING in cudnnFusedOp_t

<table>
<thead>
<tr>
<th>Attribute key</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>I/O Type</th>
<th>Description</th>
<th>Default Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_BN_SCALE</td>
<td>void *</td>
<td>input</td>
<td>Pointer to sum of $y$ square tensor on device, need to agree with previously set CUDNN_PARAM_BN_SCALE_PLACEHOLDER attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_BN_BIAS</td>
<td>void *</td>
<td>input</td>
<td>Pointer to sum of $y$ square tensor on device, need to agree with previously set CUDNN_PARAM_BN_BIAS_PLACEHOLDER attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_BN_RUNNING_MEAN</td>
<td>void *</td>
<td>input/output</td>
<td>Pointer to sum of $y$ square tensor on device, need to agree with previously set CUDNN_PARAM_Bn_RUNNING_MEAN_PLACEHOLDER attribute *</td>
<td>NULL</td>
</tr>
<tr>
<td>X_BN_RUNNING_VAR</td>
<td>void *</td>
<td>input/output</td>
<td>Pointer to sum of $y$ square tensor on device, need to</td>
<td>NULL</td>
</tr>
</tbody>
</table>

Note:
- If the corresponding pointer placeholder in ConstParamPack is set to CUDNN_PTR_NULL, then the device pointer in the VariantParamPack needs to be NULL as well.
- If the corresponding pointer placeholder in ConstParamPack is set to CUDNN_PTR_ELEM_ALIGNED or CUDNN_PTR_16B_ALIGNED, then the device pointer in the VariantParamPack may not be NULL and needs to be at least element-aligned or 16 bytes-aligned, respectively.

Table 33. CUDNN_FUSED_BN_FINALIZE_STATISTICS_INFERENCE
For the attribute `CUDNN_FUSED_BN_FINALIZE_STATISTICS_INFERENCE` in `cudnnFusedOp_t`

<table>
<thead>
<tr>
<th>Attribute key</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>I/O Type</th>
<th>Description</th>
<th>Default Value</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>X_BN_EQSCALE</code></td>
<td>void *</td>
<td>output</td>
<td>Pointer to batchnorm equivalent scale tensor on device, need to agree with previously set <code>CUDNN_PARAM_BN_EQSCALE_PLACEHOLDER</code> attribute *.</td>
<td>NULL</td>
</tr>
<tr>
<td><code>X_BN_EQBIAS</code></td>
<td>void *</td>
<td>output</td>
<td>Pointer to batchnorm equivalent bias tensor on device, need to agree with previously set <code>CUDNN_PARAM_BN_EQBIAS_PLACEHOLDER</code> attribute *.</td>
<td>NULL</td>
</tr>
<tr>
<td><code>X_DOUBLE_BN_EPSILON</code></td>
<td>double *</td>
<td>input</td>
<td>Pointer to a scalar value in double on host memory. A conditioning constant used in the batch normalization formula. Its value should be equal to or greater than the value defined for <code>CUDNN_BN_MIN_EPSILON</code> in <code>cudnn.h</code>. See <code>exponentialAverageFactor</code> in <code>cudnnBatchNormalization</code> APIs.</td>
<td>0.0</td>
</tr>
<tr>
<td><code>X_WORKSPACE</code></td>
<td>void *</td>
<td>input</td>
<td>Pointer to user allocated workspace on device. Can be NULL if the workspace size requested is 0.</td>
<td>NULL</td>
</tr>
<tr>
<td><code>X_SIZE_T_WORKSPACE_SIZE_IN_BYTES</code></td>
<td>size_t *</td>
<td>input</td>
<td>Pointer to a <code>size_t</code> value in host memory describing the user allocated workspace size in bytes. The amount needs to be equal or larger than the amount requested in <code>cudnnMakeFusedOpsPlan</code>.</td>
<td>0</td>
</tr>
</tbody>
</table>

**Note:**
- If the corresponding pointer placeholder in `ConstParamPack` is set to `CUDNN_PTR_NULL`, then the device pointer in the `VariantParamPack` needs to be NULL as well.
If the corresponding pointer placeholder in `ConstParamPack` is set to `CUDNN_PTR_ELEM_ALIGNED` or `CUDNN_PTR_16B_ALIGNED`, then the device pointer in the `VariantParamPack` may not be NULL and needs to be at least element-aligned or 16 bytes-aligned, respectively.

### Table 34. CUDNN_FUSED_SCALE_BIAS_ADD_RELU

For the attribute `CUDNN_FUSED_BN_FINALIZE_STATISTICS_INFERNC` in `cudnnFusedOp_t`

<table>
<thead>
<tr>
<th>Attribute key</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>I/O Type</th>
<th>Description</th>
<th>Default Value</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>X_XDATA</code></td>
<td>void *</td>
<td>input</td>
<td>Pointer to (x) (image) tensor on device, need to agree with previously set <code>CUDNN_PARAM_XDATA_PLACEHOLDER</code> attribute.</td>
<td>NULL</td>
</tr>
<tr>
<td><code>X_WDATA</code></td>
<td>void *</td>
<td>input</td>
<td>Pointer to (w) (filter) tensor on device, need to agree with previously set <code>CUDNN_PARAM_WDATA_PLACEHOLDER</code> attribute.</td>
<td>NULL</td>
</tr>
<tr>
<td><code>X_BN_EQSCALE</code></td>
<td>void *</td>
<td>input</td>
<td>Pointer to (\alpha_1) or batchnorm equivalent scale tensor on device; need to agree with previously set <code>CUDNN_PARAM_BN_EQSCALE_PLACEHOLDER</code> attribute.</td>
<td>NULL</td>
</tr>
<tr>
<td><code>X_ZDATA</code></td>
<td>void *</td>
<td>input</td>
<td>Pointer to (z) tensor on device; need to agree with previously set <code>CUDNN_PARAM_YDATA_PLACEHOLDER</code> attribute.</td>
<td>NULL</td>
</tr>
<tr>
<td><code>X_BN_Z_EQSCALE</code></td>
<td>void *</td>
<td>input</td>
<td>Pointer to (\alpha_2), equivalent scale tensor for (z); need to agree with previously set <code>CUDNN_PARAM_BN_Z_EQSCALE_PLACEHOLDER</code> attribute.</td>
<td>NULL</td>
</tr>
<tr>
<td><code>X_BN_Z_EQBIAS</code></td>
<td>void *</td>
<td>input</td>
<td>Pointer to batchnorm equivalent bias</td>
<td>NULL</td>
</tr>
</tbody>
</table>
### For the attribute CUDNN_FUSED_BN_FINALIZE_STATISTICS_INference in cudnnFusedOp_t

<table>
<thead>
<tr>
<th>Attribute key</th>
<th>Expected Descriptor Type Passed in, in the Setter</th>
<th>I/O Type</th>
<th>Description</th>
<th>Default Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>X_YDATA</td>
<td>void *</td>
<td>output</td>
<td>Pointer to ( y ) [output] tensor on device, need to agree with previously set CUDNN_PARAM_BN_Z_EQBIAS_PLACEHOLDER attribute.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_WORKSPACE</td>
<td>void *</td>
<td>input</td>
<td>Pointer to user allocated workspace on device. Can be NULL if the workspace size requested is 0.</td>
<td>NULL</td>
</tr>
<tr>
<td>X_SIZE_T_WORKSPACE</td>
<td>size_t *</td>
<td>input</td>
<td>Pointer to a size_t value in host memory describing the user allocated workspace size in bytes. The amount needs to be equal or larger than the amount requested in cudnnMakeFusedOpsPlan.</td>
<td>0</td>
</tr>
</tbody>
</table>

**Note:**

- If the corresponding pointer placeholder in ConstParamPack is set to CUDNN_PTR_NULL, then the device pointer in the VariantParamPack needs to be NULL as well.
- If the corresponding pointer placeholder in ConstParamPack is set to CUDNN_PTR_ELEMAligned or CUDNN_PTR_16BAligned, then the device pointer in the VariantParamPack may not be NULL and needs to be at least element-aligned or 16 bytes-aligned, respectively.

## 6.2. API Functions
6.2.1. cudnnConvolutionBackwardBias()

```c
#include <cudnn.h>

int cudnnConvolutionBackwardBias(
    cudnnHandle_t handle,
    const void *alpha,
    const cudnnTensorDescriptor_t dyDesc,
    const void *dy,
    const void *beta,
    const cudnnTensorDescriptor_t dbDesc,
    void *db)
```

This function computes the convolution function gradient with respect to the bias, which is the sum of every element belonging to the same feature map across all of the images of the input tensor. Therefore, the number of elements produced is equal to the number of features maps of the input tensor.

**Parameters**

**handle**

*Input*. Handle to a previously created cuDNN context. For more information, see *cudnnHandle_t*.

**alpha, beta**

*Input*. Pointers to scaling factors (in host memory) used to blend the computation result with prior value in the output layer as follows:

\[
\text{dstValue} = \alpha[0] \times \text{resultValue} + \beta[0] \times \text{priorDstValue}
\]

For more information, see *Scaling Parameters* in the *cuDNN Developer Guide*.

**dyDesc**

*Input*. Handle to the previously initialized input tensor descriptor. For more information, see *cudnnTensorDescriptor_t*.

**dy**

*Input*. Data pointer to GPU memory associated with the tensor descriptor dyDesc.

**dbDesc**

*Input*. Handle to the previously initialized output tensor descriptor.

**db**

*Output*. Data pointer to GPU memory associated with the output tensor descriptor dbDesc.

**Returns**

**CUDNN_STATUS_SUCCESS**

The operation was launched successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.
CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- One of the parameters n, height, width of the output tensor is not 1.
- The numbers of feature maps of the input tensor and output tensor differ.
- The dataType of the two tensor descriptors is different.

6.2.2. cudnnConvolutionBackwardFilter()

cudnnStatus_t cudnnConvolutionBackwardFilter(
    cudnnHandle_t                       handle,
    const void                         *alpha,
    const cudnnTensorDescriptor_t       xDesc,
    const void                         *x,
    const cudnnTensorDescriptor_t       dyDesc,
    const void                         *dy,
    const cudnnConvolutionDescriptor_t  convDesc,
    cudnnConvolutionBwdFilterAlgo_t     algo,
    void                               *workSpace,
    size_t                              workSpaceSizeInBytes,
    const void                         *beta,
    const cudnnFilterDescriptor_t       dwDesc,
    void                               *dw)

This function computes the convolution weight (filter) gradient of the tensor dy, where y is the output of the forward convolution in cudnnConvolutionForward(). It uses the specified algo, and returns the results in the output tensor dw. Scaling factors alpha and beta can be used to scale the computed result or accumulate with the current dw.

Parameters

handle

*Input*. Handle to a previously created cuDNN context. For more information, see cudnnHandle_t.

alpha, beta

*Input*. Pointers to scaling factors (in host memory) used to blend the computation result with prior value in the output layer as follows:

dstValue = alpha[0]*result + beta[0]*priorDstValue

For more information, see Scaling Parameters in the cuDNN Developer Guide.

xDesc

*Input*. Handle to a previously initialized tensor descriptor. For more information, see cudnnTensorDescriptor_t.

x

*Input*. Data pointer to GPU memory associated with the tensor descriptor xDesc.

dyDesc

*Input*. Handle to the previously initialized input differential tensor descriptor.
dy

*Input.* Data pointer to GPU memory associated with the backpropagation gradient tensor descriptor `dyDesc`.

convDesc

*Input.* Previously initialized convolution descriptor. For more information, see `cudnnConvolutionDescriptor_t`.

algo

*Input.* Enumerant that specifies which convolution algorithm should be used to compute the results. For more information, see `cudnnConvolutionBwdFilterAlgo_t`.

workSpace

*Input.* Data pointer to GPU memory to a workspace needed to be able to execute the specified algorithm. If no workspace is needed for a particular algorithm, that pointer can be nil.

workSpaceSizeInBytes

*Input.* Specifies the size in bytes of the provided `workSpace`.

dwDesc

*Input.* Handle to a previously initialized filter gradient descriptor. For more information, see `cudnnFilterDescriptor_t`.

dw

*Input/Output.* Data pointer to GPU memory associated with the filter gradient descriptor `dwDesc` that carries the result.

**Supported configurations**

This function supports the following combinations of data types for `xDesc`, `dyDesc`, `convDesc`, and `dwDesc`.

<table>
<thead>
<tr>
<th>Data Type Configurations</th>
<th>xDesc, dyDesc, and dwDesc Data Type</th>
<th>convDesc Data Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>TRUE_HALF_CONFIG [only supported on architectures with true FP16 support, meaning, compute capability 5.3 and later]</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_HALF</td>
</tr>
<tr>
<td>PSEUDO_HALF_CONFIG</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_FLOAT</td>
</tr>
<tr>
<td>FLOAT_CONFIG</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
</tr>
<tr>
<td>DOUBLE_CONFIG</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
</tr>
</tbody>
</table>
Supported algorithms

Note: Specifying a separate algorithm can cause changes in performance, support and computation determinism. See the following table for an exhaustive list of algorithm options and their respective supported parameters and deterministic behavior.

The table below shows the list of the supported 2D and 3D convolutions. The 2D convolutions are described first, followed by the 3D convolutions.

For the following terms, the short-form versions shown in the parentheses are used in the table below, for brevity:

- CUDNN_CONVOLUTION_BWD_FILTER_ALGO_0 (_ALGO_0)
- CUDNN_CONVOLUTION_BWD_FILTER_ALGO_1 (_ALGO_1)
- CUDNN_CONVOLUTION_BWD_FILTER_ALGO_3 (_ALGO_3)
- CUDNN_CONVOLUTION_BWD_FILTER_ALGO_FFT (_FFT)
- CUDNN_CONVOLUTION_BWD_FILTER_ALGO_FFT_TILING (_FFT_TILING)
- CUDNN_CONVOLUTION_BWD_FILTER_ALGO_WINOGRAD_NONFUSED (_WINOGRAD_NONFUSED)
- CUDNN_TENSOR_NCHW (_NCHW)
- CUDNN_TENSOR_NHWC (_NHWC)
- CUDNN_TENSOR_NCHW_VECT_C (_NCHW_VECT_C)

Table 35. For 2D convolutions: dwDesc: _NHWC

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>Deterministic (Yes or No)</th>
<th>Tensor Formats Supported for dyDesc</th>
<th>Tensor Formats Supported for dxDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td>_ALGO_0 and _ALGO_1</td>
<td></td>
<td>NHWC HWC-packed</td>
<td>NHWC HWC-packed</td>
<td>PSEUDO_HALF_CONFIG</td>
<td></td>
</tr>
</tbody>
</table>
Table 36. For 2D convolutions: Desc: _NCHW

<table>
<thead>
<tr>
<th>Filter descriptor: Desc: _NCHW</th>
<th>Tensor Formats Supported for dyDesc</th>
<th>Tensor Formats Supported for dxDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>_ALGO_0</strong></td>
<td>No</td>
<td>NCHW CHW-packed</td>
<td>PSEUDO_HALF_CONFIG DOUBLE_CONFIG</td>
<td></td>
</tr>
<tr>
<td></td>
<td>All except _NCHW_VECT_C</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>_ALGO_1</strong></td>
<td>Yes</td>
<td>NCHW CHW-packed</td>
<td>TRUE_HALF_CONFIG PSEUDO_HALF_CONFIG DOUBLE_CONFIG</td>
<td></td>
</tr>
<tr>
<td></td>
<td>All except _NCHW_VECT_C</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>_FFT</strong></td>
<td>Yes</td>
<td>NCHW CHW-packed</td>
<td>PSEUDO_HALF_CONFIG FLOAT_CONFIG</td>
<td></td>
</tr>
<tr>
<td></td>
<td>NCHW CHW-packed</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Dilation:**
- For all dimensions $convDesc$ Group Count Support: Greater than 0
- Greater than 0 for all dimensions $convDesc$ Group Count Support: Greater than 0
- 1 for all dimensions $convDesc$ Group Count Support: Greater than 0

$xDesc$ feature map height + $2 \times convDesc$ zero-padding height must equal 256 or less

$xDesc$ feature map width + $2 \times convDesc$ zero-padding
<table>
<thead>
<tr>
<th>Filter descriptor</th>
<th>Desc: _NCHW</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Algo Name</strong></td>
<td><strong>Deterministic (Yes or No)</strong></td>
</tr>
<tr>
<td>_ALGO_3</td>
<td>Yes</td>
</tr>
</tbody>
</table>
| _WINOGRAD_NONFUSED | Yes         | All except _NCHW_VECT_C                | NCHW CHW-packed                     | TRUE_HALF_CONFIG PSEUDO_HALF_CONFIG FLOAT_CONFIG | Dilation: 1 for all dimensions convDesc Group Count Support: Greater than 0 convDesc vertical and horizontal filter stride must equal 1 dwDesc filter height must be greater than convDesc zero-padding height dwDesc filter width must be greater than convDesc zero-padding width width must equal 256 or less convDesc vertical and horizontal filter stride must equal 1 dwDesc filter height must be greater than convDesc zero-padding height dwDesc filter width must be greater than convDesc zero-padding width width must equal 256 or less convDesc vertical and horizontal filter stride must equal 1 dwDesc filter height must be greater than convDesc zero-padding height dwDesc filter width must be greater than convDesc zero-padding width width must equal 256 or less convDesc vertical and horizontal filter stride must equal 1 dwDesc filter height must be greater than convDesc zero-padding height dwDesc filter width must be greater than convDesc zero-padding width width must equal 256 or less convDesc vertical and horizontal filter stride must equal 1 dwDesc filter height must be greater than convDesc zero-padding height dwDesc filter width must be greater than convDesc zero-padding width width must equal 256 or less convDesc vertical and horizontal filter stride must equal 1 dwDesc filter height must be greater than convDesc zero-padding height dwDesc filter width must be greater than convDesc zero-padding width width must equal 256 or less convDesc vertical and horizontal filter stride must equal 1 dwDesc filter height must be greater than convDesc zero-padding height dwDesc filter width must be greater than convDesc zero-padding width width must equal 256 or less convDesc vertical and horizontal filter stride must equal 1 dwDesc filter height must be greater than convDesc zero-padding height dwDesc filter width must be greater than convDesc zero-padding width width must equal 256 or less convDesc vertical and horizontal filter stride must equal 1 dwDesc filter height must be greater than convDesc zero-padding height dwDesc filter width must be greater than convDesc zero-padding width width must equal 256 or less convDesc vertical and horizontal filter stride must equal 1 dwDesc filter height must be greater than convDesc zero-padding height dwDesc filter width must be greater than convDesc zero-padding width width must equal 256 or less convDesc vertical and horizontal filter stride must equal 1 dwDesc filter height must be greater than convDesc zero-padding height dwDesc filter width must be greater than convDesc zero-padding width width must equal 256 or less convDesc vertical and horizontal filter stride must equal 1 dwDesc filter height must be greater than convDesc zero-padding height dwDesc filter width must be greater than convDesc zero-padding width width must equal 256 or less convDesc vertical and horizontal filter stride must equal 1 dwDesc filter height must be greater than convDesc zero-padding height dwDesc filter width must be greater than convDesc zero-padding width width must equal 256 or less convDesc vertical and horizontal filter stride must equal 1 dwDesc filter height must be greater than convDesc zero-padding height dwDesc filter width must be greater than convDesc zero-padding width

**Important**
- width must equal 256 or less
- convDesc vertical and horizontal filter stride must equal 1
- dwDesc filter height must be greater than convDesc zero-padding height
- dwDesc filter width must be greater than convDesc zero-padding width
Filter descriptor **Desc: _NCHW**

<table>
<thead>
<tr>
<th>Algo Name</th>
<th>Deterministic (Yes or No)</th>
<th>Tensor Formats Supported for dyDesc</th>
<th>Tensor Formats Supported for dxDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>NCHW CHW-packed</td>
<td>NCHW CHW-packed</td>
<td>PSEUDO_HALF_CONFIG FLOAT_CONFIG DOUBLE_CONFIG</td>
<td></td>
</tr>
</tbody>
</table>

**FFT_TILING**
- **Yes**
- **Important**: horizontal filter stride must equal 1
- **wDesc** filter (height, width) must be [3,3] or [5,5]
- If **wDesc** filter (height, width) is (5,5), then the data type config **TRUE_HALF_CONFIG** is not supported.
- **Dilation**: 1 for all dimensions
- **convDesc** Group Count Support: Greater than 0
- **xDesc** width or height must equal 1
- **dyDesc** width or height must equal 1 (the same dimension as in **xDesc**). The other dimension must be less than or equal to 256,
## Filter descriptor `Desc: _NCHW`

<table>
<thead>
<tr>
<th>Algo Name (3D Convolutions)</th>
<th>Deterministic (Yes or No)</th>
<th>Tensor Formats Supported for dyDesc</th>
<th>Tensor Formats Supported for dxDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td>_ALGO_0</td>
<td>No</td>
<td>All except <code>_NCDHW_VECT_C</code></td>
<td>NCDHW, CDHW-packed</td>
<td>PSEUDO_HALF_CONFIG, FLOAT_CONFIG, DOUBLE_CONFIG</td>
<td>Dilation: greater than 0 for all dimensions, convDesc Group Count</td>
</tr>
</tbody>
</table>

Table 37. For 3D convolutions: `wDesc: _NCHW`
**Filter descriptor**  \texttt{wDesc: _NCHW}.

<table>
<thead>
<tr>
<th>Algo Name (3D Convolutions)</th>
<th>Deterministic (Yes or No)</th>
<th>Tensor Formats Supported for dyDesc</th>
<th>Tensor Formats Supported for dxDesc</th>
<th>Data Type Configurations Supported</th>
<th>Important</th>
</tr>
</thead>
<tbody>
<tr>
<td>_ALGO_3</td>
<td>No</td>
<td>NCDHW fully-packed</td>
<td>NCDHW fully-packed</td>
<td>PSEUDO_HALF_CONFIG, FLOAT_CONFIG, DOUBLE_CONFIG</td>
<td>Support: Greater than 0</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Dilation: greater than 0 for all dimensions</td>
<td></td>
</tr>
</tbody>
</table>

**Returns**

**CUDNN\_STATUS\_SUCCESS**

The operation was launched successfully.

**CUDNN\_STATUS\_BAD\_PARAM**

At least one of the following conditions are met:

- At least one of the following is NULL: handle, xDesc, dyDesc, convDesc, dwDesc, xData, dyData, dwData, alpha, beta
- xDesc and dyDesc have a non-matching number of dimensions
- xDesc and dwDesc have a non-matching number of dimensions
- xDesc has fewer than three number of dimensions
- xDesc, dyDesc, and dwDesc have a non-matching data type.
- xDesc and dwDesc have a non-matching number of input feature maps per image (or group in case of grouped convolutions).
- yDesc or wDesc indicate an output channel count that isn’t a multiple of group count (if group count has been set in convDesc).

**CUDNN\_STATUS\_NOT\_SUPPORTED**

At least one of the following conditions are met:

- xDesc or dyDesc have negative tensor striding
- xDesc, dyDesc or dwDesc has a number of dimensions that is not 4 or 5
- The chosen algo does not support the parameters provided; see above for exhaustive list of parameter support for each algo.
**CUDNN_STATUS_MAPPING_ERROR**

An error occurs during the texture binding of the filter data.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

### 6.2.3. cudnnCreateFusedOpsConstParamPack()

```c
int cudnnCreateFusedOpsConstParamPack(
    cudnnFusedOpsConstParamPack_t *constPack,
    cudnnFusedOps_t ops);
```

This function creates an opaque structure to store the various problem size information, such as the shape, layout and the type of tensors, and the descriptors for convolution and activation, for the selected sequence of cudnnFusedOps computations.

**Parameters**

- **constPack**
  - *Input*. The opaque structure that is created by this function. For more information, see `cudnnFusedOpsConstParamPack_t`.

- **ops**
  - *Input*. The specific sequence of computations to perform in the cudnnFusedOps computations, as defined in the enumerant type `cudnnFusedOps_t`.

**Returns**

- **CUDNN_STATUS_BAD_PARAM**
  - If either `constPack` or `ops` is NULL.

- **CUDNN_STATUS_SUCCESS**
  - If the descriptor is created successfully.

- **CUDNN_STATUS_NOT_SUPPORTED**
  - If the `ops` enum value is not supported or reserved for future use.

### 6.2.4. cudnnCreateFusedOpsPlan()

```c
int cudnnCreateFusedOpsPlan(
    cudnnFusedOpsPlan_t *plan,
    cudnnFusedOps_t ops);
```

This function creates the plan descriptor for the cudnnFusedOps computation. This descriptor contains the plan information, including the problem type and size, which kernels should be run, and the internal workspace partition.

**Parameters**

- **plan**
  - *Input*. A pointer to the instance of the descriptor created by this function.
ops

Input. The specific sequence of fused operations computations for which this plan
descriptor should be created. For more information, see cudnnFusedOps_t.

Returns

CUDNN_STATUS_BAD_PARAM
If either the input *plan is NULL or the ops input is not a valid cudnnFusedOp enum.

CUDNN_STATUS_NOT_SUPPORTED
The ops input provided is not supported.

CUDNN_STATUS_SUCCESS
The plan descriptor is created successfully.

6.2.5. cudnnCreateFusedOpsVariantParamPack()
cudnnStatus_t cudnnCreateFusedOpsVariantParamPack(
    cudnnFusedOpsVariantParamPack_t *varPack,
    cudnnFusedOps_t ops);

This function creates a descriptor for cudnnFusedOps constant parameters.

Parameters

varPack
Input. Pointer to the descriptor created by this function. For more information, see
  cudnnFusedOpsVariantParamPack_t.

ops
Input. The specific sequence of fused operations computations for which this descriptor
should be created.

Returns

CUDNN_STATUS_SUCCESS
The descriptor is successfully created.

CUDNN_STATUS_BAD_PARAM
If any input is invalid.

6.2.6. cudnnDestroyFusedOpsConstParamPack()
cudnnStatus_t cudnnDestroyFusedOpsConstParamPack(
    cudnnFusedOpsConstParamPack_t constPack);

This function destroys a previously-created cudnnFusedOpsConstParamPack_t structure.

Parameters

cstPack
Input. The cudnnFusedOpsConstParamPack_t structure that should be destroyed.
6.2.7. **cudnnDestroyFusedOpsPlan()**

```c
    cudnnStatus_t cudnnDestroyFusedOpsPlan(
        cudnnFusedOpsPlan_t plan);
```

This function destroys the plan descriptor provided.

**Parameters**

- **plan**
  - *Input*. The descriptor that should be destroyed by this function.

**Returns**

- **CUDNN_STATUS_SUCCESS**
  - If the descriptor is destroyed successfully.
- **CUDNN_STATUS_INTERNAL_ERROR**
  - If the ops enum value is not supported or invalid.

6.2.8. **cudnnDestroyFusedOpsVariantParamPack()**

```c
    cudnnStatus_t cudnnDestroyFusedOpsVariantParamPack(
        cudnnFusedOpsVariantParamPack_t varPack);
```

This function destroys a previously-created descriptor for `cudnnFusedOps` constant parameters.

**Parameters**

- **varPack**
  - *Input*. The descriptor that should be destroyed.

**Returns**

- **CUDNN_STATUS_SUCCESS**
  - The descriptor is successfully destroyed.

6.2.9. **cudnnFindConvolutionBackwardFilterAlgorithm()**

```c
    cudnnStatus_t cudnnFindConvolutionBackwardFilterAlgorithm(
        cudnnHandle_t handle,
        const cudnnTensorDescriptor_t xDesc,
        const cudnnTensorDescriptor_t dyDesc,
        const cudnnConvolutionDescriptor_t convDesc,
        const cudnnFilterDescriptor_t dwDesc,
        const int requestedAlgoCount,
        int *returnedAlgoCount,
```

The descriptor is successfully destroyed.
This function attempts all algorithms available for `cudnnConvolutionBackwardFilter()`. It will attempt both the provided `convDesc` `mathType` and `CUDNN_DEFAULT_MATH` (assuming the two differ).

**Note:** Algorithms without the `CUDNN_TENSOR_OP_MATH` availability will only be tried with `CUDNN_DEFAULT_MATH`, and returned as such.

Memory is allocated via `cudaMalloc()`. The performance metrics are returned in the user-allocated array of `cudnnConvolutionBwdFilterAlgoPerf_t`. These metrics are written in a sorted fashion where the first element has the lowest compute time. The total number of resulting algorithms can be queried through the API `cudnnGetConvolutionBackwardFilterAlgorithmMaxCount()`.

**Parameters**

- **handle**
  
  *Input.* Handle to a previously created cuDNN context.

- **xDesc**
  
  *Input.* Handle to the previously initialized input tensor descriptor.

- **dyDesc**
  
  *Input.* Handle to the previously initialized input differential tensor descriptor.

- **convDesc**
  
  *Input.* Previously initialized convolution descriptor.

- **dwDesc**
  
  *Input.* Handle to a previously initialized filter descriptor.

- **requestedAlgoCount**
  
  *Input.* The maximum number of elements to be stored in `perfResults`.

- **returnedAlgoCount**
  
  *Output.* The number of output elements stored in `perfResults`.

- **perfResults**
  
  *Output.* A user-allocated array to store performance metrics sorted ascending by compute time.
Returns

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- handle is not allocated properly.
- xDesc, dyDesc, or dwDesc are not allocated properly.
- xDesc, dyDesc, or dwDesc has fewer than 1 dimension.
- Either returnedCount or perfResults is nil.
- requestedCount is less than 1.

**CUDNN_STATUS_ALLOC_FAILED**

This function was unable to allocate memory to store sample input, filters and output.

**CUDNN_STATUS_INTERNAL_ERROR**

At least one of the following conditions are met:

- The function was unable to allocate necessary timing objects.
- The function was unable to deallocate necessary timing objects.
- The function was unable to deallocate sample input, filters and output.

### 6.2.10. cudnnFindConvolutionBackwardFilterAlgorithmEx

```c
  cudnnStatus_t cudnnFindConvolutionBackwardFilterAlgorithmEx(
    cudnnHandle_t                          handle,
    const cudnnTensorDescriptor_t          xDesc,
    const void                            *x,
    const cudnnTensorDescriptor_t          dyDesc,
    const void                            *dy,
    const cudnnConvolutionDescriptor_t     convDesc,
    const cudnnFilterDescriptor_t          dwDesc,
    void                                  *dw,
    const int                              requestedAlgoCount,
    int                                   *returnedAlgoCount,
    cudnnConvolutionBwdFilterAlgoPerf_t   *perfResults,
    void                                  *workSpace,
    size_t                                 workSpaceSizeInBytes)
```

This function attempts all algorithms available for `cudnnConvolutionBackwardFilter[]`. It will attempt both the provided `convDesc` `mathType` and `CUDNN_DEFAULT_MATH` (assuming the two differ).

**Note:** Algorithms without the `CUDNN_TENSOR_OP_MATH` availability will only be tried with `CUDNN_DEFAULT_MATH`, and returned as such.

Memory is allocated via `cudaMalloc()`. The performance metrics are returned in the user-allocated array of `cudnnConvolutionBwdFilterAlgoPerf_t`. These metrics
are written in a sorted fashion where the first element has the lowest compute time. The total number of resulting algorithms can be queried through the API `cudnnGetConvolutionBackwardFilterAlgorithmMaxCount()`.

**Note:** This function is host blocking.

### Parameters

- **handle**
  - *Input.* Handle to a previously created cuDNN context.

- **xDesc**
  - *Input.* Handle to the previously initialized input tensor descriptor.

- **x**
  - *Input.* Data pointer to GPU memory associated with the filter descriptor `xDesc`.

- **dyDesc**
  - *Input.* Handle to the previously initialized input differential tensor descriptor.

- **dy**
  - *Input.* Data pointer to GPU memory associated with the tensor descriptor `dyDesc`.

- **convDesc**
  - *Input.* Previously initialized convolution descriptor.

- **dwDesc**
  - *Input.* Handle to a previously initialized filter descriptor.

- **dw**
  - *Input/Output.* Data pointer to GPU memory associated with the filter descriptor `dwDesc`. The content of this tensor will be overwritten with arbitrary values.

- **requestedAlgoCount**
  - *Input.* The maximum number of elements to be stored in `perfResults`.

- **returnedAlgoCount**
  - *Output.* The number of output elements stored in `perfResults`.

- **perfResults**
  - *Output.* A user-allocated array to store performance metrics sorted ascending by compute time.

- **workSpace**
  - *Input.* Data pointer to GPU memory is a necessary workspace for some algorithms. The size of this workspace will determine the availability of algorithms. A nil pointer is considered a `workSpace` of 0 bytes.
workSpaceSizeInBytes

Input. Specifies the size in bytes of the provided workSpace.

Returns

CUDNN_STATUS_SUCCESS

The query was successful.

CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- handle is not allocated properly.
- xDesc, dyDesc, or dwDesc are not allocated properly.
- xDesc, dyDesc, or dwDesc has fewer than 1 dimension.
- x, dy, or dw is nil.
- Either returnedCount or perfResults is nil.
- requestedCount is less than 1.

CUDNN_STATUS_INTERNAL_ERROR

At least one of the following conditions are met:

- The function was unable to allocate necessary timing objects.
- The function was unable to deallocate necessary timing objects.
- The function was unable to deallocate sample input, filters and output.

6.2.11. cudnnFusedOpsExecute()

cudnnStatus_t cudnnFusedOpsExecute(
    cudnnHandle_t handle,
    const cudnnFusedOpsPlan_t plan,
    cudnnFusedOpsVariantParamPack_t varPack);

This function executes the sequence of cudnnFusedOps operations.

Parameters

handle

Input. Pointer to the cuDNN library context.

plan

Input. Pointer to a previously-created and initialized plan descriptor.

varPack

Input. Pointer to the descriptor to the variant parameters pack.

Returns

CUDNN_STATUS_BAD_PARAM

If the type of cudnnFusedOps_t in the plan descriptor is unsupported.
### 6.2.12. cudnnGetConvolutionBackwardFilterAlgorithmMaxCount

```c
void cudnnGetConvolutionBackwardFilterAlgorithmMaxCount(
    cudnnHandle_t handle,
    int *count)
```

This function returns the maximum number of algorithms which can be returned from `cudnnFindConvolutionBackwardFilterAlgorithm[]` and `cudnnGetConvolutionForwardAlgorithm_v7[]`. This is the sum of all algorithms plus the sum of all algorithms with Tensor Core operations supported for the current device.

**Parameters**

- **handle**
  
  Input. Handle to a previously created cuDNN context.

- **count**
  
  Output. The resulting maximum count of algorithms.

**Returns**

- **CUDNN_STATUS_SUCCESS**
  
  The function was successful.

- **CUDNN_STATUS_BAD_PARAM**
  
  The provided handle is not allocated properly.

### 6.2.13. cudnnGetConvolutionBackwardFilterAlgorithm_v7

```c
void cudnnGetConvolutionBackwardFilterAlgorithm_v7(
    cudnnHandle_t handle,
    const cudnnTensorDescriptor_t xDesc,
    const cudnnTensorDescriptor_t dyDesc,
    const cudnnConvolutionDescriptor_t convDesc,
    const cudnnFilterDescriptor_t dwDesc,
    const int requestedAlgoCount,
    int *returnedAlgoCount,
    cudnnConvolutionBwdFilterAlgoPerf_t *perfResults)
```

This function serves as a heuristic for obtaining the best suited algorithm for `cudnnConvolutionBackwardFilter[]` for the given layer specifications. This function will return all algorithms (including CUDNN_TENSOR_OP_MATH and CUDNN_DEFAULT_MATH versions of algorithms where CUDNN_TENSOR_OP_MATH may be available) sorted by expected (based on internal heuristic) relative performance with fastest being index 0 of `perfResults`. For an exhaustive search for the fastest algorithm, use `cudnnFindConvolutionBackwardFilterAlgorithm[]`. The total number of resulting algorithms can be queried through the `returnedAlgoCount` variable.
Parameters

**handle**

*Input.* Handle to a previously created cuDNN context.

**xDesc**

*Input.* Handle to the previously initialized input tensor descriptor.

**dyDesc**

*Input.* Handle to the previously initialized input differential tensor descriptor.

**convDesc**

*Input.* Previously initialized convolution descriptor.

**dwDesc**

*Input.* Handle to a previously initialized filter descriptor.

**requestedAlgoCount**

*Input.* The maximum number of elements to be stored in `perfResults`.

**returnedAlgoCount**

*Output.* The number of output elements stored in `perfResults`.

**perfResults**

*Output.* A user-allocated array to store performance metrics sorted ascending by compute time.

Returns

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- One of the parameters `handle`, `xDesc`, `dyDesc`, `convDesc`, `dwDesc`, `perfResults`, `returnedAlgoCount` is NULL.
- The numbers of feature maps of the input tensor and output tensor differ.
- The `dataType` of the two tensor descriptors or the filter are different.
- `requestedAlgoCount` is less than or equal to 0.

### 6.2.14. cudnnGetConvolutionBackwardFilterWorkspaceSize()

```c
#include <cudnn.h>

size_t cudnnGetConvolutionBackwardFilterWorkspaceSize(
    cudnnHandle_t handle,
    const cudnnTensorDescriptor_t xDesc,
    const cudnnTensorDescriptor_t dyDesc,
    const cudnnConvolutionDescriptor_t convDesc,
    size_t requestedAlgoCount,
    size_t* returnedAlgoCount,
    size_t* perfResults, 
    cudnnStatus_t* status);
```
This function returns the amount of GPU memory workspace the user needs to allocate to be able to call `cudnnConvolutionBackwardFilter()` with the specified algorithm. The workspace allocated will then be passed to the routine `cudnnConvolutionBackwardFilter()`. The specified algorithm can be the result of the call to `cudnnGetConvolutionBackwardFilterAlgorithm_v7()` or can be chosen arbitrarily by the user. Note that not every algorithm is available for every configuration of the input tensor and/or every configuration of the convolution descriptor.

**Parameters**

**handle**

*Input.* Handle to a previously created cuDNN context.

**xDesc**

*Input.* Handle to the previously initialized input tensor descriptor.

**dyDesc**

*Input.* Handle to the previously initialized input differential tensor descriptor.

**convDesc**

*Input.* Previously initialized convolution descriptor.

**dwDesc**

*Input.* Handle to a previously initialized filter descriptor.

**algo**

*Input.* Enumerator that specifies the chosen convolution algorithm.

**sizeInBytes**

*Output.* Amount of GPU memory needed as workspace to be able to execute a forward convolution with the specified algo.

**Returns**

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The numbers of feature maps of the input tensor and output tensor differ.
- The **dataType** of the two tensor descriptors or the filter are different.

**CUDNN_STATUS_NOT_SUPPORTED**

The combination of the tensor descriptors, filter descriptor and convolution descriptor is not supported for the specified algorithm.
6.2.15. cudnnGetFusedOpsConstParamPackAttribute()

cudnnStatus_t cudnnGetFusedOpsConstParamPackAttribute(
    const cudnnFusedOpsConstParamPack_t constPack,
    cudnnFusedOpsConstParamLabel_t paramLabel,
    void *param,
    int *isNULL);

This function retrieves the values of the descriptor pointed to by the param pointer input. The type of the descriptor is indicated by the enum value of paramLabel input.

Parameters

constPack
    Input. The opaque cudnnFusedOpsConstParamPack_t structure that contains the various problem size information, such as the shape, layout and the type of tensors, and the descriptors for convolution and activation, for the selected sequence of cudnnFusedOps_t computations.

paramLabel
    Input. Several types of descriptors can be retrieved by this getter function. The param input points to the descriptor itself, and this input indicates the type of the descriptor pointed to by the param input. The cudnnFusedOpsConstParamLabel_t enumerant type enables the selection of the type of the descriptor. Refer to the param description below.

param
    Input. Data pointer to the host memory associated with the descriptor that should be retrieved. The type of this descriptor depends on the value of paramLabel. For the given paramLabel, if the associated value inside the constPack is set to NULL or by default NULL, then cuDNN will copy the value or the opaque structure in the constPack to the host memory buffer pointed to by param. For more information, see the table in cudnnFusedOpsConstParamLabel_t.

isNULL
    Input/Output. Users must pass a pointer to an integer in the host memory in this field. If the value in the constPack associated with the given paramLabel is by default NULL or previously set by the user to NULL, then cuDNN will write a non-zero value to the location pointed by isNULL.

Returns

CUDNN_STATUS_SUCCESS
    The descriptor values are retrieved successfully.

CUDNN_STATUS_BAD_PARAM
    If either constPack, param or isNULL is NULL; or if paramLabel is invalid.

6.2.16. cudnnGetFusedOpsVariantParamPackAttribute()

cudnnStatus_t cudnnGetFusedOpsVariantParamPackAttribute(
    const cudnnFusedOpsVariantParamPack_t varPack,
    cudnnFusedOpsVariantParamLabel_t paramLabel,
    void *param,
This function retrieves the settings of the variable parameter pack descriptor.

Parameters

varPack
   Input. Pointer to the cudnnFusedOps variant parameter pack [varPack] descriptor.

paramLabel
   Input. Type of the buffer pointer parameter (in the varPack descriptor). For more information, see cudnnFusedOpsConstParamLabel_t. The retrieved descriptor values vary according to this type.

ptr
   Output. Pointer to the host or device memory where the retrieved value is written by this function. The data type of the pointer, and the host/device memory location, depend on the paramLabel input selection. For more information, see cudnnFusedOpsVariantParamLabel_t.

Returns

CUDNN_STATUS_SUCCESS
   The descriptor values are retrieved successfully.

CUDNN_STATUS_BAD_PARAM
   If either varPack or ptr is NULL, or if paramLabel is set to invalid value.

6.2.17. cudnnMakeFusedOpsPlan()

cudnnStatus_t cudnnMakeFusedOpsPlan(
   cudnnHandle_t handle,
   cudnnFusedOpsPlan_t plan,
   const cudnnFusedOpsConstParamPack_t constPack,
   size_t *workspaceSizeInBytes);

This function determines the optimum kernel to execute, and the workspace size the user should allocate, prior to the actual execution of the fused operations by cudnnFusedOpsExecute[].

Parameters

handle
   Input. Pointer to the cuDNN library context.

plan
   Input. Pointer to a previously-created and initialized plan descriptor.

constPack
   Input. Pointer to the descriptor to the const parameters pack.

workspaceSizeInBytes
   Output. The amount of workspace size the user should allocate for the execution of this plan.
Returns

**CUDNN_STATUS_BAD_PARAM**
If any of the inputs is NULL, or if the type of `cudnnFusedOps_t` in the `constPack` descriptor is unsupported.

**CUDNN_STATUS_SUCCESS**
The function executed successfully.

6.2.18. **cudnnSetFusedOpsConstParamPackAttribute()**

```c
void cudnnSetFusedOpsConstParamPackAttribute(
    cudnnFusedOpsConstParamPack_t constPack,
    cudnnFusedOpsConstParamLabel_t paramLabel,
    const void *param);
```

This function sets the descriptor pointed to by the `param` pointer input. The type of the descriptor to be set is indicated by the enum value of the `paramLabel` input.

Parameters

**constPack**
*Input.* The opaque `cudnnFusedOpsConstParamPack_t` structure that contains the various problem size information, such as the shape, layout and the type of tensors, the descriptors for convolution and activation, and settings for operations such as convolution and activation.

**paramLabel**
*Input.* Several types of descriptors can be set by this setter function. The `param` input points to the descriptor itself, and this input indicates the type of the descriptor pointed to by the `param` input. The `cudnnFusedOpsConstParamLabel_t` enumerant type enables the selection of the type of the descriptor.

**param**
*Input.* Data pointer to the host memory, associated with the specific descriptor. The type of the descriptor depends on the value of `paramLabel`. For more information, see the table in `cudnnFusedOpsConstParamLabel_t`.

If this pointer is set to `NULL`, then the cuDNN library will record as such. If not, then the values pointed to by this pointer (meaning, the value or the opaque structure underneath) will be copied into the `constPack` during `cudnnSetFusedOpsConstParamPackAttribute()` operation.

Returns

**CUDNN_STATUS_SUCCESS**
The descriptor is set successfully.

**CUDNN_STATUS_BAD_PARAM**
If `constPack` is `NULL`, or if `paramLabel` or the ops setting for `constPack` is invalid.
6.2.19. **cudnnSetFusedOpsVariantParamPackAttribute()**

```c
#include <cudnn.h>

cudnnStatus_t cudnnSetFusedOpsVariantParamPackAttribute(
    cudnnFusedOpsVariantParamPack_t varPack,
    cudnnFusedOpsVariantParamLabel_t paramLabel,
    void *ptr);
```

This function sets the variable parameter pack descriptor.

**Parameters**

- **varPack**
  - *Input*. Pointer to the `cudnnFusedOps` variant parameter pack `{varPack}` descriptor.

- **paramLabel**
  - *Input*. Type to which the buffer pointer parameter (in the `varPack` descriptor) is set by this function. For more information, see `cudnnFusedOpsConstParamLabel_t`.

- **ptr**
  - *Input*. Pointer, to the host or device memory, to the value to which the descriptor parameter is set. The data type of the pointer, and the host/device memory location, depend on the `paramLabel` input selection. For more information, see `cudnnFusedOpsVariantParamLabel_t`.

**Returns**

- **CUDNN_STATUS_BAD_PARAM**
  - If `varPack` is NULL or if `paramLabel` is set to an unsupported value.

- **CUDNN_STATUS_SUCCESS**
  - The descriptor was set successfully.
Chapter 7. cudnn_adv_infer.so Library

7.1. Data Type References

7.1.1. Pointer To Opaque Struct Types

7.1.1.1. cudnnAttnDescriptor_t

cudnnAttnDescriptor_t is a pointer to an opaque structure holding parameters of the multi-head attention layer such as:

- weight and bias tensor shapes (vector lengths before and after linear projections)
- parameters that can be set in advance and do not change when invoking functions to evaluate forward responses and gradients (number of attention heads, softmax smoothing/sharpening coefficient)
- other settings that are necessary to compute temporary buffer sizes.

Use the cudnnCreateAttnDescriptor() function to create an instance of the attention descriptor object and cudnnDestroyAttnDescriptor() to delete the previously created descriptor. Use the cudnnSetAttnDescriptor() function to configure the descriptor.

7.1.1.2. cudnnPersistentRNNPlan_t

This function is deprecated starting in cuDNN 8.0.0.

cudnnPersistentRNNPlan_t is a pointer to an opaque structure holding a plan to execute a dynamic persistent RNN. cudnnCreatePersistentRNNPlan() is used to create and initialize one instance.

7.1.1.3. cudnnRNNDataDescriptor_t

CudnnRNNDataDescriptor_t is a pointer to an opaque structure holding the description of an RNN data set. The function cudnnCreateRNNDataDescriptor() is used to create one instance, and cudnnSetRNNDataDescriptor() must be used to initialize this instance.
7.1.1.4. cudnnRNNDescrcriptor_t

cudnnRNNDescrcriptor_t is a pointer to an opaque structure holding the description of an RNN operation. cudnnCreateRNNDescrcriptor() is used to create one instance.

7.1.1.5. cudnnSeqDataDescriptor_t

cudnnSeqDataDescriptor_t is a pointer to an opaque structure holding parameters of the sequence data container or buffer. The sequence data container is used to store fixed size vectors defined by the VECT dimension. Vectors are arranged in additional three dimensions: TIME, BATCH and BEAM.

The TIME dimension is used to bundle vectors into sequences of vectors. The actual sequences can be shorter than the TIME dimension, therefore, additional information is needed about each sequence length and how unused (padding) vectors should be saved.

It is assumed that the sequence data container is fully packed. The TIME, BATCH and BEAM dimensions can be in any order when vectors are traversed in the ascending order of addresses. Six data layouts (permutation of TIME, BATCH and BEAM) are possible.

The cudnnSeqDataDescriptor_t object holds the following parameters:

- data type used by vectors
- TIME, BATCH, BEAM and VECT dimensions
- data layout
- the length of each sequence along the TIME dimension
- an optional value to be copied to output padding vectors

Use the cudnnCreateSeqDataDescriptor[] function to create one instance of the sequence data descriptor object and cudnnDestroySeqDataDescriptor[] to delete a previously created descriptor. Use the cudnnSetSeqDataDescriptor[] function to configure the descriptor.

This descriptor is used by multi-head attention API functions.

7.1.2. Enumeration Types

7.1.2.1. cudnnDirectionMode_t

cudnnDirectionMode_t is an enumerated type used to specify the recurrence pattern in the cudnnRNNForwardInference[], cudnnRNNForwardTraining[], cudnnRNNBackwardData[] and cudnnRNNBackwardWeights[] routines.

Values

CUDNN_UNIDIRECTIONAL
The network iterates recurrently from the first input to the last.
CUDNN_BIDIRECTIONAL
Each layer of the network iterates recurrently from the first input to the last and separately from the last input to the first. The outputs of the two are concatenated at each iteration giving the output of the layer.

7.1.2.2. cudnnForwardMode_t

cudnnForwardMode_t is an enumerated type to specify inference or training mode in RNN API. This parameter allows the cuDNN library to tune more precisely the size of the workspace buffer that could be different in inference and training regimens.

Values

CUDNN_FWD_MODE_INFERENCEm Selects the inference mode.

CUDNN_FWD_MODE_TRAININGSelects the training mode.

7.1.2.3. cudnnMultiHeadAttnWeightKind_t
cudnnMultiHeadAttnWeightKind_t is an enumerated type that specifies a group of weights or biases in the cudnnGetMultiHeadAttnWeights() function.

Values

CUDNN_MH_ATTN_Q_WEIGHTSSelects the input projection weights for queries.

CUDNN_MH_ATTN_K_WEIGHTSSelects the input projection weights for keys.

CUDNN_MH_ATTN_V_WEIGHTSSelects the input projection weights for values.

CUDNN_MH_ATTN_O_WEIGHTSSelects the output projection weights.

CUDNN_MH_ATTN_Q_BIASESSelects the input projection biases for queries.

CUDNN_MH_ATTN_K_BIASESSelects the input projection biases for keys.

CUDNN_MH_ATTN_V_BIASESSelects the input projection biases for values.
CUDNN_MH_ATTN_O_BIASES
   Selects the output projection biases.

7.1.2.4. **cudnnRNNBiasMode_t**

cudnnRNNBiasMode_t is an enumerated type used to specify the number of bias vectors for RNN functions. See the description of the cudnnRNNMode_t enumerated type for the equations for each cell type based on the bias mode.

**Values**

**CUDNN_RNN_NO_BIAS**
   Applies RNN cell formulas that do not use biases.

**CUDNN_RNN_SINGLE_INP_BIAS**
   Applies RNN cell formulas that use one input bias vector in the input GEMM.

**CUDNN_RNN_DOUBLE_BIAS**
   Applies RNN cell formulas that use two bias vectors.

**CUDNN_RNN_SINGLE_REC_BIAS**
   Applies RNN cell formulas that use one recurrent bias vector in the recurrent GEMM.

7.1.2.5. **cudnnRNNClipMode_t**

cudnnRNNClipMode_t is an enumerated type used to select the LSTM cell clipping mode. It is used with cudnnRNNSetClip(), cudnnRNNGetClip() functions, and internally within LSTM cells.

**Values**

**CUDNN_RNN_CLIP_NONE**
   Disables LSTM cell clipping.

**CUDNN_RNN_CLIP_MINMAX**
   Enables LSTM cell clipping.

7.1.2.6. **cudnnRNNDataLayout_t**

cudnnRNNDataLayout_t is an enumerated type used to select the RNN data layout. It is used in the API calls cudnnGetRNNDataDescriptor[] and cudnnSetRNNDataDescriptor[].

**Values**

**CUDNN_RNN_DATA_LAYOUT_SEQ_MAJOR_UNPACKED**
   Data layout is padded, with outer stride from one time-step to the next.
CUDNN_RNN_DATA_LAYOUT_SEQ_MAJOR_PACKED

The sequence length is sorted and packed as in the basic RNN API.

CUDNN_RNN_DATA_LAYOUT_BATCH_MAJOR_UNPACKED

Data layout is padded, with outer stride from one batch to the next.

7.1.2.7. cudnnRNNInputMode_t

cudnnRNNInputMode_t is an enumerated type used to specify the behavior of the first layer in the cudnnRNNForwardInference, cudnnRNNForwardTraining, cudnnRNNBackwardData and cudnnRNNBackwardWeights routines.

Values

CUDNN_LINEAR_INPUT

A biased matrix multiplication is performed at the input of the first recurrent layer.

CUDNN_SKIP_INPUT

No operation is performed at the input of the first recurrent layer. If CUDNN_SKIP_INPUT is used the leading dimension of the input tensor must be equal to the hidden state size of the network.

7.1.2.8. cudnnRNNMode_t

cudnnRNNMode_t is an enumerated type used to specify the type of network used in the cudnnRNNForwardInference, cudnnRNNForwardTraining, cudnnRNNBackwardData and cudnnRNNBackwardWeights routines.

Values

CUDNN_RNN_RELU

A single-gate recurrent neural network with a ReLU activation function.

In the forward pass, the output $h_t$ for a given iteration can be computed from the recurrent input $h_{t-1}$ and the previous layer input $x_t$, given the matrices $W$, $R$ and the bias vectors, where $ReLU(x) = \max(x, 0)$.

If cudnnRNNBiasMode_t biasMode in rnnDesc is CUDNN_RNN_DOUBLE_BIAS (default model), then the following equation with biases $b_W$ and $b_R$ applies:

$$h_t = ReLU(W_i x_t + R_i h_{t-1} + b_W + b_R)$$

If cudnnRNNBiasMode_t biasMode in rnnDesc is CUDNN_RNN_SINGLE_INP_BIAS or CUDNN_RNN_SINGLE_REC_BIAS, then the following equation with bias $b$ applies:

$$h_t = ReLU(W_i x_t + R_i h_{t-1} + b_i)$$

If cudnnRNNBiasMode_t biasMode in rnnDesc is CUDNN_RNN_NO_BIAS, then the following equation applies:

$$h_t = ReLU(W_i x_t + R_i h_{t-1})$$
**CUDNN_RNN_TANH**

A single-gate recurrent neural network with a \text{tanh} activation function.

In the forward pass, the output \( h_t \) for a given iteration can be computed from the recurrent input \( h_{t-1} \) and the previous layer input \( x_t \), given the matrices \( W, R \) and the bias vectors, and where \text{tanh} is the hyperbolic tangent function.

If `cudnnRNNBiasMode_t biasMode in rnnDesc` is `CUDNN_RNN_DOUBLE_BIAS` (default mode), then the following equation with biases \( b_W \) and \( b_R \) applies:

\[
h_t = \text{tanh}(W x_t + R h_{t-1} + b_W + b_R)
\]

If `cudnnRNNBiasMode_t biasMode in rnnDesc` is `CUDNN_RNN_SINGLE_INP_BIAS` or `CUDNN_RNN_SINGLE_REC_BIAS`, then the following equation with bias \( b \) applies:

\[
h_t = \text{tanh}(W x_t + R h_{t-1} + b)
\]

If `cudnnRNNBiasMode_t biasMode in rnnDesc` is `CUDNN_RNN_NO_BIAS`, then the following equation applies:

\[
h_t = \text{tanh}(W x_t + R h_{t-1})
\]

**CUDNN_LSTM**

A four-gate Long Short-Term Memory (LSTM) network with no peephole connections.

In the forward pass, the output \( h_t \) and cell output \( c_t \) for a given iteration can be computed from the recurrent input \( h_{t-1} \), the cell input \( c_{t-1} \) and the previous layer input \( x_t \), given the matrices \( W, R \) and the bias vectors.

In addition, the following applies:

- \( \sigma \) is the sigmoid operator such that: \( \sigma(x) = 1 / (1 + e^{-x}) \),
- \( \circ \) represents a point-wise multiplication,
- \( \text{tanh} \) is the hyperbolic tangent function, and
- \( i_t, f_t, o_t, c'_t \) represent the input, forget, output and new gates respectively.

If `cudnnRNNBiasMode_t biasMode in rnnDesc` is `CUDNN_RNN_DOUBLE_BIAS` (default mode), then the following equations with biases \( b_W \) and \( b_R \) apply:

\[
i_t = \sigma(W_i x_t + R_i h_{t-1} + b_Wi + b_Ri)
\]
\[
f_t = \sigma(W_f x_t + R_f h_{t-1} + b_Wf + b_Rf)
\]
\[
o_t = \sigma(W_o x_t + R_o h_{t-1} + b_Wo + b_Ro)
\]
\[
c'_t = \text{tanh}(W_c x_t + R_c h_{t-1} + b_Wc + b_Rc)
\]
\[
c_t = f_t \circ c_{t-1} + i_t \circ c'_t
\]
\[
h_t = o_t \circ \text{tanh}(c_t)
\]

If `cudnnRNNBiasMode_t biasMode in rnnDesc` is `CUDNN_RNN_SINGLE_INP_BIAS` or `CUDNN_RNN_SINGLE_REC_BIAS`, then the following equations with bias \( b \) apply:

\[
i_t = \sigma(W_i x_t + R_i h_{t-1} + b_i)
\]
\[
f_t = \sigma(W_f x_t + R_f h_{t-1} + b_f)
\]
\[
o_t = \sigma(W_o x_t + R_o h_{t-1} + b_o)
\]
\[
c'_t = \text{tanh}(W_c x_t + R_c h_{t-1} + b_c)
\]
\[
c_t = f_t \circ c_{t-1} + i_t \circ c'_t
\]
\[
h_t = o_t \circ \text{tanh}(c_t)
\]
If `cudnnRNNBiasMode_t biasMode in rnnDesc is CUDNN_RNN_NO_BIAS`, then the following equations apply:

\[
\begin{align*}
i_t &= \sigma(W_i x_t + R_i h_{t-1}) \\
r_t &= \sigma(W_r x_t + R_r h_{t-1}) \\
c_t &= \sigma(W_c x_t + R_c h_{t-1}) \\
c'_t &= \tanh(W_c x_t + R_c h_{t-1}) \\
c_t &= f_t \circ c_{t-1} + i_t \circ c'_t \\
h_t &= o_t \circ \tanh(c_t)
\end{align*}
\]

**CUDNN_GRU**

A three-gate network consisting of Gated Recurrent Units.

In the forward pass, the output \( h_t \) for a given iteration can be computed from the recurrent input \( h_{t-1} \) and the previous layer input \( x_t \) given matrices \( W, R \) and the bias vectors.

In addition, the following applies:

- \( \sigma \) is the sigmoid operator such that: \( \sigma(x) = 1 / (1 + e^{-x}) \),
- \( \circ \) represents a point-wise multiplication,
- \( \tanh \) is the hyperbolic tangent function, and
- \( i_t, r_t, h'_t \) represent the input, reset, new gates respectively.

If `cudnnRNNBiasMode_t biasMode in rnnDesc is CUDNN_RNN_DOUBLE_BIAS` (default model), then the following equations with biases \( b_W \) and \( b_R \) apply:

\[
\begin{align*}
i_t &= \sigma(W_i x_t + R_i h_{t-1} + b_{W_i} + b_{R_i}) \\
r_t &= \sigma(W_r x_t + R_r h_{t-1} + b_{W_r} + b_{R_r}) \\
h'_t &= \tanh(W_h x_t + r_t \circ (R_h h_{t-1} + b_{R_h}) + b_{W_h}) \\
h_t &= (1 - i_t) \circ h'_t + i_t \circ h_{t-1}
\end{align*}
\]

If `cudnnRNNBiasMode_t biasMode in rnnDesc is CUDNN_RNN_SINGLE_INP_BIAS`, then the following equations with bias \( b \) apply:

\[
\begin{align*}
i_t &= \sigma(W_i x_t + R_i h_{t-1} + b) \\
r_t &= \sigma(W_r x_t + R_r h_{t-1} + b) \\
h'_t &= \tanh(W_h x_t + r_t \circ (R_h h_{t-1}) + b_{R_h}) \\
h_t &= (1 - i_t) \circ h'_t + i_t \circ h_{t-1}
\end{align*}
\]

If `cudnnRNNBiasMode_t biasMode in rnnDesc is CUDNN_RNN_SINGLE_REC_BIAS`, then the following equations with bias \( b \) apply:

\[
\begin{align*}
i_t &= \sigma(W_i x_t + R_i h_{t-1} + b) \\
r_t &= \sigma(W_r x_t + R_r h_{t-1} + b) \\
h'_t &= \tanh(W_h x_t + r_t \circ (R_h h_{t-1} + b_{R_h})) \\
h_t &= (1 - i_t) \circ h'_t + i_t \circ h_{t-1}
\end{align*}
\]

If `cudnnRNNBiasMode_t biasMode in rnnDesc is CUDNN_RNN_NO_BIAS`, then the following equations apply:

\[
\begin{align*}
i_t &= \sigma(W_i x_t + R_i h_{t-1}) \\
r_t &= \sigma(W_r x_t + R_r h_{t-1}) \\
h'_t &= \tanh(W_h x_t + r_t \circ (R_h h_{t-1})) \\
h_t &= (1 - i_t) \circ h'_t + i_t \circ h_{t-1}
\end{align*}
\]

7.1.2.9. `cudnnRNNPaddingMode_t`

`cudnnRNNPaddingMode_t` is an enumerated type used to enable or disable the padded input/output.
Values

**CUDNN_RNN_PADDED_IO_DISABLED**

Disables the padded input/output.

**CUDNN_RNN_PADDED_IO_ENABLED**

Enables the padded input/output.

7.1.2.10. **cudnnSeqDataAxis_t**

cudnnSeqDataAxis_t is an enumerated type that indexes active dimensions in the dimA[] argument that is passed to the cudnnSetSeqDataDescriptor() function to configure the sequence data descriptor of type cudnnSeqDataDescriptor_t.

cudnnSeqDataAxis_t constants are also used in the axis[] argument of the cudnnSetSeqDataDescriptor() call to define the layout of the sequence data buffer in memory.

See cudnnSetSeqDataDescriptor() for a detailed description on how to use the cudnnSeqDataAxis_t enumerated type.

The CUDNN_SEQDATA_DIM_COUNT macro defines the number of constants in the cudnnSeqDataAxis_t enumerated type. This value is currently set to 4.

Values

**CUDNN_SEQDATA_TIME_DIM**

Identifies the TIME [sequence length] dimension or specifies the TIME in the data layout.

**CUDNN_SEQDATA_BATCH_DIM**

Identifies the BATCH dimension or specifies the BATCH in the data layout.

**CUDNN_SEQDATA_BEAM_DIM**

Identifies the BEAM dimension or specifies the BEAM in the data layout.

**CUDNN_SEQDATA_VECT_DIM**

Identifies the VECT [vector] dimension or specifies the VECT in the data layout.

7.2. **API Functions**

7.2.1. **cudnnAdvInferVersionCheck()**

cudnnStatus_t cudnnAdvInferVersionCheck(void)

This function checks to see whether the version of the AdvInfer subset of the library is consistent with the other sub-libraries.
Returns

**CUDNN_STATUS_SUCCESS**

The version is consistent with other sub-libraries.

**CUDNN_STATUS_VERSION_MISMATCH**

The version of AdvInfer is not consistent with other sub-libraries. Users should check the installation and make sure all sub-component versions are consistent.

### 7.2.2. cudnnBuildRNNDynamic()

cudnnStatus_t cudnnBuildRNNDynamic(
  cudnnHandle_t handle,
  cudnnRNNDescriptor_t rnnDesc,
  int32_t miniBatch);

This function compiles the RNN persistent code using CUDA runtime compilation library (NVRTC) when the **CUDNN_RNN_ALGO_PERSIST_DYNAMIC** algo is selected. The code is tailored to the current GPU and specific hyperparameters (miniBatch). This call is expected to be expensive in terms of runtime and should be invoked infrequently. Note that the **CUDNN_RNN_ALGO_PERSIST_DYNAMIC** algo does not support variable length sequences within the batch.

Parameters

**handle**

*Input*. Handle to a previously created cuDNN context.

**rnnDesc**

*Input*. A previously initialized RNN descriptor.

**miniBatch**

*Input*. The exact number of sequences in a batch.

Returns

**CUDNN_STATUS_SUCCESS**

The code was built and linked successfully.

**CUDNN_STATUS_ALLOC_FAILED**

The resources could not be allocated.

**CUDNN_STATUS_RUNTIME_PREREQUISITE_MISSING**

The prerequisite runtime library could not be found.

**CUDNN_STATUS_NOT_SUPPORTED**

The current hyperparameters are invalid.
7.2.3. **cudnnCreateAttnDescriptor()**

```c

cudnnStatus_t cudnnCreateAttnDescriptor(cudnnAttnDescriptor_t *attnDesc);
```

This function creates one instance of an opaque attention descriptor object by allocating the host memory for it and initializing all descriptor fields. The function writes NULL to `attnDesc` when the attention descriptor object cannot be allocated.

Use the `cudnnSetAttnDescriptor()` function to configure the attention descriptor and `cudnnDestroyAttnDescriptor()` to destroy it and release the allocated memory.

**Parameters**

`attnDesc`

Output. Pointer where the address to the newly created attention descriptor should be written.

**Returns**

- **CUDNN_STATUS_SUCCESS**
  - The descriptor object was created successfully.
- **CUDNN_STATUS_BAD_PARAM**
  - An invalid input argument was encountered (`attnDesc=NULL`).
- **CUDNN_STATUS_ALLOC_FAILED**
  - The memory allocation failed.

7.2.4. **cudnnCreatePersistentRNNPlan()**

This function has been deprecated in cuDNN 8.0. Use `cudnnBuildRNNDynamic()` instead of `cudnnCreatePersistentRNNPlan()`.

```c

cudnnStatus_t cudnnCreatePersistentRNNPlan(
  cudnnRNNDescriptor_t        rnnDesc,
  const int                   minibatch,
  const cudnnDataType_t       dataType,
  cudnnPersistentRNNPlan_t   *plan)
```

This function creates a plan to execute persistent RNNs when using the CUDNN_RNN_ALGO_PERSIST_DYNAMIC algo. This plan is tailored to the current GPU and problem hyperparameters. This function call is expected to be expensive in terms of runtime and should be used infrequently. For more information, see `cudnnRNNDescriptor_t`, `cudnnDataType_t`, and `cudnnPersistentRNNPlan_t`.

**Returns**

- **CUDNN_STATUS_SUCCESS**
  - The object was created successfully.
- **CUDNN_STATUS_ALLOC_FAILED**
  - The resources could not be allocated.
CUDNN_STATUS_RUNTIME_PREREQUISITE_MISSING

A prerequisite runtime library cannot be found.

CUDNN_STATUS_NOT_SUPPORTED

The current hyperparameters are invalid.

7.2.5. cudnnCreateRNNDataDescriptor()

cudnnStatus_t cudnnCreateRNNDataDescriptor(
    cudnnRNNDataDescriptor_t *RNNDataDesc)

This function creates a RNN data descriptor object by allocating the memory needed to hold its opaque structure.

Returns

CUDNN_STATUS_SUCCESS

The RNN data descriptor object was created successfully.

CUDNN_STATUS_BAD_PARAM

RNNDataDesc is NULL.

CUDNN_STATUS_ALLOC_FAILED

The resources could not be allocated.

7.2.6. cudnnCreateRNNDescriptor()

cudnnStatus_t cudnnCreateRNNDescriptor(
    cudnnRNNDescriptor_t *rnnDesc)

This function creates a generic RNN descriptor object by allocating the memory needed to hold its opaque structure.

Returns

CUDNN_STATUS_SUCCESS

The object was created successfully.

CUDNN_STATUS_ALLOC_FAILED

The resources could not be allocated.

7.2.7. cudnnCreateSeqDataDescriptor()

cudnnStatus_t cudnnCreateSeqDataDescriptor(cudnnSeqDataDescriptor_t *seqDataDesc);

This function creates one instance of an opaque sequence data descriptor object by allocating the host memory for it and initializing all descriptor fields. The function writes NULL to seqDataDesc when the sequence data descriptor object cannot be allocated.
Use the `cudnnSetSeqDataDescriptor()` function to configure the sequence data descriptor and `cudnnDestroySeqDataDescriptor()` to destroy it and release the allocated memory.

**Parameters**

`seqDataDesc`

*Output.* Pointer where the address to the newly created sequence data descriptor should be written.

**Returns**

**CUDNN_STATUS_SUCCESS**

The descriptor object was created successfully.

**CUDNN_STATUS_BAD_PARAM**

An invalid input argument was encountered (`seqDataDesc=NULL`).

**CUDNN_STATUS_ALLOC_FAILED**

The memory allocation failed.

### 7.2.8. `cudnnDestroyAttnDescriptor()`

```c
cudnnStatus_t cudnnDestroyAttnDescriptor(cudnnAttnDescriptor_t attnDesc);
```

This function destroys the attention descriptor object and releases its memory. The `attnDesc` argument can be NULL. Invoking `cudnnDestroyAttnDescriptor()` with a NULL argument is a no operation (NOP).

The `cudnnDestroyAttnDescriptor()` function is not able to detect if the `attnDesc` argument holds a valid address. Undefined behavior will occur in case of passing an invalid pointer, not returned by the `cudnnCreateAttnDescriptor()` function, or in the double deletion scenario of a valid address.

**Parameters**

`attnDesc`

*Input.* Pointer to the attention descriptor object to be destroyed.

**Returns**

**CUDNN_STATUS_SUCCESS**

The descriptor was destroyed successfully.

### 7.2.9. `cudnnDestroyPersistentRNNPlan()`

This function has been deprecated in cuDNN 8.0.

```c
cudnnStatus_t cudnnDestroyPersistentRNNPlan(cudnnPersistentRNNPlan_t plan)
```

This function destroys a previously created persistent RNN plan object.
Returns

**CUDNN_STATUS_SUCCESS**

The object was destroyed successfully.

### 7.2.10. **cudnnDestroyRNNDataDescriptor()**

```c
#include <cuda.h>
cudnnStatus_t cudnnDestroyRNNDataDescriptor( 
cudnnRNNDataDescriptor_t RNNDataDesc)
```

This function destroys a previously created RNN data descriptor object.

Returns

**CUDNN_STATUS_SUCCESS**

The RNN data descriptor object was destroyed successfully.

### 7.2.11. **cudnnDestroyRNNDescriptor()**

```c
#include <cuda.h>
cudnnStatus_t cudnnDestroyRNNDescriptor( 
cudnnRNNDescriptor_t rnnDesc)
```

This function destroys a previously created RNN descriptor object.

Returns

**CUDNN_STATUS_SUCCESS**

The object was destroyed successfully.

### 7.2.12. **cudnnDestroySeqDataDescriptor()**

```c
#include <cuda.h>
cudnnStatus_t cudnnDestroySeqDataDescriptor(cudnnSeqDataDescriptor_t seqDataDesc);
```

This function destroys the sequence data descriptor object and releases its memory. The `seqDataDesc` argument can be NULL. Invoking `cudnnDestroySeqDataDescriptor()` with a NULL argument is a no operation (NOP).

The `cudnnDestroySeqDataDescriptor()` function is not able to detect if the `seqDataDesc` argument holds a valid address. Undefined behavior will occur in case of passing an invalid pointer, not returned by the `cudnnCreateSeqDataDescriptor()` function, or in the double deletion scenario of a valid address.

Parameters

- `seqDataDesc`
  
  *Input.* Pointer to the sequence data descriptor object to be destroyed.
Returns

**CUDNN_STATUS_SUCCESS**

The descriptor was destroyed successfully.

### 7.2.13. **cudnnFindRNNForwardInferenceAlgorithmEx()**

This function has been deprecated in cuDNN 8.0.

```c
extern "C" {
    cudnnStatus_t cudnnFindRNNForwardInferenceAlgorithmEx(
        cudnnHandle_t handle,
        const cudnnRNNDescriptor_t rnnDesc,
        const int seqLength,
        const cudnnTensorDescriptor_t *xDesc,
        const void *x,
        const cudnnTensorDescriptor_t *hxDesc,
        const void *hx,
        const cudnnTensorDescriptor_t *cxDesc,
        const void *cx,
        const cudnnFilterDescriptor_t *wDesc,
        const void *w,
        const cudnnTensorDescriptor_t *yDesc,
        void *y,
        const cudnnTensorDescriptor_t *hyDesc,
        void *hy,
        const cudnnTensorDescriptor_t *cyDesc,
        void *cy,
        const float findIntensity,
        const int requestedAlgoCount,
        int *returnedAlgoCount,
        cudnnAlgorithmPerformance_t *perfResults,
        void *workspace,
        size_t workspaceSizeInBytes)
}
```

This function attempts all available cuDNN algorithms for **cudnnRNNForwardInference**(), using user-allocated GPU memory. It outputs the parameters that influence the performance of the algorithm to a user-allocated array of **cudnnAlgorithmPerformance_t**. These parameter metrics are written in sorted fashion where the first element has the lowest compute time.

**Parameters**

**handle**

*Input*. Handle to a previously created cuDNN context.

**rnnDesc**

*Input*. A previously initialized RNN descriptor.

**seqLength**

*Input*. Number of iterations to unroll over. The value of this **seqLength** must not exceed the value that was used in **cudnnGetRNNWorkspaceSize()** function for querying the workspace size required to execute the RNN.
**xDesc**

*Input.* An array of fully packed tensor descriptors describing the input to each recurrent iteration (one descriptor per iteration). The first dimension (batch size) of the tensors may decrease from element $n$ to element $n+1$ but may not increase. Each tensor descriptor must have the same second dimension (vector length).

**x**

*Input.* Data pointer to GPU memory associated with the tensor descriptors in the array xDesc. The data are expected to be packed contiguously with the first element of iteration $n+1$ following directly from the last element of iteration $n$.

**hxDesc**

*Input.* A fully packed tensor descriptor describing the initial hidden state of the RNN. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is CUDNN_UNIDIRECTIONAL the first dimension should match the `numLayers` argument.
- If `direction` is CUDNN_BIDIRECTIONAL the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in xDesc. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.

**hx**

*Input.* Data pointer to GPU memory associated with the tensor descriptor hxDesc. If a NULL pointer is passed, the initial hidden state of the network will be initialized to zero.

**cxDesc**

*Input.* A fully packed tensor descriptor describing the initial cell state for LSTM networks. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is CUDNN_UNIDIRECTIONAL the first dimension should match the `numLayers` argument.
- If `direction` is CUDNN_BIDIRECTIONAL the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in xDesc. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.

**cx**

*Input.* Data pointer to GPU memory associated with the tensor descriptor cxDesc. If a NULL pointer is passed, the initial cell state of the network will be initialized to zero.
**wDesc**

*Input*. Handle to a previously initialized filter descriptor describing the weights for the RNN.

**w**

*Input*. Data pointer to GPU memory associated with the filter descriptor wDesc.

**yDesc**

*Input*. An array of fully packed tensor descriptors describing the output from each recurrent iteration (one descriptor per iteration). The second dimension of the tensor depends on the direction argument used to initialize rnnDesc:

- If direction is CUDNN_UNIDIRECTIONAL the second dimension should match the hiddenSize argument.
- If direction is CUDNN_BIDIRECTIONAL the second dimension should match double the hiddenSize argument.

The first dimension of the tensor n must match the first dimension of the tensor n in xDesc.

**y**

*Output*. Data pointer to GPU memory associated with the output tensor descriptor yDesc. The data are expected to be packed contiguously with the first element of iteration n+1 following directly from the last element of iteration n.

**hyDesc**

*Input*. A fully packed tensor descriptor describing the final hidden state of the RNN. The first dimension of the tensor depends on the direction argument used to initialize rnnDesc:

- If direction is CUDNN_UNIDIRECTIONAL the first dimension should match the numLayers argument.
- If direction is CUDNN_BIDIRECTIONAL the first dimension should match double the numLayers argument.

The second dimension must match the first dimension of the tensors described in xDesc. The third dimension must match the hiddenSize argument used to initialize rnnDesc. The tensor must be fully packed.

**hy**

*Output*. Data pointer to GPU memory associated with the tensor descriptor hyDesc. If a NULL pointer is passed, the final hidden state of the network will not be saved.

**cyDesc**

*Input*. A fully packed tensor descriptor describing the final cell state for LSTM networks. The first dimension of the tensor depends on the direction argument used to initialize rnnDesc:

- If direction is CUDNN_UNIDIRECTIONAL the first dimension should match the numLayers argument.
If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `xDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.

`cy`

*Output*. Data pointer to GPU memory associated with the tensor descriptor `cyDesc`. If a `NULL` pointer is passed, the final cell state of the network will not be saved.

**findIntensity**

*Input*. This input was previously unused in versions prior to 7.2.0. It is used in cuDNN 7.2.0 and later versions to control the overall runtime of the RNN find algorithms, by selecting the percentage of a large Cartesian product space to be searched.

- Setting `findIntensity` within the range `[0,1.]` will set a percentage of the entire RNN search space to search. When `findIntensity` is set to 1.0, a full search is performed over all RNN parameters.
- When `findIntensity` is set to 0.0f, a quick, minimal search is performed. This setting has the best runtime. However, in this case the parameters returned by this function will not correspond to the best performance of the algorithm; a longer search might discover better parameters. This option will execute up to three instances of the configured RNN problem. Runtime will vary proportionally to RNN problem size, as it will in the other cases, hence no guarantee of an explicit time bound can be given.
- Setting `findIntensity` within the range `[-1.,0)` sets a percentage of a reduced Cartesian product space to be searched. This reduced search space has been heuristically selected to have good performance. The setting of -1.0 represents a full search over this reduced search space.
- Values outside the range `[-1,1]` are truncated to the range `[-1,1]`, and then interpreted as per the above.
- Setting `findIntensity` to 1.0 in cuDNN 7.2 and later versions is equivalent to the behavior of this function in versions prior to cuDNN 7.2.0.
- This function times the single RNN executions over large parameter spaces - one execution per parameter combination. The times returned by this function are latencies.

**requestedAlgoCount**

*Input*. The maximum number of elements to be stored in `perfResults`.

**returnedAlgoCount**

*Output*. The number of output elements stored in `perfResults`.

**perfResults**

*Output*. A user-allocated array to store performance metrics sorted ascending by compute time.
workspace

*Input.* Data pointer to GPU memory to be used as a workspace for this call.

workSpaceSizeInBytes

*Input.* Specifies the size in bytes of the provided workspace.

**Returns**

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The descriptor `rnnDesc` is invalid.
- At least one of the descriptors `hxDesc`, `cxDesc`, `wDesc`, `hyDesc`, `cyDesc` or one of the descriptors in `xDesc`, `yDesc` is invalid.
- The descriptors in one of `xDesc`, `hxDesc`, `cxDesc`, `wDesc`, `yDesc`, `hyDesc`, `cyDesc` have incorrect strides or dimensions.
- `workSpaceSizeInBytes` is too small.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

**CUDNN_STATUS_ALLOC_FAILED**

The function was unable to allocate memory.

### 7.2.14. `cudnnGetAttnDescriptor()`

cudnnStatus_t cudnnGetAttnDescriptor(
    cudnnAttnDescriptor_t attnDesc,
    unsigned *attnMode,
    int *nHeads,
    double *smScaler,
    cudnnDataType_t *dataType,
    cudnnDataType_t *computePrec,
    cudnnMathType_t *mathType,
    cudnnDropoutDescriptor_t *attnDropoutDesc,
    cudnnDropoutDescriptor_t *postDropoutDesc,
    int *qSize,
    int *kSize,
    int *vSize,
    int *qProjSize,
    int *kProjSize,
    int *vProjSize,
    int *oProjSize,
    int *qMaxSeqLength,
    int *kMaxSeqLength,
    int *maxBatchSize,
    int *maxBeamSize);
This function retrieves settings from the previously created attention descriptor. The user can assign NULL to any pointer except `attnDesc` when the retrieved value is not needed.

**Parameters**

- **attnDesc**
  - Input. Attention descriptor.
- **attnMode**
  - Output. Pointer to the storage for binary attention flags.
- **nHeads**
  - Output. Pointer to the storage for the number of attention heads.
- **smScaler**
  - Output. Pointer to the storage for the softmax smoothing/sharpening coefficient.
- **dataType**
  - Output. Data type for attention weights, sequence data inputs, and outputs.
- **computePrec**
  - Output. Pointer to the storage for the compute precision.
- **mathType**
  - Output. NVIDIA Tensor Core settings.
- **attnDropoutDesc**
  - Output. Descriptor of the dropout operation applied to the softmax output.
- **postDropoutDesc**
  - Output. Descriptor of the dropout operation applied to the multi-head attention output.
- **qSize, kSize, vSize**
  - Output. Q, K, and V embedding vector lengths.
- **qProjSize, kProjSize, vProjSize**
- **oProjSize**
  - Output. Pointer to store the output vector length after projection.
- **qoMaxSeqLength**
  - Output. Largest sequence length expected in sequence data descriptors related to Q, O, dQ, dO inputs and outputs.
- **kvMaxSeqLength**
  - Output. Largest sequence length expected in sequence data descriptors related to K, V, dK, dV inputs and outputs.
- **maxBatchSize**
  - Output. Largest batch size expected in the `cudnnSeqDataDescriptor_t` container.
- **maxBeamSize**
  - Output. Largest beam size expected in the `cudnnSeqDataDescriptor_t` container.

**Returns**

**CUDNN_STATUS_SUCCESS**
- Requested attention descriptor fields were retrieved successfully.
CUDNN_STATUS_BAD_PARAM
An invalid input argument was found.

7.2.15. cudnnGetMultiHeadAttnBuffers()

cudnnStatus_t cudnnGetMultiHeadAttnBuffers(
    cudnnHandle_t handle,
    const cudnnAttnDescriptor_t attnDesc,
    size_t *weightSizeInBytes,
    size_t *workSpaceSizeInBytes,
    size_t *reserveSpaceSizeInBytes);

This function computes weight, work, and reserve space buffer sizes used by the following functions:

- cudnnMultiHeadAttnForward()
- cudnnMultiHeadAttnBackwardData()
- cudnnMultiHeadAttnBackwardWeights()

Assigning NULL to the reserveSpaceSizeInBytes argument indicates that the user does not plan to invoke multi-head attention gradient functions: cudnnMultiHeadAttnBackwardData() and cudnnMultiHeadAttnBackwardWeights(). This situation occurs in the inference mode.

Note: NULL cannot be assigned to weightSizeInBytes and workSpaceSizeInBytes pointers.

The user must allocate weight, work, and reserve space buffer sizes in the GPU memory using cudaMalloc() with the reported buffer sizes. The buffers can be also carved out from a larger chunk of allocated memory but the buffer addresses must be at least 16B aligned.

The work-space buffer is used for temporary storage. Its content can be discarded or modified after all GPU kernels launched by the corresponding API complete. The reserve-space buffer is used to transfer intermediate results from cudnnMultiHeadAttnForward() to cudnnMultiHeadAttnBackwardData(), and from cudnnMultiHeadAttnBackwardData() to cudnnMultiHeadAttnBackwardWeights(). The content of the reserve-space buffer cannot be modified until all GPU kernels launched by the above three multi-head attention API functions finish.

All multi-head attention weight and bias tensors are stored in a single weight buffer. For speed optimizations, the cuDNN API may change tensor layouts and their relative locations in the weight buffer based on the provided attention parameters. Use the cudnnGetMultiHeadAttnWeights() function to obtain the start address and the shape of each weight or bias tensor.

Parameters

handle

*Input*. The current cuDNN context handle.

attnDesc

*Input*. Pointer to a previously initialized attention descriptor.
weightSizeInBytes

*Output.* Minimum buffer size required to store all multi-head attention trainable parameters.

workSpaceSizeInBytes

*Output.* Minimum buffer size required to hold all temporary surfaces used by the forward and gradient multi-head attention API calls.

reserveSpaceSizeInBytes

*Output.* Minimum buffer size required to store all intermediate data exchanged between forward and backward (gradient) multi-head attention functions. Set this parameter to NULL in the inference mode indicating that gradient API calls will not be invoked.

Returns

**CUDNN_STATUS_SUCCESS**

The requested buffer sizes were computed successfully.

**CUDNN_STATUS_BAD_PARAM**

An invalid input argument was found.

### 7.2.16. `cudnnGetMultiHeadAttnWeights()`

cudnnStatus_t cudnnGetMultiHeadAttnWeights(
    cudnnHandle_t handle,
    const cudnnAttnDescriptor_t attnDesc,
    cudnnMultiHeadAttnWeightKind_t wKind,
    size_t weightSizeInBytes,
    const void *weights,
    cudnnTensorDescriptor_t wDesc,
    void **wAddr);

This function obtains the shape of the weight or bias tensor. It also retrieves the start address of tensor data located in the weight buffer. Use the `wKind` argument to select a particular tensor. For more information, see `cudnnMultiHeadAttnWeightKind_t` for the description of the enumerator type.

Biases are used in the input and output projections when the `CUDNN_ATTN_ENABLE_PROJ_BIASES` flag is set in the attention descriptor. See `cudnnSetAttnDescriptor()` for the description of flags to control projection biases.

When the corresponding weight or bias tensor does not exist, the function writes NULL to the storage location pointed by `wAddr` and returns zeros in the `wDesc` tensor descriptor. The return status of the `cudnnGetMultiHeadAttnWeights()` function is `CUDNN_STATUS_SUCCESS` in this case.

The cuDNN `multiHeadAttention` sample code demonstrates how to access multi-head attention weights. Although the buffer with weights and biases should be allocated in the GPU memory, the user can copy it to the host memory and invoke the `cudnnGetMultiHeadAttnWeights()` function with the host weights address to obtain tensor pointers in the host memory. This scheme allows the user to inspect trainable parameters directly in the CPU memory.
Parameters

handle

*Input.* The current cuDNN context handle.

attnDesc

*Input.* A previously configured attention descriptor.

wKind

*Input.* Enumerant type to specify which weight or bias tensor should be retrieved.

weightSizeInBytes

*Input.* Buffer size that stores all multi-head attention weights and biases.

weights

*Input.* Pointer to the weight buffer in the host or device memory.

wDesc

*Output.* The descriptor specifying weight or bias tensor shape. For weights, the wDesc.dimA[] array has three elements: [nHeads, projected size, original size]. For biases, the wDesc.dimA[] array also has three elements: [nHeads, projected size, 1]. The wDesc.strideA[] array describes how tensor elements are arranged in memory.

wAddr

*Output.* Pointer to a location where the start address of the requested tensor should be written. When the corresponding projection is disabled, the address written to wAddr is NULL.

Returns

**CUDNN_STATUS_SUCCESS**

The weight tensor descriptor and the address of data in the device memory were successfully retrieved.

**CUDNN_STATUS_BAD_PARAM**

An invalid or incompatible input argument was encountered. For example, wKind did not have a valid value or weightSizeInBytes was too small.

7.2.17. `cudnnGetRNNBackwardDataAlgorithmMaxCount()`

This function has been deprecated in cuDNN 8.0.

7.2.18. `cudnnGetRNNBiasMode()`
This function has been deprecated in cuDNN 8.0. Use `cudnnGetRNNDescriptor_v8()` instead of `cudnnGetRNNBiasMode()`.

```c
int cudnnGetRNNBiasMode(
    cudnnRNNDescriptor_t   rnnDesc,
    cudnnRNNBiasMode_t* biasMode)
```

This function retrieves the RNN bias mode that was configured by `cudnnSetRNNBiasMode()`. The default value of `biasMode` in `rnnDesc` after `cudnnCreateRNNDescriptor()` is `CUDNN_RNN_DOUBLE_BIAS`.

**Parameters**

- **rnnDesc**
  - *Input*. A previously created RNN descriptor.

- ***biasMode**
  - *Output*. Pointer to where RNN bias mode should be saved.

**Returns**

- **CUDNN_STATUS_BAD_PARAM**
  - Either the `rnnDesc` or `*biasMode` is NULL.

- **CUDNN_STATUS_SUCCESS**
  - The `biasMode` parameter was retrieved successfully.

### 7.2.19. `cudnnGetRNNDataDescriptor()`

```c
int cudnnGetRNNDataDescriptor(
    cudnnRNNDataDescriptor_t RNNDataDesc,
    cudnnDataType_t* dataType,
    cudnnRNNDataLayout_t* layout,
    int* maxSeqLength,
    int* batchSize,
    int* vectorSize,
    int arrayLengthRequested,
    int* seqLengthArray[],
    void* paddingFill);
```

This function retrieves a previously created RNN data descriptor object.

**Parameters**

- **RNNDataDesc**
  - *Input*. A previously created and initialized RNN descriptor.

- **dataType**
  - *Output*. Pointer to the host memory location to store the datatype of the RNN data tensor.
**layout**

*Output.* Pointer to the host memory location to store the memory layout of the RNN data tensor.

**maxSeqLength**

*Output.* The maximum sequence length within this RNN data tensor, including the padding vectors.

**batchSize**

*Output.* The number of sequences within the mini-batch.

**vectorSize**

*Output.* The vector length (meaning, embedding size) of the input or output tensor at each time-step.

**arrayLengthRequested**

*Input.* The number of elements that the user requested for `seqLengthArray`.

**seqLengthArray**

*Output.* Pointer to the host memory location to store the integer array describing the length (meaning, number of time-steps) of each sequence. This is allowed to be a NULL pointer if `arrayLengthRequested` is 0.

**paddingFill**

*Output.* Pointer to the host memory location to store the user defined symbol. The symbol should be interpreted as the same data type as the RNN data tensor.

**Returns**

**CUDNN_STATUS_SUCCESS**

The parameters are fetched successfully.

**CUDNN_STATUS_BAD_PARAM**

Any one of these have occurred:

- Any of `RNNDataDesc`, `dataType`, `layout`, `maxSeqLength`, `batchSize`, `vectorSize`, `paddingFill` is NULL.
- `seqLengthArray` is NULL while `arrayLengthRequested` is greater than zero.
- `arrayLengthRequested` is less than zero.

### 7.2.20. cudnnGetRNNDescriptor_v6()

This function has been deprecated in cuDNN 8.0. Use `cudnnGetRNNDescriptor_v8()` instead of `cudnnGetRNNDescriptor_v6()`.

```c

cudnnStatus_t cudnnGetRNNDescriptor_v6(
    cudnnHandle_t handle,
    cudnnRNNDescriptor_t rnnDesc,
    int *hiddenSize,
)
```
This function retrieves RNN network parameters that were configured by `cudnnSetRNNDescriptor_v6()`. All pointers passed to the function should be not-NULL or `CUDNN_STATUS_BAD_PARAM` is reported. The function does not check the validity of retrieved parameters.

**Parameters**

- **handle**
  - *Input*. Handle to a previously created cuDNN library descriptor.

- **rnnDesc**
  - *Input*. A previously created and initialized RNN descriptor.

- **hiddenSize**
  - *Output*. Pointer to where the size of the hidden state should be stored (the same value is used in every RNN layer).

- **numLayers**
  - *Output*. Pointer to where the number of RNN layers should be stored.

- **dropoutDesc**
  - *Output*. Pointer to where the handle to a previously configured dropout descriptor should be stored.

- **inputMode**
  - *Output*. Pointer to where RNN uni-directional/bi-directional mode should be saved.

- **direction**
  - *Output*. Pointer to where RNN uni-directional/bi-directional mode should be saved.

- **mode**
  - *Output*. Pointer to where RNN cell type should be saved.

- **algo**
  - *Output*. Pointer to where RNN algorithm type should be stored.

- **mathPrec**
  - *Output*. Pointer to where the math precision type should be stored.

**Returns**

- `CUDNN_STATUS_SUCCESS`
  - RNN parameters were successfully retrieved from the RNN descriptor.
At least one pointer passed to the function is NULL.

7.2.21. **cudnnGetRNNDescriptor_v8()**

```c
void cudnnGetRNNDescriptor_v8(cudnnRNNDescriptor_t rnnDesc,
   cudnnRNNAlgo_t *algo,
   cudnnRNNMode_t *cellMode,
   cudnnRNNBiasMode_t *biasMode,
   cudnnDirectionMode_t *dirMode,
   cudnnRNNInputMode_t *inputMode,
   cudnnDataType_t *dataType,
   cudnnDataType_t *mathPrec,
   cudnnMathType_t *mathType,
   cudnnMathType_t *auxFlags,
   int32_t *inputSize,
   int32_t *hiddenSize,
   int32_t *projSize,
   int32_t *numLayers,
   cudnnDropoutDescriptor_t *dropoutDesc,
   uint32_t *auxFlags);
```

This function retrieves RNN network parameters that were configured by `cudnnSetRNNDescriptor_v8()`. The user can assign `NULL` to any pointer except `rnnDesc` when the retrieved value is not needed. The function does not check the validity of retrieved parameters.

**Parameters**

**rnnDesc**

*Input.* A previously created and initialized RNN descriptor.

**algo**

*Output.* Pointer to where RNN algorithm type should be stored.

**cellMode**

*Output.* Pointer to where RNN cell type should be saved.

**biasMode**

*Output.* Pointer to where RNN bias mode `cudnnRNNBiasMode_t` should be saved.

**dirMode**

*Output.* Pointer to where RNN uni-directional/bi-directional mode should be saved.

**inputMode**

*Output.* Pointer to where the mode of the first RNN layer should be saved.

**dataType**

*Output.* Pointer to where the data type of RNN weights/biases should be stored.

**mathPrec**

*Output.* Pointer to where the math precision type should be stored.
mathType

*Output.* Pointer to where the preferred option for Tensor Cores are saved.

inputSize

*Output.* Pointer to where the RNN input vector size is stored.

hiddenSize

*Output.* Pointer to where the size of the hidden state should be stored [the same value is used in every RNN layer].

projSize

*Output.* Pointer to where the LSTM cell output size after the recurrent projection is stored.

numLayers

*Output.* Pointer to where the number of RNN layers should be stored.

dropoutDesc

*Output.* Pointer to where the handle to a previously configured dropout descriptor should be stored.

auxFlags

*Output.* Pointer to miscellaneous RNN options [flags] that do not require passing additional numerical values to configure.

Returns

**CUDNN_STATUS_SUCCESS**

RNN parameters were successfully retrieved from the RNN descriptor.

**CUDNN_STATUS_BAD_PARAM**

An invalid input argument was found (rnnDesc was NULL).

**CUDNN_STATUS_NOT_INITIALIZED**

The RNN descriptor was configured with the legacy cudnnSetRNNDescriptor_v6() call.

7.2.22. **cudnnGetRNNForwardInferenceAlgorithmMaxCount()**

This function has been deprecated in cuDNN 8.0.

7.2.23. **cudnnGetRNNForwardTrainingAlgorithmMaxCount()**

This function has been deprecated in cuDNN 8.0.

7.2.24. **cudnnGetRNNLinLayerBiasParams()**

This function has been deprecated in cuDNN 8.0. Use **cudnnGetRNNWeightParams()** instead of cudnnGetRNNLinLayerBiasParams().

```cudnnStatus_t cudnnGetRNNLinLayerBiasParams()```
This function is used to obtain a pointer and a descriptor of every RNN bias column vector in each pseudo-layer within the recurrent network defined by \texttt{rnnDesc} and its input width specified in \texttt{xDesc}.

\textbf{Note:} The \texttt{cudnnGetRNNLinLayerBiasParams()} function was changed in cuDNN version 7.1.1 to match the behavior of \texttt{cudnnGetRNNLinLayerMatrixParams()}.

The \texttt{cudnnGetRNNLinLayerBiasParams()} function returns the RNN bias vector size in two dimensions: rows and columns.

Due to historical reasons, the minimum number of dimensions in the filter descriptor is three. In previous versions of the cuDNN library, the function returns the total number of vector elements in \texttt{linLayerBiasDesc} as follows:

\begin{verbatim}
filterDimA[0]=total_size,
filterDimA[1]=1,
\end{verbatim}

For more information, see the description of the \texttt{cudnnGetFilterNdDescriptor()} function.

In cuDNN 7.1.1, the format was changed to:

\begin{verbatim}
filterDimA[0]=1,
filterDimA[1]=rows,
\end{verbatim}

In both cases, the format field of the filter descriptor should be ignored when retrieved by \texttt{cudnnGetFilterNdDescriptor()}.

The RNN implementation in cuDNN uses two bias vectors before the cell non-linear function. Note that the RNN implementation in cuDNN depends on the number of bias vectors before the cell non-linear function. Refer to the equations in the \texttt{cudnnRNNMode_t} description, for the enumerant type based on the value of \texttt{cudnnRNNBiasMode_t biasMode} in \texttt{rnnDesc}. If nonexistent biases are referenced by \texttt{linLayerID}, then this function sets \texttt{linLayerBiasDesc} to a zeroed filter descriptor where:

\begin{verbatim}
filterDimA[0]=0,
filterDimA[1]=0, and
\end{verbatim}

and sets \texttt{linLayerBias} to NULL. Refer to the details for the function parameter \texttt{linLayerID} to determine the relevant values of \texttt{linLayerID} based on \texttt{biasMode}.

\section*{Parameters}

\textbf{handle}

\textit{Input}. Handle to a previously created cuDNN library descriptor.

\textbf{rnnDesc}

\textit{Input}. A previously initialized RNN descriptor.
**pseudoLayer**

*Input.* The pseudo-layer to query. In uni-directional RNNs, a pseudo-layer is the same as a physical layer (*pseudoLayer*=0 is the RNN input layer, *pseudoLayer*=1 is the first hidden layer). In bi-directional RNNs, there are twice as many pseudo-layers in comparison to physical layers.

- *pseudoLayer*=0 refers to the forward part of the physical input layer
- *pseudoLayer*=1 refers to the backward part of the physical input layer
- *pseudoLayer*=2 is the forward part of the first hidden layer, and so on

**xDesc**

*Input.* A fully packed tensor descriptor describing the input to one recurrent iteration (to retrieve the RNN input width).

**wDesc**

*Input.* Handle to a previously initialized filter descriptor describing the weights for the RNN.

**w**

*Input.* Data pointer to GPU memory associated with the filter descriptor *wDesc*.

**linLayerID**

*Input.* Linear ID index of the weight matrix.

If *cellMode* in *rnnDesc* was set to CUDNN_RNN_RELU or CUDNN_RNN_TANH:

- Value 0 references the weight matrix used in conjunction with the input from the previous layer or input to the RNN model.
- Value 1 references the weight matrix used in conjunction with the hidden state from the previous time step or the initial hidden state.

If *cellMode* in *rnnDesc* was set to CUDNN_LSTM:

- Values 0, 1, 2, and 3 reference weight matrices used in conjunction with the input from the previous layer or input to the RNN model.
- Values 4, 5, 6, and 7 reference weight matrices used in conjunction with the hidden state from the previous time step or the initial hidden state.
- Value 8 corresponds to the projection matrix, if enabled.

Values and their LSTM gates:

- *linLayerID*0 and 4 correspond to the input gate.
- *linLayerID*1 and 5 correspond to the forget gate.
- *linLayerID*2 and 6 correspond to the new cell state calculations with a hyperbolic tangent.
- *linLayerID*3 and 7 correspond to the output gate.

If *cellMode* in *rnnDesc* was set to CUDNN_GRU:
Values 0, 1, and 2 reference weight matrices used in conjunction with the input from the previous layer or input to the RNN model.

Values 3, 4, and 5 reference weight matrices used in conjunction with the hidden state from the previous time step or the initial hidden state.

Values and their GRU gates:

- linLayerID0 and 3 correspond to the reset gate.
- linLayerID1 and 4 references to the update gate.
- linLayerID2 and 5 correspond to the new hidden state calculations with a hyperbolic tangent.

**linLayerBiasDesc**

*Output.* Handle to a previously created filter descriptor.

**linLayerBias**

*Output.* Data pointer to GPU memory associated with the filter descriptor linLayerBiasDesc.

**Returns**

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- One of the following arguments is NULL: handle, rnnDesc, xDesc, wDesc, linLayerBiasDesc, linLayerBias.
- A data type mismatch was detected between rnnDesc and other descriptors.
- Minimum requirement for the w pointer alignment is not satisfied.
- The value of pseudoLayer or linLayerID is out of range.

**CUDNN_STATUS_INVALID_VALUE**

Some elements of the linLayerBias vector are outside the w buffer boundaries as specified by the wDesc descriptor.

### 7.2.25. cudnnGetRNNLinLayerMatrixParams()

This function has been deprecated in cuDNN 8.0. Use cudnnGetRNNWeightParams() instead of cudnnGetRNNLinLayerMatrixParams().

```c
void cudnnGetRNNLinLayerMatrixParams(
    cudnnHandle_t handle,   // Handle to the cuDNN context.
    cudnnRNNLinLayerMatrixDesc_t linLayerDesc,    // Pointer to RNN LinLayer matrix descriptor.
    cudnnLinLayerBiasDesc_t linLayerBiasDesc)    // Pointer to bias descriptor.
```
This function is used to obtain a pointer and a descriptor of every RNN weight matrix in each pseudo-layer within the recurrent network defined by `rnnDesc` and its input width specified in `xDesc`.

**Note:** The `cudnnGetRNNLinLayerMatrixParams()` function was enhanced in cuDNN version 7.1.1 without changing its prototype. Instead of reporting the total number of elements in each weight matrix in the `linLayerMatDesc` filter descriptor, the function returns the matrix size as two dimensions: rows and columns. Moreover, when a weight matrix does not exist, for example, due to CUDNN_SKIP_INPUT mode, the function returns `NULL` in `linLayerMat` and all fields of `linLayerMatDesc` are zero.

The `cudnnGetRNNLinLayerMatrixParams()` function returns the RNN matrix size in two dimensions: rows and columns. This allows the user to easily print and initialize RNN weight matrices. Elements in each weight matrix are arranged in the row-major order. Due to historical reasons, the minimum number of dimensions in the filter descriptor is three. In previous versions of the cuDNN library, the function returned the total number of weights in `linLayerMatDesc` as follows: `filterDimA[0]=total_size`, `filterDimA[1]=1`, `filterDimA[2]=1` (see the description of the `cudnnGetFilterNdDescriptor()` function).

In cuDNN 7.1.1, the format was changed to: `filterDimA[0]=1`, `filterDimA[1]=rows`, `filterDimA[2]=columns`. In both cases, the “format” field of the filter descriptor should be ignored when retrieved by `cudnnGetFilterNdDescriptor()`.

**Parameters**

**handle**

_Input._ Handle to a previously created cuDNN library descriptor.

**rnnDesc**

_Input._ A previously initialized RNN descriptor.

**pseudoLayer**

_Input._ The pseudo-layer to query. In uni-directional RNNs, a pseudo-layer is the same as a physical layer (pseudoLayer=0 is the RNN input layer, pseudoLayer=1 is the first hidden layer). In bi-directional RNNs, there are twice as many pseudo-layers in comparison to physical layers.

- pseudoLayer=0 refers to the forward part of the physical input layer
- pseudoLayer=1 refers to the backward part of the physical input layer
- pseudoLayer=2 is the forward part of the first hidden layer, and so on
**xDesc**

*Input.* A fully packed tensor descriptor describing the input to one recurrent iteration (to retrieve the RNN input width).

**wDesc**

*Input.* Handle to a previously initialized filter descriptor describing the weights for the RNN.

**w**

*Input.* Data pointer to GPU memory associated with the filter descriptor wDesc.

**linLayerID**

*Input.* The linear layer to obtain information about:

- **If** mode in `rnnDesc` was set to `CUDNN_RNN_RELU` or `CUDNN_RNN_TANH`:
  - Value 0 references the bias applied to the input from the previous layer (relevant if `biasMode` in `rnnDesc` is `CUDNN_RNN_SINGLE_INP_BIAS` or `CUDNN_RNN_DOUBLE_BIAS`).
  - Value 1 references the bias applied to the recurrent input (relevant if `biasMode` in `rnnDesc` is `CUDNN_RNN_DOUBLE_BIAS` or `CUDNN_RNN_SINGLE_REC_BIAS`).

- **If** mode in `rnnDesc` was set to `CUDNN_LSTM`:
  - Values of 0, 1, 2 and 3 reference bias applied to the input from the previous layer (relevant if `biasMode` in `rnnDesc` is `CUDNN_RNN_SINGLE_INP_BIAS` or `CUDNN_RNN_DOUBLE_BIAS`).
  - Values of 4, 5, 6 and 7 reference bias applied to the recurrent input (relevant if `biasMode` in `rnnDesc` is `CUDNN_RNN_DOUBLE_BIAS` or `CUDNN_RNN_SINGLE_REC_BIAS`).
  - Values and their associated gates:
    - Values 0 and 4 reference the input gate.
    - Values 1 and 5 reference the forget gate.
    - Values 2 and 6 reference the new memory gate.
    - Values 3 and 7 reference the output gate.

- **If** mode in `rnnDesc` was set to `CUDNN_GRU`:
  - Values of 0, 1 and 2 reference bias applied to the input from the previous layer (relevant if `biasMode` in `rnnDesc` is `CUDNN_RNN_SINGLE_INP_BIAS` or `CUDNN_RNN_DOUBLE_BIAS`).
  - Values of 3, 4 and 5 reference bias applied to the recurrent input (relevant if `biasMode` in `rnnDesc` is `CUDNN_RNN_DOUBLE_BIAS` or `CUDNN_RNN_SINGLE_REC_BIAS`).
  - Values and their associated gates:
    - Values 0 and 3 reference the reset gate.
Values 1 and 4 reference the update gate.
Values 2 and 5 reference the new memory gate.

For more information on modes and bias modes, see cudnnRNNMode_t.

linLayerMatDesc

*Output.* Handle to a previously created filter descriptor. When the weight matrix does not exist, the returned filter descriptor has all fields set to zero.

linLayerMat

*Output.* Data pointer to GPU memory associated with the filter descriptor linLayerMatDesc. When the weight matrix does not exist, the returned pointer is NULL.

Returns

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- One of the following arguments is NULL: handle, rnnDesc, xDesc, wDesc, linLayerMatDesc, linLayerMat.
- A data type mismatch was detected between rnnDesc and other descriptors.
- Minimum requirement for the w pointer alignment is not satisfied.
- The value of pseudoLayer or linLayerID is out of range.

**CUDNN_STATUS_INVALID_VALUE**

Some elements of the linLayerMat vector are outside the w buffer boundaries as specified by the wDesc descriptor.

### 7.2.26. cudnnGetRNNMatrixMathType()

This function has been deprecated in cuDNN 8.0. Use cudnnGetRNNDescriptor_v8() instead of cudnnGetRNNMatrixMathType().

```c
     cudnnStatus_t cudnnGetRNNMatrixMathType(
             cudnnRNNDescriptor_t rnnDesc,
             cudnnMathType_t *mType);
```

This function retrieves the preferred settings for NVIDIA Tensor Cores on Volta (SM 7.0) or higher GPUs. See the cudnnMathType_t description for more details.
Parameters

rnnDesc

*Input. A previously created and initialized RNN descriptor.

mType

*Output. Address where the preferred Tensor Core settings should be stored.

Returns

**CUDNN_STATUS_SUCCESS**

The requested RNN descriptor field was retrieved successfully.

**CUDNN_STATUS_BAD_PARAM**

An invalid input argument was found (<rnnDesc> or <mType> was NULL).

7.2.27. **cudnnGetRNNPaddingMode()**

This function has been deprecated in cuDNN 8.0. Use **cudnnGetRNNDescriptor_v8()** instead of **cudnnGetRNNPaddingMode()**.

```c
#include <cuda_runtime.h>

__global__ void cudnnGetRNNPaddingMode(
    cudnnRNNDescriptor_t  rnnDesc,
    cudnnRNNPaddingMode_t *paddingMode)
```

This function retrieves the RNN padding mode from the RNN descriptor.

Parameters

rnnDesc

*Input/Output. A previously created RNN descriptor.

*paddingMode

*Input. Pointer to the host memory where the RNN padding mode is saved.

Returns

**CUDNN_STATUS_SUCCESS**

The RNN padding mode parameter was retrieved successfully.

**CUDNN_STATUS_BAD_PARAM**

Either the <rnnDesc> or <paddingMode> is NULL.

7.2.28. **cudnnGetRNNParamsSize()**

This function has been deprecated in cuDNN 8.0. Use **cudnnGetRNNWeightSpaceSize()** instead of **cudnnGetRNNParamsSize()**.

```c
#include <cuda_runtime.h>

__global__ void cudnnGetRNNParamsSize(
    cudnnStatus_t cudnnGetRNNParamsSize
```
This function is used to query the amount of parameter space required to execute the RNN described by `rnnDesc` with input dimensions defined by `xDesc`.

**Parameters**

- `handle`
  - Input. Handle to a previously created cuDNN library descriptor.

- `rnnDesc`
  - Input. A previously initialized RNN descriptor.

- `xDesc`
  - Input. A fully packed tensor descriptor describing the input to one recurrent iteration.

- `sizeInBytes`
  - Output. Minimum amount of GPU memory needed as parameter space to be able to execute an RNN with the specified descriptor and input tensors.

- `dataType`
  - Input. The data type of the parameters.

**Returns**

- **CUDNN_STATUS_SUCCESS**
  - The query was successful.

- **CUDNN_STATUS_BAD_PARAM**
  - At least one of the following conditions are met:
    - The descriptor `rnnDesc` is invalid.
    - The descriptor `xDesc` is invalid.
    - The descriptor `xDesc` is not fully packed.
    - The combination of `dataType` and tensor descriptor data type is invalid.

- **CUDNN_STATUS_NOT_SUPPORTED**
  - The combination of the RNN descriptor and tensor descriptors is not supported.

### 7.2.29. `cudnnGetRNNProjectionLayers()`

This function has been deprecated in cuDNN 8.0. Use `cudnnGetRNNDescriptor_v8()` instead of `cudnnGetRNNProjectionLayers()`.

```c
    cudnnStatus_t cudnnGetRNNProjectionLayers(    
        cudnnHandle_t handle,    
        const cudnnRNNDescriptor_t rnnDesc,    
        const cudnnTensorDescriptor_t xDesc,    
        size_t *sizeInBytes,    
        cudnnDataType_t dataType)
```
This function retrieves the current RNN projection parameters. By default, the projection feature is disabled so invoking this function will yield `recProjSize` equal to `hiddenSize` and `outProjSize` set to zero. The `cudnnSetRNNProjectionLayers()` method enables the RNN projection.

**Parameters**

**handle**

*Input*. Handle to a previously created cuDNN library descriptor.

**rnnDesc**

*Input*. A previously created and initialized RNN descriptor.

**recProjSize**

*Output*. Pointer where the recurrent projection size should be stored.

**outProjSize**

*Output*. Pointer where the output projection size should be stored.

**Returns**

**CUDNN_STATUS_SUCCESS**

RNN projection parameters were retrieved successfully.

**CUDNN_STATUS_BAD_PARAM**

A NULL pointer was passed to the function.

**7.2.30. cudnnGetRNNTempSpaceSizes()**

```c
int cudnnStatus_t cudnnGetRNNTempSpaceSizes(
    cudnnHandle_t handle,
    cudnnRNNDescriptor_t rnnDesc,
    cudnnForwardMode_t fMode,
    cudnnRNNDataDescriptor_t xDesc,
    size_t *workSpaceSize,
    size_t *reserveSpaceSize);
```

This function computes the work and reserve space buffer sizes based on the RNN network geometry stored in `rnnDesc`, designated usage (inference or training) defined by the `fMode` argument, and the current RNN data dimensions (`maxSeqLength`, `batchSize`) retrieved from `xDesc`. When RNN data dimensions change, the `cudnnGetRNNTempSpaceSizes()` must be called again because RNN temporary buffer sizes are not monotonic.

The user can assign NULL to `workSpaceSize` or `reserveSpaceSize` pointers when the corresponding value is not needed.
Parameters

handle

*Input*. The current cuDNN context handle.

rnnDesc

*Input*. A previously initialized RNN descriptor.

fMode

*Input*. Specifies whether temporary buffers are used in inference or training modes. The reserve-space buffer is not used during inference. Therefore, the returned size of the reserve space buffer will be zero when the `fMode` argument is `CUDNN_FWD_MODE_INFERENCE`.

xDesc

*Input*. A single RNN data descriptor that specifies current RNN data dimensions: `maxSeqLength` and `batchSize`.

workSpaceSize

*Output*. Minimum amount of GPU memory in bytes needed as a workspace buffer. The workspace buffer is not used to pass intermediate results between APIs but as a temporary read/write buffer.

reserveSpaceSize

*Output*. Minimum amount of GPU memory in bytes needed as the reserve-space buffer. The reserve space buffer is used to pass intermediate results from `cudnnRNNForward` to RNN BackwardData and BackwardWeights routines that compute first order derivatives with respect to RNN inputs or trainable weight and biases.

Returns

**CUDNN_STATUS_SUCCESS**

RNN temporary buffer sizes were computed successfully.

**CUDNN_STATUS_BAD_PARAM**

An invalid input argument was detected.

**CUDNN_STATUS_NOT_SUPPORTED**

An incompatible or unsupported combination of input arguments was detected.

7.2.31. `cudnnGetRNNWeightParams()`

cudnnStatus_t cudnnGetRNNWeightParams(
    cudnnHandle_t handle,
    cudnnRNNDescriptor_t rnnDesc,
    int32_t pseudoLayer,
    size_t weightSpaceSize,
    const void *weightSpace,
    int32_t linLayerID,

)
This function is used to obtain the start address and shape of every RNN weight matrix and bias vector in each pseudo-layer within the recurrent network.

**Parameters**

**handle**

*Input.* Handle to a previously created cuDNN library descriptor.

**rnnDesc**

*Input.* A previously initialized RNN descriptor.

**pseudoLayer**

*Input.* The pseudo-layer to query. In uni-directional RNNs, a pseudo-layer is the same as a physical layer (pseudoLayer=0 is the RNN input layer, pseudoLayer=1 is the first hidden layer). In bi-directional RNNs, there are twice as many pseudo-layers in comparison to physical layers:

- pseudoLayer=0 refers to the forward direction sub-layer of the physical input layer
- pseudoLayer=1 refers to the backward direction sub-layer of the physical input layer
- pseudoLayer=2 is the forward direction sub-layer of the first hidden layer, and so on

**weightSpaceSize**

*Input.* Size of the weight space buffer in bytes.

**weightSpace**

*Input.* Pointer to the weight space buffer.

**linLayerID**

*Input.* Weight matrix or bias vector linear ID index.

If `cellMode` in `rnnDesc` was set to `CUDNN_RNN_RELU` or `CUDNN_RNN_TANH`:

- Value 0 references the weight matrix or bias vector used in conjunction with the input from the previous layer or input to the RNN model.
- Value 1 references the weight matrix or bias vector used in conjunction with the hidden state from the previous time step or the initial hidden state.

If `cellMode` in `rnnDesc` was set to `CUDNN_LSTM`:

- Values 0, 1, 2 and 3 reference weight matrices or bias vectors used in conjunction with the input from the previous layer or input to the RNN model.
- Values 4, 5, 6 and 7 reference weight matrices or bias vectors used in conjunction with the hidden state from the previous time step or the initial hidden state.
- Value 8 corresponds to the projection matrix, if enabled (there is no bias in this operation).
If `cellMode` in `rnnDesc` was set to `CUDNN_GRU`:

- Values 0, 1 and 2 reference weight matrices or bias vectors used in conjunction with the input from the previous layer or input to the RNN model.
- Values 3, 4 and 5 reference weight matrices or bias vectors used in conjunction with the hidden state from the previous time step or the initial hidden state.

Values and their GRU gates:

- `linLayerID0` and 3 correspond to the reset gate.
- `linLayerID1` and 4 reference to the update gate.
- `linLayerID2` and 5 correspond to the new hidden state calculations with hyperbolic tangent.

For more information on modes and bias modes, see `cudnnRNMode_t`.

**mDesc**

*Output.* Handle to a previously created tensor descriptor. The shape of the corresponding weight matrix is returned in this descriptor in the following format: `dimA[3] = {1, rows, cols}`. The reported number of tensor dimensions is zero when the weight matrix does not exist. This situation occurs for input GEMM matrices of the first layer when `CUDNN_SKIP_INPUT` is selected or for the LSTM projection matrix when the feature is disabled.

**mAddr**

*Output.* Pointer to the beginning of the weight matrix within the weight space buffer. When the weight matrix does not exist, the returned address is `NULL`.

**bDesc**

*Output.* Handle to a previously created tensor descriptor. The shape of the corresponding bias vector is returned in this descriptor in the following format: `dimA[3] = {1, rows, 1}`. The reported number of tensor dimensions is zero when the bias vector does not exist.

**bAddr**

*Output.* Pointer to the beginning of the bias vector within the weight space buffer. When the bias vector does not exist, the returned address is `NULL`.

**Returns**

**CUDNN_STATUS_SUCCESS**

The query was completed successfully.

**CUDNN_STATUS_BAD_PARAM**

An invalid input argument was encountered. For example, the value of `pseudoLayer` is out of range or `linLayerID` is negative or larger than 8.
CUDNN_STATUS_INVALID_VALUE

Some weight/bias elements are outside the weight space buffer boundaries.

CUDNN_STATUS_NOT_INITIALIZED

The RNN descriptor was configured with the legacy cudnnSetRNNDescriptor_v6() call.

7.2.32. cudnnGetRNNWorkspaceSize()

cudnnStatus_t cudnnGetRNNWorkspaceSize(
    cudnnHandle_t handle,
    cudnnRNNDescriptor_t rnnDesc,
    size_t *weightSpaceSize);

This function reports the required size of the weight space buffer in bytes. The weight space buffer holds all RNN weight matrices and bias vectors.

Parameters

handle

Input. The current cuDNN context handle.

rnnDesc

Input. A previously initialized RNN descriptor.

weightSpaceSize

Output. Minimum size in bytes of GPU memory needed for all RNN trainable parameters.

Returns

CUDNN_STATUS_SUCCESS

The query was successful.

CUDNN_STATUS_BAD_PARAM

An invalid input argument was encountered. For example, any input argument was NULL.

CUDNN_STATUS_NOT_INITIALIZED

The RNN descriptor was configured with the legacy cudnnSetRNNDescriptor_v6() call.

7.2.33. cudnnGetRNNWorkspaceSize()

This function has been deprecated in cuDNN 8.0. Use cudnnGetRNNTempSpaceSizes() instead of cudnnGetRNNWorkspaceSize().

cudnnStatus_t cudnnGetRNNWorkspaceSize(
    cudnnHandle_t handle,
    const cudnnRNNDescriptor_t rnnDesc,
    const int seqLength,
    const cudnnTensorDescriptor_t *xDesc,
    size_t *sizeInBytes)

This function is used to query the amount of work space required to execute the RNN described by rnnDesc with input dimensions defined by xDesc.
Parameters

**handle**

*Input.* Handle to a previously created cuDNN library descriptor.

**rnnDesc**

*Input.* A previously initialized RNN descriptor.

**seqLength**

*Input.* Number of iterations to unroll over. Workspace that is allocated, based on the size that this function provides, cannot be used for sequences longer than seqLength.

**xDesc**

*Input.* An array of tensor descriptors describing the input to each recurrent iteration (one descriptor per iteration). The first dimension (batch size) of the tensors may decrease from element n to element n+1 but may not increase. For example, if you have multiple time series in a batch, they can be different lengths. This dimension is the batch size for the particular iteration of the sequence, and so it should decrease when a sequence in the batch has been terminated.

Each tensor descriptor must have the same second dimension (vector length).

**sizeInBytes**

*Output.* Minimum amount of GPU memory needed as workspace to be able to execute an RNN with the specified descriptor and input tensors.

Returns

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The descriptor `rnnDesc` is invalid.
- At least one of the descriptors in `xDesc` is invalid.
- The descriptors in `xDesc` have inconsistent second dimensions, strides or data types.
- The descriptors in `xDesc` have increasing first dimensions.
- The descriptors in `xDesc` are not fully packed.

**CUDNN_STATUS_NOT_SUPPORTED**

The data types in tensors described by `xDesc` are not supported.

7.2.34. `cudnnGetSeqDataDescriptor()`

cudnnStatus_t cudnnGetSeqDataDescriptor(
This function retrieves settings from a previously created sequence data descriptor. The user can assign NULL to any pointer except seqDataDesc when the retrieved value is not needed. The nbDimsRequested argument applies to both dimA[] and axes[] arrays. A positive value of nbDimsRequested or seqLengthSizeRequested is ignored when the corresponding array, dimA[], axes[], or seqLengthArray[] is NULL.

The cudnnGetSeqDataDescriptor() function does not report the actual strides in the sequence data buffer. Those strides can be handy in computing the offset to any sequence data element. The user must precompute strides based on the axes[] and dimA[] arrays reported by the cudnnGetSeqDataDescriptor() function. Below is sample code that performs this task:

```c
// Array holding sequence data strides.
size_t strA[CUDNN_SEQDATA_DIM_COUNT] = {0};

// Compute strides from dimension and order arrays.
size_t stride = 1;
for (int i = nbDims - 1; i >= 0; i--) {
    int j = int(axes[i]);
    if (unsigned(j) < CUDNN_SEQDATA_DIM_COUNT-1 && strA[j] == 0) {
        strA[j] = stride;
        stride *= dimA[j];
    } else {
        fprintf(stderr, "ERROR: invalid axes[%d]=%d\n\n", i, j);
        abort();
    }
}
```

Now, the strA[] array can be used to compute the index to any sequence data element, for example:

```c
// Using four indices (batch, beam, time, vect) with ranges already checked.
size_t base = strA[CUDNN_SEQDATA_BATCH_DIM] * batch
    + strA[CUDNN_SEQDATA_BEAM_DIM] * beam
    + strA[CUDNN_SEQDATA_TIME_DIM] * time;
val = seqDataPtr[base + vect];
```

The above code assumes that all four indices (batch, beam, time, vect) are less than the corresponding value in the dimA[] array. The sample code also omits the strA[CUDNN_SEQDATA_VECT_DIM] stride because its value is always 1, meaning, elements of one vector occupy a contiguous block of memory.

**Parameters**

- **seqDataDesc**
  - *Input*. Sequence data descriptor.

- **dataType**
  - *Output*. Data type used in the sequence data buffer.

- **nbDims**
  - *Output*. The number of active dimensions in the dimA[] and axes[] arrays.
**nbDimsRequested**

*Input.* The maximum number of consecutive elements that can be written to `dimA[]` and `axes[]` arrays starting from index zero. The recommended value for this argument is `CUDNN_SEQDATA_DIM_COUNT`.

**dimA[]**

*Output.* Integer array holding sequence data dimensions.

**axes[]**

*Output.* Array of `cudnnSeqDataAxis_t` that defines the layout of sequence data in memory.

**seqLengthArraySize**

*Output.* The number of required elements in `seqLengthArray[]` to save all sequence lengths.

**seqLengthSizeRequested**

*Input.* The maximum number of consecutive elements that can be written to the `seqLengthArray[]` array starting from index zero.

**seqLengthArray[]**

*Output.* Integer array holding sequence lengths.

**paddingFill**

*Output.* Pointer to a storage location of `dataType` with the fill value that should be written to all padding vectors. Use `NULL` when an explicit initialization of output padding vectors was not requested.

**Returns**

**CUDNN_STATUS_SUCCESS**

Requested sequence data descriptor fields were retrieved successfully.

**CUDNN_STATUS_BAD_PARAM**

An invalid input argument was found.

**CUDNN_STATUS_INTERNAL_ERROR**

An inconsistent internal state was encountered.

### 7.2.35. `cudnnMultiHeadAttnForward()`

```c
size_t cudnnMultiHeadAttnForward(
  cudnnHandle_t handle,
  const cudnnAttnDescriptor_t attnDesc,
  int currIdx,
  const int loWinIdx[],
  const int hiWinIdx[],
  const int devSeqLengthsQO[],
  const int devSeqLengthsKV[],
  const cudnnSeqDataDescriptor_t qDesc,
  const void *queries,
  const void *residuals,
  const cudnnSeqDataDescriptor_t kDesc,
  const void *keys,
  const cudnnSeqDataDescriptor_t vDesc,
  const void *values,
  const cudnnSeqDataDescriptor_t oDesc,
  void *out,
  size_t weightSizeInBytes,
  const void *weights,
  size_t blockSize,   // Optional stream
)
```
The `cudnnMultiHeadAttnForward()` function computes the forward responses of the multi-head attention layer. When `reserveSpaceSizeInBytes=0` and `reserveSpace=NULL`, the function operates in the inference mode in which backward (gradient) functions are not invoked, otherwise, the training mode is assumed. In the training mode, the reserve space is used to pass intermediate results from `cudnnMultiHeadAttnForward()` to `cudnnMultiHeadAttnBackwardData[]` and from `cudnnMultiHeadAttnBackwardData[]` to `cudnnMultiHeadAttnBackwardWeights[]`.

In the inference mode, the `currIdx` specifies the time-step or sequence index of the embedding vectors to be processed. In this mode, the user can perform one iteration for time-step zero (`currIdx=0`), then update `Q, K, V` vectors and the attention window, and execute the next step (`currIdx=1`). The iterative process can be repeated for all time-steps.

When all `Q` time-steps are available (for example, in the training mode or in the inference mode on the encoder side in self-attention), the user can assign a negative value to `currIdx` and the `cudnnMultiHeadAttnForward()` API will automatically sweep through all `Q` time-steps.

The `loWinIdx[]` and `hiWinIdx[]` host arrays specify the attention window size for each `Q` time-step. In a typical self-attention case, the user must include all previously visited embedding vectors but not the current or future vectors. In this situation, the user should set:

```
currIdx=0: loWinIdx[0]=0; hiWinIdx[0]=0;  // initial time-step, no attention window
currIdx=1: loWinIdx[1]=0; hiWinIdx[1]=1;  // attention window spans one vector
currIdx=2: loWinIdx[2]=0; hiWinIdx[2]=2;  // attention window spans two vectors
(...)
```

When `currIdx` is negative in `cudnnMultiHeadAttnForward()`, the `loWinIdx[]` and `hiWinIdx[]` arrays must be fully initialized for all time-steps. When `cudnnMultiHeadAttnForward()` is invoked with `currIdx=0`, `currIdx=1`, `currIdx=2`, etc., then the user can update `loWinIdx[currIdx]` and `hiWinIdx[currIdx]` elements only before invoking the forward response function. All other elements in the `loWinIdx[]` and `hiWinIdx[]` arrays will not be accessed. Any adaptive attention window scheme can be implemented that way.

Use the following settings when the attention window should be the maximum size, for example, in cross-attention:

```
currIdx=0: loWinIdx[0]=0; hiWinIdx[0]=maxSeqLenK;
currIdx=1: loWinIdx[1]=0; hiWinIdx[1]=maxSeqLenK;
(...)
```

The `maxSeqLenK` value above should be equal to or larger than `dimA[CUDNN_SEQDATA_TIME_DIM]` in the `kDesc` descriptor. A good choice is to use `maxSeqLenK=INT_MAX` from `limits.h`.

**Note:** The actual length of any `K` sequence defined in `seqLengthArray[]` in `cudnnSetSeqDataDescriptor[]` can be shorter than `maxSeqLenK`. The effective attention window span is computed based on `seqLengthArray[]` stored in the `K` sequence descriptor and indices held in `loWinIdx[]` and `hiWinIdx[]` arrays.
devSeqLengthsQO[] and devSeqLengthsKV[] are pointers to device (not host) arrays with Q, O, and K, V sequence lengths. Note that the same information is also passed in the corresponding descriptors of type cudnnSeqDataDescriptor_t on the host side. The need for extra device arrays comes from the asynchronous nature of cuDNN calls and limited size of the constant memory dedicated to GPU kernel arguments. When the cudnnMultiHeadAttnForward() API returns, the sequence length arrays stored in the descriptors can be immediately modified for the next iteration. However, the GPU kernels launched by the forward call may not have started at this point. For this reason, copies of sequence arrays are needed on the device side to be accessed directly by GPU kernels. Those copies cannot be created inside the cudnnMultiHeadAttnForward() function for very large K, V inputs without the device memory allocation and CUDA stream synchronization.

To reduce the cudnnMultiHeadAttnForward() API overhead, devSeqLengthsQO[] and devSeqLengthsKV[] device arrays are not validated to contain the same settings as seqLengthArray[] in the sequence data descriptors. Sequence lengths in the kDesc and vDesc descriptors should be the same. Similarly, sequence lengths in the qDesc and oDesc descriptors should match. The user can define six different data layouts in the qDesc, kDesc, vDesc and oDesc descriptors. See the cudnnSetSeqDataDescriptor() function for the discussion of those layouts. All multi-head attention API calls require that the same layout is used in all sequence data descriptors.

In the transformer model, the multi-head attention block is tightly coupled with the layer normalization and residual connections. cudnnMultiHeadAttnForward() does not encompass the layer normalization but it can be used to handle residual connections as depicted in the following figure.

Queries and residuals share the same qDesc descriptor in cudnnMultiHeadAttnForward(). When residual connections are disabled, the residuals pointer should be NULL. When residual connections are enabled, the vector length in qDesc should match the vector length specified in the oDesc descriptor, so that a vector addition is feasible.

The queries, keys, and values pointers are not allowed to be NULL, even when K and V are the same inputs or Q, K, V are the same inputs.
Parameters

handle

*Input*. The current cuDNN context handle.

attnDesc

*Input*. A previously initialized attention descriptor.

currIdx

*Input*. Time-step in queries to process. When the `currIdx` argument is negative, all Q time-steps are processed. When `currIdx` is zero or positive, the forward response is computed for the selected time-step only. The latter input can be used in inference mode only, to process one time-step while updating the next attention window and Q, R, K, V inputs in-between calls.

loWinIdx[], hiWinIdx[]

*Input*. Two host integer arrays specifying the start and end indices of the attention window for each Q time-step. The start index in K, V sets is inclusive, and the end index is exclusive.

devSeqLengthsQO[]

*Input*. Device array specifying sequence lengths of query, residual, and output sequence data.

devSeqLengthsKV[]

*Input*. Device array specifying sequence lengths of key and value input data.

qDesc

*Input*. Descriptor for the query and residual sequence data.

queries

*Input*. Pointer to queries data in the device memory.

residuals

*Input*. Pointer to residual data in device memory. Set this argument to NULL if no residual connections are required.

kDesc

*Input*. Descriptor for the keys sequence data.

keys

*Input*. Pointer to keys data in device memory.

vDesc

*Input*. Descriptor for the values sequence data.

values

*Input*. Pointer to values data in device memory.
cDesc

*Input*. Descriptor for the multi-head attention output sequence data.

t

*Output*. Pointer to device memory where the output response should be written.

**weightSizeInBytes**

*Input*. Size of the weight buffer in bytes where all multi-head attention trainable parameters are stored.

**weights**

*Input*. Pointer to the weight buffer in device memory.

**workSpaceSizeInBytes**

*Input*. Size of the work-space buffer in bytes used for temporary API storage.

**workSpace**

*Input/Output*. Pointer to the work-space buffer in device memory.

**reserveSpaceSizeInBytes**

*Input*. Size of the reserve-space buffer in bytes used for data exchange between forward and backward (gradient) API calls. This parameter should be zero in the inference mode and non-zero in the training mode.

**reserveSpace**

*Input/Output*. Pointer to the reserve-space buffer in device memory. This argument should be **NULL** in inference mode and **non-NULL** in the training mode.

**Returns**

**CUDNN_STATUS_SUCCESS**

No errors were detected while processing API input arguments and launching GPU kernels.

**CUDNN_STATUS_BAD_PARAM**

An invalid or incompatible input argument was encountered. Some examples include:

- a required input pointer was **NULL**
- `currIdx` was out of bound
- the descriptor value for attention, query, key, value, and output were incompatible with one another

**CUDNN_STATUS_EXECUTION_FAILED**

The process of launching a GPU kernel returned an error, or an earlier kernel did not complete successfully.

**CUDNN_STATUS_INTERNAL_ERROR**

An inconsistent internal state was encountered.
CUDNN_STATUS_NOT_SUPPORTED

A requested option or a combination of input arguments is not supported.

CUDNN_STATUSALLOC_FAILED

Insufficient amount of shared memory to launch a GPU kernel.

7.2.36. cudnnRNNForward()

cudnnStatus_t cudnnRNNForward(
    cudnnHandle_t handle,
    cudnnRNNDescriptor_t rnnDesc,
    cudnnForwardMode_t fwdMode,
    const int32_t devSeqLengths[],
    cudnnRNNDataDescriptor_t xDesc,
    const void *x,
    cudnnRNNDataDescriptor_t yDesc,
    void *y,
    cudnnTensorDescriptor_t hDesc,
    const void *hx,
    void *hx,
    cudnnTensorDescriptor_t cDesc,
    const void *cx,
    void *cx,
    size_t weightSpaceSize,
    const void *weightSpace,
    size_t workSpaceSize,
    void *workSpace,
    size_t reserveSpaceSize,
    void *reserveSpace);

This routine computes the forward response of the recurrent neural network described by
rnnDesc with inputs in x, hx, cx, and weights/biases in the weightSpace buffer. RNN outputs
are written to y, hy, and cy buffers. Locations of x, y, hx, cx, hy, and cy signals in the multi-
layer RNN model are shown in the Figure below. Note that internal RNN signals between
time-steps and between layers are not exposed to the user.
Figure 1. Locations of x, y, hx, cx, hy, and cy signals in the multi-layer RNN model.

The next Figure depicts data flow when the RNN model is bi-directional. In this mode each RNN physical layer consists of two consecutive pseudo-layers, each with its own weights, biases, the initial hidden state hx, and for LSTM, also the initial cell state cx. Even pseudo-layers 0, 2, 4 process input vectors from left to right or in the forward (F) direction. Odd pseudo-layers 1, 3, 5 process input vectors from right to left or in the reverse (R) direction. Two successive pseudo-layers operate on the same input vectors, just in a different order. Pseudo-layers 0 and 1 access the original sequences stored in the x buffer. Outputs of F and R cells are concatenated so vectors fed to the next two pseudo-layers have lengths of 2x hiddenSize or 2x projSize. Input GEMMs in subsequent pseudo-layers adjust vector lengths to 1x hiddenSize.
Figure 2. Data flow when the RNN model is bi-directional.

When the `fwdMode` parameter is set to `CUDNN_FWD_MODE_TRAINING`, the `cudnnRNNForward()` function stores intermediate data required to compute first order derivatives in the reserve space buffer. Work and reserve space buffer sizes should be computed by the `cudnnGetRNNTempSpaceSizes()` function with the same `fwdMode` setting as used in the `cudnnRNNForward()` call.

The same layout type must be specified in `xDesc` and `yDesc` descriptors. The same sequence lengths must be configured in `xDesc`, `yDesc` and in the device array `devSeqLengths`. The `cudnnRNNForward()` function does not verify that sequence lengths stored in `devSeqLengths` in GPU memory are the same as in `xDesc` and `yDesc` descriptors in CPU memory. Sequence length arrays from `xDesc` and `yDesc` descriptors are checked for consistency, however.

**Parameters**

- **handle**
  
  *Input.* The current cuDNN context handle.

- **rnnDesc**
  
  *Input.* A previously initialized RNN descriptor.

- **fwdMode**
  
  *Input.* Specifies inference or training mode (`CUDNN_FWD_MODE_INFERENCE` and `CUDNN_FWD_MODE_TRAINING`). In the training mode, additional data is stored in the reserve space buffer. This information is used in the backward pass to compute derivatives.

- **devSeqLengths**
  
  *Input.* A copy of `seqLengthArray` from `xDesc` or `yDesc` RNN data descriptor. The `devSeqLengths` array must be stored in GPU memory as it is accessed asynchronously by
GPU kernels, possibly after the `cudnnRNNForward()` function exists. This argument cannot be NULL.

**xDesc**

*Input.* A previously initialized descriptor corresponding to the RNN model primary input. The `dataType`, `layout`, `maxSeqLength`, `batchSize`, and `seqLengthArray` must match that of `yDesc`. The parameter `vectorSize` must match the `inputSize` argument passed to the `cudnnSetRNNDescriptor_v8[]` function.

**x**

*Input.* Data pointer to the GPU memory associated with the RNN data descriptor `xDesc`. The vectors are expected to be arranged in memory according to the layout specified by `xDesc`. The elements in the tensor (including padding vectors) must be densely packed.

**yDesc**

*Input.* A previously initialized RNN data descriptor. The `dataType`, `layout`, `maxSeqLength`, `batchSize`, and `seqLengthArray` must match that of `xDesc`. The parameter `vectorSize` depends on whether LSTM projection is enabled and whether the network is bidirectional. Specifically:

- For unidirectional models, the parameter `vectorSize` must match the `hiddenSize` argument passed to `cudnnSetRNNDescriptor_v8[]`. If the LSTM projection is enabled, the `vectorSize` must be the same as the `projSize` argument passed to `cudnnSetRNNDescriptor_v8[]`.
- For bidirectional models, if the RNN cellMode is `CUDNN_LSTM` and the projection feature is enabled, the parameter `vectorSize` must be 2x the `projSize` argument passed to `cudnnSetRNNDescriptor_v8[]`. Otherwise, it should be 2x the `hiddenSize` value.

**y**

*Output.* Data pointer to the GPU memory associated with the RNN data descriptor `yDesc`. The vectors are expected to be laid out in memory according to the layout specified by `yDesc`. The elements in the tensor (including elements in the padding vector) must be densely packed, and no strides are supported.

**hDesc**

*Input.* A tensor descriptor describing the initial or final hidden state of RNN. Hidden state data are fully packed. The first dimension of the tensor depends on the `dirMode` argument passed to the `cudnnSetRNNDescriptor_v8[]` function.

- If `dirMode` is `CUDNN_UNIDIRECTIONAL`, then the first dimension should match the `numLayers` argument passed to `cudnnSetRNNDescriptor_v8[]`.
- If `dirMode` is `CUDNN_BIDIRECTIONAL`, then the first dimension should be double the `numLayers` argument passed to `cudnnSetRNNDescriptor_v8[]`.
The second dimension must match the \texttt{batchSize} parameter described in \texttt{xDesc}. The third dimension depends on whether RNN mode is \texttt{CUDNN\_LSTM} and whether the LSTM projection is enabled. Specifically:

- If RNN mode is \texttt{CUDNN\_LSTM} and LSTM projection is enabled, the third dimension must match the \texttt{projSize} argument passed to the \texttt{cudnnSetRNNProjectionLayers()} call.
- Otherwise, the third dimension must match the \texttt{hiddenSize} argument passed to the \texttt{cudnnSetRNNDescriptor\_v8()} call used to initialize \texttt{rnnDesc}.

\textit{hx}

\textit{Input}. Pointer to the GPU buffer with the RNN initial hidden state. Data dimensions are described by the \texttt{hDesc} tensor descriptor. If a \texttt{NULL} pointer is passed, the initial hidden state of the network will be initialized to zero.

\textit{hy}

\textit{Output}. Pointer to the GPU buffer where the final RNN hidden state should be stored. Data dimensions are described by the \texttt{hDesc} tensor descriptor. If a \texttt{NULL} pointer is passed, the final hidden state of the network will not be saved.

\textit{cDesc}

\textit{Input}. For LSTM networks only. A tensor descriptor describing the initial or final cell state for LSTM networks only. Cell state data are fully packed. The first dimension of the tensor depends on the \texttt{dirMode} argument passed to the \texttt{cudnnSetRNNDescriptor\_v8()} call.

- If \texttt{dirMode} is \texttt{CUDNN\_UNIDIRECTIONAL} the first dimension should match the \texttt{numLayers} argument passed to \texttt{cudnnSetRNNDescriptor\_v8()}.
- If \texttt{dirMode} is \texttt{CUDNN\_BIDIRECTIONAL} the first dimension should match double the \texttt{numLayers} argument passed to \texttt{cudnnSetRNNDescriptor\_v8()}.

The second tensor dimension must match the \texttt{batchSize} parameter in \texttt{xDesc}. The third dimension must match the \texttt{hiddenSize} argument passed to the \texttt{cudnnSetRNNDescriptor\_v8()} call.

\textit{cx}

\textit{Input}. For LSTM networks only. Pointer to the GPU buffer with the initial LSTM state data. Data dimensions are described by the \texttt{cDesc} tensor descriptor. If a \texttt{NULL} pointer is passed, the initial cell state of the network will be initialized to zero.

\textit{cy}

\textit{Output}. For LSTM networks only. Pointer to the GPU buffer where final LSTM state data should be stored. Data dimensions are described by the \texttt{cDesc} tensor descriptor. If a \texttt{NULL} pointer is passed, the final LSTM cell state will not be saved.

\texttt{weightSpaceSize}

\textit{Input}. Specifies the size in bytes of the provided weight-space buffer.
weightSpace

Input. Address of the weight space buffer in GPU memory.

workSpaceSize

Input. Specifies the size in bytes of the provided workspace buffer.

workSpace

Input/Output. Address of the workspace buffer in GPU memory to store temporary data.

reserveSpaceSize

Input. Specifies the size in bytes of the reserve-space buffer.

reserveSpace

Input/Output. Address of the reserve-space buffer in GPU memory.

Returns

CUDNN_STATUS_SUCCESS

No errors were detected while processing API input arguments and launching GPU kernels.

CUDNN_STATUS_NOT_SUPPORTED

At least one of the following conditions are met:

- variable sequence length input is passed while CUDNN_RNN_ALGO_PERSIST_STATIC or CUDNN_RNN_ALGO_PERSIST_DYNAMIC is specified
- CUDNN_RNN_ALGO_PERSIST_STATIC or CUDNN_RNN_ALGO_PERSIST_DYNAMIC is requested on pre-Pascal devices
- the 'double' floating point type is used for input/output and the CUDNN_RNN_ALGO_PERSIST_STATIC algo

CUDNN_STATUS_BAD_PARAM

An invalid or incompatible input argument was encountered. For example:

- some input descriptors are NULL
- at least one of the settings in rnnDesc, xDesc, yDesc, hDesc, or cDesc descriptors is invalid
- weightSpaceSize, workSpaceSize, or reserveSpaceSize is too small

CUDNN_STATUS_EXECUTION_FAILED

The process of launching a GPU kernel returned an error, or an earlier kernel did not complete successfully.

CUDNN_STATUS_ALLOC_FAILED

The function was unable to allocate CPU memory.
7.2.37. **cudnnRNNForwardInference()**

This function has been deprecated in cuDNN 8.0. Use **cudnnRNNForward()** instead of **cudnnRNNForwardInference()**.

```c
void cudnnRNNForwardInference(
    cudnnHandle_t                   handle,
    const cudnnRNNDescriptor_t      rnnDesc,
    const int                       seqLength,
    const cudnnTensorDescriptor_t   *xDesc,
    const void                     *x,
    const cudnnTensorDescriptor_t   hxDesc,
    const void                     *hx,
    const cudnnTensorDescriptor_t   cxDesc,
    const void                     *cx,
    const cudnnFilterDescriptor_t   wDesc,
    const void                     *w,
    const cudnnTensorDescriptor_t   *yDesc,
    void                           *y,
    const cudnnTensorDescriptor_t   hyDesc,
    void                           *hy,
    const cudnnTensorDescriptor_t   cyDesc,
    void                           *cy,
    void                           *workspace,
    size_t                          workSpaceSizeInBytes)
```

This routine executes the recurrent neural network described by **rnnDesc** with inputs **x**, **hx**, and **cx**, weights **w** and outputs **y**, **hy**, and **cy**. **workspace** is required for intermediate storage. This function does not store intermediate data required for training; **cudnnRNNForwardTraining()** should be used for that purpose.

**Parameters**

**handle**

*Input*. Handle to a previously created cuDNN context.

**rnnDesc**

*Input*. A previously initialized RNN descriptor.

**seqLength**

*Input*. Number of iterations to unroll over. The value of this **seqLength** must not exceed the value that was used in **cudnnGetRNNWorkspaceSize()** function for querying the workspace size required to execute the RNN.

**xDesc**

*Input*. An array of **seqLength** fully packed tensor descriptors. Each descriptor in the array should have three dimensions that describe the input data format to one recurrent iteration (one descriptor per RNN time-step). The first dimension (batch size) of the tensors may decrease from iteration \( n \) to iteration \( n+1 \) but may not increase. Each tensor descriptor must have the same second dimension (RNN input vector length, **inputSize**). The third dimension of each tensor should be 1. Input data are expected to be arranged in the column-major order so strides in **xDesc** should be set as follows:

```c
```
**x**

*Input.* Data pointer to GPU memory associated with the array of tensor descriptors `xDesc`. The input vectors are expected to be packed contiguously with the first vector of iteration (time-step) \( n+1 \) following directly from the last vector of iteration \( n \). In other words, input vectors for all RNN time-steps should be packed in the contiguous block of GPU memory with no gaps between the vectors.

**hxDesc**

*Input.* A fully packed tensor descriptor describing the initial hidden state of the RNN. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `xDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.

**hx**

*Input.* Data pointer to GPU memory associated with the tensor descriptor `hxDesc`. If a NULL pointer is passed, the initial hidden state of the network will be initialized to zero.

**cxDesc**

*Input.* A fully packed tensor descriptor describing the initial cell state for LSTM networks. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `xDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.

**cx**

*Input.* Data pointer to GPU memory associated with the tensor descriptor `cxDesc`. If a NULL pointer is passed, the initial cell state of the network will be initialized to zero.

**wDesc**

*Input.* Handle to a previously initialized filter descriptor describing the weights for the RNN.
w

*Input*. Data pointer to GPU memory associated with the filter descriptor `wDesc`.

**yDesc**

*Input*. An array of fully packed tensor descriptors describing the output from each recurrent iteration (one descriptor per iteration). The second dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the second dimension should match the `hiddenSize` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the second dimension should match double the `hiddenSize` argument.

The first dimension of the tensor `n` must match the first dimension of the tensor `n` in `xDesc`.

**y**

*Output*. Data pointer to GPU memory associated with the output tensor descriptor `yDesc`. The data are expected to be packed contiguously with the first element of iteration `n+1` following directly from the last element of iteration `n`.

**hyDesc**

*Input*. A fully packed tensor descriptor describing the final hidden state of the RNN. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `xDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.

**hy**

*Output*. Data pointer to GPU memory associated with the tensor descriptor `hyDesc`. If a NULL pointer is passed, the final hidden state of the network will not be saved.

**cyDesc**

*Input*. A fully packed tensor descriptor describing the final cell state for LSTM networks. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.
The second dimension must match the first dimension of the tensors described in xDesc. The third dimension must match the hiddenSize argument used to initialize rnnDesc. The tensor must be fully packed.

cy

Output. Data pointer to GPU memory associated with the tensor descriptor cyDesc. If a NULL pointer is passed, the final cell state of the network will not be saved.

workspace

Input. Data pointer to GPU memory to be used as a workspace for this call.

workSpaceSizeInBytes

Input. Specifies the size in bytes of the provided workspace.

Returns

CUDNN_STATUS_SUCCESS

The function launched successfully.

CUDNN_STATUS_NOT_SUPPORTED

The function does not support the provided configuration.

CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- The descriptor rnnDesc is invalid.
- At least one of the descriptors hxDesc, cxDesc, wDesc, hyDesc, cyDesc or one of the descriptors in xDesc, yDesc is invalid.
- The descriptors in one of xDesc, hxDesc, cxDesc, wDesc, yDesc, hyDesc, cyDesc have incorrect strides or dimensions.
- workSpaceSizeInBytes is too small.

CUDNN_STATUS_EXECUTION_FAILED

The function failed to launch on the GPU.

CUDNN_STATUS_ALLOC_FAILED

The function was unable to allocate memory.

7.2.38. cudnnRNNForwardInferenceEx()

This function has been deprecated in cuDNN 8.0. Use cudnnRNNForward() instead of cudnnRNNForwardInference().

```c

cudnnStatus_t cudnnRNNForwardInferenceEx(
    cudnnHandle_t                   handle,  
    const cudnnRNNDescriptor_t      rnnDesc, 
    const cudnnRNNDataDescriptor_t  xDesc, 
    const void                      *x, 
    const cudnnTensorDescriptor_t   hxDesc, 
    ...)
```
This routine is the extended version of the cudnnRNNForwardInference() function. The cudnnRNNForwardTrainingEx() function allows the user to use an unpacked (padded) layout for input x and output y. In the unpacked layout, each sequence in the mini-batch is considered to be of fixed length, specified by maxSeqLength in its corresponding RNNDataDescriptor. Each fixed-length sequence, for example, the nth sequence in the mini-batch, is composed of a valid segment, specified by the seqLengthArray[n] in its corresponding RNNDataDescriptor, and a padding segment to make the combined sequence length equal to maxSeqLength.

With unpacked layout, both sequence major (meaning, time major) and batch major are supported. For backward compatibility, the packed sequence major layout is supported. However, similar to the non-extended function cudnnRNNForwardInference(), the sequences in the mini-batch need to be sorted in descending order according to length.

Parameters

**handle**

*Input.* Handle to a previously created cuDNN context.

**rnnDesc**

*Input.* A previously initialized RNN descriptor.

**xDesc**

*Input.* A previously initialized RNN Data descriptor. The dataType, layout, maxSeqLength, batchSize, and seqLengthArray need to match that of yDesc.

**x**

*Input.* Data pointer to the GPU memory associated with the RNN data descriptor xDesc. The vectors are expected to be laid out in memory according to the layout specified by xDesc. The elements in the tensor (including elements in the padding vector) must be densely packed, and no strides are supported.
hxDesc

*Input.* A fully packed tensor descriptor describing the initial hidden state of the RNN. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the `batchSize` parameter described in `xDesc`. The third dimension depends on whether RNN mode is `CUDNN_LSTM` and whether LSTM projection is enabled. Specifically:

- If RNN mode is `CUDNN_LSTM` and LSTM projection is enabled, the third dimension must match the `recProjSize` argument passed to `cudnnSetRNNProjectionLayers()` call used to set `rnnDesc`.
- Otherwise, the third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`.

hx

*Input.* Data pointer to GPU memory associated with the tensor descriptor `hxDesc`. If a NULL pointer is passed, the initial hidden state of the network will be initialized to zero.

cxDesc

*Input.* A fully packed tensor descriptor describing the initial cell state for LSTM networks. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the `batchSize` parameter in `xDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`.

cx

*Input.* Data pointer to GPU memory associated with the tensor descriptor `cxDesc`. If a NULL pointer is passed, the initial cell state of the network will be initialized to zero.

wDesc

*Input.* Handle to a previously initialized filter descriptor describing the weights for the RNN.

w

*Input.* Data pointer to GPU memory associated with the filter descriptor `wDesc`. 
**yDesc**

*Input.* A previously initialized RNN data descriptor. The `dataType`, `layout`, `maxSeqLength`, `batchSize`, and `seqLengthArray` must match that of `dyDesc` and `dxDesc`. The parameter `vectorSize` depends on whether RNN mode is `CUDNN_LSTM` and whether LSTM projection is enabled and whether the network is bidirectional. Specifically:

- For unidirectional network, if the RNN mode is `CUDNN_LSTM` and LSTM projection is enabled, the parameter `vectorSize` must match the `recProjSize` argument passed to `cudnnSetRNNProjectionLayers()` call used to set `rnnDesc`. If the network is bidirectional, then multiply the value by 2.
- Otherwise, for a unidirectional network, the parameter `vectorSize` must match the `hiddenSize` argument used to initialize `rnnDesc`. If the network is bidirectional, then multiply the value by 2.

**y**

*Output.* Data pointer to the GPU memory associated with the RNN data descriptor `yDesc`. The vectors are expected to be laid out in memory according to the layout specified by `yDesc`. The elements in the tensor (including elements in the padding vector) must be densely packed, and no strides are supported.

**hyDesc**

*Input.* A fully packed tensor descriptor describing the final hidden state of the RNN. The descriptor must be set exactly the same way as `hxDesc`.

**hy**

*Output.* Data pointer to GPU memory associated with the tensor descriptor `hyDesc`. If a `NULL` pointer is passed, the final hidden state of the network will not be saved.

**cyDesc**

*Input.* A fully packed tensor descriptor describing the final cell state for LSTM networks. The descriptor must be set exactly the same way as `cxDesc`.

**cy**

*Output.* Data pointer to GPU memory associated with the tensor descriptor `cyDesc`. If a `NULL` pointer is passed, the final cell state of the network will not be saved.

**kDesc**

Reserved. User may pass in `NULL`.

**keys**

Reserved. Users may pass in `NULL`.

**cDesc**

Reserved. Users may pass in `NULL`.

**cAttn**

Reserved. Users may pass in `NULL`. 
iDesc
Reserved. Users may pass in NULL.

iAttn
Reserved. Users may pass in NULL.

qDesc
Reserved. Users may pass in NULL.

queries
Reserved. Users may pass in NULL.

workspace
*Input.* Data pointer to GPU memory to be used as a workspace for this call.

workSpaceSizeInBytes
*Input.* Specifies the size in bytes of the provided workspace.

Returns

**CUDNN_STATUS_SUCCESS**
The function launched successfully.

**CUDNN_STATUS_NOT_SUPPORTED**
At least one of the following conditions are met:

- Variable sequence length input is passed in while CUDNN_RNN_ALGO_PERSIST_STATIC or CUDNN_RNN_ALGO_PERSIST_DYNAMIC is used.
- CUDNN_RNN_ALGO_PERSIST_STATIC or CUDNN_RNN_ALGO_PERSIST_DYNAMIC is used on pre-Pascal devices.
- Double input/output is used for CUDNN_RNN_ALGO_PERSIST_STATIC.

**CUDNN_STATUS_BAD_PARAM**
At least one of the following conditions are met:

- The descriptor rnnDesc is invalid.
- At least one of the descriptors in xDesc, yDesc, hxDesc, cxDesc, wDesc, hyDesc, cyDesc is invalid, or have incorrect strides or dimensions.
- reserveSpaceSizeInBytes is too small.
- workSpaceSizeInBytes is too small.

**CUDNN_STATUS_EXECUTION_FAILED**
The function failed to launch on the GPU.

**CUDNN_STATUS_ALLOC_FAILED**
The function was unable to allocate memory.
7.2.39. **cudnnRNNGetClip()**

This function has been deprecated in cuDNN 8.0. Use `cudnnRNNGetClip_v8()` instead of `cudnnRNNGetClip()`.

```c
#include <cuda.hpp>

cudnnStatus_t cudnnRNNGetClip(
    cudnnHandle_t               handle,
    cudnnRNNDescriptor_t        rnnDesc,
    cudnnRNNClipMode_t          *clipMode,
    cudnnNanPropagation_t       *clipNanOpt,
    double                      *lclip,
    double                      *rclip);
```

Retrieves the current LSTM cell clipping parameters, and stores them in the arguments provided.

**Parameters**

*clipMode

*Output*. Pointer to the location where the retrieved `clipMode` is stored. The `clipMode` can be `CUDNN_RNN_CLIP_NONE` in which case no LSTM cell state clipping is being performed; or `CUDNN_RNN_CLIP_MINMAX`, in which case the cell state activation to other units are being clipped.

*lclip, rclip

*Output*. Pointers to the location where the retrieved LSTM cell clipping range 

\[lclip, rclip\]

is stored.

*clipNanOpt

*Output*. Pointer to the location where the retrieved `clipNanOpt` is stored.

**Returns**

- **CUDNN_STATUS_SUCCESS**
  The function launched successfully.

- **CUDNN_STATUS_BAD_PARAM**
  If any of the pointer arguments provided are `NULL`.

7.2.40. **cudnnRNNGetClip_v8()**

```c
#include <cuda.hpp>

cudnnStatus_t cudnnRNNGetClip_v8(
    cudnnRNNDescriptor_t        rnnDesc,
    cudnnRNNClipMode_t          *clipMode,
    cudnnNanPropagation_t       *clipNanOpt,
    double                      *lclip,
    double                      *rclip);
```

Retrieves the current LSTM cell clipping parameters, and stores them in the arguments provided. The user can assign `NULL` to any pointer except `rnnDesc` when the retrieved value is not needed. The function does not check the validity of retrieved parameters.
Parameters

rnnDesc

*Input.* A previously initialized RNN descriptor.

clipMode

*Output.* Pointer to the location where the retrieved cudnnRNNClipMode_t value is stored. The clipMode can be CUDNN_RNN_CLIP_NONE in which case no LSTM cell state clipping is being performed; or CUDNN_RNN_CLIP_MINMAX, in which case the cell state activation to other units are being clipped.

clipNanOpt

*Output.* Pointer to the location where the retrieved cudnnNanPropagation_t value is stored.

lclip, rclip

*Output.* Pointers to the location where the retrieved LSTM cell clipping range [lclip, rclip] is stored.

Returns

CUDNN_STATUS_SUCCESS

LSTM clipping parameters were successfully retrieved from the RNN descriptor.

CUDNN_STATUS_BAD_PARAM

An invalid input argument was found (rnnDesc was NULL).

### 7.2.41. cudnnRNNSetClip()

This function has been deprecated in cuDNN 8.0. Use cudnnRNNSetClip_v8() instead of cudnnRNNSetClip().

```c
  cudnnStatus_t cudnnRNNSetClip(
    cudnnHandle_t handle,
    cudnnRNNDescriptor_t rnnDesc,
    cudnnRNNClipMode_t clipMode,
    cudnnNanPropagation_t clipNanOpt,
    double lclip,
    double rclip);
```

Sets the LSTM cell clipping mode. The LSTM clipping is disabled by default. When enabled, clipping is applied to all layers. This cudnnRNNSetClip() function may be called multiple times.

Parameters

clipMode

*Input.* Enables or disables the LSTM cell clipping. When clipMode is set to CUDNN_RNN_CLIP_NONE no LSTM cell state clipping is performed. When clipMode is CUDNN_RNN_CLIP_MINMAX the cell state activation to other units is clipped.
7.2.42. **cudnnRNNSetClip_v8()**

Sets the LSTM cell clipping mode. The LSTM clipping is disabled by default. When enabled, clipping is applied to all layers. This `cudnnRNNSetClip()` function does not affect the work, reserve, and weight-space buffer sizes and may be called multiple times.

**Parameters**

- **rnnDesc**
  - *Input.* A previously initialized RNN descriptor.

- **clipMode**
  - *Input.* Enables or disables the LSTM cell clipping. When `clipMode` is set to `CUDNN_RNN_CLIP_NONE` no LSTM cell state clipping is performed. When `clipMode` is `CUDNN_RNN_CLIP_MINMAX` the cell state activation to other units is clipped.

- **clipNanOpt**
  - *Input.* When set to `CUDNN_PROPAGATE_NAN` (see the description for `cudnnNanPropagation_t`), NaN is propagated from the LSTM cell, or it can be set to one of the clipping range boundary values, instead of propagating.

- **lclip, rclip**
  - *Input.* The range `[lclip, rclip]` to which the LSTM cell clipping should be set.
Returns

**CUDNN_STATUS_SUCCESS**

The function completed successfully.

**CUDNN_STATUS_BAD_PARAM**

An invalid input argument was found, for example:

- `rnnDesc` was `NULL`
- `lclip > rclip`
- either `lclip` or `rclip` is `NaN`

**CUDNN_STATUS_BAD_PARAM**

The dimensions of the bias tensor refer to an amount of data that is incompatible with the output tensor dimensions or the `dataType` of the two tensor descriptors are different.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

### 7.2.43. `cudnnSetAttnDescriptor()`

```c
int cudnnSetAttnDescriptor(  
cudnnAttnDescriptor_t attnDesc,  
unsigned attnMode,  
int nHeads,  
double smScaler,  
cudnnDataType_t dataType,  
cudnnDataType_t computePrec,  
cudnnMathType_t mathType,  
cudnnDropoutDescriptor_t attnDropoutDesc,  
cudnnDropoutDescriptor_t postDropoutDesc,  
int qSize,  
int kSize,  
int vSize,  
int qProjSize,  
int kProjSize,  
int vProjSize,  
int oProjSize,  
int qoMaxSeqLength,  
int kvMaxSeqLength,  
int maxBatchSize,  
int maxBeamSize);
```

This function configures a multi-head attention descriptor that was previously created using the `cudnnCreateAttnDescriptor()` function. The function sets attention parameters that are necessary to compute internal buffer sizes, dimensions of weight and bias tensors, or to select optimized code paths.

Input sequence data descriptors in `cudnnMultiHeadAttnForward()`, `cudnnMultiHeadAttnBackwardData()` and `cudnnMultiHeadAttnBackwardWeights()` functions are checked against the configuration parameters stored in the attention descriptor. Some parameters must match exactly while max arguments such as `maxBatchSize` or `qoMaxSeqLength` establish upper limits for the corresponding dimensions.
The multi-head attention model can be described by the following equations:

\[
\mathbf{h}_i = (\mathbf{W}_V \mathbf{V}) \operatorname{softmax}\left(\text{smScaler}(\mathbf{K}^T \mathbf{W}_K) (\mathbf{W}_Q \mathbf{q})\right), \text{ for } i = 0 \ldots \text{nHeads} - 1
\]

\[
\text{MultiHeadAttn}(\mathbf{q}, \mathbf{K}, \mathbf{V}, \mathbf{W}_Q, \mathbf{W}_K, \mathbf{W}_V, \mathbf{W}_O) = \sum_{i=0}^{\text{nHeads}-1} \mathbf{W}_{Oi} \mathbf{h}_i
\]

Where:

- \(\text{nHeads}\) is the number of independent attention heads that evaluate \(\mathbf{h}_i\) vectors.
- \(\mathbf{q}\) is a primary input, a single \text{query} column vector.
- \(\mathbf{K}, \mathbf{V}\) are two matrices of \text{key} and \text{value} column vectors.

For simplicity, the above equations are presented using a single embedding vector \(\mathbf{q}\) but the API can handle multiple \(\mathbf{q}\) candidates in the beam search scheme, process \(\mathbf{q}\) vectors from multiple sequences bundled into a batch, or automatically iterate through all embedding vectors (time-steps) of a sequence. Thus, in general, \(\mathbf{q}, \mathbf{K}, \mathbf{V}\) inputs are tensors with additional pieces of information such as the active length of each sequence or how unused padding vectors should be saved.

In some publications, \(\mathbf{W}_{Oj}\) matrices are combined into one output projection matrix and \(\mathbf{h}_i\) vectors are merged explicitly into a single vector. This is an equivalent notation. In the library, \(\mathbf{W}_{Oj}\) matrices are conceptually treated the same way as \(\mathbf{W}_{Qj}, \mathbf{W}_{Kj}\) or \(\mathbf{W}_{Vj}\) input projection weights. See the description of the \text{cudnnGetMultiHeadAttnWeights()} function for more details.

Weight matrices \(\mathbf{W}_{Qj}, \mathbf{W}_{Kj}, \mathbf{W}_{Vj}\) and \(\mathbf{W}_{Oj}\) play similar roles, adjusting vector lengths in \(\mathbf{q}, \mathbf{K}, \mathbf{V}\) inputs and in the multi-head attention final output. The user can disable any or all projections by setting \(\text{qProjSize}, \text{kProjSize}, \text{vProjSize}\) or \(\text{oProjSize}\) arguments to zero.

Embedding vector sizes in \(\mathbf{q}, \mathbf{K}, \mathbf{V}\) and the vector lengths after projections need to be selected in such a way that matrix multiplications described above are feasible. Otherwise, \text{CUDNN_STATUS_BAD_PARAM} is returned by the \text{cudnnSetAttnDescriptor()} function. All four weight matrices are used when it is desirable to maintain rank deficiency of \(\mathbf{W}_{KQj} = \mathbf{W}_{Kj}^T \mathbf{W}_{Qj}\) or \(\mathbf{W}_{Oj} = \mathbf{W}_{Oj} \mathbf{W}_{Vj}\) matrices to eliminate one or more dimensions during linear transformations in each head. This is a form of feature extraction. In such cases, the projected sizes are smaller than the original vector lengths.

For each attention head, weight matrix sizes are defined as follows:

- \(\mathbf{W}_{Qj}\) - size \([\text{qProjSize} \times \text{qSize}], i = 0 \ldots \text{nHeads} - 1\)
- \(\mathbf{W}_{Kj}\) - size \([\text{kProjSize} \times \text{kSize}], i = 0 \ldots \text{nHeads} - 1, \text{kProjSize} = \text{qProjSize}\)
- \(\mathbf{W}_{Vj}\) - size \([\text{vProjSize} \times \text{vSize}], i = 0 \ldots \text{nHeads} - 1\)
- \(\mathbf{W}_{Oj}\) - size \([\text{oProjSize} \times (\text{vProjSize} > 0 ? \text{vProjSize} : \text{vSize})], i = 0 \ldots \text{nHeads} - 1\)

When the output projection is disabled \((\text{oProjSize} = 0)\), the output vector length is \(\text{nHeads} \times (\text{vProjSize} > 0 ? \text{vProjSize} : \text{vSize})\), meaning, the output is a concatenation of all \(\mathbf{h}_i\) vectors. In the alternative interpretation, a concatenated matrix \(\mathbf{W}_O = [\mathbf{W}_{O,0}, \mathbf{W}_{O,1}, \mathbf{W}_{O,2} \ldots]\) forms the identity matrix.
Softmax is a normalized, exponential vector function that takes and outputs vectors of the same size. The multi-head attention API utilizes softmax of the CUDNN_SOFTMAX_ACCURATE type to reduce the likelihood of the floating-point overflow.

The smScaler parameter is the softmax sharpening/smoothing coefficient. When smScaler=1.0, softmax uses the natural exponential function $\exp(x)$ or $2.7183^x$. When smScaler<1.0, for example smScaler=0.2, the function used by the softmax block will not grow as fast because $\exp(0.2^x) \approx 1.2214^x$.

The smScaler parameter can be adjusted to process larger ranges of values fed to softmax. When the range is too large (or smScaler is not sufficiently small for the given range), the output vector of the softmax block becomes categorical, meaning, one vector element is close to 1.0 and other outputs are zero or very close to zero. When this occurs, the Jacobian matrix of the softmax block is also close to zero so deltas are not back-propagated during training from output to input except through residual connections, if these connections are enabled. The user can set smScaler to any positive floating-point value or even zero. The smScaler parameter is not trainable.

The qoMaxSeqLength, kvMaxSeqLength, maxBatchSize, and maxBeamSize arguments declare the maximum sequence lengths, maximum batch size, and maximum beam size respectively, in the cudnnSeqDataDescriptor_t containers. The actual dimensions supplied to forward and backward (gradient) API functions should not exceed the max limits. The max arguments should be set carefully because too large values will result in excessive memory usage due to oversized work and reserve space buffers.

The attnMode argument is treated as a binary mask where various on/off options are set. These options can affect the internal buffer sizes, enforce certain argument checks, select optimized code execution paths, or enable attention variants that do not require additional numerical arguments. An example of such options is the inclusion of biases in input and output projections.

The attnDropoutDesc and postDropoutDesc arguments are descriptors that define two dropout layers active in the training mode. The first dropout operation defined by attnDropoutDesc, is applied directly to the softmax output. The second dropout operation, specified by postDropoutDesc, alters the multi-head attention output, just before the point where residual connections are added.

Note: The cudnnSetAttnDescriptor() function performs a shallow copy of attnDropoutDesc and postDropoutDesc, meaning, the addresses of both dropout descriptors are stored in the attention descriptor and not the entire structure. Therefore, the user should keep dropout descriptors during the entire life of the attention descriptor.

Parameters

**attnDesc**

Output. Attention descriptor to be configured.

**attnMode**

Input. Enables various attention options that do not require additional numerical values. See the table below for the list of supported flags. The user should assign a preferred set of bitwise OR-ed flags to this argument.
nHeads
Input. Number of attention heads.

smScaler
Input. Softmax smoothing \([1.0 \geq \text{smScaler} \geq 0.0]\) or sharpening \(\text{smScaler} > 1.0\) coefficient. Negative values are not accepted.

dataType
Input. Data type used to represent attention inputs, attention weights and attention outputs.

computePrec
Input. Compute precision.

mathType
Input. NVIDIA Tensor Core settings.

attnDropoutDesc
Input. Descriptor of the dropout operation applied to the softmax output. See the table below for a list of unsupported features.

postDropoutDesc
Input. Descriptor of the dropout operation applied to the multi-head attention output, just before the point where residual connections are added. See the table below for a list of unsupported features.

qSize, kSize, vSize
Input. Q, K, V embedding vector lengths.

qProjSize, kProjSize, vProjSize
Input. Q, K, V embedding vector lengths after input projections. Use zero to disable the corresponding projection.

oProjSize
Input. The \(h_\text{t}\) vector length after the output projection. Use zero to disable this projection.

qoMaxSeqLength
Input. Largest sequence length expected in sequence data descriptors related to Q, O, dQ and dO inputs and outputs.

kvMaxSeqLength
Input. Largest sequence length expected in sequence data descriptors related to K, V, dK and dV inputs and outputs.

maxBatchSize
Input. Largest batch size expected in any cudnnSeqDataDescriptor_t container.

maxBeamSize
Input. Largest beam size expected in any cudnnSeqDataDescriptor_t container.
Supported `attnMode` flags

**CUDNN_ATTN_QUERYMAP_ALL_TO_ONE**

Forward declaration of mapping between \( Q \) and \( K, V \) vectors when the beam size is greater than one in the \( Q \) input. Multiple \( Q \) vectors from the same beam bundle map to the same \( K, V \) vectors. This means that beam sizes in the \( K, V \) sets are equal to one.

**CUDNN_ATTN_QUERYMAP_ONE_TO_ONE**

Forward declaration of mapping between \( Q \) and \( K, V \) vectors when the beam size is greater than one in the \( Q \) input. Multiple \( Q \) vectors from the same beam bundle map to different \( K, V \) vectors. This requires beam sizes in \( K, V \) sets to be the same as in the \( Q \) input.

**CUDNN_ATTN_DISABLE_PROJ_BIASES**

Use no biases in the attention input and output projections.

**CUDNN_ATTN_ENABLE_PROJ_BIASES**

Use extra biases in the attention input and output projections. In this case the projected \( \tilde{K} \) vectors are computed as \( \tilde{K}_i = W_{Kj}K + b^* [1, 1, \ldots, 1]_{\text{on}} \), where \( n \) is the number of columns in the \( K \) matrix. In other words, the same column vector \( b \) is added to all columns of \( K \) after the weight matrix multiplication.

**Supported combinations of `dataType`, `computePrec`, and `mathType`**

<table>
<thead>
<tr>
<th><code>dataType</code></th>
<th><code>computePrec</code></th>
<th><code>mathType</code></th>
</tr>
</thead>
<tbody>
<tr>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DATA_DOUBLE</td>
<td>CUDNN_DEFAULT_MATH</td>
</tr>
<tr>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DATA_FLOAT</td>
<td>CUDNN_DEFAULT_MATH, CUDNN_TENSOR_OP_MATH</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CUDNN_TENSOR_OP_MATH_ALLOW_CONVERSION</td>
</tr>
<tr>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DATA_HALF</td>
<td>CUDNN_DEFAULT_MATH, CUDNN_TENSOR_OP_MATH</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CUDNN_TENSOR_OP_MATH_ALLOW_CONVERSION</td>
</tr>
</tbody>
</table>

**Unsupported features**

1. The dropout option is currently not supported by the multi-head attention API. Assign `NULL` to `attnDropoutDesc` and `postDropoutDesc` arguments when configuring the attention descriptor.

2. The `CUDNN_ATTN_ENABLE_PROJ_BIASES` option is not supported in the multi-head attention gradient functions.

3. The `paddingFill` argument in `cudnnSeqDataDescriptor_t` is currently ignored by all multi-head attention functions.
Returns

**CUDNN_STATUS_SUCCESS**

The attention descriptor was configured successfully.

**CUDNN_STATUS_BAD_PARAM**

An invalid input argument was encountered. Some examples include:

- post projection $Q$ and $K$ sizes were not equal
- `dataType`, `computePrec`, or `mathType` were invalid
- one or more of the following arguments were either negative or zero: `nHeads`, `qSize`, `kSize`, `vSize`, `qoMaxSeqLength`, `kvMaxSeqLength`, `maxBatchSize`, `maxBeamSize`
- one or more of the following arguments were negative: `qProjSize`, `kProjSize`, `vProjSize`, `smScaler`

**CUDNN_STATUS_NOT_SUPPORTED**

A requested option or a combination of input arguments is not supported.

7.2.44. **cudnnSetPersistentRNNPlan()**

This function has been deprecated in cuDNN 8.0.

```c
void cudnnSetPersistentRNNPlan(
    cudnnRNNDescriptor_t        rnnDesc,
    cudnnPersistentRNNPlan_t    plan)
```

This function sets the persistent RNN plan to be executed when using `rnnDesc` and `CUDNN_RNN_ALGO_PERSIST_DYNAMIC` `algo`.

Returns

**CUDNN_STATUS_SUCCESS**

The plan was set successfully.

**CUDNN_STATUS_BAD_PARAM**

The algo selected in `rnnDesc` is not `CUDNN_RNN_ALGO_PERSIST_DYNAMIC`.

7.2.45. **cudnnSetRNNAlgorithmDescriptor()**

This function has been deprecated in cuDNN 8.0.

7.2.46. **cudnnSetRNNBiasMode()**

This function has been deprecated in cuDNN 8.0. Use `cudnnSetRNNDescriptor_v8()` instead of `cudnnSetRNNBiasMode()`.

```c
void cudnnSetRNNBiasMode(
    cudnnRNNDescriptor_t        rnnDesc,
    cudnnRNNBiasMode_t           biasMode)
```
The cudnnSetRNNBiasMode() function sets the number of bias vectors for a previously created and initialized RNN descriptor. This function should be called to enable the specified bias mode in an RNN. The default value of biasMode in rnnDesc after cudnnCreateRNNDescriptor() is CUDNN_RNN_DOUBLE_BIAS.

Parameters

rnnDesc

*Input/Output.* A previously created RNN descriptor.

biasMode

*Input.* Sets the number of bias vectors. For more information, see cudnnRNNBiasMode_t.

Returns

CUDNN_STATUS_BAD_PARAM

Either the rnnDesc is NULL or biasMode has an invalid enumerant value.

CUDNN_STATUS_SUCCESS

The biasMode was set successfully.

CUDNN_STATUS_NOT_SUPPORTED

Non-default bias mode [an enumerated type besides CUDNN_RNN_DOUBLE_BIAS] applied to an RNN algo other than CUDNN_RNN_ALGO_STANDARD.

7.2.47. cudnnSetRNNDataDescriptor()

cudnnStatus_t cudnnSetRNNDataDescriptor(
    cudnnRNNDataDescriptor_t RNNDataDesc,
    cudnnDataType_t dataType,
    cudnnRNNDataLayout_t layout,
    int maxSeqLength,
    int batchSize,
    int vectorSize,
    const int seqLengthArray[],
    void *paddingFill);

This function initializes a previously created RNN data descriptor object. This data structure is intended to support the unpacked [padded] layout for input and output of extended RNN inference and training functions. A packed [unpadded] layout is also supported for backward compatibility.

Parameters

RNNDataDesc

*Input/Output.* A previously created RNN descriptor. For more information, see cudnnRNNDataDescriptor_t.

dataType

*Input.* The datatype of the RNN data tensor. For more information, see cudnnDataType_t.
**layout**

*Input.* The memory layout of the RNN data tensor.

**maxSeqLength**

*Input.* The maximum sequence length within this RNN data tensor. In the unpacked (padded) layout, this should include the padding vectors in each sequence. In the packed (unpadded) layout, this should be equal to the greatest element in `seqLengthArray`.

**batchSize**

*Input.* The number of sequences within the mini-batch.

**vectorSize**

*Input.* The vector length (embedding size) of the input or output tensor at each time-step.

**seqLengthArray**

*Input.* An integer array with `batchSize` number of elements. Describes the length [number of time-steps] of each sequence. Each element in `seqLengthArray` must be greater than 0 but less than or equal to `maxSeqLength`. In the packed layout, the elements should be sorted in descending order, similar to the layout required by the non-extended RNN compute functions.

**paddingFill**

*Input.* A user-defined symbol for filling the padding position in RNN output. This is only effective when the descriptor is describing the RNN output, and the unpacked layout is specified. The symbol should be in the host memory, and is interpreted as the same data type as that of the RNN data tensor. If a NULL pointer is passed in, then the padding position in the output will be undefined.

**Returns**

**CUDNN_STATUS_SUCCESS**

The object was set successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

dataType is not one of CUDNN_DATA_HALF, CUDNN_DATA_FLOAT or CUDNN_DATA_DOUBLE.

**CUDNN_STATUS_BAD_PARAM**

Any one of these have occurred:

- RNNDesc is NULL.
- Any one of `maxSeqLength`, `batchSize` or `vectorSize` is less than or equal to zero.
- An element of `seqLengthArray` is less than or equal to zero or greater than `maxSeqLength`.
- Layout is not one of CUDNN_RNN_DATA_LAYOUT_SEQ_MAJOR_UNPACKED, CUDNN_RNN_DATA_LAYOUT_SEQ_MAJOR_PACKED or CUDNN_RNN_DATA_LAYOUT_BATCH_MAJOR_UNPACKED.
CUDNN_STATUS_ALLOC_FAILED

The allocation of internal array storage has failed.

7.2.48. cudnnSetRNNDescriptor_v6()

This function has been deprecated in cuDNN 8.0. Use cudnnSetRNNDescriptor_v8() instead of cudnnSetRNNDescriptor_v6().

```
cudnnStatus_t cudnnSetRNNDescriptor_v6(
    cudnnHandle_t                    handle,
    cudnnRNNDescriptor_t             rnnDesc,
    const int                        hiddenSize,
    const int                        numLayers,
    cudnnDropoutDescriptor_t         dropoutDesc,
    cudnnRNNInputMode_t              inputMode,
    cudnnDirectionMode_t             direction,
    cudnnRNNMode_t                   mode,
    cudnnRNNAlgo_t                   algo,
    cudnnDataType_t                  mathPrec)
```

This function initializes a previously created RNN descriptor object.

Note: Larger networks, for example, longer sequences or more layers, are expected to be more efficient than smaller networks.

Parameters

**handle**

*Input.* Handle to a previously created cuDNN library descriptor.

**rnnDesc**

*Input/Output.* A previously created RNN descriptor.

**hiddenSize**

*Input.* Size of the internal hidden state for each layer.

**numLayers**

*Input.* Number of stacked layers.

**dropoutDesc**

*Input.* Handle to a previously created and initialized dropout descriptor. Dropout will be applied between layers, for example, a single layer network will have no dropout applied.

**inputMode**

*Input.* Specifies the behavior at the input to the first layer.

**direction**

*Input.* Specifies the recurrence pattern, for example, bidirectional.

**mode**

*Input.* Specifies the type of RNN to compute.
**algo**

*Input.* Specifies which RNN algorithm should be used to compute the results.

**mathPrec**

*Input.* Math precision. This parameter is used for controlling the math precision in RNN. The following applies:

- For the input/output in FP16, the parameter `mathPrec` can be `CUDNN_DATA_HALF` or `CUDNN_DATA_FLOAT`.
- For the input/output in FP32, the parameter `mathPrec` can only be `CUDNN_DATA_FLOAT`.
- For the input/output in FP64, double type, the parameter `mathPrec` can only be `CUDNN_DATA_DOUBLE`.

**Returns**

**CUDNN_STATUS_SUCCESS**

The object was set successfully.

**CUDNN_STATUS_BAD_PARAM**

Either at least one of the parameters `hiddenSize` or `numLayers` was zero or negative, one of `inputMode`, `direction`, `mode`, `algo` or `dataType` has an invalid enumerant value, `dropoutDesc` is an invalid dropout descriptor or `rnnDesc` has not been created correctly.

### 7.2.49. `cudnnSetRNNDescriptor_v8()`

cudnnStatus_t cudnnSetRNNDescriptor_v8(
        cudnnRNNDescriptor_t rnnDesc,
        cudnnRNNAlgo_t algo,
        cudnnRNNMode_t cellMode,
        cudnnRNNBiasMode_t biasMode,
        cudnnDirectionMode_t dirMode,
        cudnnRNNInputMode_t inputMode,
        cudnnDataType_t dataType,
        cudnnDataType_t mathPrec,
        cudnnMathType_t mathType,
        int32_t inputSize,
        int32_t hiddenSize,
        int32_t projSize,
        int32_t numLayers,
        cudnnDropoutDescriptor_t dropoutDesc,
        uint32_t auxFlags);

This function initializes a previously created RNN descriptor object. The RNN descriptor configured by `cudnnSetRNNDescriptor_v8()` was enhanced to store all information needed to compute the total number of adjustable weights/biases in the RNN model.

**Parameters**

**rnnDesc**

*Input.* A previously initialized RNN descriptor.
algo

Input. RNN algo (CUDNN_RNN_ALGO_STANDARD, CUDNN_RNN_ALGO_PERSIST_STATIC, or CUDNN_RNN_ALGO_PERSIST_DYNAMIC).

cellMode

Input. Specifies the RNN cell type in the entire model (RELU, TANH, LSTM, GRU).

biasMode

Input. Sets the number of bias vectors (CUDNN_RNN_NO_BIAS, CUDNN_RNN_SINGLE_INP_BIAS, CUDNN_RNN_SINGLE_REC_BIAS, CUDNN_RNN_DOUBLE_BIAS). The two single bias settings are functionally the same for RELU, TANH and LSTM cell types. For differences in GRU cells, see the description of CUDNN_GRU in the cudnnRNNMode_t enumerated type.

dirMode

Input. Specifies the recurrence pattern: CUDNN_UNIDIRECTIONAL or CUDNN_BIDIRECTIONAL. In bidirectional RNNs, the hidden states passed between physical layers are concatenations of forward and backward hidden states.

inputMode

Input. Specifies how the input to the RNN model is processed by the first layer. When inputMode is CUDNN_LINEAR_INPUT, original input vectors of size inputSize are multiplied by the weight matrix to obtain vectors of hiddenSize. When inputMode is CUDNN_SKIP_INPUT, the original input vectors to the first layer are used as is without multiplying them by the weight matrix.

dataType

Input. Specifies data type for RNN weights/biases and input and output data.

mathPrec

Input. This parameter is used to control the compute math precision in the RNN model. The following applies:

- For the input/output in FP16, the parameter mathPrec can be CUDNN_DATA_HALF or CUDNN_DATA_FLOAT.
- For the input/output in FP32, the parameter mathPrec can only be CUDNN_DATA_FLOAT.
- For the input/output in FP64, double type, the parameter mathPrec can only be CUDNN_DATA_DOUBLE.

mathType

Input. Sets the preferred option to use NVIDIA Tensor Cores accelerators on Volta (SM 7.0) or higher GPU-s.

- When dataType is CUDNN_DATA_HALF, the mathType parameter can be CUDNN_DEFAULT_MATH or CUDNN_TENSOR_OP_MATH. The ALLOW_CONVERSION setting is treated the same CUDNN_TENSOR_OP_MATH for this data type.
When `dataType` is `CUDNN_DATA_FLOAT`, the `mathType` parameter can be `CUDNN_DEFAULT_MATH` or `CUDNN_TENSOR_OP_MATH_ALLOW_CONVERSION`. When the latter settings are used, original weights and intermediate results will be down-converted to `CUDNN_DATA_HALF` before they are used in another recursive iteration.

When `dataType` is `CUDNN_DATA_DOUBLE`, the `mathType` parameter can be `CUDNN_DEFAULT_MATH`.

This option has an advisory status meaning Tensor Cores may not be always utilized, for example, due to specific GEMM dimensions restrictions.

**inputSize**

*Input.* Size of the input vector in the RNN model. When the `inputMode`=`CUDNN_SKIP_INPUT`, the `inputSize` should match the `hiddenSize` value.

**hiddenSize**

*Input.* Size of the hidden state vector in the RNN model. The same hidden size is used in all RNN layers.

**projSize**

*Input.* The size of the LSTM cell output after the recurrent projection. This value should not be larger than `hiddenSize`. It is legal to set `projSize` equal to `hiddenSize`, however, in this case, the recurrent projection feature is disabled. The recurrent projection is an additional matrix multiplication in the LSTM cell to project hidden state vectors $h_t$ into smaller vectors $r_t = W_r h_t$, where $W_r$ is a rectangular matrix with `projSize` rows and `hiddenSize` columns. When the recurrent projection is enabled, the output of the LSTM cell (both to the next layer and unrolled in-time) is $r_t$ instead of $h_t$. The recurrent projection can be enabled for LSTM cells and `CUDNN_RNN_ALGO_STANDARD` only.

**numLayers**

*Input.* Number of stacked, physical layers in the deep RNN model. When `dirMode`=`CUDNN_BIDIRECTIONAL`, the physical layer consists of two pseudo-layers corresponding to forward and backward directions.

**dropoutDesc**

*Input.* Handle to a previously created and initialized dropout descriptor. Dropout operation will be applied between physical layers. A single layer network will have no dropout applied. Dropout is used in the training mode only.

**auxFlags**

*Input.* This argument is used to pass miscellaneous switches that do not require additional numerical values to configure the corresponding feature. In future cuDNN releases, this parameter will be used to extend the RNN functionality without adding new API functions (applicable options should be bitwise OR-ed). Currently, this parameter is used to enable or disable padded input/output ([`CUDNN_RNN_PADDED_IO_DISABLED`, `CUDNN_RNN_PADDED_IO_ENABLED`]). When the padded I/O is enabled, layouts `CUDNN_RNN_DATA_LAYOUT_SEQ_MAJOR_UNPACKED`
and CUDNN_RNN_DATA_LAYOUT_BATCH_MAJOR_UNPACKED are permitted in RNN data descriptors.

**Returns**

**CUDNN_STATUS_SUCCESS**

The RNN descriptor was configured successfully.

**CUDNN_STATUS_BAD_PARAM**

An invalid input argument was detected.

**CUDNN_STATUS_NOT_SUPPORTED**

The dimensions of the bias tensor refer to an amount of data that is incompatible with the output tensor dimensions or the dataType of the two tensor descriptors are different.

**CUDNN_STATUS_EXECUTION_FAILED**

An incompatible or unsupported combination of input arguments was detected.

### 7.2.50. cudnnSetRNNMatrixMathType()

This function has been deprecated in cuDNN 8.0. Use cudnnSetRNNDescriptor_v8() instead of cudnnSetRNNMatrixMathType().

```c
#include <cutensor.h>

CUDNN_err_t cudnnSetRNNMatrixMathType(cudnnRNNDescriptor_t rnnDesc, cudnnMathType_t mType)
```

This function sets the preferred option to use NVIDIA Tensor Cores accelerators on Volta GPUs [SM 7.0 or higher]. When the mType parameter is CUDNN_TENSOR_OP_MATH, inference and training RNN APIs will attempt use Tensor Cores when weights/ biases are of type CUDNN_DATA_HALF or CUDNN_DATA_FLOAT. When RNN weights/ biases are stored in the CUDNN_DATA_FLOAT format, the original weights and intermediate results will be down- converted to CUDNN_DATA_HALF before they are used in another recursive iteration.

**Parameters**

**rnnDesc**

*Input.* A previously created and initialized RNN descriptor.

**mType**

*Input.* A preferred compute option when performing RNN GEMMs (general matrix-matrix multiplications). This option has an advisory status meaning that Tensor Cores may not be utilized, for example, due to specific GEMM dimensions.

**Returns**

**CUDNN_STATUS_SUCCESS**

The preferred compute option for the RNN network was set successfully.
7.2.51. cudnnSetRNNPaddingMode()

This function has been deprecated in cuDNN 8.0. Use cudnnSetRNNDescriptor_v8() instead of cudnnSetRNNPaddingMode().

```
cudnnStatus_t cudnnSetRNNPaddingMode(
    cudnnRNNDescriptor_t        rnnDesc,
    cudnnRNNPaddingMode_t       paddingMode)
```

This function enables or disables the padded RNN input/output for a previously created and initialized RNN descriptor. This information is required before calling the cudnnGetRNNWorkspaceSize() and cudnnGetRNNTrainingReserveSize() functions, to determine whether additional workspace and training reserve space is needed. By default, the padded RNN input/output is not enabled.

Parameters

rnnDesc

*Input/Output.* A previously created RNN descriptor.

paddingMode

*Input.* Enables or disables the padded input/output. For more information, see cudnnRNNPaddingMode_t.

Returns

CUDNN_STATUS_SUCCESS

The paddingMode was set successfully.

CUDNN_STATUS_BAD_PARAM

Either the rnnDesc is NULL or paddingMode has an invalid enumerant value.

7.2.52. cudnnSetRNNProjectionLayers()

This function has been deprecated in cuDNN 8.0. Use cudnnSetRNNDescriptor_v8() instead of cudnnSetRNNProjectionLayers().

```
cudnnStatus_t cudnnSetRNNProjectionLayers(
    cudnnHandle_t           handle,
    cudnnRNNDescriptor_t    rnnDesc,
    int                     recProjSize,
    int                     outProjSize)
```

The cudnnSetRNNProjectionLayers() function should be called to enable the recurrent and/or output projection in a recursive neural network. The recurrent projection is an additional matrix multiplication in the LSTM cell to project hidden state vectors $h_t$ into smaller vectors $r_t = W_r h_t$, where $W_r$ is a rectangular matrix with $\text{recProjSize}$ rows and $\text{hiddenSize}$ columns. When the recurrent projection is enabled, the output of the LSTM cell (both to the
next layer and unrolled in-time) is r\_t instead of h\_t. The dimensionality of i\_t, f\_t, o\_t, and c\_t vectors used in conjunction with non-linear functions remains the same as in the canonical LSTM cell. To make this possible, the shapes of matrices in the LSTM formulas (see cudnnRNNMode\_t type), such as W\_i in hidden RNN layers or R\_i in the entire network, become rectangular versus square in the canonical LSTM mode. Obviously, the result of R\_i* W\_i is a square matrix but it is rank deficient, reflecting the compression of LSTM output. The recurrent projection is typically employed when the number of independent (adjustable) weights in the RNN network with projection is smaller in comparison to canonical LSTM for the same hiddenSize value.

The recurrent projection can be enabled for LSTM cells and cudnn\_RNN\_ALGO\_STANDARD only. The recProjSize parameter should be smaller than the hiddenSize value. It is legal to set recProjSize equal to hiddenSize but in that case the recurrent projection feature is disabled.

The output projection is currently not implemented.

For more information on the recurrent and output RNN projections, see the paper by Hasim Sak, et al.: Long Short-Term Memory Based Recurrent Neural Network Architectures For Large Vocabulary Speech Recognition.

Parameters

**handle**

*Input.* Handle to a previously created cuDNN library descriptor.

**rnnDesc**

*Input.* A previously created and initialized RNN descriptor.

**recProjSize**

*Input.* The size of the LSTM cell output after the recurrent projection. This value should not be larger than hiddenSize.

**outProjSize**

*Input.* This parameter should be zero.

Returns

**CUDNN\_STATUS\_SUCCESS**

RNN projection parameters were set successfully.

**CUDNN\_STATUS\_BAD\_PARAM**

An invalid input argument was detected (for example, NULL handles, negative values for projection parameters).

**CUDNN\_STATUS\_NOT\_SUPPORTED**

Projection applied to RNN algo other than cudnn\_RNN\_ALGO\_STANDARD, cell type other than cudnn\_LSTM, recProjSize larger than hiddenSize.
7.2.53. **cudnnSetSeqDataDescriptor()**

```c
const cudnnStatus_t cudnnSetSeqDataDescriptor(
    const cudnnSeqDataDescriptor_t seqDataDesc,
    cudnnDataType_t dataType,
    int nbDims,
    const int dimA[],
    const cudnnSeqDataAxis_t axes[],
    size_t seqLengthArraySize,
    const int seqLengthArray[],
    void *paddingFill);
```

This function initializes a previously created sequence data descriptor object. In the most simplified view, this descriptor defines dimensions \( \text{dimA} \) and the data layout \( \text{axes} \) of a four-dimensional tensor. All four dimensions of the sequence data descriptor have unique identifiers that can be used to index the \( \text{dimA}[] \) array:

- `CUDNN_SEQDATA_TIME_DIM`
- `CUDNN_SEQDATA_BATCH_DIM`
- `CUDNN_SEQDATA_BEAM_DIM`
- `CUDNN_SEQDATA_VECT_DIM`

For example, to express information that vectors in our sequence data buffer are five elements long, we need to assign \( \text{dimA}[\text{CUDNN_SEQDATA_VECT_DIM}]=5 \) in the \( \text{dimA}[] \) array.

The number of active dimensions in the \( \text{dimA}[] \) and \( \text{axes}[] \) arrays is defined by the \( \text{nbDims} \) argument. Currently, the value of this argument should be four. The actual size of the \( \text{dimA}[] \) and \( \text{axes}[] \) arrays should be declared using the `CUDNN_SEQDATA_DIM_COUNT` macro.

The `cudnnSeqDataDescriptor_t` container is treated as a collection of fixed length vectors that form sequences, similarly to words (vectors of characters) constructing sentences. The `TIME` dimension spans the sequence length. Different sequences are bundled together in a batch. A `BATCH` may be a group of individual sequences or beams. A `BEAM` is a cluster of alternative sequences or candidates. When thinking about the beam, consider a translation task from one language to another. You may want to keep around and experiment with several translated versions of the original sentence before selecting the best one. The number of candidates kept around is the `BEAM` size.

Every sequence can have a different length, even within the same beam, so vectors toward the end of the sequence can be just padding. The `paddingFill` argument specifies how the padding vectors should be written in output sequence data buffers. The `paddingFill` argument points to one value of type `dataType` that should be copied to all elements in padding vectors. Currently, the only supported value for `paddingFill` is `NULL` which means this option should be ignored. In this case, elements of the padding vectors in output buffers will have undefined values.

It is assumed that a non-empty sequence always starts from the time index zero. The `seqLengthArray[]` must specify all sequence lengths in the container so the total size of this array should be \( \text{dimA}[\text{CUDNN_SEQDATA_BATCH_DIM}] \times \text{dimA}[\text{CUDNN_SEQDATA_BEAM_DIM}] \). Each element of the `seqLengthArray[]` array should have a non-negative value, less than or equal to \( \text{dimA}[\text{CUDNN_SEQDATA_TIME_DIM}] \); the maximum sequence length. Elements in `seqLengthArray[]` are always arranged in the same batch-major order, meaning, when considering `BEAM` and `BATCH` dimensions, `BATCH` is the outer or the slower changing index.
when we traverse the array in ascending order of the addresses. Using a simple example, the `seqLengthArray[]` array should hold sequence lengths in the following order:

{batch_idx=0, beam_idx=0}
{batch_idx=0, beam_idx=1}
{batch_idx=1, beam_idx=0}
{batch_idx=1, beam_idx=1}
{batch_idx=2, beam_idx=0}
{batch_idx=2, beam_idx=1}


Data stored in the `cudnnSeqDataDescriptor_t` container must comply with the following constraints:

- All data is fully packed. There are no unused spaces or gaps between individual vector elements or consecutive vectors.
- The most inner dimension of the container is the vector. In other words, the first contiguous group of `dimA[CUDNN_SEQDATA_VECT_DIM]` elements belongs to the first vector, followed by elements of the second vector, and so on.

The `axes` argument in the `cudnnSetSeqDataDescriptor()` function is a bit more complicated. This array should have the same capacity as `dimA[]`. The `axes[]` array specifies the actual data layout in the GPU memory. In this function, the layout is described in the following way: as we move from one element of a vector to another in memory by incrementing the element pointer, what is the order of `VECT`, `TIME`, `BATCH`, and `BEAM` dimensions that we encounter. Let us assume that we want to define the following data layout:

```
  int dimA[CUDNN_SEQDATA_DIM_COUNT];
dimA[CUDNN_SEQDATA_TIME_DIM]  = 4;
dimA[CUDNN_SEQDATA_BATCH_DIM] = 3;
dimA[CUDNN_SEQDATA_BEAM_DIM]  = 2;
dimA[CUDNN_SEQDATA_VECT_DIM]  = 5;
```

Now, let’s initialize the `axes[]` array. Note that the most inner dimension is described by the last active element of `axes[]`. There is only one valid configuration here as we always traverse a full vector first. Thus, we need to write `CUDNN_SEQDATA_VECT_DIM` in the last active element of `axes[]`.

```
cudnnSeqDataAxis_t axes[CUDNN_SEQDATA_DIM_COUNT];
axes[3] = CUDNN_SEQDATA_VECT_DIM;  // 3 = nbDims-1
```

Now, let’s work on the remaining three elements of `axes[]`. When we reach the end of the first vector, we jump to the next beam, therefore:

```
axes[2] = CUDNN_SEQDATA_BEAM_DIM;
```
When we approach the end of the second vector, we move to the next batch, therefore:

\[ \text{axes}[1] = \text{CUDNN_SEQDATA_BATCH_DIM}; \]

The last [outermost] dimension is \( \text{TIME} \):

\[ \text{axes}[0] = \text{CUDNN_SEQDATA_TIME_DIM}; \]

The four values of the \( \text{axes[]} \) array fully describe the data layout depicted in the figure.

The sequence data descriptor allows the user to select \( 3! = 6 \) different data layouts or permutations of \( \text{BEAM}, \text{BATCH} \) and \( \text{TIME} \) dimensions. The multi-head attention API supports all six layouts.

Parameters

- **seqDataDesc**
  - Output. Pointer to a previously created sequence data descriptor.

- **dataType**
  - Input. Data type of the sequence data buffer (CUDNN_DATA_HALF, CUDNN_DATA_FLOAT or CUDNN_DATA_DOUBLE).

- **nbDims**
  - Input. Must be 4. The number of active dimensions in \( \text{dimA[]} \) and \( \text{axes[]} \) arrays. Both arrays should be declared to contain at least CUDNN_SEQDATA_DIM_COUNT elements.

- **dimA[]**
  - Input. Integer array specifying sequence data dimensions. Use the cudnnSeqDataAxis_t enumerated type to index all active \( \text{dimA[]} \) elements.

- **axes[]**
  - Input. Array of cudnnSeqDataAxis_t that defines the layout of sequence data in memory. The first \( \text{nbDims} \) elements of \( \text{axes[]} \) should be initialized with the outermost dimension in \( \text{axes}[0] \) and the innermost dimension in \( \text{axes}[\text{nbDims}-1] \).

- **seqLengthArraySize**
  - Input. Number of elements in the sequence length array, \( \text{seqLengthArray[]} \).

- **seqLengthArray[]**
  - Input. An integer array that defines all sequence lengths of the container.

- **paddingFill**
  - Input. Must be NULL. Pointer to a value of \( \text{dataType} \) that is used to fill up output vectors beyond the valid length of each sequence or NULL to ignore this setting.

Returns

- **CUDNN_STATUS_SUCCESS**
  - All input arguments were validated and the sequence data descriptor was successfully updated.

- **CUDNN_STATUS_BAD_PARAM**
  - An invalid input argument was found. Some examples include:
    - \( \text{seqDataDesc} = \text{NULL} \)
    - \( \text{dataType} \) was not a valid type of cudnnDataType_t
    - \( \text{nbDims} \) was negative or zero
- seqLengthArraySize did not match the expected length
- some elements of seqLengthArray[] were invalid

**CUDNN_STATUS_NOT_SUPPORTED**
An unsupported input argument was encountered. Some examples include:
- nbDims is not equal to 4
- paddingFill is not NULL

**CUDNN_STATUS_ALLOC_FAILED**
Failed to allocate storage for the sequence data descriptor object.
Chapter 8. cudnn_adv_train.so Library

8.1. Data Type References

8.1.1. Enumeration Types

8.1.1.1. cudnnLossNormalizationMode_t

cudnnLossNormalizationMode_t is an enumerated type that controls the input normalization mode for a loss function. This type can be used with cudnnSetCTCLossDescriptorEx().

Values

CUDNN LOSS_NORMALIZATION_NONE

The input probs of cudnnCTCLoss() function is expected to be the normalized probability, and the output gradients is the gradient of loss with respect to the unnormalized probability.

CUDNN LOSS_NORMALIZATION_SOFTMAX

The input probs of cudnnCTCLoss() function is expected to be the unnormalized activation from the previous layer, and the output gradients is the gradient with respect to the activation. Internally the probability is computed by softmax normalization.

8.1.1.2. cudnnWgradMode_t

cudnnWgradMode_t is an enumerated type that selects how buffers holding gradients of the loss function, computed with respect to trainable parameters, are updated. Currently, this type is used by the cudnnGetMultiHeadAttnWeights() function only.
Values

**CUDNN_WGRAD_MODE_ADD**

A weight gradient component corresponding to a new batch of inputs is added to previously evaluated weight gradients. Before using this mode, the buffer holding weight gradients should be initialized to zero. Alternatively, the first API call outputting to an uninitialized buffer should use the **CUDNN_WGRAD_MODE_SET** option.

**CUDNN_WGRAD_MODE_SET**

A weight gradient component, corresponding to a new batch of inputs, overwrites previously stored weight gradients in the output buffer.

8.2. API Functions

8.2.1. **cudnnAdvTrainVersionCheck()**

cudnnStatus_t cudnnAdvTrainVersionCheck(void)

This function checks whether the version of the AdvTrain subset of the library is consistent with the other sub-libraries.

Returns

**CUDNN_STATUS_SUCCESS**

The version is consistent with other sub-libraries.

**CUDNN_STATUS_VERSION_MISMATCH**

The version of AdvTrain is not consistent with other sub-libraries. Users should check the installation and make sure all sub-component versions are consistent.

8.2.2. **cudnnCreateCTCLossDescriptor()**

cudnnStatus_t cudnnCreateCTCLossDescriptor(
   cudnnCTCLossDescriptor_t* ctcLossDesc)

This function creates a CTC loss function descriptor.

Parameters

ctcLossDesc

*Output*. CTC loss descriptor to be set. For more information, see `cudnnCTCLossDescriptor_t`. 
8.2.3. **cudnnCTCLoss()**

```c
    cudnnStatus_t cudnnCTCLoss(
        cudnHandle_t            handle,
        const cudnnTensorDescriptor_t  probsDesc,
        const void              *probs,
        const int               hostLabels[],
        const int               hostLabelLengths[],
        const int               hostInputLengths[],
        void                    *costs,
        const cudnnTensorDescriptor_t  gradientsDesc,
        const void              *gradients,
        cudnnCTCLossAlgo_t       algo,
        const cudnnCTCLossDescriptor_t  ctcLossDesc,
        void                    *workspace,
        size_t                  *workSpaceSizeInBytes)
```

This function returns the CTC costs and gradients, given the probabilities and labels.

**Note:** This function can have an inconsistent interface depending on the `cudnnLossNormalizationMode_t` chosen (bound to the `cudnnCTCLossDescriptor_t` with `cudnnSetCTCLossDescriptorEx()`). For the `CUDNN_LOSS_NORMALIZATION_NONE`, this function has an inconsistent interface, for example, the `probs` input is probability normalized by softmax, but the `gradients` output is with respect to the unnormalized activation. However, for `CUDNN_LOSS_NORMALIZATION_SOFTMAX`, the function has a consistent interface; all values are normalized by softmax.

### Parameters

- **handle**
  - *Input*. Handle to a previously created cuDNN context. For more information, see `cudnnHandle_t`.

- **probsDesc**
  - *Input*. Handle to the previously initialized probabilities tensor descriptor. For more information, see `cudnnTensorDescriptor_t`.

- **probs**
  - *Input*. Pointer to a previously initialized probabilities tensor. These input probabilities are normalized by softmax.
**hostLabels**

*Input.* Pointer to a previously initialized labels list, in CPU memory.

**hostLabelLengths**

*Input.* Pointer to a previously initialized lengths list in CPU memory, to walk the above labels list.

**hostInputLengths**

*Input.* Pointer to a previously initialized list of the lengths of the timing steps in each batch, in CPU memory.

**costs**

*Output.* Pointer to the computed costs of CTC.

**gradientsDesc**

*Input.* Handle to a previously initialized gradient tensor descriptor.

**gradients**

*Output.* Pointer to the computed gradients of CTC. These computed gradient outputs are with respect to the unnormalized activation.

**algo**

*Input.* Enumerant that specifies the chosen CTC loss algorithm. For more information, see `cudnnCTCLossAlgo_t`.

**ctcLossDesc**

*Input.* Handle to the previously initialized CTC loss descriptor. For more information, see `cudnnCTCLossDescriptor_t`.

**workspace**

*Input.* Pointer to GPU memory of a workspace needed to be able to execute the specified algorithm.

**sizeInBytes**

*Input.* Amount of GPU memory needed as workspace to be able to execute the CTC loss computation with the specified algo.

**Returns**

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The dimensions of `probsDesc` do not match the dimensions of `gradientsDesc`.
- The `inputLengths` do not agree with the first dimension of `probsDesc`. 
The `workSpaceSizeInBytes` is not sufficient.

- The `labelLengths` is greater than 256.

**CUDNN_STATUS_NOT_SUPPORTED**

A compute or data type other than `FLOAT` was chosen, or an unknown algorithm type was chosen.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

### 8.2.4. **cudnnCTCLoss_v8()**

```c
#include <cudnn.h>

#define handle
#define algo
#define ctcLossDesc
#define probsDesc
#define *probs
#define *labels
#define *labelLengths
#define inputLengths
#define *costs
#define *gradients
#define *workSpaceSizeInBytes
#define *workspace

void cudnnCTCLoss_v8(
    cudnnHandle_t handle,
    cudnnCTCLossAlgo_t algo,
    const cudnnCTCLossDescriptor_t ctcLossDesc,
    const cudnnTensorDescriptor_t probsDesc,
    const void *probs,
    const int *labels[],
    const int *labelLengths[],
    const int *inputLengths[],
    void *costs,
    const cudnnTensorDescriptor_t gradientsDesc,
    const void *gradients,
    size_t *workSpaceSizeInBytes,
    void *workspace)
```

This function returns the CTC costs and gradients, given the probabilities and labels. Many CTC API functions were updated in v8 with the `_v8` suffix to support CUDA graphs. Label and input data is now passed in GPU memory, and `cudnnCTCLossDescriptor_t` should be set using `cudnnSetCTCLossDescriptor_v8()`.

**Note:** This function can have an inconsistent interface depending on the `cudnnLossNormalizationMode_t` chosen (bound to the `cudnnCTCLossDescriptor_t` with `cudnnSetCTCLossDescriptorEx()`). For the CUDNN_LOSS_NORMALIZATION_NONE, this function has an inconsistent interface, for example, the probs input is probability normalized by softmax, but the gradients output is with respect to the unnormalized activation. However, for CUDNN_LOSS_NORMALIZATION_SOFTMAX, the function has a consistent interface; all values are normalized by softmax.

**Parameters**

- **handle**
  - *Input.* Handle to a previously created cuDNN context. For more information, see `cudnnHandle_t`.

- **algo**
  - *Input.* Enumerator that specifies the chosen CTC loss algorithm. For more information, see `cudnnCTCLossAlgo_t`.
ctcLossDesc

*Input.* Handle to the previously initialized CTC loss descriptor. To use this `_v8` function, this descriptor must be set using `cudnnSetCTCLossDescriptor_v8()`. For more information, see `cudnnCTCLossDescriptor_t`.

probsDesc

*Input.* Handle to the previously initialized probabilities tensor descriptor. For more information, see `cudnnTensorDescriptor_t`.

probs

*Input.* Pointer to a previously initialized probabilities tensor. These input probabilities are normalized by softmax.

labels

*Input.* Pointer to a previously initialized labels list, in GPU memory.

labelLengths

*Input.* Pointer to a previously initialized lengths list in GPU memory, to walk the above labels list.

inputLengths

*Input.* Pointer to a previously initialized list of the lengths of the timing steps in each batch, in GPU memory.

costs

*Output.* Pointer to the computed costs of CTC.

gradientsDesc

*Input.* Handle to a previously initialized gradient tensor descriptor.

gradients

*Output.* Pointer to the computed gradients of CTC. These computed gradient outputs are with respect to the unnormalized activation.

workspace

*Input.* Pointer to GPU memory of a workspace needed to be able to execute the specified algorithm.

sizeInBytes

*Input.* Amount of GPU memory needed as a workspace to be able to execute the CTC loss computation with the specified algorithm.

**Returns**

**CUDNN_STATUS_SUCCESS**

The query was successful.
CUDDN_STATUS_BAD_PARAM

At least one of the following conditions are met:

▷ The dimensions of `probsDesc` do not match the dimensions of `gradientsDesc`.
▷ The `inputLengths` do not agree with the first dimension of `probsDesc`.
▷ The `workSpaceSizeInBytes` is not sufficient.
▷ The `labelLengths` is greater than 256.

CUDDN_STATUS_NOT_SUPPORTED

A compute or data type other than `FLOAT` was chosen, or an unknown algorithm type was chosen.

CUDDN_STATUS_EXECUTION_FAILED

The function failed to launch on the GPU.

8.2.5. `cudnnDestroyCTCLossDescriptor()`

cudnnStatus_t cudnnDestroyCTCLossDescriptor(
  cudnnCTCLossDescriptor_t  ctcLossDesc)

This function destroys a CTC loss function descriptor object.

Parameters

ctcLossDesc

Input. CTC loss function descriptor to be destroyed.

Returns

CUDDN_STATUS_SUCCESS

The function returned successfully.

8.2.6. `cudnnFindRNNBackwardDataAlgorithmEx()`

This function has been deprecated in cuDNN 8.0.

cudnnStatus_t cudnnFindRNNBackwardDataAlgorithmEx{
  cudnnHandle_t  handle,
  const cudnnRNNDescriptor_t  rnnDesc,
  const int  seqLength,
  const cudnnTensorDescriptor_t    *yDesc,
  const void  *y,
  const cudnnTensorDescriptor_t  *dyDesc,
  const void  *dy,
  const cudnnTensorDescriptor_t    dhyDesc,
  const void  *dhy,
  const cudnnTensorDescriptor_t    dcyDesc,
  const void  *dcy,
  const cudnnFilterDescriptor_t    wDesc,
  const void  *w,
  const cudnnTensorDescriptor_t    hxDesc,
  const void  *hx,
}
This function attempts all available cuDNN algorithms for `cudnnRNNBackwardData()`, using user-allocated GPU memory. It outputs the parameters that influence the performance of the algorithm to a user-allocated array of `cudnnAlgorithmPerformance_t`. These parameter metrics are written in sorted fashion where the first element has the lowest compute time.

**Parameters**

**handle**

*Input*. Handle to a previously created cuDNN context.

**rnnDesc**

*Input*. A previously initialized RNN descriptor.

**seqLength**

*Input*. Number of iterations to unroll over. The value of this `seqLength` must not exceed the value that was used in `cudnnGetRNNWorkspaceSize()` function for querying the workspace size required to execute the RNN.

**yDesc**

*Input*. An array of fully packed tensor descriptors describing the output from each recurrent iteration (one descriptor per iteration). The second dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction is CUDNN_UNIDIRECTIONAL` the second dimension should match the `hiddenSize` argument.
- If `direction is CUDNN_BIDIRECTIONAL` the second dimension should match double the `hiddenSize` argument.

The first dimension of the tensor `n` must match the first dimension of the tensor `n` in `dyDesc`.

**y**

*Input*. Data pointer to GPU memory associated with the output tensor descriptor `yDesc`. 
**dyDesc**

*Input.* An array of fully packed tensor descriptors describing the gradient at the output from each recurrent iteration [one descriptor per iteration]. The second dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the second dimension should match the `hiddenSize` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the second dimension should match double the `hiddenSize` argument.

The first dimension of the tensor must match the second dimension of the tensor `n` in `dxDesc`.

**dy**

*Input.* Data pointer to GPU memory associated with the tensor descriptors in the array `dyDesc`.

**dhyDesc**

*Input.* A fully packed tensor descriptor describing the gradients at the final hidden state of the RNN. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `dxDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.

**dhy**

*Input.* Data pointer to GPU memory associated with the tensor descriptor `dhyDesc`. If a NULL pointer is passed, the gradients at the final hidden state of the network will be initialized to zero.

**dcyDesc**

*Input.* A fully packed tensor descriptor describing the gradients at the final cell state of the RNN. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.
The second dimension must match the first dimension of the tensors described in dxDesc. The third dimension must match the hiddenSize argument used to initialize rnnDesc. The tensor must be fully packed.

**dcy**

*Input.* Data pointer to GPU memory associated with the tensor descriptor dcyDesc. If a NULL pointer is passed, the gradients at the final cell state of the network will be initialized to zero.

**wDesc**

*Input.* Handle to a previously initialized filter descriptor describing the weights for the RNN.

**w**

*Input.* Data pointer to GPU memory associated with the filter descriptor wDesc.

**hxDesc**

*Input.* A fully packed tensor descriptor describing the initial hidden state of the RNN. The first dimension of the tensor depends on the direction argument used to initialize rnnDesc:

- If direction is CUDNN_UNIDIRECTIONAL the first dimension should match the numLayers argument.
- If direction is CUDNN_BIDIRECTIONAL the first dimension should match double the numLayers argument.

The second dimension must match the first dimension of the tensors described in dxDesc. The third dimension must match the hiddenSize argument used to initialize rnnDesc. The tensor must be fully packed.

**hx**

*Input.* Data pointer to GPU memory associated with the tensor descriptor hxDesc. If a NULL pointer is passed, the initial hidden state of the network will be initialized to zero.

**cxDesc**

*Input.* A fully packed tensor descriptor describing the initial cell state for LSTM networks. The first dimension of the tensor depends on the direction argument used to initialize rnnDesc:

- If direction is CUDNN_UNIDIRECTIONAL the first dimension should match the numLayers argument.
- If direction is CUDNN_BIDIRECTIONAL the first dimension should match double the numLayers argument.

The second dimension must match the first dimension of the tensors described in dxDesc. The third dimension must match the hiddenSize argument used to initialize rnnDesc. The tensor must be fully packed.
cx

*Input.* Data pointer to GPU memory associated with the tensor descriptor \( \text{cxDesc} \). If a NULL pointer is passed, the initial cell state of the network will be initialized to zero.

dxDesc

*Input.* An array of fully packed tensor descriptors describing the gradient at the input of each recurrent iteration [one descriptor per iteration]. The first dimension (batch size) of the tensors may decrease from element \( n \) to element \( n+1 \) but may not increase. Each tensor descriptor must have the same second dimension (vector length).

dx

*Output.* Data pointer to GPU memory associated with the tensor descriptors in the array \( \text{dxDesc} \).

dhxDesc

*Input.* A fully packed tensor descriptor describing the gradient at the initial hidden state of the RNN. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `dxDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.

dhx

*Output.* Data pointer to GPU memory associated with the tensor descriptor \( \text{dhxDesc} \). If a NULL pointer is passed, the gradient at the hidden input of the network will not be set.

dcxDesc

*Input.* A fully packed tensor descriptor describing the gradient at the initial cell state of the RNN. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `dxDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.
dcx

*Output*. Data pointer to GPU memory associated with the tensor descriptor dcxDesc. If a NULL pointer is passed, the gradient at the cell input of the network will not be set.

**findIntensity**

*Input*. This input was previously unused in versions prior to cuDNN 7.2.0. It is used in cuDNN 7.2.0 and later versions to control the overall runtime of the RNN find algorithms, by selecting the percentage of a large Cartesian product space to be searched.

- Setting `findIntensity` within the range [0,1] will set a percentage of the entire RNN search space to search. When `findIntensity` is set to 1.0, a full search is performed over all RNN parameters.
- When `findIntensity` is set to 0.0f, a quick, minimal search is performed. This setting has the best runtime. However, in this case the parameters returned by this function will not correspond to the best performance of the algorithm; a longer search might discover better parameters. This option will execute up to three instances of the configured RNN problem. Runtime will vary proportionally to RNN problem size, as it will in the other cases, hence no guarantee of an explicit time bound can be given.
- Setting `findIntensity` within the range [-1,0) sets a percentage of a reduced Cartesian product space to be searched. This reduced search space has been heuristically selected to have good performance. The setting of -1.0 represents a full search over this reduced search space.
- Values outside the range [-1,1] are truncated to the range [-1,1], and then interpreted as per the above.
- Setting `findIntensity` to 1.0 in cuDNN 7.2 and later versions is equivalent to the behavior of this function in versions prior to cuDNN 7.2.0.
- This function times the single RNN executions over large parameter spaces - one execution per parameter combination. The times returned by this function are latencies.

**requestedAlgoCount**

*Input*. The maximum number of elements to be stored in `perfResults`.

**returnedAlgoCount**

*Output*. The number of output elements stored in `perfResults`.

**perfResults**

*Output*. A user-allocated array to store performance metrics sorted ascending by compute time.

**workspace**

*Input*. Data pointer to GPU memory to be used as a workspace for this call.

**workSpaceSizeInBytes**

*Input*. Specifies the size in bytes of the provided `workspace`.
reserveSpace

*Input/Output.* Data pointer to GPU memory to be used as a reserve space for this call.

reserveSpaceSizeInBytes

*Input.* Specifies the size in bytes of the provided *reserveSpace*.

**Returns**

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The descriptor *rnnDesc* is invalid.
- At least one of the descriptors *dhxDesc, wDesc, hxDesc, cxDesc, dcxDesc, dhyDesc, dcyDesc* or one of the descriptors in *yDesc, dxDesc, dyDesc* is invalid.
- The descriptors in one of *yDesc, dxDesc, dyDesc, dhxDesc, wDesc, hxDesc, cxDesc, dcxDesc, dhyDesc, dcyDesc* has incorrect strides or dimensions.
- *workSpaceSizeInBytes* is too small.
- *reserveSpaceSizeInBytes* is too small.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

**CUDNN_STATUS_ALLOC_FAILED**

The function was unable to allocate memory.

### 8.2.7. `cudnnFindRNNBackwardWeightsAlgorithmEx()`

This function has been deprecated in cuDNN 8.0.

```c
void cudnnFindRNNBackwardWeightsAlgorithmEx(
    cudnnHandle_t handle,
    const cudnnRNNDescriptor_t *rnnDesc,
    const int seqLength,
    const cudnnTensorDescriptor_t *xDesc, const void *x,
    const cudnnTensorDescriptor_t *hxDesc, const void *hx,
    const cudnnTensorDescriptor_t *yDesc, const void *y,
    const float findIntensity,
    const int requestedAlgoCount, int *returnedAlgoCount,
    cudnnAlgorithmPerformance_t *perfResults,
    const void *workspace, size_t workSpaceSizeInBytes,
);
```
This function attempts all available cuDNN algorithms for `cudnnRNNBackwardWeights()`, using user-allocated GPU memory. It outputs the parameters that influence the performance of the algorithm to a user-allocated array of `cudnnAlgorithmPerformance_t`. These parameter metrics are written in sorted fashion where the first element has the lowest compute time.

**Parameters**

**handle**

*Input*. Handle to a previously created cuDNN context.

**rnnDesc**

*Input*. A previously initialized RNN descriptor.

**seqLength**

*Input*. Number of iterations to unroll over. The value of this `seqLength` must not exceed the value that was used in `cudnnGetRNNSpaceSize()` function for querying the workspace size required to execute the RNN.

**xDesc**

*Input*. An array of fully packed tensor descriptors describing the input to each recurrent iteration (one descriptor per iteration). The first dimension (batch size) of the tensors may decrease from element `n` to element `n+1` but may not increase. Each tensor descriptor must have the same second dimension (vector length).

**x**

*Input*. Data pointer to GPU memory associated with the tensor descriptors in the array `xDesc`.

**hxDesc**

*Input*. A fully packed tensor descriptor describing the initial hidden state of the RNN. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `xDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.
hx

*Input.* Data pointer to GPU memory associated with the tensor descriptor \(hxDesc\). If a NULL pointer is passed, the initial hidden state of the network will be initialized to zero.

\(yDesc\)

*Input.* An array of fully packed tensor descriptors describing the output from each recurrent iteration (one descriptor per iteration). The second dimension of the tensor depends on the *direction* argument used to initialize \(rnnDesc\):

- If *direction* is \(CUDNN\_UNIDIRECTIONAL\) the second dimension should match the \(\text{hiddenSize}\) argument.
- If *direction* is \(CUDNN\_BIDIRECTIONAL\) the second dimension should match double the \(\text{hiddenSize}\) argument.

The first dimension of the tensor \(n\) must match the first dimension of the tensor \(n\) in \(dyDesc\).

\(y\)

*Input.* Data pointer to GPU memory associated with the output tensor descriptor \(yDesc\).

\(\text{findIntensity}\)

*Input.* This input was previously unused in versions prior to cuDNN 7.2.0. It is used in cuDNN 7.2.0 and later versions to control the overall runtime of the RNN find algorithms, by selecting the percentage of a large Cartesian product space to be searched.

- Setting \(\text{findIntensity}\) within the range \([0,1.]\) will set a percentage of the entire RNN search space to search. When \(\text{findIntensity}\) is set to 1.0, a full search is performed over all RNN parameters.
- When \(\text{findIntensity}\) is set to 0.0f, a quick, minimal search is performed. This setting has the best runtime. However, in this case the parameters returned by this function will not correspond to the best performance of the algorithm; a longer search might discover better parameters. This option will execute up to three instances of the configured RNN problem. Runtime will vary proportionally to RNN problem size, as it will in the other cases, hence no guarantee of an explicit time bound can be given.
- Setting \(\text{findIntensity}\) within the range \([-1,0)\) sets a percentage of a reduced Cartesian product space to be searched. This reduced search space has been heuristically selected to have good performance. The setting of -1.0 represents a full search over this reduced search space.
- Values outside the range \([-1,1]\) are truncated to the range \([-1,1]\), and then interpreted as per the above.
- Setting \(\text{findIntensity}\) to 1.0 in cuDNN 7.2 and later versions is equivalent to the behavior of this function in versions prior to cuDNN 7.2.0.

This function times the single RNN executions over large parameter spaces - one execution per parameter combination. The times returned by this function are latencies.
requestedAlgoCount

*Input.* The maximum number of elements to be stored in `perfResults`.

returnedAlgoCount

*Output.* The number of output elements stored in `perfResults`.

perfResults

*Output.* A user-allocated array to store performance metrics sorted ascending by compute time.

workspace

*Input.* Data pointer to GPU memory to be used as a workspace for this call.

workSpaceSizeInBytes

*Input.* Specifies the size in bytes of the provided `workspace`.

dwDesc

*Input.* Handle to a previously initialized filter descriptor describing the gradients of the weights for the RNN.

dl

*Input/Output.* Data pointer to GPU memory associated with the filter descriptor `dwDesc`.

reserveSpace

*Input.* Data pointer to GPU memory to be used as a reserve space for this call.

reserveSpaceSizeInBytes

*Input.* Specifies the size in bytes of the provided `reserveSpace`.

Returns

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The descriptor `rnnDesc` is invalid.
- At least one of the descriptors `hxDesc`, `dwDesc` or one of the descriptors in `xDesc`, `yDesc` is invalid.
- The descriptors in one of `xDesc`, `hxDesc`, `yDesc`, `dwDesc` have incorrect strides or dimensions.
- `workSpaceSizeInBytes` is too small.
- `reserveSpaceSizeInBytes` is too small.
CUDNN_STATUS_EXECUTION_FAILED

The function failed to launch on the GPU.

CUDNN_STATUS_ALLOC_FAILED

The function was unable to allocate memory.

8.2.8. cudnnFindRNNForwardTrainingAlgorithmEx()

This function has been deprecated in cuDNN 8.0.

```c
cudnnStatus_t cudnnFindRNNForwardTrainingAlgorithmEx(
    cudnnHandle_t                  handle,
    const cudnnRNNDescriptor_t     rnnDesc,
    const int                      seqLength,
    const cudnnTensorDescriptor_t  *xDesc,
    const void                     *x,
    const cudnnTensorDescriptor_t   hxDesc,
    const void                     *hx,
    const cudnnTensorDescriptor_t   cxDesc,
    const void                     *cx,
    const cudnnFilterDescriptor_t   wDesc,
    const void                     *w,
    const cudnnTensorDescriptor_t  *yDesc,
    void                           *y,
    const cudnnTensorDescriptor_t  hyDesc,
    void                           *hy,
    const cudnnTensorDescriptor_t   cyDesc,
    void                           *cy,
    const float                    findIntensity,
    const int                      requestedAlgoCount,
    int                            *returnedAlgoCount,
    cudnnAlgorithmPerformance_t    *perfResults,
    void                           *workspace,
    size_t                         workSpaceSizeInBytes,
    void                           *reserveSpace,
    size_t                         reserveSpaceSizeInBytes)
```

This function attempts all available cuDNN algorithms for `cudnnRNNForwardTraining()`, using user-allocated GPU memory. It outputs the parameters that influence the performance of the algorithm to a user-allocated array of `cudnnAlgorithmPerformance_t`. These parameter metrics are written in sorted fashion where the first element has the lowest compute time.

Parameters

**handle**

*Input.* Handle to a previously created cuDNN context.

**rnnDesc**

*Input.* A previously initialized RNN descriptor.

**xDesc**

*Input.* An array of fully packed tensor descriptors describing the input to each recurrent iteration [one descriptor per iteration]. The first dimension (batch size) of the tensors may decrease from element \( n \) to element \( n+1 \) but may not increase. Each tensor descriptor must have the same second dimension (vector length).
**seqLength**

*Input.* Number of iterations to unroll over. The value of this `seqLength` must not exceed the value that was used in `cudnnGetRNNWorkspaceSize()` function for querying the workspace size required to execute the RNN.

**x**

*Input.* Data pointer to GPU memory associated with the tensor descriptors in the array `xDesc`.

**hxDesc**

*Input.* A fully packed tensor descriptor describing the initial hidden state of the RNN. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `xDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.

**hx**

*Input.* Data pointer to GPU memory associated with the tensor descriptor `hxDesc`. If a NULL pointer is passed, the initial hidden state of the network will be initialized to zero.

**cxDesc**

*Input.* A fully packed tensor descriptor describing the initial cell state for LSTM networks. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `xDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.

**cx**

*Input.* Data pointer to GPU memory associated with the tensor descriptor `cxDesc`. If a NULL pointer is passed, the initial cell state of the network will be initialized to zero.

**wDesc**

*Input.* Handle to a previously initialized filter descriptor describing the weights for the RNN.
w

Input. Data pointer to GPU memory associated with the filter descriptor wDesc.

yDesc

Input. An array of fully packed tensor descriptors describing the output from each recurrent iteration (one descriptor per iteration). The second dimension of the tensor depends on the direction argument used to initialize rnnDesc:

- If direction is CUDNN_UNIDIRECTIONAL the second dimension should match the hiddenSize argument.
- If direction is CUDNN_BIDIRECTIONAL the second dimension should match double the hiddenSize argument.

The first dimension of the tensor n must match the first dimension of the tensor n in xDesc.

y

Output. Data pointer to GPU memory associated with the output tensor descriptor yDesc.

hyDesc

Input. A fully packed tensor descriptor describing the final hidden state of the RNN. The first dimension of the tensor depends on the direction argument used to initialize rnnDesc:

- If direction is CUDNN_UNIDIRECTIONAL the first dimension should match the numLayers argument.
- If direction is CUDNN_BIDIRECTIONAL the first dimension should match double the numLayers argument.

The second dimension must match the first dimension of the tensors described in xDesc. The third dimension must match the hiddenSize argument used to initialize rnnDesc. The tensor must be fully packed.

hy

Output. Data pointer to GPU memory associated with the tensor descriptor hyDesc. If a NULL pointer is passed, the final hidden state of the network will not be saved.

cyDesc

Input. A fully packed tensor descriptor describing the final cell state for LSTM networks. The first dimension of the tensor depends on the direction argument used to initialize rnnDesc:

- If direction is CUDNN_UNIDIRECTIONAL the first dimension should match the numLayers argument.
- If direction is CUDNN_BIDIRECTIONAL the first dimension should match double the numLayers argument.
The second dimension must match the first dimension of the tensors described in xDesc. The third dimension must match the hiddenSize argument used to initialize rnnDesc. The tensor must be fully packed.

cy

*Output.* Data pointer to GPU memory associated with the tensor descriptor cyDesc. If a NULL pointer is passed, the final cell state of the network will not be saved.

**findIntensity**

*Input.* This input was previously unused in versions prior to cuDNN 7.2.0. It is used in cuDNN 7.2.0 and later versions to control the overall runtime of the RNN find algorithms, by selecting the percentage of a large Cartesian product space to be searched.

- Setting findIntensity within the range \([0,1]\) will set a percentage of the entire RNN search space to search. When findIntensity is set to 1.0, a full search is performed over all RNN parameters.
- When findIntensity is set to 0.0f, a quick, minimal search is performed. This setting has the best runtime. However, in this case the parameters returned by this function will not correspond to the best performance of the algorithm; a longer search might discover better parameters. This option will execute up to three instances of the configured RNN problem. Runtime will vary proportionally to RNN problem size, as it will in the other cases, hence no guarantee of an explicit time bound can be given.
- Setting findIntensity within the range \([-1,0)\) sets a percentage of a reduced Cartesian product space to be searched. This reduced search space has been heuristically selected to have good performance. The setting of -1.0 represents a full search over this reduced search space.
- Values outside the range \([-1,1]\) are truncated to the range \([-1,1]\), and then interpreted as per the above.
- Setting findIntensity to 1.0 in cuDNN 7.2 and later versions is equivalent to the behavior of this function in versions prior to cuDNN 7.2.0.
- This function times the single RNN executions over large parameter spaces - one execution per parameter combination. The times returned by this function are latencies.

**requestedAlgoCount**

*Input.* The maximum number of elements to be stored in perfResults.

**returnedAlgoCount**

*Output.* The number of output elements stored in perfResults.

**perfResults**

*Output.* A user-allocated array to store performance metrics sorted ascending by compute time.

**workspace**

*Input.* Data pointer to GPU memory to be used as a workspace for this call.
workSpaceSizeInBytes

*Input.* Specifies the size in bytes of the provided *workspace.*

reserveSpace

*Input/Output.* Data pointer to GPU memory to be used as a reserve space for this call.

reserveSpaceSizeInBytes

*Input.* Specifies the size in bytes of the provided *reserveSpace.*

**Returns**

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The descriptor `rnnDesc` is invalid.
- At least one of the descriptors `hxDesc`, `cxDesc`, `wDesc`, `hyDesc`, `cyDesc` or one of the descriptors in `xDesc`, `yDesc` is invalid.
- The descriptors in one of `xDesc`, `hxDesc`, `cxDesc`, `wDesc`, `yDesc`, `hyDesc`, `cyDesc` have incorrect strides or dimensions.
- `workSpaceSizeInBytes` is too small.
- `reserveSpaceSizeInBytes` is too small.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

**CUDNN_STATUS_ALLOC_FAILED**

The function was unable to allocate memory.

**8.2.9. cudnnGetCTCLossDescriptor()**

cudnnStatus_t cudnnGetCTCLossDescriptor(cudnnCTCLossDescriptor_t ctcLossDesc, cudnnDataType_t* compType)

This function returns the configuration of the passed CTC loss function descriptor.

**Parameters**

**ctcLossDesc**

*Input.* CTC loss function descriptor passed, from which to retrieve the configuration.

**compType**

*Output.* Compute type associated with this CTC loss function descriptor.
Returns

**CUDNN_STATUS_SUCCESS**

The function returned successfully.

**CUDNN_STATUS_BAD_PARAM**

Input `OpTensor` descriptor passed is invalid.

### 8.2.10. `cudnnGetCTCLossDescriptorEx()`

This function returns the configuration of the passed CTC loss function descriptor.

#### Parameters

- **ctcLossDesc**
  
  *Input.* CTC loss function descriptor passed, from which to retrieve the configuration.

- **compType**
  
  *Output.* Compute type associated with this CTC loss function descriptor.

- **normMode**
  
  *Output.* Input normalization type for this CTC loss function descriptor. For more information, see `cudnnLossNormalizationMode_t`.

- **gradMode**
  
  *Output.* NaN propagation type for this CTC loss function descriptor.

#### Returns

**CUDNN_STATUS_SUCCESS**

The function returned successfully.

**CUDNN_STATUS_BAD_PARAM**

Input `OpTensor` descriptor passed is invalid.

### 8.2.11. `cudnnGetCTCLossDescriptor_v8()`

This function returns the configuration of the passed CTC loss function descriptor.
Parameters

ctcLossDesc

*Input*. CTC loss function descriptor passed, from which to retrieve the configuration.

compType

*Output*. Compute type associated with this CTC loss function descriptor.

normMode

*Output*. Input normalization type for this CTC loss function descriptor. For more information, see `cudnnLossNormalizationMode_t`.

gradMode

*Output*. NaN propagation type for this CTC loss function descriptor.

maxLabelLength

*Output*. The max label length for this CTC loss function descriptor.

Returns

CUDNN_STATUS_SUCCESS

The function returned successfully.

CUDNN_STATUS_BAD_PARAM

Input `opTensor` descriptor passed is invalid.

8.2.12. `cudnnGetCTCLossWorkspaceSize()`

cudnnStatus_t cudnnGetCTCLossWorkspaceSize(
    cudnnHandle_t                        handle,
    const   cudnnTensorDescriptor_t      probsDesc,
    const   cudnnTensorDescriptor_t      gradientsDesc,
    const   int                         *labels,
    const   int                         *labelLengths,
    const   int                         *inputLengths,
    cudnnCTCLossAlgo_t                   algo,
    const   cudnnCTCLossDescriptor_t     ctcLossDesc,
    size_t                              *sizeInBytes)

This function returns the amount of GPU memory workspace the user needs to allocate to be able to call `cudnnCTCLoss[]` with the specified algorithm. The workspace allocated will then be passed to the routine `cudnnCTCLoss[]`.

Parameters

handle

*Input*. Handle to a previously created cuDNN context.

probsDesc

*Input*. Handle to the previously initialized probabilities tensor descriptor.
gradientsDesc

*Input*. Handle to a previously initialized gradient tensor descriptor.

labels

*Input*. Pointer to a previously initialized labels list.

labelLengths

*Input*. Pointer to a previously initialized lengths list, to walk the above labels list.

inputLengths

*Input*. Pointer to a previously initialized list of the lengths of the timing steps in each batch.

algo

*Input*. Enumerant that specifies the chosen CTC loss algorithm

ctcLossDesc

*Input*. Handle to the previously initialized CTC loss descriptor.

sizeInBytes

*Output*. Amount of GPU memory needed as workspace to be able to execute the CTC loss computation with the specified algo.

Returns

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The dimensions of *probsDesc* do not match the dimensions of *gradientsDesc*.
- The *inputLengths* do not agree with the first dimension of *probsDesc*.
- The *workspaceSizeInBytes* is not sufficient.
- The *labelLengths* is greater than 256.

**CUDNN_STATUS_NOT_SUPPORTED**

A compute or data type other than *FLOAT* was chosen, or an unknown algorithm type was chosen.

### 8.2.13. cudnnGetCTCLossWorkspaceSize_v8()

```c
void cudnnGetCTCLossWorkspaceSize_v8(
    cudnnHandle_t                        handle,
    cudnnCTCLossAlgo_t                   algo,
    const   cudnnCTCLossDescriptor_t     ctcLossDesc,
    const   cudnnTensorDescriptor_t      probsDesc,
    const   cudnnTensorDescriptor_t      gradientsDesc,
    size_t                              *sizeInBytes
)
```
This function returns the amount of GPU memory workspace the user needs to allocate to be able to call `cudnnCTCLoss_v8()` with the specified algorithm. The workspace allocated will then be passed to the routine `cudnnCTCLoss_v8()`.

Parameters

**handle**

*Input.* Handle to a previously created cuDNN context.

**algo**

*Input.* Enumerant that specifies the chosen CTC loss algorithm.

**ctcLossDesc**

*Input.* Handle to the previously initialized CTC loss descriptor.

**probsDesc**

*Input.* Handle to the previously initialized probabilities tensor descriptor.

**gradientsDesc**

*Input.* Handle to a previously initialized gradient tensor descriptor.

**sizeInBytes**

*Output.* Amount of GPU memory needed as workspace to be able to execute the CTC loss computation with the specified `algo`.

Returns

**CUDNN_STATUS_SUCCESS**

The query was successful.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The dimensions of `probsDesc` do not match the dimensions of `gradientsDesc`.

**CUDNN_STATUS_NOT_SUPPORTED**

A compute or data type other than `FLOAT` was chosen, or an unknown algorithm type was chosen.

8.2.14. **cudnnGetRNNTrainingReserveSize()**

This function has been deprecated in cuDNN 8.0. Use `cudnnGetRNNTempSpaceSizes()` instead of `cudnnGetRNNWorkspaceSize()`.

```c
#include <cudnn.h>

int cudnnGetRNNTrainingReserveSize(
    cudnnHandle_t                 handle,
    const cudnnRNNDescriptor_t    rnnDesc,
    const int                     seqLength,
    const cudnnTensorDescriptor_t *xDesc,
    size_t                        *sizeInBytes
)
```
This function is used to query the amount of reserved space required for training the RNN described by \texttt{rnnDesc} with input dimensions defined by \texttt{xDesc}. The same reserved space buffer must be passed to \texttt{cudnnRNNForwardTraining()}, \texttt{cudnnRNNBackwardData()}, and \texttt{cudnnRNNBackwardWeights()}. Each of these calls overwrites the contents of the reserved space, however it can safely be backed up and restored between calls if reuse of the memory is desired.

**Parameters**

\textbf{handle}

\textit{Input}. Handle to a previously created cuDNN library descriptor.

\textbf{rnnDesc}

\textit{Input}. A previously initialized RNN descriptor.

\textbf{seqLength}

\textit{Input}. Number of iterations to unroll over. The value of this \texttt{seqLength} must not exceed the value that was used in \texttt{cudnnGetRNNWorkspaceSize()} function for querying the workspace size required to execute the RNN.

\textbf{xDesc}

\textit{Input}. An array of tensor descriptors describing the input to each recurrent iteration (one descriptor per iteration). The first dimension (batch size) of the tensors may decrease from element \texttt{n} to element \texttt{n+1} but may not increase. Each tensor descriptor must have the same second dimension (vector length).

\textbf{sizeInBytes}

\textit{Output}. Minimum amount of GPU memory needed as reserve space to be able to train an RNN with the specified descriptor and input tensors.

**Returns**

\textbf{CUDNN\_STATUS\_SUCCESS}

The query was successful.

\textbf{CUDNN\_STATUS\_BAD\_PARAM}

At least one of the following conditions are met:

- The descriptor \texttt{rnnDesc} is invalid.
- At least one of the descriptors in \texttt{xDesc} is invalid.
- The descriptors in \texttt{xDesc} have inconsistent second dimensions, strides or data types.
- The descriptors in \texttt{xDesc} have increasing first dimensions.
- The descriptors in \texttt{xDesc} are not fully packed.

\textbf{CUDNN\_STATUS\_NOT\_SUPPORTED}

The data types in tensors described by \texttt{xDesc} are not supported.
8.2.15. `cudnnMultiHeadAttnBackwardData()`

This function computes exact, first-order derivatives of the multi-head attention block with respect to its inputs: \( Q, K, V \). If \( y = F(x) \) is a vector-valued function that represents the multi-head attention layer and it takes some vector \( x \in \mathbb{R}^n \) as an input (with all other parameters and inputs constant), and outputs vector \( y \in \mathbb{R}^m \), then `cudnnMultiHeadAttnBackwardData()` computes the result of \( \left( \frac{\partial y}{\partial x} \right)^T \delta_\text{out} \) where \( \delta_\text{out} \) is the \( m \times 1 \) gradient of the loss function with respect to multi-head attention outputs. The \( \delta_\text{out} \) gradient is back propagated through prior layers of the deep learning model. \( \frac{\partial y}{\partial x} \) is the \( m \times n \) Jacobian matrix of \( F(x) \). The input is supplied via the `dout` argument and gradient results for \( Q, K, V \) are written to the `dqueries`, `dkeys`, and `dvalues` buffers.

The `cudnnMultiHeadAttnBackwardData()` function does not output partial derivatives for residual connections because this result is equal to \( \delta_\text{out} \). If the multi-head attention model enables residual connections sourced directly from \( Q \), then the `dout` tensor needs to be added to `dqueries` to obtain the correct result of the latter. This operation is demonstrated in the cuDNN multiHeadAttention sample code.

The `cudnnMultiHeadAttnBackwardData()` function must be invoked after `cudnnMultiHeadAttnForward()`. The `loWinIdx[]`, `hiWinIdx[]`, `queries`, `keys`, `values`, `weights`, and `reserveSpace` arguments should be the same as in the `cudnnMultiHeadAttnForward()` call. `devSeqLengthsDQDO[]` and `devSeqLengthsDKDV[]` device arrays should contain the same start and end attention window indices as `devSeqLengthsQO[]` and `devSeqLengthsKV[]` arrays in the forward function invocation.

**Note:** `cudnnMultiHeadAttnBackwardData()` does not verify that sequence lengths stored in `devSeqLengthsDQDO[]` and `devSeqLengthsDKDV[]` contain the same settings as `seqLengthArray[]` in the corresponding sequence data descriptor.
Parameters

handle

*Input.* The current context handle.

attnDesc

*Input.* A previously initialized attention descriptor.

loWinIdx[], hiWinIdx[]

*Input.* Two host integer arrays specifying the start and end indices of the attention window for each Q time-step. The start index in K, V sets is inclusive, and the end index is exclusive.

devSeqLengthsDQDO[]

*Input.* Device array containing a copy of the sequence length array from the dqDesc or doDesc sequence data descriptor.

devSeqLengthsDKDV[]

*Input.* Device array containing a copy of the sequence length array from the dkDesc or dvDesc sequence data descriptor.

doDesc

*Input.* Descriptor for the $\delta_{out}$ gradients (vectors of partial derivatives of the loss function with respect to the multi-head attention outputs).

dout

Pointer to $\delta_{out}$ gradient data in the device memory.

dqDesc

*Input.* Descriptor for queries and dqueries sequence data.

dqueries

*Output.* Device pointer to gradients of the loss function computed with respect to queries vectors.

queries

*Input.* Pointer to queries data in the device memory. This is the same input as in cudnnMultiHeadAttnForward[].

dkDesc

*Input.* Descriptor for keys and dkeys sequence data.

dkeys

*Output.* Device pointer to gradients of the loss function computed with respect to keys vectors.
keys

*Input*. Pointer to keys data in the device memory. This is the same input as in `cudnnMultiHeadAttnForward()`. 

dvDesc

*Input*. Descriptor for values and dvalues sequence data. 

dvalues

*Output*. Device pointer to gradients of the loss function computed with respect to values vectors. 

values

*Input*. Pointer to values data in the device memory. This is the same input as in `cudnnMultiHeadAttnForward()`. 

weightSizeInBytes

*Input*. Size of the weight buffer in bytes where all multi-head attention trainable parameters are stored. 

weights

*Input*. Address of the weight buffer in the device memory. 

workSpaceSizeInBytes

*Input*. Size of the work-space buffer in bytes used for temporary API storage. 

workSpace

*Input/Output*. Address of the work-space buffer in the device memory. 

reserveSpaceSizeInBytes

*Input*. Size of the reserve-space buffer in bytes used for data exchange between forward and backward (gradient) API calls. 

reserveSpace

*Input/Output*. Address to the reserve-space buffer in the device memory. 

Returns

**CUDNN_STATUS_SUCCESS**

No errors were detected while processing API input arguments and launching GPU kernels. 

**CUDNN_STATUS_BAD_PARAM**

An invalid or incompatible input argument was encountered. 

**CUDNN_STATUS_EXECUTION_FAILED**

The process of launching a GPU kernel returned an error, or an earlier kernel did not complete successfully.
CUDNN_STATUS_INTERNAL_ERROR
An inconsistent internal state was encountered.

CUDNN_STATUS_NOT_SUPPORTED
A requested option or a combination of input arguments is not supported.

CUDNN_STATUS_ALLOC_FAILED
Insufficient amount of shared memory to launch a GPU kernel.

8.2.16. cudnnMultiHeadAttnBackwardWeights()

This function computes exact, first-order derivatives of the multi-head attention block with respect to its trainable parameters: projection weights and projection biases. If $y = F[w]$ is a vector-valued function that represents the multi-head attention layer and it takes some vector $x \in \mathbb{R}^n$ of flatten weights or biases as an input [with all other parameters and inputs fixed], and outputs vector $y \in \mathbb{R}^m$, then cudnnMultiHeadAttnBackwardWeights() computes the result of $(\frac{\partial y}{\partial x})^T \delta_{\text{out}}$ where $\delta_{\text{out}}$ is the $m \times 1$ gradient of the loss function with respect to multi-head attention outputs. The $\delta_{\text{out}}$ gradient is back propagated through prior layers of the deep learning model. $\frac{\partial y}{\partial x}$ is the $m \times n$ Jacobian matrix of $F[w]$. The $\delta_{\text{out}}$ input is supplied via the dout argument.

All gradient results with respect to weights and biases are written to the dweights buffer. The size and the organization of the dweights buffer is the same as the weights buffer that holds multi-head attention weights and biases. The cuDNN multiHeadAttention sample code demonstrates how to access those weights.

Gradient of the loss function with respect to weights or biases is typically computed over multiple batches. In such a case, partial results computed for each batch should be summed together. The addGrad argument specifies if the gradients from the current batch should be added to previously computed results or the dweights buffer should be overwritten with the new results.

The cudnnMultiHeadAttnBackwardWeights() function should be invoked after cudnnMultiHeadAttnBackwardData[]. The queries, keys, values, weights, and reserveSpace arguments should be the same as in cudnnMultiHeadAttnForward[] and
cudnn_multiHeadAttnBackwardData() calls. The dout argument should be the same as in cudnn_multiHeadAttnBackwardData().

Parameters

handle
   Input. The current context handle.

attnDesc
   Input. A previously initialized attention descriptor.

addGrad
   Input. Weight gradient output mode.

qDesc
   Input. Descriptor for the query sequence data.

queries
   Input. Pointer to queries sequence data in the device memory.

kDesc
   Input. Descriptor for the keys sequence data.

keys
   Input. Pointer to keys sequence data in the device memory.

vDesc
   Input. Descriptor for the values sequence data.

values
   Input. Pointer to values sequence data in the device memory.

doDesc
   Input. Descriptor for the δ_{out} gradients (vectors of partial derivatives of the loss function with respect to the multi-head attention outputs).

dout
   Input. Pointer to δ_{out} gradient data in the device memory.

weightSizeInBytes
   Input. Size of the weights and dweights buffers in bytes.

weights
   Input. Address of the weight buffer in the device memory.

dweights
   Output. Address of the weight gradient buffer in the device memory.
workSpaceSizeInBytes

*Input.* Size of the work-space buffer in bytes used for temporary API storage.

workSpace

*Input/Output.* Address of the work-space buffer in the device memory.

reserveSpaceSizeInBytes

*Input.* Size of the reserve-space buffer in bytes used for data exchange between forward and backward (gradient) API calls.

reserveSpace

*Input/Output.* Address to the reserve-space buffer in the device memory.

Returns

**CUDNN_STATUS_SUCCESS**

No errors were detected while processing API input arguments and launching GPU kernels.

**CUDNN_STATUS_BAD_PARAM**

An invalid or incompatible input argument was encountered.

**CUDNN_STATUS_EXECUTION_FAILED**

The process of launching a GPU kernel returned an error, or an earlier kernel did not complete successfully.

**CUDNN_STATUS_INTERNAL_ERROR**

An inconsistent internal state was encountered.

**CUDNN_STATUS_NOT_SUPPORTED**

A requested option or a combination of input arguments is not supported.

8.2.17.  **cudnnRNNBackwardData()**

This function has been deprecated in cuDNN 8.0. Use **cudnnRNNBackwardData_v8()** instead of **cudnnRNNBackwardData().**

```c
#include <cudnn.h>

int cudnnRNNBackwardData( 
    cudnnHandle_t                   handle, 
    const cudnnRNNDescriptor_t      rnnDesc, 
    const int                       seqLength, 
    const cudnnTensorDescriptor_t  *yDesc, 
    const void                     *y, 
    const cudnnTensorDescriptor_t  *dyDesc, 
    const void                     *dy, 
    const cudnnTensorDescriptor_t   dhyDesc, 
    const void                     *dhy, 
    const cudnnTensorDescriptor_t   dcyDesc, 
    const void                     *dcy, 
    const cudnnFilterDescriptor_t   wDesc, 
    const void                     *w, 
    const cudnnTensorDescriptor_t   hxDesc, 
    const void                     *hx, 
    const cudnnTensorDescriptor_t   cxDesc
)
```
This routine executes the recurrent neural network described by `rnnDesc` with output gradients `dy`, `dhy`, and `dhc`, weights `w` and input gradients `dx`, `dhx`, and `dcx`. `workspace` is required for intermediate storage. The data in `reserveSpace` must have previously been generated by `cudnnRNNForwardTraining()`. The same `reserveSpace` data must be used for future calls to `cudnnRNNBackwardWeights()` if they execute on the same input data.

### Parameters

**handle**

*Input.* Handle to a previously created cuDNN context. For more information, see `cudnnHandle_t`.

**rnnDesc**

*Input.* A previously initialized RNN descriptor. For more information, see `cudnnRNNDescriptor_t`.

**seqLength**

*Input.* Number of iterations to unroll over. The value of this `seqLength` must not exceed the value that was used in the `cudnnGetRNNWorkspaceSize()` function for querying the workspace size required to execute the RNN.

**yDesc**

*Input.* An array of fully packed tensor descriptors describing the output from each recurrent iteration (one descriptor per iteration). For more information, see `cudnnTensorDescriptor_t`. The second dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the second dimension should match the `hiddenSize` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the second dimension should match double the `hiddenSize` argument.

The first dimension of the tensor `n` must match the first dimension of the tensor `n` in `dyDesc`.

**y**

*Input.* Data pointer to GPU memory associated with the output tensor descriptor `yDesc`. 

```c
const void *cx,
const cudnnTensorDescriptor_t *dxDesc,
void *dx,
const cudnnTensorDescriptor_t *dhxDesc,
void *dhx,
const cudnnTensorDescriptor_t *dcxDesc,
void *dcx,
size_t *workspace,
const void *reserveSpace,
size_t *reserveSpaceSizeInBytes,
```
dyDesc

*Input.* An array of fully packed tensor descriptors describing the gradient at the output from each recurrent iteration (one descriptor per iteration). The second dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the second dimension should match the `hiddenSize` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the second dimension should match double the `hiddenSize` argument.

The first dimension of the tensor `n` must match the first dimension of the tensor `n` in `dxDesc`.

dy

*Input.* Data pointer to GPU memory associated with the tensor descriptors in the array `dyDesc`.

dhyDesc

*Input.* A fully packed tensor descriptor describing the gradients at the final hidden state of the RNN. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `xDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.

dhy

*Input.* Data pointer to GPU memory associated with the tensor descriptor `dhyDesc`. If a NULL pointer is passed, the gradients at the final hidden state of the network will be initialized to zero.

dcyDesc

*Input.* A fully packed tensor descriptor describing the gradients at the final cell state of the RNN. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.
The second dimension must match the first dimension of the tensors described in xDesc. The third dimension must match the hiddenSize argument used to initialize rnnDesc. The tensor must be fully packed.

dcy

*Input.* Data pointer to GPU memory associated with the tensor descriptor dcyDesc. If a NULL pointer is passed, the gradients at the final cell state of the network will be initialized to zero.

wDesc

*Input.* Handle to a previously initialized filter descriptor describing the weights for the RNN. For more information, see cudnnFilterDescriptor_t.

w

*Input.* Data pointer to GPU memory associated with the filter descriptor wDesc.

hxDesc

*Input.* A fully packed tensor descriptor describing the initial hidden state of the RNN. The first dimension of the tensor depends on the direction argument used to initialize rnnDesc:

- If direction is CUDNN_UNIDIRECTIONAL the first dimension should match the numLayers argument.
- If direction is CUDNN_BIDIRECTIONAL the first dimension should match double the numLayers argument.

The second dimension must match the second dimension of the tensors described in xDesc. The third dimension must match the hiddenSize argument used to initialize rnnDesc. The tensor must be fully packed.

hx

*Input.* Data pointer to GPU memory associated with the tensor descriptor hxDesc. If a NULL pointer is passed, the initial hidden state of the network will be initialized to zero.

cxDesc

*Input.* A fully packed tensor descriptor describing the initial cell state for LSTM networks. The first dimension of the tensor depends on the direction argument used to initialize rnnDesc:

- If direction is CUDNN_UNIDIRECTIONAL the first dimension should match the numLayers argument.
- If direction is CUDNN_BIDIRECTIONAL the first dimension should match double the numLayers argument.

The second dimension must match the second dimension of the tensors described in xDesc. The third dimension must match the hiddenSize argument used to initialize rnnDesc. The tensor must be fully packed.
cx

**Input.** Data pointer to GPU memory associated with the tensor descriptor \(cxDesc\). If a NULL pointer is passed, the initial cell state of the network will be initialized to zero.

dxDesc

**Input.** An array of fully packed tensor descriptors describing the gradient at the input of each recurrent iteration (one descriptor per iteration). The first dimension (batch size) of the tensors may decrease from element \(n\) to element \(n+1\) but may not increase. Each tensor descriptor must have the same second dimension (vector length).

dx

**Output.** Data pointer to GPU memory associated with the tensor descriptors in the array dxDesc.

dhxDesc

**Input.** A fully packed tensor descriptor describing the gradient at the initial hidden state of the RNN. The first dimension of the tensor depends on the direction argument used to initialize \(rnnDesc\):

- If `direction` is CUDNN_UNIDIRECTIONAL the first dimension should match the `numLayers` argument.
- If `direction` is CUDNN_BIDIRECTIONAL the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in xDesc. The third dimension must match the `hiddenSize` argument used to initialize \(rnnDesc\). The tensor must be fully packed.

dhx

**Output.** Data pointer to GPU memory associated with the tensor descriptor dhxDesc. If a NULL pointer is passed, the gradient at the hidden input of the network will not be set.

dcxDesc

**Input.** A fully packed tensor descriptor describing the gradient at the initial cell state of the RNN. The first dimension of the tensor depends on the direction argument used to initialize \(rnnDesc\):

- If `direction` is CUDNN_UNIDIRECTIONAL the first dimension should match the `numLayers` argument.
- If `direction` is CUDNN_BIDIRECTIONAL the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in xDesc. The third dimension must match the `hiddenSize` argument used to initialize \(rnnDesc\). The tensor must be fully packed.
dcx

*Output.* Data pointer to GPU memory associated with the tensor descriptor `dcxDesc`. If a NULL pointer is passed, the gradient at the cell input of the network will not be set.

**workspace**

*Input.* Data pointer to GPU memory to be used as a workspace for this call.

**workSpaceSizeInBytes**

*Input.* Specifies the size in bytes of the provided `workspace`.

**reserveSpace**

*Input/Output.* Data pointer to GPU memory to be used as a reserve space for this call.

**reserveSpaceSizeInBytes**

*Input.* Specifies the size in bytes of the provided `reserveSpace`.

**Returns**

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The descriptor `rnnDesc` is invalid.
- At least one of the descriptors `dhxDesc`, `wDesc`, `hxDesc`, `cxDesc`, `dcxDesc`, `dhyDesc`, `dcyDesc` or one of the descriptors in `yDesc`, `dxDesc`, `dyDesc` is invalid.
- The descriptors in one of `yDesc`, `dxDesc`, `dyDesc`, `dhxDesc`, `wDesc`, `hxDesc`, `cxDesc`, `dcxDesc`, `dhyDesc`, `dcyDesc` has incorrect strides or dimensions.
- `workSpaceSizeInBytes` is too small.
- `reserveSpaceSizeInBytes` is too small.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

**CUDNN_STATUS_ALLOC_FAILED**

The function was unable to allocate memory.

### 8.2.18. cudnnRNNBackwardData_v8()

```c
    cudnnStatus_t cudnnRNNBackwardData_v8(
        cudnnHandle_t handle,
        cudnnRNNDescriptor_t rnnDesc,
        const int32_t devSeqLengths[],
        cudnnRNNDataDescriptor_t yDesc,
```
const void *y,
const void *dy,
cudnnRNNDataDescriptor_t xDesc,
void *dx,
cudnnTensorDescriptor_t hDesc,
const void *hx,
const void *dhy,
void *dhx,
cudnnTensorDescriptor_t cDesc,
const void *cx,
const void *dcy,
void *dcx,
size_t weightSpaceSize,
const void *weightSpace,
size_t workSpaceSize,
void *workSpace,
size_t reserveSpaceSize,
void *reserveSpace);

This function computes exact, first-order derivatives of the RNN model with respect to its inputs: \( x \), \( h_x \) and for the LSTM cell type also \( c_x \). If \( o = [y, h_y, c_y] = F(x, h_x, c_x) = F(z) \) is a vector-valued function that represents the entire RNN model and it takes vectors \( x \) (for all time-steps) and vectors \( h_x, c_x \) (for all layers) as inputs, concatenated into \( z \in \mathbb{R}^n \) (network weights and biases are assumed constant), and outputs vectors \( y, h_y, c_y \) concatenated into a vector \( o \in \mathbb{R}^m \), then \( \text{cudnnRNNBackwardData}_v8() \) computes the result of \( \frac{\partial o_i}{\partial z_j}^T \delta_{\text{out}} \) where \( \delta_{\text{out}} \) is the \( m \times 1 \) gradient of the loss function with respect to all RNN outputs. The \( \delta_{\text{out}} \) gradient is back propagated through prior layers of the deep learning model, starting from the model output. \( \frac{\partial o_i}{\partial z_j} \) is the \( m \times n \) Jacobian matrix of \( F(z) \). The \( \delta_{\text{out}} \) input is supplied via the \( dy, dhy, \) and \( dcy \) arguments and gradient results \( \frac{\partial o_i}{\partial z_j}^T \delta_{\text{out}} \) are written to the \( dx, dhx, \) and \( dcx \) buffers.

Locations of \( x, y, h_x, c_x, h_y, c_y, dx, dy, dhx, dcx, dhy, \) and \( dcy \) signals a multi-layer RNN model are shown in the Figure below. Note that internal RNN signals (between time-steps and between layers) are not exposed by the \( \text{cudnnRNNBackwardData}_v8() \) function.
Figure 3. Locations of $x$, $y$, $hx$, $cx$, $hy$, $cy$, $dx$, $dy$, $dhx$, $dcx$, $dhy$, and $dcy$ signals a multi-layer RNN model.

Memory addresses to the primary RNN output $y$, the initial hidden state $hx$, and the initial cell state $cx$ (for LSTM only) should point to the same data as in the preceding `cudnnRNNForward()` call. The $dy$ and $dx$ pointers cannot be NULL.

The `cudnnRNNBackwardData_v8()` function accepts any combination of $dhy$, $dhx$, $dcy$, $dcx$ buffer addresses being NULL. When $dhy$ or $dcy$ are NULL, it is assumed that those inputs are zero. When $dhx$ or $dcx$ pointers are NULL then the corresponding results are not written by `cudnnRNNBackwardData_v8()`.

When all $hx$, $dhy$, $dhx$ pointers are NULL, then the corresponding tensor descriptor $hDesc$ can be NULL too. The same rule applies to the $cx$, $dcy$, $dcx$ pointers and the $cDesc$ tensor descriptor.

The `cudnnRNNBackwardData_v8()` function allows the user to use padded layouts for inputs $y$, $dy$, and output $dx$. In padded or unpacked layouts (CUDNN_RNN_DATA_LAYOUT_SEQ_MAJOR_UNPACKED, CUDNN_RNN_DATA_LAYOUT_BATCH_MAJOR_UNPACKED) each sequence of vectors in a mini-batch has a fixed length defined by the `maxSeqLength` argument in the `cudnnSetRNNDataDescriptor()` function. The term “unpacked” refers here to the presence of padding vectors, and not unused address ranges between contiguous vectors.

Each padded, fixed-length sequence starts from a segment of valid vectors. The valid vector count is stored in `seqLengthArray` passed to `cudnnSetRNNDataDescriptor()`, such that $0 < \text{seqLengthArray}[i] \leq \text{maxSeqLength}$ for all sequences in a mini-batch, i.e., for $i=0..\text{batchSize}-1$. The remaining padding vectors make the combined sequence length equal to `maxSeqLength`. Both sequence-major and batch-major padded layouts are supported.

In addition, a packed sequence-major layout: CUDNN_RNN_DATA_LAYOUT_SEQ_MAJOR_PACKED can be selected by the user. In the latter layout, sequences of vectors in a mini-batch are sorted in the descending order according to the sequence lengths. First, all vectors for time
step zero are stored. They are followed by vectors for time step one, and so on. This layout uses no padding vectors.

The same layout type must be specified in xDesc and yDesc descriptors.

Two host arrays named seqLengthArray in xDesc and yDesc RNN data descriptors must be the same. In addition, a copy of seqLengthArray in the device memory must be passed via the devSeqLengths argument. This array is supplied directly to GPU kernels. The cudnnRNNBackwardData_v8() function does not verify that sequence lengths stored in devSeqLengths in GPU memory are the same as in xDesc and yDesc descriptors in CPU memory. Sequence length arrays from xDesc and yDesc descriptors are checked for consistency, however.

The cudnnRNNBackwardData_v8() function must be called after cudnnRNNForward(). The cudnnRNNForward() function should be invoked with the fwdMode argument of type cudnnRNNForward() set to CUDNN_FWD_MODE_TRAINING.

Parameters

**handle**

*Input.* The current cuDNN context handle.

**rnnDesc**

*Input.* A previously initialized RNN descriptor.

**devSeqLengths**

*Input.* A copy of seqLengthArray from xDesc or yDesc RNN data descriptors. The devSeqLengths array must be stored in GPU memory as it is accessed asynchronously by GPU kernels, possibly after the cudnnRNNBackwardData_v8() function exists. This argument cannot be NULL.

**yDesc**

*Input.* A previously initialized descriptor corresponding to the RNN model primary output. The dataType, layout, maxSeqLength, batchSize, and seqLengthArray need to match that of xDesc.

**y, dy**

*Input.* Data pointers to GPU buffers holding the RNN model primary output and gradient deltas (gradient of the loss function with respect to y). The y output should be produced by the preceding cudnnRNNForward() call. The y and dy vectors are expected to be laid out in memory according to the layout specified by yDesc. The elements in the tensor (including elements in padding vectors) must be densely packed. The y and dy arguments cannot be NULL.

**xDesc**

*Input.* A previously initialized RNN data descriptor corresponding to the gradient of the loss function with respect to the RNN primary model input. The dataType, layout, maxSeqLength, batchSize, and seqLengthArray must match that of yDesc.
The parameter `vectorSize` must match the `inputSize` argument passed to the `cudnnSetRNNDescriptor_v8()` function.

dx

*Output.* Data pointer to GPU memory where backpropagated gradients of the loss function with respect to the RNN primary input `x` should be stored. The vectors are expected to be arranged in memory according to the layout specified by `xDesc`. The elements in the tensor (including padding vectors) must be densely packed. This argument cannot be `NULL`.

hDesc

*Input.* A tensor descriptor describing the initial RNN hidden state `hx` and gradients of the loss function with respect to the initial of final hidden state. Hidden state data and the corresponding gradients are fully packed. The first dimension of the tensor depends on the `dirMode` argument passed to the `cudnnSetRNNDescriptor_v8()` function.

- If `dirMode` is `CUDNN_UNIDIRECTIONAL`, then the first dimension should match the `numLayers` argument passed to `cudnnSetRNNDescriptor_v8()`.
- If `dirMode` is `CUDNN_BIDIRECTIONAL`, then the first dimension should be double the `numLayers` argument passed to `cudnnSetRNNDescriptor_v8()`.

The second dimension must match the `batchSize` parameter described in `xDesc`. The third dimension depends on whether RNN mode is `CUDNN_LSTM` and whether the LSTM projection is enabled. Specifically:

- If RNN mode is `CUDNN_LSTM` and LSTM projection is enabled, the third dimension must match the `projSize` argument passed to the `cudnnSetRNNDescriptor_v8()` call.
- Otherwise, the third dimension must match the `hiddenSize` argument passed to the `cudnnSetRNNDescriptor_v8()` call used to initialize `rnnDesc`.

hx, dhy

*Input.* Addresses of GPU buffers with the RNN initial hidden state `hx` and gradient deltas `dhy`. Data dimensions are described by the `hDesc` tensor descriptor. If a `NULL` pointer is passed in `hx` or `dhy` arguments, the corresponding buffer is assumed to contain all zeros.

dhx

*Output.* Pointer to the GPU buffer where first-order derivatives corresponding to initial hidden state variables should be stored. Data dimensions are described by the `hDesc` tensor descriptor. If a `NULL` pointer is assigned to `dhx`, the backpropagated derivatives are not saved.

cDesc

*Input.* For LSTM networks only. A tensor descriptor describing the initial cell state `cx` and gradients of the loss function with respect to the initial of final cell state. Cell state data are fully packed. The first dimension of the tensor depends on the `dirMode` argument passed to the `cudnnSetRNNDescriptor_v8()` call.
If `dirMode` is **CUDNN_UNIDIRECTIONAL**, then the first dimension should match the `numLayers` argument passed to `cudnnSetRNNDescriptor_v8()`.

If `dirMode` is **CUDNN_BIDIRECTIONAL**, then the first dimension should be double the `numLayers` argument passed to `cudnnSetRNNDescriptor_v8()`.

The second tensor dimension must match the `batchSize` parameter in `xDesc`. The third dimension must match the `hiddenSize` argument passed to the `cudnnSetRNNDescriptor_v8()` call.

**cx, dcy**

*Input.* For LSTM networks only. Addresses of GPU buffers with the initial LSTM state data and gradient deltas `dcy`. Data dimensions are described by the `cDesc` tensor descriptor. If a **NULL** pointer is passed in `cx` or `dcy` arguments, the corresponding buffer is assumed to contain all zeros.

**dcx**

*Output.* For LSTM networks only. Pointer to the GPU buffer where first-order derivatives corresponding to initial LSTM state variables should be stored. Data dimensions are described by the `cDesc` tensor descriptor. If a **NULL** pointer is assigned to `dcx`, the backpropagated derivatives are not saved.

**weightSpaceSize**

*Input.* Specifies the size in bytes of the provided weight-space buffer.

**weightSpace**

*Input.* Address of the weight space buffer in GPU memory.

**workSpaceSize**

*Input.* Specifies the size in bytes of the provided workspace buffer.

**workSpace**

*Input/Output.* Address of the workspace buffer in GPU memory to store temporary data.

**reserveSpaceSize**

*Input.* Specifies the size in bytes of the reserve-space buffer.

**reserveSpace**

*Input/Output.* Address of the reserve-space buffer in GPU memory.

**Returns**

**CUDNN_STATUS_SUCCESS**

No errors were detected while processing API input arguments and launching GPU kernels.

**CUDNN_STATUS_NOT_SUPPORTED**

At least one of the following conditions are met:
variable sequence length input is passed while CUDNN_RNN_ALGO_PERSIST_STATIC or CUDNN_RNN_ALGO_PERSIST_DYNAMIC is specified

- CUDNN_RNN_ALGO_PERSIST_STATIC or CUDNN_RNN_ALGO_PERSIST_DYNAMIC is requested on pre-Pascal devices
- the ‘double’ floating point type is used for input/output and the CUDNN_RNN_ALGO_PERSIST_STATIC algo

**CUDNN_STATUS_BAD_PARAM**

An invalid or incompatible input argument was encountered. For example:

- some input descriptors are NULL
- settings in rnnDesc, xDesc, yDesc, hDesc, or cDesc descriptors are invalid
- weightSpaceSize, workSpaceSize, or reserveSpaceSize is too small

**CUDNN_STATUS_EXECUTION_FAILED**

The process of launching a GPU kernel returned an error, or an earlier kernel did not complete successfully.

**CUDNN_STATUS_ALLOC_FAILED**

The function was unable to allocate CPU memory.

### 8.2.19. cudnnRNNBackwardDataEx()

This function has been deprecated in cuDNN 8.0. Use [cudnnRNNBackwardData_v8](#) instead of cudnnRNNBackwardDataEx().

```c
 cusnStatus_t cudnnRNNBackwardDataEx(    
    cudnnHandle_t                     handle,    
    const cudnnRNNDescriptor_t        rnnDesc,    
    const cudnnRNNDataDescriptor_t    yDesc,    
    const void                        *y,    
    const cudnnRNNDataDescriptor_t    dyDesc,    
    const void                        *dy,    
    const cudnnRNNDataDescriptor_t    dcDesc,    
    const void                        *dcAttn,    
    const cudnnTensorDescriptor_t     dhyDesc,    
    const void                        *dhy,    
    const cudnnTensorDescriptor_t     dcyDesc,    
    const void                        *dcy,    
    const cudnnFilterDescriptor_t     wDesc,    
    const void                        *w,    
    const cudnnTensorDescriptor_t     hxDesc,    
    const void                        *hx,    
    const cudnnTensorDescriptor_t     cxDesc,    
    const void                        *cx,    
    void                              *dxDesc,    
    void                              *dx,    
    void                              *dhxDesc,    
    void                              *dhx,    
    void                              *dcxDesc,    
    void                              *dcx,    
    void                              *dkeys,    
    void                              *workSpace,
```
This routine is the extended version of the function `cudnnRNNBackwardData()`. This function `cudnnRNNBackwardDataEx()` allows the user to use unpacked (padded) layout for input y and output dx.

In the unpacked layout, each sequence in the mini-batch is considered to be of fixed length, specified by `maxSeqLength` in its corresponding `RNNDataDescriptor`. Each fixed-length sequence, for example, the nth sequence in the mini-batch, is composed of a valid segment specified by the `seqLengthArray[n]` in its corresponding `RNNDataDescriptor`; and a padding segment to make the combined sequence length equal to `maxSeqLength`.

With the unpacked layout, both sequence major (meaning, time major) and batch major are supported. For backward compatibility, the packed sequence major layout is supported. However, similar to the non-extended function `cudnnRNNBackwardData()`, the sequences in the mini-batch need to be sorted in descending order according to length.

### Parameters

**handle**

*Input*. Handle to a previously created This function is deprecated starting in cuDNN 8.0.0. context.

**rnnDesc**

*Input*. A previously initialized RNN descriptor.

**yDesc**

*Input*. A previously initialized RNN data descriptor. Must match or be the exact same descriptor previously passed into `cudnnRNNForwardTrainingEx()`.

**y**

*Input*. Data pointer to the GPU memory associated with the RNN data descriptor `yDesc`. The vectors are expected to be laid out in memory according to the layout specified by `yDesc`. The elements in the tensor (including elements in the padding vector) must be densely packed, and no strides are supported. Must contain the exact same data previously produced by `cudnnRNNForwardTrainingEx()`.

**dyDesc**

*Input*. A previously initialized RNN data descriptor. The `dataType`, `layout`, `maxSeqLength`, `batchSize`, `vectorSize`, and `seqLengthArray` need to match the `yDesc` previously passed to `cudnnRNNForwardTrainingEx()`.

**dy**

*Input*. Data pointer to the GPU memory associated with the RNN data descriptor `dyDesc`. The vectors are expected to be laid out in memory according to the layout specified by `dyDesc`. The elements in the tensor (including elements in the padding vector) must be densely packed, and no strides are supported.
**dhyDesc**

*Input.* A fully packed tensor descriptor describing the gradients at the final hidden state of the RNN. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`. Additionally:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the `batchSize` parameter in `xDesc`. The third dimension depends on whether the RNN mode is `CUDNN_LSTM` and whether LSTM projection is enabled. Additionally:

- If the RNN mode is `CUDNN_LSTM` and LSTM projection is enabled, the third dimension must match the `recProjSize` argument passed to `cudnnSetRNNProjectionLayers()` call used to set `rnnDesc`.
- Otherwise, the third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`.

**dhy**

*Input.* Data pointer to GPU memory associated with the tensor descriptor `dhyDesc`. If a NULL pointer is passed, the gradients at the final hidden state of the network will be initialized to zero.

**dcyDesc**

*Input.* A fully packed tensor descriptor describing the gradients at the final cell state of the RNN. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`. Additionally:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `xDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.

**dcy**

*Input.* Data pointer to GPU memory associated with the tensor descriptor `dcyDesc`. If a NULL pointer is passed, the gradients at the final cell state of the network will be initialized to zero.

**wDesc**

*Input.* Handle to a previously initialized filter descriptor describing the weights for the RNN.
w

*Input.* Data pointer to GPU memory associated with the filter descriptor \( w_{\text{Desc}} \).

**hxDesc**

*Input.* A fully packed tensor descriptor describing the initial hidden state of the RNN. Must match or be the exact same descriptor previously passed into `cudnnRNNForwardTrainingEx[]`.

**hx**

*Input.* Data pointer to GPU memory associated with the tensor descriptor \( hx_{\text{Desc}} \). If a NULL pointer is passed, the initial hidden state of the network will be initialized to zero. Must contain the exact same data previously passed into `cudnnRNNForwardTrainingEx[]`, or be NULL if NULL was previously passed to `cudnnRNNForwardTrainingEx[]`.

**cxDesc**

*Input.* A fully packed tensor descriptor describing the initial cell state for LSTM networks. Must match or be the exact same descriptor previously passed into `cudnnRNNForwardTrainingEx[]`.

**cx**

*Input.* Data pointer to GPU memory associated with the tensor descriptor \( cx_{\text{Desc}} \). If a NULL pointer is passed, the initial cell state of the network will be initialized to zero. Must contain the exact same data previously passed into `cudnnRNNForwardTrainingEx[]`, or be NULL if NULL was previously passed to `cudnnRNNForwardTrainingEx[]`.

**dxDesc**

*Input.* A previously initialized RNN data descriptor. The \( \text{dataType} \), \( \text{layout} \), \( \text{maxSeqLength} \), \( \text{batchSize} \), \( \text{vectorSize} \) and \( \text{seqLengthArray} \) need to match that of \( x_{\text{Desc}} \) previously passed to `cudnnRNNForwardTrainingEx[]`.

**dx**

*Output.* Data pointer to the GPU memory associated with the RNN data descriptor \( dx_{\text{Desc}} \). The vectors are expected to be laid out in memory according to the layout specified by \( dx_{\text{Desc}} \). The elements in the tensor (including elements in the padding vector) must be densely packed, and no strides are supported.

**dhxDesc**

*Input.* A fully packed tensor descriptor describing the gradient at the initial hidden state of the RNN. The descriptor must be set exactly the same way as \( dh_{\text{yDesc}} \).

**dhx**

*Output.* Data pointer to GPU memory associated with the tensor descriptor \( dhx_{\text{Desc}} \). If a NULL pointer is passed, the gradient at the hidden input of the network will not be set.

**dcxDesc**

*Input.* A fully packed tensor descriptor describing the gradient at the initial cell state of the RNN. The descriptor must be set exactly the same way as \( dc_{\text{yDesc}} \).
dcx

Output. Data pointer to GPU memory associated with the tensor descriptor dcxDesc. If a NULL pointer is passed, the gradient at the cell input of the network will not be set.

dkDesc

Reserved. User may pass in NULL.

dkeys

Reserved. User may pass in NULL.

workspace

Input. Data pointer to GPU memory to be used as a workspace for this call.

workSpaceSizeInBytes

Input. Specifies the size in bytes of the provided workspace.

reserveSpace

Input/Output. Data pointer to GPU memory to be used as a reserve space for this call.

reserveSpaceSizeInBytes

Input. Specifies the size in bytes of the provided reserveSpace.

Returns

CUDNN_STATUS_SUCCESS

The function launched successfully.

CUDNN_STATUS_NOT_SUPPORTED

At least one of the following conditions are met:

- Variable sequence length input is passed in while CUDNN_RNN_ALGO_PERSIST_STATIC or CUDNN_RNN_ALGO_PERSIST_DYNAMIC is used.
- CUDNN_RNN_ALGO_PERSIST_STATIC or CUDNN_RNN_ALGO_PERSIST_DYNAMIC is used on pre-Pascal devices.
- Double input/output is used for CUDNN_RNN_ALGO_PERSIST_STATIC.

CUDNN_STATUS_BAD_PARAM

At least one of the following conditions are met:

- The descriptor rnnDesc is invalid.
- At least one of the descriptors yDesc, dxdesc, dydesc, dhxDesc, wDesc, hxDesc, cxDesc, dcxDesc, dhyDesc, dcyDesc is invalid or has incorrect strides or dimensions.
- workSpaceSizeInBytes is too small.
- reserveSpaceSizeInBytes is too small.
**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

**CUDNN_STATUS_ALLOC_FAILED**

The function was unable to allocate memory.

### 8.2.20. `cudnnRNNBackwardWeights()`

This function has been deprecated in cuDNN 8.0. Use `cudnnRNNBackwardWeights_v8()` instead of `cudnnRNNBackwardWeights()`.

```c
#include <cudnn.h>

void cudnnRNNBackwardWeights(
    const cudnnHandle_t                   handle,
    const cudnnRNNDescriptor_t      rnnDesc,
    const int                       seqLength,
    const cudnnTensorDescriptor_t  *xDesc,
    const void                     *x,
    const cudnnTensorDescriptor_t   hxDesc,
    const void                     *hx,
    const cudnnTensorDescriptor_t  *yDesc,
    const void                     *y,
    const void                     *workspace,
    size_t                          workSpaceSizeInBytes,
    const cudnnFilterDescriptor_t   dwDesc,
    void                           *dw,
    const void                     *reserveSpace,
    size_t                          reserveSpaceSizeInBytes)
```

This routine accumulates weight gradients `dw` from the recurrent neural network described by `rnnDesc` with inputs `x`, `hx` and outputs `y`. The mode of operation in this case is additive, the weight gradients calculated will be added to those already existing in `dw`. `workspace` is required for intermediate storage. The data in `reserveSpace` must have previously been generated by `cudnnRNNBackwardData()`.

**Parameters**

**handle**

*Input*. Handle to a previously created cuDNN context.

**rnnDesc**

*Input*. A previously initialized RNN descriptor.

**seqLength**

*Input*. Number of iterations to unroll over. The value of this `seqLength` must not exceed the value that was used in `cudnnGetRNNWorkspaceSize()` function for querying the workspace size required to execute the RNN.

**xDesc**

*Input*. An array of fully packed tensor descriptors describing the input to each recurrent iteration (one descriptor per iteration). The first dimension (batch size) of the tensors may decrease from element `n` to element `n+1` but may not increase. Each tensor descriptor must have the same second dimension (vector length).
x

Input. Data pointer to GPU memory associated with the tensor descriptors in the array xDesc.

hxDesc

Input. A fully packed tensor descriptor describing the initial hidden state of the RNN. The first dimension of the tensor depends on the direction argument used to initialize rnnDesc:

- If direction is CUDNN_UNIDIRECTIONAL the first dimension should match the numLayers argument.
- If direction is CUDNN_BIDIRECTIONAL the first dimension should match double the numLayers argument.

The second dimension must match the first dimension of the tensors described in xDesc. The third dimension must match the hiddenSize argument used to initialize rnnDesc. The tensor must be fully packed.

hx

Input. Data pointer to GPU memory associated with the tensor descriptor hxDesc. If a NULL pointer is passed, the initial hidden state of the network will be initialized to zero.

yDesc

Input. An array of fully packed tensor descriptors describing the output from each recurrent iteration (one descriptor per iteration). The second dimension of the tensor depends on the direction argument used to initialize rnnDesc:

- If direction is CUDNN_UNIDIRECTIONAL the second dimension should match the hiddenSize argument.
- If direction is CUDNN_BIDIRECTIONAL the second dimension should match double the hiddenSize argument.

The first dimension of the tensor n must match the first dimension of the tensor n in dyDesc.

y

Input. Data pointer to GPU memory associated with the output tensor descriptor yDesc.

workspace

Input. Data pointer to GPU memory to be used as a workspace for this call.

workSpaceSizeInBytes

Input. Specifies the size in bytes of the provided workspace.

dwDesc

Input. Handle to a previously initialized filter descriptor describing the gradients of the weights for the RNN.
Input/Output. Data pointer to GPU memory associated with the filter descriptor dwDesc.

reserveSpace

Input. Data pointer to GPU memory to be used as a reserve space for this call.

reserveSpaceSizeInBytes

Input. Specifies the size in bytes of the provided reserveSpace.

Returns

CUDNN_STATUS_SUCCESS
The function launched successfully.

CUDNN_STATUS_NOT_SUPPORTED
The function does not support the provided configuration.

CUDNN_STATUS_BAD_PARAM
At least one of the following conditions are met:

- The descriptor rnnDesc is invalid.
- At least one of the descriptors hxDesc, dwDesc or one of the descriptors in xDesc, yDesc is invalid.
- The descriptors in one of xDesc, hxDesc, yDesc, dwDesc have incorrect strides or dimensions.
- workSpaceSizeInBytes is too small.
- reserveSpaceSizeInBytes is too small.

CUDNN_STATUS_EXECUTION_FAILED
The function failed to launch on the GPU.

CUDNN_STATUS_ALLOC_FAILED
The function was unable to allocate memory.

8.2.21. cudnnRNNBackwardWeights_v8()

cudnnStatus_t cudnnRNNBackwardWeights_v8(
  cudnnHandle_t handle,
  cudnnRNNDescriptor_t rnnDesc,
  cudnnWgradMode_t addGrad,
  const int32_t *devSeqLengths[],
  cudnnRNNDataDescriptor_t xDesc,
  const void *x,
  cudnnTensorDescriptor_t hDesc,
  const void *hx,
  cudnnRNNDataDescriptor_t yDesc,
  const void *y,
  size_t weightSpaceSize,
  void *dweightSpace,
  size_t workSpaceSize,
  void *workspace,
size_t reserveSpaceSize,
void *reserveSpace);

This function computes exact, first-order derivatives of the RNN model with respect to all trainable parameters: weights and biases. If \( o = [y, hy, cy] = F(w) \) is a vector-valued function that represents the multi-layer RNN model and it takes some vector \( w \in \mathbb{R}^n \) of “flatten” weights or biases as input (with all other data inputs constant), and outputs vector \( o \in \mathbb{R}^m \), then cudnnRNNBackwardWeights_v8() computes the result of \( (\partial o_i / \partial w_j)^T \delta_{out} \) where \( \delta_{out} \) is the \( m \times 1 \) gradient of the loss function with respect to all RNN outputs. The \( \delta_{out} \) gradient is back propagated through prior layers of the deep learning model, starting from the model output. \( \partial o_i / \partial w_j \) is the \( m \times n \) Jacobian matrix of \( F(w) \). The \( \delta_{out} \) input is supplied via the dy, dhy, and dcy arguments in the cudnnRNNBackwardData_v8() function.

All gradient results \( (\partial o_i / \partial w_j)^T \delta_{out} \) with respect to weights and biases are written to the dweightSpace buffer. The size and the organization of the dweightSpace buffer is the same as the weightSpace buffer that holds RNN weights and biases.

Gradient of the loss function with respect to weights and biases is typically computed over multiple mini-batches. In such a case, partial results computed for each mini-batch should be aggregated. The addGrad argument specifies if gradients from the current mini-batch should be added to previously computed results [CUDNN_WGRAD_MODE_ADD] or the dweightSpace buffer should be overwritten with the new results [CUDNN_WGRAD_MODE_SET]. Currently, the cudnnRNNBackwardWeights_v8() function supports the CUDNN_WGRAD_MODE_ADD mode only so the dweightSpace buffer should be zeroed by the user before invoking the routine for the first time.

The same sequence lengths must be specified in the xDesc descriptor and in the device array devSeqLengths. The cudnnRNNBackwardWeights_v8() function should be invoked after cudnnRNNBackwardData().

Parameters

**handle**

*Input*. The current cuDNN context handle.

**rnnDesc**

*Input*. A previously initialized RNN descriptor.

**addGrad**

*Input*. Weight gradient output mode. For more details, see the description of the cudnnWgradMode_t enumerated type. Currently, only the CUDNN_WGRAD_MODE_ADD mode is supported by the cudnnRNNBackwardWeights_v8() function.

**devSeqLengths**

*Input*. A copy of seqLengthArray from the xDesc RNN data descriptor. The devSeqLengths array must be stored in GPU memory as it is accessed asynchronously by GPU kernels, possibly after the cudnnRNNBackwardWeights_v8() function exists.
**xDesc**

*Input.* A previously initialized descriptor corresponding to the RNN model input data. This is the same RNN data descriptor as used in the preceding `cudnnRNNForward[]` and `cudnnRNNBackwardData_v8[]` calls.

**x**

*Input.* Pointer to the GPU buffer with the primary RNN input. The same buffer address `x` should be provided in prior `cudnnRNNForward[]` and `cudnnRNNBackwardData_v8[]` calls.

**hDesc**

*Input.* A tensor descriptor describing the initial RNN hidden state. Hidden state data are fully packed. This is the same tensor descriptor as used in prior `cudnnRNNForward[]` and `cudnnRNNBackwardData_v8[]` calls.

**hx**

*Input.* Pointer to the GPU buffer with the RNN initial hidden state. The same buffer address `hx` should be provided in prior `cudnnRNNForward[]` and `cudnnRNNBackwardData_v8[]` calls.

**yDesc**

*Input.* A previously initialized descriptor corresponding to the RNN model output data. This is the same RNN data descriptor as used in prior `cudnnRNNForward[]` and `cudnnRNNBackwardData_v8[]` calls.

**y**

*Output.* Pointer to the GPU buffer with the primary RNN output as generated by the prior `cudnnRNNForward[]` call. Data in the `y` buffer are described by the `yDesc` descriptor. Elements in the `y` tensor (including elements in padding vectors) must be densely packed.

**weightSpaceSize**

*Input.* Specifies the size in bytes of the provided weight-space buffer.

**dweightSpace**

*Output.* Address of the weight space buffer in GPU memory.

**workSpaceSize**

*Input.* Specifies the size in bytes of the provided workspace buffer.

**workSpace**

*Input/Output.* Address of the workspace buffer in GPU memory to store temporary data.

**reserveSpaceSize**

*Input.* Specifies the size in bytes of the reserve-space buffer.

**reserveSpace**

*Input/Output.* Address of the reserve-space buffer in GPU memory.
Returns

CUDNN_STATUS_SUCCESS

No errors were detected while processing API input arguments and launching GPU kernels.

CUDNN_STATUS_NOT_SUPPORTED

The function does not support the provided configuration.

CUDNN_STATUS_BAD_PARAM

An invalid or incompatible input argument was encountered. For example:

- some input descriptors are NULL
- settings in rnnDesc, xDesc, yDesc, or hDesc descriptors are invalid
- weightSpaceSize, workSpaceSize, or reserveSpaceSize values are too small
- the addGrad argument is not equal to CUDNN_WGRAD_MODE_ADD

CUDNN_STATUS_EXECUTION_FAILED

The process of launching a GPU kernel returned an error, or an earlier kernel did not complete successfully.

CUDNN_STATUS_ALLOC_FAILED

The function was unable to allocate CPU memory.

8.2.22. cudnnRNNBackwardWeightsEx()

This function has been deprecated in cuDNN 8.0. Use cudnnRNNBackwardWeights_v8[] instead of cudnnRNNBackwardWeightsEx().

```c
#include <cudnn.h>

typedef cudnnStatus_t cudnnRNNBackwardWeightsEx(
    cudnnHandle_t handle,
    const cudnnRNNDescriptor_t rnnDesc,
    const cudnnRNNDataDescriptor_t xDesc,
    const void *x,
    const cudnnTensorDescriptor_t hxDesc,
    const void *hx,
    const cudnnRNNDataDescriptor_t yDesc,
    const void *y,
    void *workSpace,
    size_t workSpaceSizeInBytes,
    const cudnnFilterDescriptor_t dwDesc,
    void *dw,
    void *reserveSpace,
    size_t reserveSpaceSizeInBytes)
```

This routine is the extended version of the function cudnnRNNBackwardWeights[]. This function cudnnRNNBackwardWeightsEx() allows the user to use an unpacked (padded) layout for input x and output dw.

In the unpacked layout, each sequence in the mini-batch is considered to be of fixed length, specified by maxSeqLength in its corresponding RNNDataDescriptor. Each fixed-length sequence, for example, the nth sequence in the mini-batch, is composed of a valid segment
specified by the `seqLengthArray[n]` in its corresponding `RNNDataDescriptor`; and a padding segment to make the combined sequence length equal to `maxSeqLength`.

With the unpacked layout, both sequence major (meaning, time major) and batch major are supported. For backward compatibility, the packed sequence major layout is supported. However, similar to the non-extended function `cudnnRNNBackwardWeights()`, the sequences in the mini-batch need to be sorted in descending order according to length.

**Parameters**

**handle**

*Input.* Handle to a previously created cuDNN context.

**rnnDesc**

*Input.* A previously initialized RNN descriptor.

**xDesc**

*Input.* A previously initialized RNN data descriptor. Must match or be the exact same descriptor previously passed into `cudnnRNNForwardTrainingEx()`.

**x**

*Input.* Data pointer to GPU memory associated with the tensor descriptors in the array `xDesc`. Must contain the exact same data previously passed into `cudnnRNNForwardTrainingEx()`.

**hxDesc**

*Input.* A fully packed tensor descriptor describing the initial hidden state of the RNN. Must match or be the exact same descriptor previously passed into `cudnnRNNForwardTrainingEx()`.

**hx**

*Input.* Data pointer to GPU memory associated with the tensor descriptor `hxDesc`. If a `NULL` pointer is passed, the initial hidden state of the network will be initialized to zero. Must contain the exact same data previously passed into `cudnnRNNForwardTrainingEx()`, or be `NULL` if `NULL` was previously passed to `cudnnRNNForwardTrainingEx()`.

**yDesc**

*Input.* A previously initialized RNN data descriptor. Must match or be the exact same descriptor previously passed into `cudnnRNNForwardTrainingEx()`.

**y**

*Input.* Data pointer to GPU memory associated with the output tensor descriptor `yDesc`. Must contain the exact same data previously produced by `cudnnRNNForwardTrainingEx()`.

**workspace**

*Input.* Data pointer to GPU memory to be used as a workspace for this call.
workSpaceSizeInBytes

*Input*. Specifies the size in bytes of the provided *workspace*.

dwDesc

*Input*. Handle to a previously initialized filter descriptor describing the gradients of the weights for the RNN.

dw

*Input/Output*. Data pointer to GPU memory associated with the filter descriptor `dwDesc`.

reserveSpace

*Input*. Data pointer to GPU memory to be used as a reserve space for this call.

reserveSpaceSizeInBytes

*Input*. Specifies the size in bytes of the provided *reserveSpace*.

Returns

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_NOT_SUPPORTED**

The function does not support the provided configuration.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The descriptor `rnnDesc` is invalid.
- At least one of the descriptors `xDesc`, `yDesc`, `hxDesc`, `dwDesc` is invalid, or has incorrect strides or dimensions.
- `workSpaceSizeInBytes` is too small.
- `reserveSpaceSizeInBytes` is too small.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

**CUDNN_STATUS_ALLOC_FAILED**

The function was unable to allocate memory.

### 8.2.23. `cudnnRNNForwardTraining()`

This function is deprecated starting in cuDNN 8.0.0.

Use `cudnnRNNForward()` instead of `cudnnRNNForwardTraining()`.

```c
#include <cudnn.h>

cudnnStatus_t cudnnRNNForwardTraining(
    cudnnHandle_t     handle,  
    const cudnnRNNDescriptor_t rnnDesc,  
    const int         seqLength,  
    const cudnnTensorDescriptor_t *xDesc,
```
This routine executes the recurrent neural network described by `rnnDesc` with inputs `x`, `hx`, and `cx`, weights `w` and outputs `y`, `hy`, and `cy`. `workspace` is required for intermediate storage. `reserveSpace` stores data required for training. The same `reserveSpace` data must be used for future calls to `cudnnRNNBackwardData[]` and `cudnnRNNBackwardWeights[]` if these execute on the same input data.

**Parameters**

**handle**

*Input.* Handle to a previously created cuDNN context.

**rnnDesc**

*Input.* A previously initialized RNN descriptor.

**seqLength**

*Input.* Number of iterations to unroll over. The value of this `seqLength` must not exceed the value that was used in `cudnnGetRNNWorkspaceSize[]` function for querying the workspace size required to execute the RNN.

**xDesc**

*Input.* An array of `seqLength` fully packed tensor descriptors. Each descriptor in the array should have three dimensions that describe the input data format to one recurrent iteration (one descriptor per RNN time-step). The first dimension (batch size) of the tensors may decrease from iteration element `n` to iteration element `n+1` but may not increase. Each tensor descriptor must have the same second dimension (RNN input vector length, `inputSize`). The third dimension of each tensor should be 1. Input vectors are expected to be arranged in the column-major order so strides in `xDesc` should be set as follows:

```c
```

**x**

*Input.* Data pointer to GPU memory associated with the array of tensor descriptors `xDesc`. The input vectors are expected to be packed contiguously with the first vector of iterations (time-step) `n+1` following directly the last vector of iteration `n`. In other words, input vectors
for all RNN time-steps should be packed in the contiguous block of GPU memory with no
gaps between the vectors.

**hxDesc**

*Input.* A fully packed tensor descriptor describing the initial hidden state of the RNN.
The first dimension of the tensor depends on the `direction` argument used to initialize
`rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the
  `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the
  `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `xDesc`. The
third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The
tensor must be fully packed.

**hx**

*Input.* Data pointer to GPU memory associated with the tensor descriptor `hxDesc`. If a `NULL`
pointer is passed, the initial hidden state of the network will be initialized to zero.

**cxDesc**

*Input.* A fully packed tensor descriptor describing the initial cell state for LSTM networks.
The first dimension of the tensor depends on the `direction` argument used to initialize
`rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the
  `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the
  `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `xDesc`. The
third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The
tensor must be fully packed.

**cx**

*Input.* Data pointer to GPU memory associated with the tensor descriptor `cxDesc`. If a `NULL`
pointer is passed, the initial cell state of the network will be initialized to zero.

**wDesc**

*Input.* Handle to a previously initialized filter descriptor describing the weights for the RNN.

**w**

*Input.* Data pointer to GPU memory associated with the filter descriptor `wDesc`. 
**yDesc**

*Input.* An array of fully packed tensor descriptors describing the output from each recurrent iteration [one descriptor per iteration]. The second dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the second dimension should match the `hiddenSize` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the second dimension should match double the `hiddenSize` argument.

The first dimension of the tensor `n` must match the first dimension of the tensor `n` in `xDesc`.

**y**

*Output.* Data pointer to GPU memory associated with the output tensor descriptor `yDesc`.

**hyDesc**

*Input.* A fully packed tensor descriptor describing the final hidden state of the RNN. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `xDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.

**hy**

*Output.* Data pointer to GPU memory associated with the tensor descriptor `hyDesc`. If a NULL pointer is passed, the final hidden state of the network will not be saved.

**cyDesc**

*Input.* A fully packed tensor descriptor describing the final cell state for LSTM networks. The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `xDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.
cy

*Output.* Data pointer to GPU memory associated with the tensor descriptor `cyDesc`. If a NULL pointer is passed, the final cell state of the network will not be saved.

**workspace**

*Input.* Data pointer to GPU memory to be used as a workspace for this call.

**workSpaceSizeInBytes**

*Input.* Specifies the size in bytes of the provided `workspace`.

**reserveSpace**

*Input/Output.* Data pointer to GPU memory to be used as a reserve space for this call.

**reserveSpaceSizeInBytes**

*Input.* Specifies the size in bytes of the provided `reserveSpace`.

**Returns**

**CUDNN_STATUS_SUCCESS**

The function launched successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of the following conditions are met:

- The descriptor `rnnDesc` is invalid.
- At least one of the descriptors `hxDesc`, `cxDesc`, `wDesc`, `hyDesc`, `cyDesc` or one of the descriptors in `xDesc`, `yDesc` is invalid.
- The descriptors in one of `xDesc`, `hxDesc`, `cxDesc`, `wDesc`, `yDesc`, `hyDesc`, `cyDesc` have incorrect strides or dimensions.
- `workSpaceSizeInBytes` is too small.
- `reserveSpaceSizeInBytes` is too small.

**CUDNN_STATUS_EXECUTION_FAILED**

The function failed to launch on the GPU.

**CUDNN_STATUS_ALLOC_FAILED**

The function was unable to allocate memory.

**8.2.24. cudnnRNNForwardTrainingEx()**

This function has been deprecated starting in cuDNN 8.0. Use `cudnnRNNForward()` instead of `cudnnRNNForwardTrainingEx()`.

```c
void cudnnRNNForwardTrainingEx(
  cudnnHandle_t handle,
  const cudnnRNNDescriptor_t rnnDesc,
  const cudnnRNNDataDescriptor_t xDesc,
  const void *x,
  const void *y,
  const cudnnRNNOutputDescriptor_t yDesc,
  void *yDesc,
  const cudnnRNNWorkspaceDescriptor_t workspaceDesc,
  void *workspaceDesc
);
```
This routine is the extended version of the cudnnRNNForwardTraining() function. The cudnnRNNForwardTrainingEx() allows the user to use unpacked [padded] layout for input \( x \) and output \( y \).

In the unpacked layout, each sequence in the mini-batch is considered to be of fixed length, specified by \( \text{maxSeqLength} \) in its corresponding RNNDataDescriptor. Each fixed-length sequence, for example, the \( n \)th sequence in the mini-batch, is composed of a valid segment specified by the \( \text{seqLengthArray}[n] \) in its corresponding RNNDataDescriptor; and a padding segment to make the combined sequence length equal to \( \text{maxSeqLength} \).

With the unpacked layout, both sequence major (meaning, time major) and batch major are supported. For backward compatibility, the packed sequence major layout is supported. However, similar to the non-extended function cudnnRNNForwardTraining(), the sequences in the mini-batch need to be sorted in descending order according to length.

**Parameters**

**handle**

*Input.* Handle to a previously created cuDNN context.

**rnnDesc**

*Input.* A previously initialized RNN descriptor.

**xDesc**

*Input.* A previously initialized RNN Data descriptor. The \( \text{dataType}, \text{layout}, \text{maxSeqLength}, \text{batchSize}, \) and \( \text{seqLengthArray} \) need to match that of \( yDesc \).

**x**

*Input.* Data pointer to the GPU memory associated with the RNN data descriptor \( xDesc \). The input vectors are expected to be laid out in memory according to the layout specified.
The elements in the tensor (including elements in the padding vector) must be densely packed, and no strides are supported.

**hxDesc**

*Input.* A fully packed tensor descriptor describing the initial hidden state of the RNN.

The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`. Moreover:

- If `direction` is `CUDNN_UNIDIRECTIONAL` then the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` then the first dimension should match double the `numLayers` argument.

The second dimension must match the `batchSize` parameter in `xDesc`. The third dimension depends on whether RNN mode is `CUDNN_LSTM` and whether LSTM projection is enabled. Additionally:

- If RNN mode is `CUDNN_LSTM` and LSTM projection is enabled, the third dimension must match the `recProjSize` argument passed to `cudnnSetRNNProjectionLayers()` call used to set `rnnDesc`.
- Otherwise, the third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`.

**hx**

*Input.* Data pointer to GPU memory associated with the tensor descriptor `hxDesc`. If a NULL pointer is passed, the initial hidden state of the network will be initialized to zero.

**cxDesc**

*Input.* A fully packed tensor descriptor describing the initial cell state for LSTM networks.

The first dimension of the tensor depends on the `direction` argument used to initialize `rnnDesc`. Additionally:

- If `direction` is `CUDNN_UNIDIRECTIONAL` the first dimension should match the `numLayers` argument.
- If `direction` is `CUDNN_BIDIRECTIONAL` the first dimension should match double the `numLayers` argument.

The second dimension must match the first dimension of the tensors described in `xDesc`. The third dimension must match the `hiddenSize` argument used to initialize `rnnDesc`. The tensor must be fully packed.

**cx**

*Input.* Data pointer to GPU memory associated with the tensor descriptor `cxDesc`. If a NULL pointer is passed, the initial cell state of the network will be initialized to zero.
\textbf{wDesc}\n
\textit{Input.} Handle to a previously initialized filter descriptor describing the weights for the RNN.

\textbf{w}\n
\textit{Input.} Data pointer to GPU memory associated with the filter descriptor \texttt{wDesc}.

\textbf{yDesc}\n
\textit{Input.} A previously initialized RNN data descriptor. The \texttt{dataType}, \texttt{layout}, \texttt{maxSeqLength}, \texttt{batchSize}, and \texttt{seqLengthArray} need to match that of \texttt{dyDesc} and \texttt{dxDesc}. The parameter \texttt{vectorSize} depends on whether the RNN mode is \texttt{CUDNN_LSTM} and whether LSTM projection is enabled and whether the network is bidirectional. Specifically:

- For unidirectional network, if the RNN mode is \texttt{CUDNN_LSTM} and LSTM projection is enabled, the parameter \texttt{vectorSize} must match the \texttt{recProjSize} argument passed to \texttt{cudnnSetRNNProjectionLayers()} call used to set \texttt{rnnDesc}. If the network is bidirectional, then multiply the value by 2.
- Otherwise, for unidirectional network, the parameter \texttt{vectorSize} must match the \texttt{hiddenSize} argument used to initialize \texttt{rnnDesc}. If the network is bidirectional, then multiply the value by 2.

\textbf{y}\n
\textit{Output.} Data pointer to GPU memory associated with the RNN data descriptor \texttt{yDesc}. The input vectors are expected to be laid out in memory according to the layout specified by \texttt{yDesc}. The elements in the tensor (including elements in the padding vector) must be densely packed, and no strides are supported.

\textbf{hyDesc}\n
\textit{Input.} A fully packed tensor descriptor describing the final hidden state of the RNN. The descriptor must be set exactly the same as \texttt{hxDesc}.

\textbf{hy}\n
\textit{Output.} Data pointer to GPU memory associated with the tensor descriptor \texttt{hyDesc}. If a \texttt{NULL} pointer is passed, the final hidden state of the network will not be saved.

\textbf{cyDesc}\n
\textit{Input.} A fully packed tensor descriptor describing the final cell state for LSTM networks. The descriptor must be set exactly the same as \texttt{cxDesc}.

\textbf{cy}\n
\textit{Output.} Data pointer to GPU memory associated with the tensor descriptor \texttt{cyDesc}. If a \texttt{NULL} pointer is passed, the final cell state of the network will not be saved.

\textbf{kDesc}\n
Reserved. Users may pass in \texttt{NULL}.

\textbf{keys}\n
Reserved. Users may pass in \texttt{NULL}. 
cDesc
Reserved. Users may pass in NULL.

cAttn
Reserved. Users may pass in NULL.

iDesc
Reserved. Users may pass in NULL.

iAttn
Reserved. Users may pass in NULL.

qDesc
Reserved. Users may pass in NULL.

queries
Reserved. Users may pass in NULL.

workspace
Input. Data pointer to GPU memory to be used as a workspace for this call.

workSpaceSizeInBytes
Input. Specifies the size in bytes of the provided workspace.

reserveSpace
Input/Output. Data pointer to GPU memory to be used as a reserve space for this call.

reserveSpaceSizeInBytes
Input. Specifies the size in bytes of the provided reserveSpace.

Returns

CUDNN_STATUS_SUCCESS
The function launched successfully.

CUDNN_STATUS_NOT_SUPPORTED
At least one of the following conditions are met:

▷ Variable sequence length input is passed in while CUDNN_RNN_ALGO_PERSIST_STATIC or CUDNN_RNN_ALGO_PERSIST_DYNAMIC is used.
▷ CUDNN_RNN_ALGO_PERSIST_STATIC or CUDNN_RNN_ALGO_PERSIST_DYNAMIC is used on pre-Pascal devices.
▷ Double input/output is used for CUDNN_RNN_ALGO_PERSIST_STATIC.

CUDNN_STATUS_BAD_PARAM
At least one of the following conditions are met:

▷ The descriptor rnnDesc is invalid.
At least one of the descriptors \texttt{xDesc}, \texttt{yDesc}, \texttt{hxDesc}, \texttt{cxDesc}, \texttt{wDesc}, \texttt{hyDesc}, and \texttt{cyDesc} is invalid, or have incorrect strides or dimensions.

- workSpaceSizeInBytes is too small.
- reserveSpaceSizeInBytes is too small.

**CUDNN\_STATUS\_EXECUTION\_FAILED**

The function failed to launch on the GPU.

**CUDNN\_STATUS\_ALLOC\_FAILED**

The function was unable to allocate memory.

### 8.2.25. cudnnSetCTCLossDescriptor()

```c
cudnnStatus_t cudnnSetCTCLossDescriptor(
    cudnnCTCLossDescriptor_t ctcLossDesc,
    cudnnDataType_t compType)
```

This function sets a CTC loss function descriptor. See also the extended version \texttt{cudnnSetCTCLossDescriptorEx()} to set the input normalization mode.

When the extended version \texttt{cudnnSetCTCLossDescriptorEx()} is used with \texttt{normMode} set to \texttt{CUDNN\_LOSS\_NORMALIZATION\_NONE} and the \texttt{gradMode} set to \texttt{CUDNN\_NOT\_PROPAGATE\_NAN}, then it is the same as the current function \texttt{cudnnSetCTCLossDescriptor()}, meaning:

```c
cudnnSetCtcLossDescriptor(*) = cudnnSetCtcLossDescriptorEx(*,
    normMode=CUDNN\_LOSS\_NORMALIZATION\_NONE, gradMode=CUDNN\_NOT\_PROPAGATE\_NAN)
```

**Parameters**

- **ctcLossDesc**
  
  *Output*. CTC loss descriptor to be set.

- **compType**
  
  *Input*. Compute type for this CTC loss function.

**Returns**

- **CUDNN\_STATUS\_SUCCESS**
  
  The function returned successfully.

- **CUDNN\_STATUS\_BAD\_PARAM**
  
  At least one of input parameters passed is invalid.

### 8.2.26. cudnnSetCTCLossDescriptorEx()

```c
cudnnStatus_t cudnnSetCTCLossDescriptorEx(
    cudnnCTCLossDescriptor_t ctcLossDesc,
    cudnnDataType_t compType,
    cudnnLossNormalizationMode_t normMode,
    cudnnNanPropagation_t gradMode)
```

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This function is an extension of `cudnnSetCTCLossDescriptor()`. This function provides an additional interface `normMode` to set the input normalization mode for the CTC loss function, and `gradMode` to control the NaN propagation type.

When this function `cudnnSetCTCLossDescriptorEx()` is used with `normMode` set to `CUDNN_LOSS_NORMALIZATION_NONE` and the `gradMode` set to `CUDNN_NOT_PROPAGATE_NAN`, then it is the same as `cudnnSetCTCLossDescriptor()`, meaning:

```
cudnnSetCtcLossDescriptor(*) = cudnnSetCtcLossDescriptorEx(*, normMode=CUDNN_LOSS_NORMALIZATION_NONE, gradMode=CUDNN_NOT_PROPAGATE_NAN)
```

**Parameters**

**ctcLossDesc**

*Output.* CTC loss descriptor to be set.

**compType**

*Input.* Compute type for this CTC loss function.

**normMode**

*Input.* Input normalization type for this CTC loss function. For more information, see `cudnnLossNormalizationMode_t`.

**gradMode**

*Input.* NaN propagation type for this CTC loss function. For the sequence length, `L` the number of repeated letters in the sequence, and `T` the length of sequential data, the following applies: when a sample with `L+R > T` is encountered during the gradient calculation, if `gradMode` is set to `CUDNN_PROPAGATE_NAN` (see `cudnnNanPropagation_t`), then the CTC loss function does not write to the gradient buffer for that sample. Instead, the current values, even not finite, are retained. If `gradMode` is set to `CUDNN_NOT_PROPAGATE_NAN`, then the gradient for that sample is set to zero. This guarantees finite gradient.

**Returns**

**CUDNN_STATUS_SUCCESS**

The function returned successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of input parameters passed is invalid.

8.2.27. `cudnnSetCTCLossDescriptor_v8()`

```c

cudnnStatus_t cudnnSetCTCLossDescriptorEx(
    cudnnCTCLossDescriptor_t        ctcLossDesc,
    cudnnDataType_t                 compType,
    cudnnLossNormalizationMode_t    normMode,
    cudnnNanPropagation_t           gradMode,
    int                             maxLabelLength)
```
Many CTC API functions are updated in cuDNN version 8.0.0 to support CUDA graphs. In order to do so, a new parameter is needed, `maxLabelLength`. Now that label and input data are assumed to be in GPU memory, this information is not otherwise readily available.

**Parameters**

**ctcLossDesc**

*Output.* CTC loss descriptor to be set.

**compType**

*Input.* Compute type for this CTC loss function.

**normMode**

*Input.* Input normalization type for this CTC loss function. For more information, see `cudnnLossNormalizationMode_t`.

**gradMode**

*Input.* NaN propagation type for this CTC loss function. For the sequence length, \( L \) the number of repeated letters in the sequence, and \( T \) the length of sequential data, the following applies: when a sample with \( L+R > T \) is encountered during the gradient calculation, if \( \text{gradMode} \) is set to `CUDNN_PROPAGATE_NAN` (see `cudnnNanPropagation_t`), then the CTC loss function does not write to the gradient buffer for that sample. Instead, the current values, even not finite, are retained. If \( \text{gradMode} \) is set to `CUDNN_NOT_PROPAGATE_NAN`, then the gradient for that sample is set to zero. This guarantees finite gradient.

**maxLabelLength**

*Input.* The maximum label length from the labels data.

**Returns**

**CUDNN_STATUS_SUCCESS**

The function returned successfully.

**CUDNN_STATUS_BAD_PARAM**

At least one of input parameters passed is invalid.
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