

NVIDIA Collective Communication Library (NCCL)

Release Notes

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Chapter 1. NCCL Overview

The NVIDIA® Collective Communications Library ™ (NCCL) (pronounced "Nickel") is a library of multi-GPU collective communication primitives that are topology-aware and can be easily integrated into applications.

Collective communication algorithms employ many processors working in concert to aggregate data. NCCL is not a full-blown parallel programming framework; rather, it is a library focused on accelerating collective communication primitives. The following collective operations are currently supported:

- AllReduce
- Broadcast
- Reduce
- AllGather
- ReduceScatter

Tight synchronization between communicating processors is a key aspect of collective communication. CUDA® based collectives would traditionally be realized through a combination of CUDA memory copy operations and CUDA kernels for local reductions. NCCL, on the other hand, implements each collective in a single kernel handling both communication and computation operations. This allows for fast synchronization and minimizes the resources needed to reach peak bandwidth.

NCCL conveniently removes the need for developers to optimize their applications for specific machines. NCCL provides fast collectives over multiple GPUs both within and across nodes. It supports a variety of interconnect technologies including PCIe, NVLink™ , InfiniBand Verbs, and IP sockets. NCCL also automatically patterns its communication strategy to match the system's underlying GPU interconnect topology.

Next to performance, ease of programming was the primary consideration in the design of NCCL. NCCL uses a simple C API, which can be easily accessed from a variety of programming languages. NCCL closely follows the popular collectives API defined by MPI (Message Passing Interface). Anyone familiar with MPI will thus find NCCL API very natural to use. In a minor departure from MPI, NCCL collectives take a "stream" argument which provides direct integration with the CUDA programming model. Finally, NCCL is compatible with virtually any multi-GPU parallelization model, for example:

- single-threaded
- multi-threaded, for example, using one thread per GPU

multi-process, for example, MPI combined with multi-threaded operation on GPUs

NCCL has found great application in deep learning frameworks, where the AllReduce collective is heavily used for neural network training. Efficient scaling of neural network training is possible with the multi-GPU and multi node communication provided by NCCL.

Chapter 2. NCCL Release 2.18.5

This is the NCCL 2.18.5 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.18.5 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ▶ This NCCL release supports CUDA 11.0, CUDA 12.0, and CUDA 12.2.

Fixed Issues

The following issues have been resolved in NCCL 2.18.5:

- Fixed NVLS search issues.
- Increased Max IB network interfaces to 32.
- Fixed inconsistent network device ordering when creating communicators with only one GPU per node.
- Try to have different GPUs use all network interfaces on systems with more than one network interface per GPU.

Known Issues

 Send/receive communication using CUDA VISIBLE DEVICES and PXN only works if the GPU mappings to local ranks is the same across nodes. Disabing PXN for Send/ Receive communication can workaround the issue (NCCL P2P PXN LEVEL=0).

Updating the GPG Repository Key

Chapter 3. NCCL Release 2.18.3

This is the NCCL 2.18.3 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.18.3 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- This NCCL release supports CUDA 11.0, CUDA 12.0, CUDA 12.1, and CUDA 12.2.

Fixed Issues

The following issues have been resolved in NCCL 2.18.3:

- Fixed data corruption on DGX/HGX H100 systems when using LL128 protocol.
- Fixed hang with IB SHARP and bfloat 16 on systems with less than one NIC per GPU.
- Fixed regression in initialization time.
- Fixed data corruption with IB SHARP on H100 platforms when combining multiple GPUs per process and multiple processes per node.
- Fixed crash when shared memory creation fails.
- Fixed Avg operation with IB SHARP when using Collnet/Chain algorithm.
- Fixed performance for all-to-all operations at large scale on systems with more than one NIC per GPU.
- Fixed performance on DGX H800.
- Fixed race condition in connection progress that caused a crash.
- Fixed network flush with IB SHARP.
- ▶ Fixed PXN operation when CUDA VISIBLE DEVICES is set.
- Fixed performance of aggregated reduceScatter/allGather operations.

Known Issues

▶ Send/receive communication using CUDA VISIBLE DEVICES and PXN only works if the GPU mappings to local ranks is the same across nodes. Disabing PXN for Send/ Receive communication can workaround the issue (NCCL P2P PXN LEVEL=0).

Updating the GPG Repository Key

Chapter 4. NCCL Release 2.18.1

This is the NCCL 2.18.1 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.18.1 has been tested with the following:

- Deep learning framework containers. Refer to the Support Matrix for the supported container version.
- ▶ This NCCL release supports CUDA 11.0, CUDA 12.0, and CUDA 12.1.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Add inter-node algorithms for NVLink SHARP: NVLink SHARP + IB SHARP (NVLS), NVLink SHARP + Tree (NVLSTREE).
- Add ncclCommSplit primitive, with optional resource sharing.
- Add support for memory management using cuMem functions (disabled by default).
- Add option to use multiple QPs in round-robin mode.

Known Issues

On systems where a NIC shares a PCI switch with only one GPU (like on HGX H100), the Tree algorithm will make data transit through the CPU, making the LL128 protocol unsafe. This could result in data corruption. You can workaround this issue by setting the following:

NCCL IB PCI RELAXED ORDERING=0

Another solution is to disable the LL128 protocol with the following:

NCCL PROTO=^LL128

- On systems with less than 1 NIC per GPU, running bfloat16 reductions with IB SHARP will cause a hang.
- Running allreduce on H100 platforms with IB SHARP with multiple GPUs per process can result in data corruption if all GPUs on the node are not part of the same process, or cannot access other GPUs buffers directly.

Fixed Issues

The following issues have been resolved in NCCL 2.18.1:

- Fixed hangs with irregular send/receive patterns (e.g., alltoallv).
- Use all NICs for Send/Receive operations on systems with more than one NIC per GPU.
- Increased number of channels on H100 for network communication when bandwidth is not limited by NVLink bandwidth.
- Improved error reporting in case of IB Verbs errors.
- Fixed context creation for progress thread.
- Fixed hang in commReclaim.
- Fixed performance issue when NVB was disabled.

Updating the GPG Repository Key

Chapter 5. NCCL Release 2.17.1

This is the NCCL 2.17.1 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.17.1 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ▶ This NCCL release supports CUDA 11.0, CUDA 12.0, and CUDA 12.1.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Add support for NVLink SHARP Reduction / Broadcast to accelerate intra-node allreduce operations.
- Add new fields in the communicator configuration structure: Cooperative Group Array cluster size, minimum and maximum number of CTAs, network plugin name to use.
- Update NVTX3 includes.

Known Issues

On systems where a NIC shares a PCI switch with only one GPU (like on HGX H100), the Tree algorithm will make data transit through the CPU, making the LL128 protocol unsafe. This could result in data corruption. You can workaround this issue by setting the following:

```
NCCL_IB_PCI_RELAXED_ORDERING=0
```

Another solution is to disable the LL128 protocol with the following:

```
NCCL PROTO=^LL128
```

Performance is sub-optimal for NCCL communicators using 1 NIC per node on DGX H100/HGX H100 + NDR. It can be worked around by setting the following parameter:

```
NCCL MIN NCHANNELS=4
```

Fixed Issues

The following issues have been resolved in NCCL 2.17.1:

- Fix crash when one CollNet (SHARP) rail fails to initialize.
- Re-enable the LL128 protocol on H100 when we use PXN to close rings.

Updating the GPG Repository Key

Chapter 6. NCCL Release 2.16.5

This is the NCCL 2.16.5 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.16.5 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ▶ This NCCL release supports CUDA 11.0, CUDA 11.8, and CUDA 12.0..

Known Issues

Performance is sub-optimal for NCCL communicators using 1 NIC per node on DGX H100/HGX H100 + NDR. It can be worked around by setting the following parameter: NCCL MIN NCHANNELS=4

Fixed Issues

The following issues have been resolved in NCCL 2.16.5:

- Fix speed of IB NDR links
- Fix handling of EINTR in socket polling
- Improve proxy progress scheduling
- Fix resource cleanup
- Fix double free on case of init failure
- Fix crash in case of communicator abort
- Revert performance optimization causing significant regressions on some AMD platforms

Updating the GPG Repository Key

To best ensure the security and reliability of our RPM and Debian package repositories, NVIDIA is updating and rotating the signing keys used by apt, dnf/yum, and zypper package managers beginning on April 27, 2022. Failure to update your repository signing

keys will result in package management errors when attempting to access or install NCCL packages. To ensure continued access to the latest NCCL release, please follow the updated NCCL installation guide.

Chapter 7. NCCL Release 2.16.2

This is the NCCL 2.16.2 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.16.2 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ▶ This NCCL release supports CUDA 11.0, CUDA 11.8, and CUDA 12.0..

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Add support for CUDA 12.0
- Make socket support more resistant to network scanners
- ▶ Improve performance on large CUDA graphs, reducing dependencies
- Compile with profiling API by default
- Extend NVTX instrumentation with call arguments

Fixed Issues

The following issues have been resolved in NCCL 2.16.2:

- ▶ Various fixes to ncclCommAbort
- Make service thread polling resistant to EINTR
- Adjust inter-socket AMD bandwidth model to favor faster paths

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NCCL packages. To ensure continued access to the latest NCCL release, please follow the updated NCCL installation guide.

Chapter 8. NCCL Release 2.15.5

This is the NCCL 2.15.5 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.15.5 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ▶ This NCCL release supports CUDA 10.2, CUDA 11.0, and CUDA 11.8.

Fixed Issues

The following issues have been resolved in NCCL 2.15.5:

- Fix crash with CollnetChain on some node topologies
- Fix hang when interleaving the capture of different graphs
- Fix hang during init in multi-threaded mode
- Fix potential data corruption with LL128 protocol on unaligned buffers
- Fix CPU usage during preconnect
- Fixes double-free in the error path for ncclCommInitAll
- Workaround hang on H100 with Ring/LL128 on 2 GPUs

Updating the GPG Repository Key

Chapter 9. NCCL Release 2.15.1

This is the NCCL 2.15.1 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.15.1 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ▶ This NCCL release supports CUDA 10.2, CUDA 11.0, and CUDA 11.8.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

Support for H100 (sm90).

Fixed Issues

The following issues have been resolved in NCCL 2.15.1:

Make sure NCCL kernel honors user stream priorities.

Updating the GPG Repository Key

Chapter 10. NCCL Release 2.14.3

This is the NCCL 2.14.3 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.14.3 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ▶ This NCCL release supports CUDA 10.2, CUDA 11.0, and CUDA 11.7.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Add support for improved fault tolerance: non-blocking mode, new init function with configuration, new finalize function.
- Reintroduce the collnet+chain algorithm.
- Add LL protocol for intra-node send/recv communication, and inter-node (disabled by default).
- Communicate through the network within a node instead of shared memory if performance would be better that way.

Fixed Issues

The following issues have been resolved in NCCL 2.14.3:

- Wait for CUDA graph destruction before freeing communicator.
- Remove aggressive polling during enqueue.
- Fix DMABUF fallback on MOFED 5.4 and earlier.
- ► Fix NCCL DEBUG FILE functionality.

Updating the GPG Repository Key

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package managers beginning on April 27, 2022. Failure to update your repository signing keys will result in package management errors when attempting to access or install NCCL packages. To ensure continued access to the latest NCCL release, please follow the updated NCCL installation guide.

Chapter 11. NCCL Release 2.13.4

This is the NCCL 2.13.4 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.13.4 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ▶ This NCCL release supports CUDA 10.2, CUDA 11.0, and CUDA 11.7.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Optimize CUDA graph launch; avoid launching a CPU callback for intra-node operations.
- Simplify kernel common code to improve the latency of send/recv operations.
- Strengthen CUDA streams semantics.
- Change NET API to v6, to add dmabuf support.
- ▶ Add ncclGetLastError() function.
- ▶ Add ncclRemoteError code and use it for remote network errors.
- ▶ Support the use of a different NCCL NET parameter per communicator.
- Add support for SHM and P2P transfers using cudaMemcpy.

Fixed Issues

The following issues have been resolved in NCCL 2.13.4:

- Fix multi-receive size encoding which could cause flush to be skipped in corner cases mixing zero-bytes send/receive operations and non-zero-bytes send/receive operations.
- Replace busy polling in the bootstrap thread waiting for ranks to check in by a blocking accept.

Updating the GPG Repository Key

Chapter 12. NCCL Release 2.12.12

This is the NCCL 2.12.12 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.12.12 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- This NCCL release supports CUDA 10.2, CUDA 11.0, CUDA 11.6, and CUDA 11.7.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Improved allreduce performance when you have more than one network interface per GPU and you need to use PXN to close rings.
- ▶ Added P2P DIRECT DISABLE parameter to disable direct access to pointers within a process.
- Added support for PCI Gen5 on 5.4 kernels.

Fixed Issues

The following issues have been resolved in NCCL 2.12.12:

- Fixed hang on cubemesh topologies.
- ▶ Fixed random crash in init due to uninitialized struct.
- ► Fixed crash when setting NCCL SET THREAD NAME.

Updating the GPG Repository Key

To best ensure the security and reliability of our RPM and Debian package repositories, NVIDIA is updating and rotating the signing keys used by apt, dnf/yum, and zypper package managers beginning on April 27, 2022. Failure to update your repository signing keys will result in package management errors when attempting to access or install

NCCL packages. To ensure continued access to the latest NCCL release, please follow the updated NCCL installation guide.

Chapter 13. NCCL Release 2.12.10

This is the NCCL 2.12.10 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.12.10 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ► This NCCL release supports <u>CUDA 10.2</u>, <u>CUDA 11.0</u>, and <u>CUDA 11.6</u>.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

Improved error messages for network errors, with hostname instead of IP address.

Fixed Issues

The following issues have been resolved in NCCL 2.12.10:

- Fixed bug with collNet.
- Fixed bug with zero-byte send/recv operations.
- ► Fixed NCCL PARAM implementation taking a lock every time a parameter value was queried.
- ► Fixed bug when setting NCCL IB QPS PER CONNECTION to more than one.

Chapter 14. NCCL Release 2.12.7

This is the NCCL 2.12.7 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.12.7 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ▶ This NCCL release supports CUDA 10.2, CUDA 11.0, and CUDA 11.6.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Added NVLink-optimized network communication to keep traffic rail-local (PXN).
- Improved alltoall latency by aggregating messages within a node to a given destination.
- Added new v5 plugin API with grouped receives and tags, keeping compatibility for v4 plugins.
- Added naming of NCCL threads to help debugging.
- Added support for Relaxed Ordering for IB.
- Added profiling and timing infrastructure.

Fixed Issues

The following issues have been resolved in NCCL 2.12.7:

Fixed NVLink detection and avoid data corruption when some NVLinks are down.

Chapter 15. NCCL Release 2.11.4

This is the NCCL 2.11.4 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.11.4 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ► This NCCL release supports CUDA 10.2, CUDA 11.0, CUDA 11.4, CUDA 11.5, and CUDA 11.6.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Added new API for creating a reduction operation which multiplies the input by a rank-specific scalar before doing an inter-rank summation (see: ncclRedOpCreatePreMulSum).
- Improved CollNet (SHARP) performance of ncclAllReduce when captured in a CUDA Graph via user buffer registration.
- Added env NCCL NET PLUGIN="<suffix>" to allow the user a way to choose among multiple NCCL net plugins by substituting into libnccl-net-<suffix>.so.

Fixed Issues

The following issues have been resolved in NCCL 2.11.4:

- Fixed memory leak of NVB connections.
- Fixed crash of ncclGroup() containing mixed datatypes/operations (GitHub issue #560, introduced in NCCL 2.10.3).
- Fixed topology detection of IB Virtual Functions (SR-IOV).

Chapter 16. NCCL Release 2.10.3

This is the NCCL 2.10.3 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.10.3 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ▶ This NCCL release supports CUDA 10.2, CUDA 11.0, and CUDA 11.4.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Added ncclAvg operation
- Added support for bfloat 16 type
- Added support for multiple IB queue pairs
- Added WSL2 support (single GPU only)
- Improved performance for aggregation
- Improved performance for medium sizes
- Improved network error reporting
- Added NCCL_NET environment variable to use a specific network
- Added auto-load of XML topology from default location

Fixed Issues

The following issues have been resolved in NCCL 2.10.3:

- Fixed graph search on cubemesh topologies.
- Fixed all-to-all affinity to improve latency.
- Fixed hang in cubemesh NVB connections during initialization.

Chapter 17. NCCL Release 2.9.9

This is the NCCL 2.9.9 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.9.9 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ► This NCCL release supports CUDA 10.1, CUDA 10.2, CUDA 11.0, and CUDA 11.3.

Fixed Issues

The following issues have been resolved in NCCL 2.9.9:

- Fixed crash when setting NCCL MAX P2P NCHANNELS.
- Fixed hang during sendrecv dynamic connection on cubemesh topologies.
- ► Fixed compilation with TRACE=1.

Chapter 18. NCCL Release 2.9.8

This is the NCCL 2.9.8 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.9.8 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ► This NCCL release supports CUDA 10.1, CUDA 10.2, CUDA 11.0, and CUDA 11.3.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

Added support for nvidia-peermem module.

Fixed Issues

The following issues have been resolved in NCCL 2.9.8:

- Fixed error when injecting a topology file without vendor/device information.
- Fixed crash in bootstrap error case.
- Fixed memory leaks.
- Fixed collnet clean-up issue.

Chapter 19. NCCL Release 2.9.6

This is the NCCL 2.9.6 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.9.6 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ► This NCCL release supports CUDA 10.1, CUDA 10.2, CUDA 11.0, and CUDA 11.3.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Added support for CUDA graphs
- Improved performance for CollNet (SHARP)
- ► Fuse PCI Gen4 switches showing a two-level hierarchy into a single level.
- Improve NIC balancing for communicators using a single GPU per node.

Fixed Issues

The following issues have been resolved in NCCL 2.9.6:

- Fixed bootstrap hang in case of reordered packets causing connections to be inverted.
- Fix locking issue causing NCCL calls to block until previous operations were complete.

Chapter 20. NCCL Release 2.8.4

This is the NCCL 2.8.4 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.8.4 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ► This NCCL release supports CUDA 10.1, CUDA 10.2, CUDA 11.0, CUDA 11.1, and CUDA 11.2.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

Added support for Zhaoxin CPUs

Known Issues

Send/receive operations have a number of limitations:

Using send/receive operations in combination to launch work on multiple GPUs from a single process can fail or hang if the GPUs process different amounts of data. Setting NCCL LAUNCH MODE=PARALLEL can work around the issue, but can also cause other problems. For more information, see the NCCL User Guide section Troubleshooting > Known Issues > Concurrency Between NCCL and CUDA calls.

Fixed Issues

The following issues have been resolved in NCCL 2.8.4:

Fixed hang for some imbalanced send/recv operation (alltoally).

Chapter 21. NCCL Release 2.8.3

This is the NCCL 2.8.3 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.8.3 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- This NCCL release supports CUDA 10.1, CUDA 10.2, CUDA 11.0, CUDA 11.1, and CUDA 11.2.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Optimized Tree performance on A100
- Improved performance for aggregated operations
- Improved performance for all-to-all operations at scale
- Reduced memory usage for all-to-all operations at scale
- Optimized all-to-all performance on DGX-1

Known Issues

Send/receive operations have a number of limitations:

Using send/receive operations in combination to launch work on multiple GPUs from a single process can fail or hang if the GPUs process different amounts of data. Setting NCCL LAUNCH MODE=PARALLEL can work around the issue, but can also cause other problems. For more information, see the NCCL User Guide section Troubleshooting > Known Issues > Concurrency Between NCCL and CUDA calls.

Fixed Issues

The following issues have been resolved in NCCL 2.8.3:

Hang in LL128 protocol after 2^31 steps.

- ▶ Topology injection error when using fewer GPUs than described. (github issue #379)
- Protocol mismatch causing hangs or crashes when using one GPU per node. (github issue #394)

Chapter 22. NCCL Release 2.7.8

This is the NCCL 2.7.8 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.7.8 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- This NCCL release supports CUDA 10.1, CUDA 10.2, CUDA 11.0, and CUDA 11.1.

Known Issues

Send/receive operations have a number of limitations:

- Using send/receive operations in combination to launch work on multiple GPUs from a single process can fail or hang if the GPUs process different amounts of data. Setting NCCL LAUNCH MODE=PARALLEL can work around the issue, but can also cause other problems. For more information, see the NCCL User Guide section Troubleshooting > Known Issues > Concurrency Between NCCL and CUDA calls.
- Aggregation is not supported on a given source-destination pair, meaning that there can only be one send/receive per source-destination pair.
- Each source-destination pair allocates a dedicated fifo of 4 MB (see NCCL BUFFSIZE variable) which can use a significant amount of GPU memory at scale.
- When using GPU Direct RDMA, each point-to-point connection will also use resources on the GPU PCI address space, which we might run out of on some models. If that happens, consider disabling GPU Direct RDMA (NCCL NET GDR LEVEL=0) or reduce the per-peer buffer size (NCCL BUFFSIZE).
- Send/receive operations are not yet optimized for the DGX-1 NVLink topology.

Fixed Issues

The following issues have been resolved in NCCL 2.7.8:

•	Resolved "Collective Mismatch" errors reported erroneously when using send/recv operations.

Chapter 23. NCCL Release 2.7.6

This is the NCCL 2.7.6 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.7.6 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ▶ This NCCL release supports CUDA 10.1, CUDA 10.2, and CUDA 11.0.

Known Issues

Send/receive operations have a number of limitations:

- Using send/receive operations in combination to launch work on multiple GPUs from a single process can fail or hang if the GPUs process different amounts of data. Setting NCCL LAUNCH MODE=PARALLEL can work around the issue, but can also cause other problems. For more information, see the NCCL User Guide section Troubleshooting > Known Issues > Concurrency Between NCCL and CUDA calls.
- Aggregation is not supported on a given source-destination pair, meaning that there can only be one send/receive per source-destination pair.
- ► Each source-destination pair allocates a dedicated fifo of 4 MB (see NCCL BUFFSIZE variable) which can use a significant amount of GPU memory at scale.
- When using GPU Direct RDMA, each point-to-point connection will also use resources on the GPU PCI address space, which we might run out of on some models. If that happens, consider disabling GPU Direct RDMA (NCCL NET GDR LEVEL=0) or reduce the per-peer buffer size (NCCL BUFFSIZE).
- Send/receive operations are not yet optimized for the DGX-1 NVLink topology.

Fixed Issues

The following issues have been resolved in NCCL 2.7.6:

Fixed crash when NVswitch is not visible inside a virtual machine.

Chapter 24. NCCL Release 2.7.5

This is the NCCL 2.7.5 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Compatibility

NCCL 2.7.5 has been tested with the following:

- Deep learning framework containers. Refer to the Support Matrix for the supported container version.
- ▶ This NCCL release supports CUDA 10.1, CUDA 10.2, and CUDA 11.0.

Known Issues

Send/receive operations have a number of limitations:

- Using send/receive operations in combination to launch work on multiple GPUs from a single process can fail or hang if the GPUs process different amounts of data. Setting NCCL LAUNCH MODE=PARALLEL can work around the issue, but can also cause other problems. For more information, see the NCCL User Guide section Troubleshooting > Known Issues > Concurrency Between NCCL and CUDA calls.
- Aggregation is not supported on a given source-destination pair, meaning that there can only be one send/receive per source-destination pair.
- ► Each source-destination pair allocates a dedicated fifo of 4 MB (see NCCL BUFFSIZE variable) which can use a significant amount of GPU memory at scale.
- When using GPU Direct RDMA, each point-to-point connection will also use resources on the GPU PCI address space, which we might run out of on some models. If that happens, consider disabling GPU Direct RDMA (NCCL NET GDR LEVEL=0) or reduce the per-peer buffer size (NCCL BUFFSIZE).
- Send/receive operations are not yet optimized for the DGX-1 NVLink topology.
- Running inside a virtual machine on an NVswitch platform can cause a crash if NVswitch is not visible inside the virtual machine.

Fixed Issues

The following issues have been resolved in NCCL 2.7.5:

- ▶ Minor fixes for A100 platforms.
- ▶ Add proper message for invalid GroupEnd call.

Chapter 25. NCCL Release 2.7.3

This is the NCCL 2.7.3 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Added support for A100 GPU and related platforms
- Added support for CUDA 11
- Added support for send/receive operations (beta)

Compatibility

NCCL 2.7.3 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- ► This NCCL release supports <u>CUDA 10.1</u>, <u>CUDA 10.2</u>, and <u>CUDA 11.0</u>.

Known Issues

Send/receive operations have a number of limitations:

- Using send/receive operations in combination to launch work on multiple GPUs from a single process can fail or hang if the GPUs process different amounts of data. Setting NCCL LAUNCH MODE=PARALLEL can work around the issue, but can also cause other problems. For more information, see the NCCL User Guide section Troubleshooting > Known Issues > Concurrency Between NCCL and CUDA calls.
- Aggregation is not supported on a given source-destination pair, meaning that there can only be one send/receive per source-destination pair.
- Each source-destination pair allocates a dedicated fifo of 4 MB (see NCCL BUFFSIZE variable) which can use a significant amount of GPU memory at scale.
- When using GPU Direct RDMA, each point-to-point connection will also use resources on the GPU PCI address space, which we might run out of on some models. If that

happens, consider disabling GPU Direct RDMA (NCCL_NET_GDR_LEVEL=0) or reduce the per-peer buffer size (NCCL BUFFSIZE).

▶ Send/receive operations are not yet optimized for the DGX-1 NVLink topology.

Fixed Issues

The following issues have been resolved in NCCL 2.7.3:

Fixed crash when only a subset of GPUs are visible within a container (#326).

Chapter 26. NCCL Release 2.6.4

This is the NCCL 2.6.4 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Added support for in-network collectives (beta)
- Added support for adaptive routing on Infiniband
- Added support for topology dump/injection through XML files
- Added speed detection for PCI, Infiniband and Ethernet cards
- Added CPU detection for AMD CPUs and ARM

Chapter 27. NCCL Release 2.5.6

This is the NCCL 2.5.6 release notes. For previous NCCL release notes, refer to the NCCL Archives.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Added new protocol to improve performance on small operations.
- Improved topology detection and tree/ring creation (#179, #262).
- Improved multi-node tree performance by sending/receiving from different GPUs.
- Added model-based tuning to switch between the different algorithms and protocols.
- Reworked P2P/SHM detection in containers (#155, #248).
- Added detection for duplicate CUDA devices and return an error (#231).
- Added tuning for Google Cloud's gVNIC platform.

Compatibility

NCCL 2.5.6 has been tested with the following:

- ▶ Deep learning framework containers. Refer to the <u>Support Matrix</u> for the supported container version.
- This NCCL release supports <u>CUDA 9.0</u>, <u>CUDA 10.0</u>, <u>CUDA 10.1</u>, and <u>CUDA 10.2</u>.

Fixed Issues

The following issues have been resolved in NCCL 2.5.6:

- Sporadic NCCL error "ring 0 does not loop back to start" (#179).
- NCCL doesn't form proper rings on GCP V100s (#262).

Chapter 28. NCCL Release 2.4.8

This is the NCCL 2.4.8 release notes. This release includes fixes from the previous NCCL 2.4.x releases as well as the following additional changes. For previous NCCL release notes, see the archived NCCL Release Notes.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

Improved socket transport performance by splitting transfer over multiple sockets.



Note: This feature adds two new environment variables NCCL SOCKET NTHREADS and NCCL NSOCKS PERTHREAD for users to tune NCCL performance on socket-based networks. See the NCCL documentation for more details.

Compatibility

NCCL 2.4.8 has been tested with the following:

- Deep learning framework 19.05 containers
- This NCCL release supports; CUDA 9.0, CUDA 9.2, CUDA 10.0, and CUDA 10.1.

Fixed Issues

The following issues have been resolved in NCCL 2.4.8:

Suboptimal performance with TCP over high bandwidth networks. (GitHub issue #209)

- On single node Power systems with 4 GPUs, some performance regressions have been observed compared to NCCL 2.4.2. These will be addressed in future NCCL releases.
- By default, NCCL does not enable direct P2P communication through different PCIe root ports on Intel Skylake CPU and later. This is due to a known performance issue when using P2P on these CPU versions. There is now a new BIOS and performance

tuning option available (PCIe Peer-to-Peer Serialization) from Intel and their OEM vendors that resolves this P2P bandwidth issue. If the BIOS performance tuning option has been enabled, then NCCL direct P2P connections can be re-enabled by setting NCCL_P2P_LEVEL=5.

Chapter 29. NCCL Release 2.4.7

This is the NCCL 2.4.7 release notes. This release includes fixes from the previous NCCL 2.4.x releases as well as the following additional changes. For previous NCCL release notes, see the archived NCCL Release Notes.

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Improved bootstrap socket connection reliability at scale.
- Added detection of IBM/Power NVLink bridge device.
- Added NUMA support to PCI-E distance calculations on x86 architectures.



Note: This adds a new level (5) for the NCCL P2P LEVEL and NCCL NET GDR LEVEL environment variables. See the NCCL documentation for more details.

Added the NCCL IGNORE CPU AFFINITY environment variable.

Compatibility

NCCL 2.4.7 has been tested with the following:

- Deep learning framework 19.04 containers
- This NCCL release supports; CUDA 9.0, CUDA 9.2, CUDA 10.0, and CUDA 10.1.

Fixed Issues

The following issues have been resolved in NCCL 2.4.7:

- Fixed hostname hashing issue. (GitHub issue #187)
- Fixed memory leaks. (GitHub issue #180)
- Fixed compiler warning. (GitHub issue #178)
- Replaced non-standard variable length arrays. (GitHub issue #171)
- ► Fixed Tree and Shared Memory crash. (GitHub PR #185)
- Fixed hangs during long running jobs.
- ► Fixed the NCCL RINGS environment variable handling.

▶ Added extra checks to catch duplicate calls to ncclCommDestroy(). (GitHub issue #191)

- On single node Power systems with 4 GPUs, some performance regressions have been observed compared to NCCL 2.4.2. These will be addressed in future NCCL releases.
- ▶ By default, NCCL does not enable direct P2P communication through different PCle root ports on Intel Skylake CPU and later. This is due to a known performance issue when using P2P on these CPU versions. There is now a new BIOS and performance tuning option available (PCIe Peer-to-Peer Serialization) from Intel and their OEM vendors that resolves this P2P bandwidth issue. If the BIOS performance tuning option has been enabled, then NCCL direct P2P connections can be re-enabled by setting NCCL P2P LEVEL=5.

Chapter 30. NCCL Release 2.4.2

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Implemented tree-based algorithms for better All Reduce performance at scale and with small and medium size messages.
- Support for external network plugins (e.g., libfabric).
- ▶ Add ncclCommGetAsyncError() function to report errors happening during collective operations.
- Add ncclCommAbort () function to destroy a communicator, aborting any outstanding operations.
- ▶ Support different ranks having a different CUDA VISIBLE DEVICES.
- Add a best-effort mechanism to check for size mismatch among collective calls.

- Support communication between Mesos containers (Github issue #155).
- ► Fix case where posix fallocate() returns EINTR (Github issue #137).
- NCCL threads no longer escape the CPU affinity set by the user or job scheduler.

Chapter 31. NCCL Release 2.3.7

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Minor tuning of the LL threshold for multi-node jobs.
- Improve performance of initialization on large number of ranks.

Fixed Issues

Fixed issue causing "WARN: Message truncated" errors.

Chapter 32. NCCL Release 2.3.5

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

▶ This release is open-sourced with no new features or fixes.

Chapter 33. NCCL Release 2.3.4

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Improve performance tuning on large number of ranks.
- ▶ Add NCCL P2P LEVEL and NCCL IB GDR LEVEL knobs to finely control when to use GPU Direct P2P and GPU Direct RDMA.
- Reduce setup time for large scale jobs.
- Increased maximum number of rings supported to 16.
- Added a runtime NCCL version API: ncclGetVersion().
- ▶ Added NCCL_DEBUG_SUBSYS to allow filtering of NCCL DEBUG=INFO logging from different subsystems.
- Support for Turing based systems.

- Fix hang on Power platforms.
- Fix low inter-node bandwidth issue on multi-DGX2 systems.
- Fix crash when used with PID isolator.

Chapter 34. NCCL Release 2.2.13

Key Features and Enhancements

There were no new features and enhancements in this release.

Using NCCL 2.2.13

Ensure you are familiar with the following notes when using this release.

- ▶ If NCCL returns an error code, set the environment variable NCCL DEBUG to WARN to receive an explicit error message.
- ▶ The NCCL 2.x API is different from NCCL 1.x. Some porting may be needed for NCCL 1.x applications to work correctly. Refer to the migration documentation in the NCCL Developer Guide.
- Starting in 2.2, NCCL supports collective aggregation. You can put multiple NCCL collective operations in between ncclGroupStart() and ncclGroupEnd() to enable this feature.

Known Issues

- Using multiple processes in conjunction with multiple threads to manage the different GPUs may in some cases cause ncclCommInitRank to fail while establishing IPCs (cudaIpcOpenMemHandle). This problem does not appear when using only processes or only threads. This issue is fixed in recent driver versions, therefore, consider updating to the latest driver.
- NCCL uses CUDA 9 cooperative group launch by default, which may induce increased latencies in multi-threaded programs. See the NCCL LAUNCH MODE knob to restore the original behavior.
- Driver version 390 can cause data corruption when used together with GPU Direct RDMA. Disabling GPU Direct RDMA by setting NCCL IB CUDA SUPPORT=0, or upgrading to 396.26 or newer driver should resolve the issue.

Fixed Issues

► Fix crash in child processes after calling ncclCommDestroy.

Chapter 35. NCCL Release 2.2.12

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Added support for collective operations aggregation.
- Added ncclBroadcast function.

Using NCCL 2.2.12

Ensure you are familiar with the following notes when using this release.

- ▶ If NCCL returns an error code, set the environment variable NCCL DEBUG to WARN to receive an explicit error message.
- ▶ The NCCL 2.x API is different from NCCL 1.x. Some porting may be needed for NCCL 1.x applications to work correctly. Refer to the migration documentation in the NCCL Developer Guide.
- Starting in 2.2, NCCL supports collective aggregation. You can put multiple NCCL collective operations in between ncclGroupStart() and ncclGroupEnd() to enable this feature.

- Using multiple processes in conjunction with multiple threads to manage the different GPUs may in some cases cause ncclCommInitRank to fail while establishing IPCs (cudaIpcOpenMemHandle). This problem does not appear when using only processes or only threads. This issue is fixed in recent driver versions, therefore, consider updating to the latest driver.
- NCCL uses CUDA 9 cooperative group launch by default, which may induce increased latencies in multi-threaded programs. See the NCCL LAUNCH MODE knob to restore the original behavior.
- Driver version 390 and later can cause data corruption when used together with GPU Direct RDMA. Disabling GPU Direct RDMA by setting NCCL IB CUDA SUPPORT=0 or reverting to driver 387 should resolve the issue.

- ▶ No longer clear the CPU affinity during initialization functions
- Fix various large scale issues
- Reduce the size of the library
- Fix crash or hang with PyTorch relative to the usage of calls to fork

Chapter 36. NCCL Release 2.1.15

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

Added a variable to control InfiniBand Traffic Class and Retry Count.

Using NCCL 2.1.15

Ensure you are familiar with the following notes when using this release.

- ▶ The NCCL 2.x API is different from NCCL 1.x. Some porting may be needed for NCCL 1.x applications to work correctly. Refer to the migration documentation in the NCCL Developer Guide.
- Starting in 2.2, NCCL supports collective aggregation. You can put multiple collectives in between ncclGroupStart() and ncclGroupEnd() to enable this feature.

Known Issues

- ▶ If NCCL returns an error code, set the environment variable NCCL DEBUG to WARN to receive an explicit error message.
- Using multiple processes in conjunction with multiple threads to manage the different GPUs may in some cases cause ncclCommInitRank to fail while establishing IPCs (cudaIpcOpenMemHandle). This problem does not appear when using only processes or only threads.
- NCCL uses CUDA 9 cooperative group launch by default, which may induce increased latencies in multi-threaded programs. See the NCCL LAUNCH MODE knob to restore the original behavior.

- Fixed CPU usage and scheduling of NCCL network threads.
- Fixed CUDA launch crash when mixing different types of GPUs in a node.
- Fixed a performance problem on Skylake CPUs.
- Fixed hanging issues with cudaFree and inter-node communication.

- ▶ Restored library installation path to /usr/lib/x86_64-linux-gnu in debian packages.
- Fixed RoCEv2 failure when using a non-zero GID.
- ▶ No longer link to stdc++ library statically as this can cause issues with C++ applications.
- Fixed PyTorch hanging issues when using multiple rings and many back-to-back broadcast operations.

Chapter 37. NCCL Release 2.1.4

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- Added support for InfiniBand GID selection, enabling the use of RoCE v2.
- Added support for InfiniBand Service Level (SL) selection.

Using NCCL 2.1.4

Ensure you are familiar with the following notes when using this release.

The NCCL 2.x API is different from NCCL 1.x. Some porting may be needed for NCCL 1.x applications to work correctly. Refer to the migration documentation in the NCCL Developer Guide.

Known Issues

- ▶ If NCCL returns an error code, set the environment variable NCCL DEBUG to WARN to receive an explicit error message.
- Using multiple processes in conjunction with multiple threads to manage the different GPUs may in some cases cause ncclCommInitRank to fail while establishing IPCs (cudalpcopenMemHandle). This problem does not appear when using only processes or only threads.
- ▶ NCCL uses CUDA® 9 cooperative group launch by default, which may induce increased latencies in multi-threaded programs. See the NCCL LAUNCH MODE knob in the NCCL Developer Guide to restore the original behavior.
- ▶ NCCL 2.1.4-1 embeds libstdc++ and exports its symbols. This can break C++ applications.

- Fixed bug causing CUDA IPC to fail in some situations.
- Fixed bug causing a crash when p2p mappings are exhausted instead of returning an error.

Chapter 38. NCCL Release 2.1.2

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- New algorithms for improved latency communication
- RoCE support

Using NCCL 2.1.2

Ensure you are familiar with the following notes when using this release.

The NCCL 2.x API is different from NCCL 1.x. Some porting may be needed for NCCL 1.x applications to work correctly. Refer to the migration documentation in the NCCL Developer Guide.

Known Issues

- ▶ If NCCL returns an error code, set the environment variable NCCL DEBUG to WARN to receive an explicit error message.
- Using multiple processes in conjunction with multiple threads to manage the different GPUs may in some cases cause ncclCommInitRank to fail while establishing IPCs (cudaIpcOpenMemHandle). This problem does not appear when using only processes or only threads.
- NCCL uses CUDA 9 cooperative group launch by default, which may induce increased latencies in multi-threaded programs. See the NCCL LAUNCH MODE knob in the NCCL <u>Developer Guide</u> to restore the original behavior.

Fixed Issues

 NCCL now uses CUDA 9 cooperative groups to launch the CUDA kernels, fixing a long-standing issue with CUDA and NCCL operations being interleaved and potentially causing hangs.

Chapter 39. NCCL Release 2.0.5

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- NCCL 2.0.5 provides support for intra-node and inter-node communication.
- NCCL optimizes intra-node communication using NVLink, PCI express, and shared memory.
- Between nodes, NCCL implements fast transfers over sockets or InfiniBand verbs.
- GPU-to-GPU and GPU-to-Network direct transfers, using the GPU Direct technology, are extensively used when the hardware topology permits it.

Using NCCL 2.0.5

Ensure you are familiar with the following notes when using this release.

- ▶ The NCCL 2.0 API is different from NCCL 1.x. Some porting may be needed for NCCL 1.x applications to work correctly. Refer to the migration documentation in the NCCL Developer Guide.
- NCCL 2.0.5 has the new configuration file support. The NCCL environment variables can now be set in ~/.nccl.conf and /etc/nccl.conf.
- ▶ Values defined in ~/.nccl.conf take precedence over ones in /etc/nccl.conf.
- The syntax for each line of the NCCL configuration file is <NCCL VAR NAME>=<VALUE>.

- ▶ If NCCL returns any error code, set the environment variable NCCL DEBUG to WARN to receive an explicit error message.
- RoCE support is experimental.
- Using multiple processes in conjunction with multiple threads to manage the different GPUs may in some cases cause ncclCommInitRank to fail while establishing IPCs (cudaIpcOpenMemHandle). This problem does not appear when using only processes or only threads.

Chapter 40. NCCL Release 2.0.4

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- NCCL 2.0.4 provides support for intra-node and inter-node communication.
- NCCL optimizes intra-node communication using NVLink, PCI express, and shared memory.
- Between nodes, NCCL implements fast transfers over sockets or InfiniBand verbs.
- GPU-to-GPU and GPU-to-Network direct transfers, using the GPU Direct technology, are extensively used when the hardware topology permits it.

Using NCCL 2.0.4

Ensure you are familiar with the following notes when using this release.

- ▶ The NCCL 2.0 API is different from NCCL 1.x. Some porting may be needed for NCCL 1.x applications to work correctly. Refer to the migration documentation in the NCCL Developer Guide.
- NCCL 2.0.4 has the new configuration file support. The NCCL environment variables can now be set in ~/.nccl.conf and /etc/nccl.conf.
- ▶ Values defined in ~/.nccl.conf take precedence over ones in /etc/nccl.conf.
- The syntax for each line of the NCCL configuration file is <NCCL VAR NAME>=<VALUE>.

- ▶ If NCCL returns any error code, set the environment variable NCCL DEBUG to WARN to receive an explicit error message.
- RoCE is not supported.
- Using multiple processes in conjunction with multiple threads to manage the different GPUs may in some cases cause ncclCommInitRank to fail while establishing IPCs (cudaIpcOpenMemHandle). This problem does not appear when using only processes or only threads.

Chapter 41. NCCL Release 2.0.2

Key Features and Enhancements

This NCCL release includes the following key features and enhancements.

- NCCL 2.0.2 provides support for intra-node and inter-node communication.
- NCCL optimizes intra-node communication using NVLink, PCI express, and shared memory.
- Between nodes, NCCL implements fast transfers over sockets or InfiniBand verbs.
- GPU-to-GPU and GPU-to-Network direct transfers, using the GPU Direct technology, is extensively used when the hardware topology permits it.

Using NCCL 2.0.2

Ensure you are familiar with the following notes when using this release.

▶ The NCCL 2.0 API is different from NCCL 1.x. Some porting may be needed for NCCL 1.x applications to work correctly. Refer to the migration documentation in the NCCL Developer Guide.

- NCCL 2.0.2 is known to not work with CUDA driver 384.40 and later.
- ▶ If NCCL returns any error code, set the environment variable NCCL DEBUG to WARN to receive an explicit error message.
- NCCL 2.0.2 does not support RoCE, that is, InfiniBand cards using Ethernet as link layer. The presence of an RoCE card on a node will make NCCL fail even when run within the node.
- Using multiple processes in conjunction with multiple threads to manage the different GPUs may in some cases cause ncclCommInitRank to fail while establishing IPCs (cudaIpcOpenMemHandle). This problem does not appear when using only processes or only threads.

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