



NVIDIA Magnum IO GPUDirect Storage

Installation and Troubleshooting Guide

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Chapter 1. Introduction

This guide describes how to debug and isolate the NVIDIA® Magnum IO GPUDirect® Storage (GDS) related performance and functional problems and is intended for systems administrators and developers.

GDS enables a direct data path for direct memory access (DMA) transfers between GPU memory and storage, which avoids a bounce buffer through the CPU. This direct path increases system bandwidth and decreases the latency and utilization load on the CPU.

Creating this direct path involves distributed filesystems such as NFSoRDMA, DDN EXAScaler® parallel filesystem solutions (based on the Lustre filesystem) and WekaFS, so the GDS environment is composed of multiple software and hardware components. This guide addresses questions related to the GDS installation and helps you triage functionality and performance issues. For non-GDS issues, contact the respective OEM or filesystems vendor to understand and debug the issue.

The following GDS technical specifications and guides provide additional context for the optimal use of and understanding of the solution:

- ▶ [GPUDirect Storage Design Guide](#)
- ▶ [GPUDirect Storage Overview Guide](#)
- ▶ [cuFile API Reference Guide](#)
- ▶ [GPUDirect Storage Release Notes](#)
- ▶ [GPUDirect Storage Benchmarking and Configuration Guide](#)
- ▶ [GPUDirect Storage Best Practices Guide](#)
- ▶ [GPUDirect Storage O_DIRECT Requirements Guide](#)

To learn more about GDS, refer to the following blogs:

- ▶ [GPUDirect Storage: A Direct Path Between Storage and GPU Memory.](#)
- ▶ The [Magnum IO](#) blog series.

Chapter 2. Installing GPUDirect Storage

This section includes GDS installation, uninstallation, configuration information, and using experimental repos.

2.1. Before You Install GDS

To install GDS on a non-DGX platform, complete the following steps:

1. Run the following command to check the current status of IOMMU.

```
$ dmesg | grep -i iommu
```

If IOMMU is **enabled**, complete step 2 to disable it, otherwise continue to step 3.

2. Disable IOMMU.



Note: In our experience, `iommu=off` works the best in terms of functionality and performance. On certain platforms such as DGX A100 and DGX-2, `iommu=pt` is supported. `iommu=on` is not guaranteed to work functionally or in a performant way.

- a). Run the following command:

```
$ sudo vi /etc/default/grub
```

- b). Add one of the following options to the `GRUB_CMDLINE_LINUX_DEFAULT` option.

- ▶ If you have an **AMD** CPU, add `amd_iommu=off`.
- ▶ If you have an **Intel** CPU, add `intel_iommu=off`.

If there are already other options, enter a space to separate the options, for example, `GRUB_CMDLINE_LINUX_DEFAULT="console=tty0 amd_iommu=off"`

- c). Run the following commands:

```
$ sudo update-grub  
$ sudo reboot
```

- d). After the system reboots, to verify that the change took effect, run the following command:

```
$ cat /proc/cmdline
```

3. Use the instructions in [MLNX_OFED Requirements and Installation](#) to install MLNX_OFED.

2.2. Installing GDS

Before installing GDS, note the following:

- ▶ Ensure the machine has access to the network for downloading additional packages using Ubuntu APT/ Redhat RPM, YUM and DNF packaging software (advance packaging tool).
- ▶ Make sure the NVIDIA driver is installed using the Ubuntu APT/Redhat RPM, YUM and DNF package manager. NVIDIA drivers installed using the `NVIDIA-Linux-x86_64.<version>.run` file are NOT supported with the `nvidia-gds` package.

Throughout this document, in `cuda-<x>.<y>`, `x` refers to the CUDA major version and `y` refers to the minor version.

2.2.1. Removal of Prior GDS Installation on Ubuntu Systems

If any older GDS release packages are installed, use the following steps before upgrading to release 1.0.0.

If you have 0.9.0 or above, use:

```
$ sudo apt-get remove --purge "*libcufile*" "*gds-tools*" "*nvidia-fs*"
```

2.2.2. Preparing the OS

To prepare your OS for GDS installation, use the appropriate one of the following procedures:

DGX OS:

Currently, ONLY DGX OS 5.1 (Ubuntu 20.04) is supported on the DGX platform.

Note: If you have CUDA toolkit installed then note down the currently used toolkit version and specify it in place of `<x>` in step 1. Start with step 2 onwards. If you do not have CUDA toolkit installed, run:

```
$ nvidia-smi -q | grep CUDA | awk '{print $4}' | sed 's/\./-/'
```

Replace `<x>` in step 1 with output from the command line above. Steps:

1. `$ sudo apt-get install cuda-toolkit-<x>`
2. `$ sudo apt-key adv --fetch-keys https://repo.download.nvidia.com/baseos/GPG-KEY-dgx-cosmos-support`
3. `$ sudo apt full-upgrade -y`
4. Note down the Linux kernel version:


```
$ uname -a -r
```
5. `$ sudo apt install mlnx-nvme-dkms`
6. `$ sudo update-initramfs -u -k `uname -r``
7. `$ sudo reboot`

Make sure the Linux kernel version noted in step 4 is the same version after step 7 is completed. If the versions do not match, then GDS changes to kernel modules might have been applied to the version noted in step 4.

RHEL 8.4

Enable the EPEL repository:

```
$ sudo dnf install -y
                        https://dl.fedoraproject.org/pub/epel/epel-release-
latest-8.noarch.rpm
```

Enable the CUDA repository:

```
$ sudo dnf config-manager --add-repo
                        https://developer.download.nvidia.com/compute/cuda/repos/rhel8/
x86_64/cuda-rhel8.repo
```

2.2.3. GDS Package Installation

To download and install the GDS package:

1. Download the GDS packages (Debian/RHEL) to the local client from <https://developer.nvidia.com/gpudirect-storage>:



Note: Make sure to download the correct GDS package based on the OS distribution and CUDA toolkit. You do not need to download GDS packages for DGX OS as it will be handled as part of step 2.2.2.

2. Install cuFile and related packages (GDS installation):

```
$ NVIDIA_DRV_VERSION=$(cat /proc/driver/nvidia/version | grep Module | awk
'{print $8}' |
                        cut -d '.' -f 1)
```

On DGX OS 5.0:

DGX OS 5.0 systems come with prebuilt NVIDIA kernel drivers. Use the following method to install nvidia-gds with the correct dependencies.

In the command below, use the CUDA Toolkit version number in place of <ver>, for example 11-0

```
$ sudo apt install nvidia-gds-<ver> nvidia-dkms-${NVIDIA_DRV_VERSION}-server
$ sudo modprobe nvidia_fs
```

2.2.4. Verifying the Package Installation

To verify the GDS package was installed correctly:

On DGX OS and UbuntuOS:

```
$ dpkg -s nvidia-gds
Package: nvidia-gds
Status: install ok installed
Priority: optional
Section: multiverse/devel
Installed-Size: 7
Maintainer: cudatools <cudatools@nvidia.com>
Architecture: amd64
Version: 1.0.0-1
Provides: gds
Depends: nvidia-gds-11-2 (>= 1.0.0)
```

```

Description: GPU Direct Storage meta-package
Meta-package containing all the available packages required for
libcufile and nvidia-fs.

```

On RHEL:

```

$ rpm -qi nvidia-gds
Name           : nvidia-gds
Version        : 1.0.0
Release        : 1
Architecture   : x86_64
Install Date   : Tue Jun 15 13:49:28 2021
Group          : Unspecified
Size           : 0
License        : NVIDIA Proprietary
Signature      : RSA/SHA512, Sun Jun 13 23:22:45 2021, Key ID
f60f4b3d7fa2af80
Source RPM     : nvidia-gds-1.0.0-1.src.rpm
Build Date    : Sun Jun 13 23:22:45 2021
Build Host    : cia-jenkins-agent-06.nvidia.com
Relocations   : (not relocatable)
URL           : http://nvidia.com
Summary       : GPU Direct Storage meta-package
Description    :
Meta-package for GPU Direct Storage containing all the available
packages required for libcufile and nvidia-fs.

```

2.2.5. Verifying a Successful GDS Installation

This section provides information about how you can verify whether your GDS installation was successful.



Note: The `gdscheck` command below expects `python3` to be present on the system. If it fails because of `python3` not being available then you can invoke the command with the explicit path to where `python` (i.e. `python2`) is installed. For example:

```
$ /usr/bin/python /usr/local/cuda-<x>.<y>/gds/tools/gdscheck.py -p
```

To verify that GDS installation was successful, run `gdscheck`:

```
$ /usr/local/cuda-<x>.<y>/gds/tools/gdscheck.py -p
```

The output of this command shows whether a supported filesystem or device installed on the system supports GDS. The output also shows whether PCIe ACS is enabled on any of the PCI switches.



Note: For best GDS performance, disable PCIe ACS.

Sample output:

```

GDS release version: 1.0.0.80
nvidia_fs version: 2.7 libcufile version: 2.4
=====
ENVIRONMENT:
=====
DRIVER CONFIGURATION:
=====
NVMe           : Unsupported
NVMeOF         : Unsupported
SCSI           : Unsupported

```

```

ScaleFlux CSD      : Unsupported
NVMesh            : Unsupported
DDN EXAScaler     : Unsupported
IBM Spectrum Scale : Unsupported
NFS               : Supported
WekaFS            : Unsupported
Userspace RDMA    : Unsupported
--Mellanox PeerDirect : Enabled
--rdma library     : Not Loaded (libcufile_rdma.so)
--rdma devices     : Not configured
--rdma_device_status : Up: 0 Down: 0
=====
CUFILE CONFIGURATION:
=====
properties.use_compat_mode : false
properties.gds_rdma_write_support : true
properties.use_poll_mode : false
properties.poll_mode_max_size_kb : 4
properties.max_batch_io_timeout_msecs : 5
properties.max_direct_io_size_kb : 16384
properties.max_device_cache_size_kb : 131072
properties.max_device_pinned_mem_size_kb : 33554432
properties.posix_pool_slab_size_kb : 4 1024 16384
properties.posix_pool_slab_count : 128 64 32
properties.rdma_peer_affinity_policy : RoundRobin
properties.rdma_dynamic_routing : 0
fs.generic.posix_unaligned_writes : false
fs.lustre.posix_gds_min_kb: 0
fs.weka.rdma_write_support: false
profile.nvtx : false
profile.cufile_stats : 0
miscellaneous.api_check_aggressive : false
=====
GPU INFO:
=====
GPU index 0 A100-PCIE-40GB bar:1 bar size (MiB):65536 supports GDS
=====
PLATFORM INFO:
=====
IOMMU: disabled
Platform verification succeeded

```

**Note:**

There are READMEs provided in `/usr/local/cuda-<x>.<y>/gds/tools` and `/usr/local/cuda-<x>.<y>/gds/samples` to show usage.

2.3. Installed GDS Libraries and Tools

The following is some information about determining which GDS libraries and tools you installed.



Note: GPUDirect Storage packages are installed at `/usr/local/cuda-X.Y/gds`, where **X** is the major version of the CUDA toolkit, and **Y** is the minor version.

GPUDirect Storage userspace libraries are located in the `/usr/local/cuda-<X>.<Y>/targets/x86_64-linux/lib/` directory.

```
$ ls -l /usr/local/cuda-X.Y/targets/x86_64-linux/lib/*cufile*
cufile.h
```

```

libcufile.so
libcufile.so.0
libcufile.so.1.0.0
libcufile_rdma.so
libcufile_rdma.so.0
libcufile_rdma.so.1.0.0

```

GPUDirect Storage tools and samples are located in the `/usr/local/cuda-X.Y/gds` directory.

```

$ ls -lh /usr/local/cuda-X.Y/gds/
total 20K
-rw-r--r-- 1 root root 8.4K Mar 15 13:01 README
drwxr-xr-x 2 root root 4.0K Mar 19 12:29 samples
drwxr-xr-x 2 root root 4.0K mar 19 10:28 tools

```

For this release, GPUDirect Storage is providing an additional `libcufile-dev` package (cuFile library developers package). This is primarily intended for the developer's environment. Essentially the `libcufile-dev` package contains a static version of cuFile library (`libcufile_static.a`, `libcufile_rdma_static.a`) and `cufile.h` header file which may be required by the applications that use cuFile library APIs.

2.4. Uninstalling GPUDirect Storage

To uninstall GDS from Ubuntu and DGX OS:

```
$ sudo apt-get remove --purge "*libcufile*" "*gds-tools*" "*nvidia-fs*"
```

To uninstall from RHEL:

```
$ sudo dnf remove "nvidia-gds*"
```

2.5. Environment Variables Used by GPUDirect Storage

GDS uses the following environment variables.

Table 1. GDS Environment Variables

CUFILE_ENV Variable	Description
<code>CUFILE_ENV_EXPERIMENTAL_FS=1</code>	Controls whether cufile checks for supporting filesystems. When set to 1, allows testing with new filesystems that are not yet officially enabled with cuFile.
<code>CUFILE_ENV_PATH_JSON=/home/user/cufile.json</code>	Controls the path where the cuFile library reads the configuration variables from. This can be used for container environments and applications that require different configuration settings from system default configuration at <code>/etc/cufile.json</code> .

CUFILE_ENV Variable	Description
CUFILE_LOGFILE_PATH= /etc/log/cufile_\$\$log	Controls the path for cuFile log information. Specifies the default log path, which is the current working directory of the application. Useful for containers or logging.
CUFILE_LOGGING_LEVEL= TRACE	Controls the tracing level and can override the trace level for a specific application without requiring a new configuration file.
CUFILE_IB_SL= [0-15]	Sets QOS level for userspace RDMA targets for wekaFS and GPFS.
CUFILE_RDMA_DC_KEY= "0XABABCDEF"	Controls the DC_KEY for userspace RDMA DC targets for wekaFS and GPFS.
CUFILE_NVTX= true	Enables NVTX tracing for use with Nsight systems.

2.6. JSON Config Parameters Used by GPUDirect Storage

Refer to [GPUDirect Storage Parameters](#) for details about the JSON Config parameters used by GDS

Consider `compat_mode` for systems or mounts that are not yet set up with GDS support. To learn more about Compatibility Mode, refer to [cuFile Compatibility Mode](#).

2.7. GDS Configuration File Changes to Support Dynamic Routing

For dynamic routing to support multiple file systems and mount points, users can configure the global per file system `rdma_dev_addr_list` property for a single mount or the `rdma_dev_addr_list` property for a per file system mount table.

```
"fs": {
  "lustre": {
    // if using a single lustre mount, provide the ip addresses
    // here (use : sudo lnetctl net show)
    //"rdma_dev_addr_list" : []

    // if using multiple lustre mounts, provide ip addresses
    // used by respective mount here
    //"mount_table" : {
      // "/lustre/ai200_01/client" : {
        // "rdma_dev_addr_list" : ["172.172.1.40",
          "172.172.1.42"]
      }
    }
  }
}
```

```

    //},
    // "/lustre/ai200_02/client" : {
        // "rdma_dev_addr_list" : ["172.172.2.40",
            "172.172.2.42"]
    //}
},
"nfs": {
    // "rdma_dev_addr_list" : []

    // "mount_table" : {
        // "/mnt/nfsrdma_01/" : {
            // "rdma_dev_addr_list" : []
        //},
        // "/mnt/nfsrdma_02/" : {
            // "rdma_dev_addr_list" : []
        //}
    //}
},
},
},

```

2.8. Determining Which Version of GDS is Installed

To determine which version of GDS you have, run the following command:

```
$ gdscheck.py -v
```

Review the output, for example:

```
GDS release version: 1.0.0.78
nvidia_fs version: 2.7 libcufile version: 2.4
```

2.9. Experimental Repos for Network Install of GDS Packages for DGX Systems

GDS 1.0.0 and MLNX_OFED packages can be installed by enabling the preview repository on supported DGX platforms using the following steps.

For Ubuntu 18.04/20.04 distributions:

GDS 1.0.0, NVSM and MLNX_OFED packages can be installed via network using the preview network repository.

For Ubuntu 20.04 distributions:

```
$ sudo apt-key adv --fetch-keys https://repo.download.nvidia.com/baseos/GPG-KEY-dgx-cosmos-support
```

```
$ sudo add-apt-repository "deb https://repo.download.nvidia.com/baseos/ubuntu/focal/x86_64/ focal-updates preview"
```

```
$ sudo apt update
```

Chapter 3. API Errors

This section provides information about the API errors you might get when using GDS.

3.1. CU_FILE_DRIVER_NOT_INITIALIZED

`CU_FILE_DRIVER_NOT_INITIALIZED` API error.

If the `cuFileDriverOpen` API is not called, errors encountered in the implicit call to driver initialization are reported as `cuFile` errors encountered when calling `cuFileBufRegister` or `cuFileHandleRegister`.

3.2. CU_FILE_DEVICE_NOT_SUPPORTED

`CU_FILE_DEVICE_NOT_SUPPORTED` error.

GDS is supported only on NVIDIA graphics processing units (GPU) Tesla® or Quadro® models that support compute mode, and a compute major capability greater than or equal to 6.



Note: This includes V100 and T4 cards.

3.3. CU_FILE_IO_NOT_SUPPORTED

`CU_FILE_IO_NOT_SUPPORTED` error.

See [Before You Install GDS](#) for a list of the supported filesystems. If the file descriptor is from a local filesystem, or a mount that is not GDS ready, the API returns this error.

Common reasons for this error include:

- ▶ The file descriptor belongs to an unsupported filesystem.
- ▶ The specified `fd` is not a regular UNIX file.
- ▶ `O_DIRECT` is not specified on the file.
- ▶ Any combination of encryption, and compression, compliance settings on the `fd` are set.

For example, `FS_COMPR_FL | FS_ENCRYPT_FL | FS_APPEND_FL | FS_IMMUTABLE_FL`.



Note: These settings are allowed when `compat_mode` is set to `true`.

- ▶ Any combination of unsupported file modes are specified in the open call for the `fd`. For example,

`O_APPEND | O_NOCTTY | O_NONBLOCK | O_DIRECTORY | O_NOFOLLOW | O_TMPFILE`

3.4. CU_FILE_CUDA_MEMORY_TYPE_INVALID

The following is information about the `CU_FILE_CUDA_MEMORY_TYPE_INVALID` error.

Physical memory for `cudaMallocManaged` memory is allocated dynamically at the first use. Currently, it does not provide a mechanism to expose physical memory or Base Address Register (BAR) memory to pin for use in GDS. However, GDS indirectly supports `cudaMallocManaged` memory when the memory is used as an unregistered buffer with `cuFileWrite` and `cuFileRead`.

Chapter 4. Basic Troubleshooting

This section provides information about basic troubleshooting for GDS.

4.1. Log Files for the GDS Library

Here is some information about troubleshooting the GDS library log files.

A `cufile.log` file is created in the same location where the application binaries are located. Currently the maximum log file size is 32MB. If the log file size increases to greater than 32MB, the log file is truncated and logging is resumed on the same file.

4.2. Enabling a Different `cufile.log` File for Each Application

You can enable a different `cufile.log` file for each application.

There are several relevant cases:

- ▶ If the `logging:dir` property in the default `/etc/cufile.json` file is not set, by default, the `cufile.log` file is generated in the current working directory of the application.
- ▶ If the `logging:dir` property is set in the default `/etc/cufile.json` file, the log file is created in the specified directory path.



Note: This is usually not recommended for scenarios where multiple applications use the `libcufile.so` library.

For example:

```
"logging": {
  // log directory, if not enabled
  // will create log file under current working
  // directory
  "dir": "/opt/gdslogs/",
}
```

The `cufile.log` will be created as a `/opt/gdslogs/cufile.log` file.

If the application needs to enable a different `cufile.log` for different applications, the application can override the default JSON path by doing the following steps:

1. Export `CUFILE_ENV_PATH_JSON="/opt/myapp/cufile.json"`.
2. Edit the `/opt/myapp/cufile.json` file.

```
"logging": {
  // log directory, if not enabled
  // will create log file under current working
  // directory
  "dir": "/opt/myapp",
}
```

3. Run the application.
4. To check for logs, run:

```
$ ls -l /opt/myapp/cufile.log
```

4.3. Enabling Tracing GDS Library API Calls

There are different logging levels, which can be enabled in the `/etc/cufile.json` file. By default, logging level is set to `ERROR`. Logging will have performance impact as we increase the verbosity levels like `INFO`, `DEBUG`, and `TRACE`, and should be enabled only to debug field issues.

Configure tracing and run the following:

```
"logging": {
  // log directory, if not enabled
  // will create log file under local directory
  //"dir": "/home/<xxxx>",

  // ERROR|WARN|INFO|DEBUG|TRACE (in decreasing order of priority)
  "level": "ERROR"
},
```

4.4. cuFileHandleRegister Error

Here is some information about the `cuFileHandleRegister` error.

If you see this error on the `cufile.log` file when an IO is issued:

```
"cuFileHandleRegister error: GPUDirect Storage not supported on current file."
```

Here are some reasons why this error might occur:

- ▶ The filesystem is not supported by GDS.
See [CU_FILE_DEVICE_NOT_SUPPORTED](#) for more information.
- ▶ `DIRECT_IO` functionality is not supported for the mount on which the file resides.

For more information, enable tracing in the `/etc/cufile.json` file.

4.5. Troubleshooting Applications that Return cuFile Errors

This section describes how to troubleshoot cuFile errors.

To debug these errors:

1. See the `cufile.h` file for more information about errors that are returned by the API.
2. If the IO was submitted to the GDS driver, check whether there are any errors in GDS stats.

If the IO fails, the error stats should provide information about the type of error.

See Finding the [GDS Driver Statistics](#) for more information.

3. Enable GDS library tracing and monitor the `cufile.log` file.
4. Enable GDS Driver debugging:

```
$ echo 1 >/sys/module/nvidia_fs/parameters/dbg_enabled
```

After the driver debug logs are enabled, you might get more information about the error.

4.6. cuFile-* Errors with No Activity in GPUDirect Storage Statistics

This section provides information about a scenario where there are cuFile errors in the GDS statistics.

This issue means that the API failed in the GDS library. You can enable tracing by setting the appropriate logging level in the `/etc/cufile.json` file to get more information about the failure in `cufile.log`.

4.7. CUDA Runtime and Driver Mismatch with Error Code 35

The following is information about how to resolve CUDA error 35.

Error code 35 from the CUDA documentation points to `cudaErrorInsufficientDriver`, which indicates that the installed NVIDIA CUDA driver is older than the CUDA runtime library. This is not a supported configuration. For the application to run, you must update the NVIDIA display driver.



Note: cuFile tools depend on CUDA runtime 10.1 and later. You must ensure that the installed CUDA runtime is compatible with the installed CUDA driver and is at the recommended version.

4.8. CUDA API Errors when Running the cuFile-* APIs

The following is information about CUDA API errors.

The GDS library uses the CUDA driver APIs. If you observe CUDA API errors, you will observe an error code. Refer to the error codes in the [CUDA Libraries documentation](#) for more information.

4.9. Finding GDS Driver Statistics

This section describes how you can find the driver statistics.

To find the GDS Driver Statistics, run the following command:

```
$ cat /proc/driver/nvidia-fs/stats
```

GDS Driver kernel statistics for `READ/WRITE` are available only for the EXAScaler filesystem. Refer to [Troubleshooting and FAQ for the WekaIO Filesystem](#) for more information about `READ/WRITE`.

4.10. Tracking IO Activity that Goes Through the GDS Driver

The following is information about tracking IO activity.

In GDS Driver statistics, the **ops** row shows the active IO operation. The `read` and `write` fields show the current active operation in flight. This information should provide an idea of how many total IOs are in flight across all applications in the kernel. If there is a bottleneck in the userspace, the number of active IOs will be less than the number of threads that are submitting the IO. Additionally, to get more details about the `read` and `write` bandwidth numbers, look out for counters in the `read/write` rows.

4.11. Read/Write Bandwidth and Latency Numbers in GDS Stats

The following is information about `read/write` bandwidth and latency numbers in GDS.

Measured latencies begin when the IO is submitted and end when the IO completion is received by the GDS kernel driver. Userspace latencies are not reported. This should provide

an idea whether the user space is bottlenecked or whether the IO is bottlenecked on the backend disks/fabric.



Note: The WekaIO filesystem reads do not go through the nvidia-fs driver, so Read/Write bandwidth stats are not available for WekaIO filesystem by using this interface.

Refer to the [Troubleshooting and FAQ for the WekaIO Filesystem](#) for more information.

4.12. Tracking Registration and Deregistration of GPU Buffers

This section provides information about registering and deregistering GPU buffers.

In GDS Driver stats, look for the active field in BAR1-map stats row. The pinning and unpinning of GPU memory through `cuFileBufRegister` and `cuFileBufDeregister` is an expensive operation. If you notice a large number of registrations (`n`) and deregistration (`free`) in the `nvidia-fs` stats, it can hurt performance. Refer to the [GPUDirect Storage Best Practices Guide](#) for more information about using the `cuFileBufRegister` API.

4.13. Enabling RDMA-specific Logging for Userspace File Systems

In order to troubleshoot RDMA related issues for userspace file systems, ensure that the `CUFILE_LOGGING_LEVEL` environment variable is set to a value between 0-2 prior to running the application. However, for this to work, `cufile.json` logging level also should be set to `TRACE/DEBUG/INFO` level.

For example:

```
$ export CUFILE_LOGGING_LEVEL=1
$ cat /etc/cufile.json
....
"logging": {
  // log directory, if not enabled will create log file
  // under current working directory
  //"dir": "/home/<xxxx>",
  // ERROR|WARN|INFO|DEBUG|TRACE (in decreasing order of priority)
  "level": "DEBUG"
},
....
```

4.14. CUDA_ERROR_SYSTEM_NOT_READY After Installation

On systems with NVSwitch, if you notice the `CUDA_ERROR_SYSTEM_NOT_READY` error being reported, then make sure that you install the same version of Fabric Manager as the CUDA driver.

For example, if you use:

```
$ sudo apt install nvidia-driver-460-server -y
```

then use:

```
$ apt-get install nvidia-fabricmanager-460
```

Make sure to restart the Fabric Manager service using:

```
$ sudo service nvidia-fabricmanager start
```

4.15. Adding udev Rules for RAID Volumes

To add udev rules for RAID volumes:

As a sudo user, change the following line in `/lib/udev/rules.d/63-md-raid-arrays.rules`:

```
IMPORT{program}="/usr/sbin/mdadm --detail --export $devnode"
```

Reboot the node or restart the `mdadm`.

Chapter 5. Advanced Troubleshooting

This section provides information about troubleshooting some advanced issues.

5.1. Resolving Hung cuFile* APIs with No Response

This section describes how to resolve hung cuFile APIs.

1. Check whether there are any kernel panics/warnings in `dmesg`:

```
$ dmesg > warnings.txt. less warnings.txt
```

2. Check whether the application process is in the 'D' (uninterruptible) state).
3. If the process is in the 'D' state:

- a). Get the PID of the process by running the following command:

```
$ ps axf | grep 'D'
```

- b). As a root user, get the backtrace of the 'D' state process:

```
$ su root  
$ cat /proc/<pid>/stack
```

4. Verify whether the threads are stuck in the kernel or in user space.
For more information, review the backtrace of the 'D' state threads.
5. Check whether any threads are showing heavy CPU usage.
 - a). The `htop` and `mpstat` tools should show CPU usage per core.
 - b). Get the call graph of where the CPUs are being used.

The following code snippet should narrow down whether the threads are hung in user space or in the kernel:

```
$ perf top -g
```

5.2. Sending Relevant Data to Customer Support

This section describes how to resolve a kernel panic with stack traces using NVSM or the GDS Log Collection tool.

DGX OS:

For DGX BaseOS with the preview network repo enabled and NVSM installed:

```
$ sudo apt-get install nvsm
$ sudo nvsm dump health
```

For more details on running NVSM commands, refer to [NVIDIA System Management User Guide](#).

Non DGX:

The GDS Log Collection tool, `gds_log_collection.py`, may be run by GDS users to collect relevant debugging information from the system when issues with GDS IO are seen.

Some of the important information that this tool captures is highlighted below:

- ▶ dmesg Output and relevant kernel log files.
- ▶ System map files and vmlinux image
- ▶ modinfo output for relevant modules
- ▶ `/proc/cmdline` output
- ▶ IB devices info like `ibdev2net` and `ibstatus`
- ▶ OS distribution information
- ▶ Cpuinfo, meminfo
- ▶ `nvidia-fs` stats
- ▶ Per process information like `cufile.log`, `cufile.json`, `gds_stats`, stack pointers
- ▶ Any user specified files

To use the log collection tool:

```
$ sudo /usr/local/cuda/gds//tools/gdstools/gds_log_collection.py -h
```

This tool is used to collect logs from the system that are relevant for debugging.

It collects logs such as OS and kernel info, `nvidia-fs` stats, `dmesg` logs, `syslogs`, system map files and per process logs such as `cufile.json`, `cufile.log`, `gdsstats`, process stack, and so on.

Usage:

```
./gds_log_collection.py [options]
```

options:

```
-h help
```

```
-f file1,file2,.. (Note: there should be no spaces between ',')
```

These files could be any relevant files apart from the one's being collected (such as crash files).

Usage examples:

```
sudo ./gds_log_collection.py - Collects all the relevant logs.
```

```
sudo ./gds_log_collection.py -f file1,file2 - Collects all the relevant files as well as user specified files.
```

5.3. Resolving an IO Failure with EIO and Stack Trace Warning

Here is some information about how to resolve an IO failure with EIO and a warning with a stack trace with an `nvfs_mgroup_check_and_set` function in the trace.

This might mean that the EXAScaler filesystem did not honor `O_DIRECT` and fell back to page cache mode. GDS tracks this information in the driver and returns EIO.



Note: The **WARNING** stack trace is observed only once during the lifetime of the kernel module. You will get an `Error: Input/Output (EIO)`, but the trace message will be printed only once. If you consistently experience this issue, contact support.

5.4. Controlling GPU BAR Memory Usage

Here is some information about how to manage and control your GPU BAR memory usage.

1. To show how much BAR Memory is available per GPU, run the following command:

```
$ /usr/local/cuda-x.y/gds/tools/gdscheck
```

2. Review the output, for example:

```
GPU INFO:
GPU Index: 0 bar:1 bar size (MB):32768
GPU Index: 1 bar:1 bar size (MB):32768
```

GDS uses BAR memory in the following cases:

- ▶ When the process invokes `cuFileBufRegister`.
- ▶ When GDS uses the cache internally to allocate bounce buffers per GPU.



Note: There is no per-GPU configuration for cache and BAR memory usage.

Each process can control the usage of BAR memory via the configurable property in the `/etc/cufile.json` file:

```
"properties": {
// device memory size for reserving bounce buffers for the entire GPU (in KB)
"max_device_cache_size" : 131072,
// limit on maximum memory that can be pinned for a given process (in KB)
"max_device_pinned_mem_size" : 33554432
}
```



Note: This configuration is per process, and the configuration is set across all GPUs.

5.5. Determining the Amount of Cache to Set Aside

Here is some information about how to determine how much cache to set aside.

By default, 128 MB of cache is set in the configurable `max_device_cache_size` property. However, this does not mean that GDS pre-allocates 128 MB of memory per GPU up front. Memory allocation is done on the fly and is based on need. After the allocation is complete, there is no purging of the cache.

By default, since 128 MB is set, the cache can grow up to 128 MB. Setting the cache is application specific and depends on workload. Refer to the [GPUDirect Storage Best Practices Guide](#) to understand the need of cache and how to set the limit based on guidance in the guide.

5.6. Monitoring BAR Memory Usage

Here is some information about monitoring BAR memory usage.

There is no way to monitor the BAR memory usage per process. However, GDS Stats tracks the global BAR usage across all processes. For more information, see the following stat output from `/proc/driver/nvidia_fs/stats` for the GPU with `B:D:F 0000:34:00.0`:

```
GPU 0000:34:00.0  uuid:12a86a5e-3002-108f-ee49-4b51266cdc07 : Registered_MB=32
Cache_MB=10
```

`Registered_MB` tracks how much BAR memory is used when applications are explicitly using the `cuFileBufRegister` API.

`Cache_MB` tracks GDS usage of BAR memory for internal cache.

5.7. Resolving an ENOMEM Error Code

The following is information about the `-12 ENOMEM` error code.

Each GPU has some BAR memory reserved. The `cuFileBufRegister` function makes the pages that underlie a range of GPU virtual memory accessible to a third-party device. This process is completed by pinning the GPU device memory in BAR space by using the `nvidia_p2p_get_pages` API. If the application tries to pin memory beyond the available BAR space, the `nvidia_p2p_get_pages` API returns a `-12 (ENOMEM)` error code.

To avoid running out of BAR memory, developers should use this output to manage how much memory is pinned by application. Administrators can use this output to investigate how to limit the pinned memory for different applications.

5.8. GDS and Compatibility Mode

This section describes how to determine GDS compatibility mode.

To determine the compatibility mode, complete the following tasks:

1. In the `/etc/cufile.json` file, verify that `allow_compat_mode` is set to `true`.
2. `gdscheck -p` displays whether the `allow_compat_mode` property is set to `true`.
3. Check the `cufile.log` file for the `cufile IO mode: POSIX` message.

This message is in the hot IO path, where logging each instance significantly impacts performance, so the message is only logged when `logging:level` is explicitly set to the `TRACE` mode in the `/etc/cufile.json` file.

5.9. Enabling Compatibility Mode

This section describes how to enable the compatibility mode.

Compatibility mode can be used by application developers to test the applications with cuFile-enabled libraries under the following conditions:

- ▶ When there is no support for GDS for a specific filesystem.
- ▶ The `nvidia-fs.ko` driver is not enabled in the system by the administrator.

To enable compatibility mode:

1. Remove the `nvidia-fs` kernel driver:

```
$ rmmmod nvidia-fs
```

2. In the `/etc/cufile.json` file, set `compat-mode` to `true`.

The IO through `cuFileRead/cuFileWrite` will now fall back to the CPU path.

5.10. Tracking the IO After Enabling Compatibility Mode

Here is some information about tracking the IO after you enable the compatibility mode.

When GDS is used in compatibility mode, and `cufile_stats` is enabled in the `/etc/cufile.json` file, you can use `gds_stats` or another standard Linux tools, such as `strace`, `iostat`, `iotop`, `SAR`, `ftrace`, and `perf`. You can also use the BPF compiler collection tools to track and monitor the IO.

When compatibility mode is enabled, internally, `cuFileRead` and `cuFileWrite` use POSIX `pread` and `pwrite` system calls, respectively.

5.11. Bypassing GPUDirect Storage

There are some scenarios in which you can bypass GDS.

There are some tunables where GDS IO and POSIX IO can go through simultaneously.

The following are cases where GDS can be bypassed without having to remove the GDS driver:

- ▶ On supported filesystems and block devices.

In the `/etc/cufile.json` file, if the `posix_unaligned_writes` config property is set to `true`, the unaligned writes will fall back to the compatibility mode and will not go through GDS. Refer to [Before You Install GDS](#) for a list of supported file systems.

- ▶ On an EXAScaler filesystem

In the `/etc/cufile.json` file, if the `posix_gds_min_kb` config property is set to a certain value (in KB), the IO for which the size is less than or equal to the set value, will fall back to POSIX mode. For example, if `posix_gds_min_kb` is set to 8KB, IOs with a size that is less than or equal to 8KB, will fall back to the POSIX mode.

- ▶ On a WekaIO filesystem:



Note: Currently, `cuFileWrite` will always fallback to the POSIX mode.

In the `/etc/cufile.json` file, if the `allow_compat_mode` config property is set to `true`:

- ▶ If RDMA connections and/or memory registrations cannot be established, `cuFileRead` will fall back to the POSIX mode.
- ▶ `cuFileRead` fails to allocate an internal bounce buffer for non-4K aligned GPU VA addresses.

Refer to the [GPUDirect Storage Best Practices Guide](#) for more information.

5.12. GDS Does Not Work for a Mount

The following information can help you understand why GDS is not working for a mount.

GDS will not be used for a mount in the following cases:

- ▶ When the necessary GDS drivers are not loaded on the system.
- ▶ The filesystem associated with that mount is not supported by GDS.
- ▶ The mount point is denylisted in the `/etc/cufile.json` file.

5.13. Simultaneously Running the GPUDirect Storage IO and POSIX IO on the Same File

Since a file is opened in `O_DIRECT` mode for GDS, applications should avoid mixing `O_DIRECT` and normal I/O to the same file, and especially to overlapping byte regions in the same file.

Even when the filesystem correctly handles the coherency issues in this situation, overall I/O throughput might be slower than using either mode alone. Similarly, applications should avoid mixing `mmap(2)` of files with direct I/O to the same files. Refer to the filesystem-specific documentation for information about additional `O_DIRECT` limitations.

5.14. Running Data Verification Tests Using GPUDirect Storage

This section describes how you can run data verification tests by using GDS.

GDS has an internal data verification utility, `gdsio_verify`, which is used to test data integrity of reads and writes. Run `gdsio_verify -h` for detailed usage information.

For example:

```
$ /usr/local/cuda-11.2/gds/tools/gds_verify -f /mnt/ai200/fio-seq-writes-1 -d 0 -o 0
-s 1G -n 1 -m 1
```

Here is the sample output:

```
gpu index :0, file :/mnt/ai200/fio-seq-writes-1, RING buffer size :0,
gpu buffer alignment :0, gpu buffer offset :0, file offset :0,
io_requested :1073741824, bufregister :true, sync :1, nr ios :1,
fsync :0,
address = 0x560d32c17000
Data Verification Success
```



Note: This test completes data verification of reads and writes through GDS.

Chapter 6. Troubleshooting Performance

This section covers issues related to performance.

6.1. Running Performance Benchmarks with GDS

You can run performance benchmarks with GDS and compare the results with CPU numbers.

GDS has a homegrown benchmarking utility, `/usr/local/cuda-x.y/gds/tools/gdsio`, which helps you compare GDS IO throughput numbers with CPU IO throughput. Run `gdsio -h` for detailed usage information.

Here are some examples:

GDS: Storage --> GPU Memory

```
$ /usr/local/cuda-x.y/tools/gdsio -f /mnt/ai200/fio-seq-writes-1 -d 0 -w 4 -s 10G -i 1M -I 0 -x 0
```

Storage --> CPU Memory

```
$ /usr/local/cuda-x.y/tools/gdsio -f /mnt/ai200/fio-seq-writes-1 -d 0 -w 4 -s 10G -i 1M -I 0 -x 1
```

Storage --> CPU Memory --> GPU Memory

```
$ /usr/local/cuda-x.y/tool/gdsio -f /mnt/ai200/fio-seq-writes-1 -d 0 -w 4 -s 10G -i 1M -I 0 -x 2
```

6.2. Tracking Whether GPUDirect Storage is Using an Internal Cache

You can determine whether GDS is using an internal cache.

Prerequisite: Before you start, read the [GPUDirect Storage Best Practices Guide](#).

GDS Stats has per-GPU stats, and each piece of the GPU bus device function (BDF) information is displayed. If the `cache_MB` field is active on a GPU, GDS is using the cache internally to complete the IO.

GDS might use the internal cache when one of the following conditions are true:

- ▶ The `file_offset` that was issued in `cuFileRead/cuFileWrite` is not 4K aligned.
- ▶ The size in `cuFileRead/cuFileWrite` calls are not 4K aligned.
- ▶ The `devPtr_base` that was issued in `cuFileRead/cuFileWrite` is not 4K aligned.
- ▶ The `devPtr_base+devPtr_offset` that was issued in `cuFileRead/cuFileWrite` is not 4K aligned.

6.3. Tracking when IO Crosses the PCIe Root Complex and Impacts Performance

You can track when the IO crosses the PCIe root complex and affects performance.

Refer to [Review Peer Affinity Stats for a Kernel Filesystem and Storage Devices](#) for more information.

6.4. Using GPUDirect Statistics to Monitor CPU Activity

Although you cannot use GDS statistics to monitor CPU activity, you can use the following Linux tools to complete this task:

- ▶ `htop`
- ▶ `perf`
- ▶ `mpstat`

6.5. Monitoring Performance and Tracing with `cuFile-*` APIs

You can monitor performance and tracing with the `cuFile-*` APIs.

You can use the `FTrace`, the `Perf`, or the `BCC-BPF` tools to monitor performance and tracing. Ensure that you have the symbols that you can use to track and monitor the performance with a standard Linux IO tool.

6.6. Example: Using Linux Tracing Tools

The `cuFileBufRegister` function makes the pages that underlie a range of GPU virtual memory accessible to a third-party device. This process is completed by pinning the GPU

device memory in the BAR space, which is an expensive operation and can take up to a few milliseconds.

You can use the BCC/BPF tool to trace the `cuFileBufRegister` API, understand what is happening in the Linux kernel, and understand why this process is expensive.

Scenario

1. You are running a workload with 8 threads where each thread is issuing `cuFileBufRegister` to pin to the GPU memory.

```
$ ./gdsio -f /mnt/ai200/seq-writes-1 -d 0 -w 8 -s 10G -i 1M -I 0 -x 0
```

2. When IO is in progress, use a tracing tool to understand what is going on with `cuFileBufRegister`:

```
$ /usr/share/bcc/tools# ./funccount -Ti 1 nvfs_mgroup_pin_shadow_pages
```

3. Review the sample output:

```
15:04:56
FUNC                                COUNT
nvfs_mgroup_pin_shadow_pages        8
```

As you can see, the `nvfs_mgroup_pin_shadow_pages` function has been invoked 8 times in one per thread.

4. To see the latency for that function, run:

```
$ /usr/share/bcc/tools# ./funclatency -i 1 nvfs_mgroup_pin_shadow_pages
```

5. Review the output:

Tracing 1 functions for "nvfs_mgroup_pin_shadow_pages"... Hit Ctrl-C to end.

```

nsecs          : count      distribution
  0 -> 1        : 0          |
  2 -> 3        : 0          |
  4 -> 7        : 0          |
  8 -> 15       : 0          |
 16 -> 31      : 0          |
 32 -> 63      : 0          |
 64 -> 127     : 0          |
128 -> 255    : 0          |
256 -> 511    : 0          |
512 -> 1023   : 0          |
1024 -> 2047  : 0          |
2048 -> 4095  : 0          |
4096 -> 8191  : 0          |
8192 -> 16383 : 1          |*****|
16384 -> 32767 : 7          |*****|

```

Seven calls of the `nvfs_mgroup_pin_shadow_pages` function took about 16-32 microseconds. This is probably coming from the Linux kernel `get_user_pages_fast` that is used to pin shadow pages.

`cuFileBufRegister` invokes `nvidia_p2p_get_pages` NVIDIA driver function to pin GPU device memory in the BAR space. This information is obtained by running `$ perf top -g` and getting the call graph of `cuFileBufRegister`.

The following example shows the overhead of the `nvidia_p2p_get_pages`:

```
$ /usr/share/bcc/tools# ./funclatency -Ti 1 nvidia_p2p_get_pages
```

```

15:45:19
nsecs      : count      distribution
 0 -> 1      : 0
 2 -> 3      : 0
 4 -> 7      : 0
 8 -> 15     : 0
16 -> 31    : 0
32 -> 63    : 0
64 -> 127   : 0
128 -> 255  : 0
256 -> 511  : 0
512 -> 1023 : 0
1024 -> 2047 : 0
2048 -> 4095 : 0
4096 -> 8191 : 0
8192 -> 16383 : 0
16384 -> 32767 : 0
32768 -> 65535 : 0
65536 -> 131071 : 0
131072 -> 262143 : 0
262144 -> 524287 : 2
524288 -> 1048575 : 6

```

6.7. Tracing the cuFile-* APIs

You can use nvprof/NVIDIA Nsight to trace the cuFile-* APIs.

NVTX static tracepoints are available for public interface in the `libcufile.so` library. After these static tracepoints are enabled, you can view these traces in NVIDIA Nsight just like any other CUDA® symbols.

You can enable the NVTX tracing using the JSON configuration at `/etc/cufile.json`:

```

"profile": {
    // nvtx profiling on(true)/off(false)
    "nvtx": true,
},

```

6.8. Improving Performance using Dynamic Routing

On platforms where the IO transfers between GPU(s) and the storage NICs involve PCIe traffic across PCIe-host bridge, GPUDirect Storage IO may not see a great throughput especially for writes. Also, certain chipsets may support only P2P read traffic for host bridge traffic. In such cases, the dynamic routing feature can be enabled to debug and identify what routing policy is deemed best for such platforms. This can be illustrated with a single GPU write test with the `gdsio` tool, where there is one Storage NIC and 10 GPUs with NVLINKs access enabled between the GPUS. With dynamic routing enabled, even though the GPU and NIC might be on different sockets, GDS can still achieve the maximum possible write throughput.

```

$ cat /etc/cufile.json | grep rdma_dev
    "rdma_dev_addr_list": [ "192.168.0.19" ],

```

Dynamic Routing OFF:

```

$ cat /etc/cufile.json | grep routing
    "rdma_dynamic_routing": false
$ for i in 0 1 2 3 4 5 6 7 8 9 10;

```

```

do
./gdsio -f /mnt/nfs/file1 -d $i -n 0 -w 4 -s 1G -i 1M -x 0 -I 1 -p -T 15 ;
done
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 45792256/4194304(KiB) IOSize:
1024(KiB) Throughput: 2.873560 GiB/sec, Avg_Latency: 1359.280174 usecs ops: 44719
total_time 15.197491 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 45603840/4194304(KiB) IOSize:
1024(KiB) Throughput: 2.867613 GiB/sec, Avg_Latency: 1363.891220 usecs ops: 44535
total_time 15.166344 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 42013696/4194304(KiB) IOSize:
1024(KiB) Throughput: 2.848411 GiB/sec, Avg_Latency: 1373.154082 usecs ops: 41029
total_time 14.066573 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 43517952/4194304(KiB) IOSize:
1024(KiB) Throughput: 2.880763 GiB/sec, Avg_Latency: 1358.207427 usecs ops: 42498
total_time 14.406582 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 34889728/4194304(KiB) IOSize:
1024(KiB) Throughput: 2.341907 GiB/sec, Avg_Latency: 1669.108902 usecs ops: 34072
total_time 14.207836 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 36955136/4194304(KiB) IOSize:
1024(KiB) Throughput: 2.325239 GiB/sec, Avg_Latency: 1680.001220 usecs ops: 36089
total_time 15.156790 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 37075968/4194304(KiB) IOSize:
1024(KiB) Throughput: 2.351491 GiB/sec, Avg_Latency: 1661.198487 usecs ops: 36207
total_time 15.036584 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 35066880/4194304(KiB) IOSize:
1024(KiB) Throughput: 2.235654 GiB/sec, Avg_Latency: 1748.638950 usecs ops: 34245
total_time 14.958656 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 134095872/4194304(KiB) IOSize:
1024(KiB) Throughput: 8.940253 GiB/sec, Avg_Latency: 436.982682 usecs ops: 130953
total_time 14.304269 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 135974912/4194304(KiB) IOSize:
1024(KiB) Throughput: 8.932070 GiB/sec, Avg_Latency: 437.334849 usecs ops: 132788
total_time 14.517998 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 174486528/4194304(KiB) IOSize:
1024(KiB) Throughput: 11.238476 GiB/sec, Avg_Latency: 347.603610 usecs ops: 170397
total_time 14.806573 secs

```

Dynamic Routing ON (nvlinks enabled):

```

$ cat /etc/cufile.json | grep routing
    "rdma_dynamic_routing": true
    "rdma_dynamic_routing_order": [ "GPU_MEM_NVLINKS" ]

$ for i in 0 1 2 3 4 5 6 7 8 9 10;
do
./gdsio -f /mnt/nfs/file1 -d $i -n 0 -w 4 -s 1G -i 1M -x 0 -I 1 -p -T 15 ;
done
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 134479872/4194304(KiB) IOSize:
1024(KiB) Throughput: 8.885214 GiB/sec, Avg_Latency: 437.942083 usecs ops: 131328
total_time 14.434092 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 138331136/4194304(KiB) IOSize:
1024(KiB) Throughput: 8.891407 GiB/sec, Avg_Latency: 437.668104 usecs ops: 135089
total_time 14.837118 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 133800960/4194304(KiB) IOSize:
1024(KiB) Throughput: 8.897250 GiB/sec, Avg_Latency: 437.305565 usecs ops: 130665
total_time 14.341795 secs

```

```

url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 133990400/4194304 (KiB) IOSize:
1024(KiB) Throughput: 8.888714 GiB/sec, Avg_Latency: 437.751327 usecs ops: 130850
total_time 14.375893 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 141934592/4194304 (KiB) IOSize:
1024(KiB) Throughput: 8.905190 GiB/sec, Avg_Latency: 437.032919 usecs ops: 138608
total_time 15.200055 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 133379072/4194304 (KiB) IOSize:
1024(KiB) Throughput: 8.892493 GiB/sec, Avg_Latency: 437.488259 usecs ops: 130253
total_time 14.304222 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 142271488/4194304 (KiB) IOSize:
1024(KiB) Throughput: 8.892426 GiB/sec, Avg_Latency: 437.660016 usecs ops: 138937
total_time 15.258004 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 134951936/4194304 (KiB) IOSize:
1024(KiB) Throughput: 8.890496 GiB/sec, Avg_Latency: 437.661177 usecs ops: 131789
total_time 14.476154 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 132667392/4194304 (KiB) IOSize:
1024(KiB) Throughput: 8.930203 GiB/sec, Avg_Latency: 437.420830 usecs ops: 129558
total_time 14.167817 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 137982976/4194304 (KiB) IOSize:
1024(KiB) Throughput: 8.936189 GiB/sec, Avg_Latency: 437.123356 usecs ops: 134749
total_time 14.725608 secs
url index :0, urlname :192.168.0.2 urlport :18515
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 170469376/4194304 (KiB) IOSize:
1024(KiB) Throughput: 11.231479 GiB/sec, Avg_Latency: 347.818052 usecs ops: 166474
total_time 14.474698 secs

```

Chapter 7. Troubleshooting IO Activity

This section covers issues that are related to IO activity and the interactions with the rest of Linux.

7.1. Managing Coherency with the Page Cache

Here is some information about how filesystems maintain the coherency of data in the page cache and the data on disk.

When using GDS, files are opened with the `O_DIRECT` mode. When IO is complete, in the context of DIRECT IO, it bypasses the page cache.

- ▶ On EXAScaler filesystem:
 - ▶ For reads, IO bypasses the page cache and fetches the data directly from backend storage.
 - ▶ When writes are issued, the `nvidia-fs` drivers will try to flush the data in the page cache for the range of offset-length before issuing writes to the VFS subsystem.
 - ▶ The stats that track this information are:
 - ▶ `pg_cache`
 - ▶ `pg_cache_fail`
 - ▶ `pg_cache_eio`
- ▶ On WekaIO filesystem:
 - ▶ For reads, IO bypasses the page cache and fetches the data directly from backend storage.

Chapter 8. EXAScaler Filesystem LNet Troubleshooting

This section describes how to troubleshoot issues with the EXAScaler Filesystem.

8.1. Determining the EXAScaler Filesystem Client Module Version

You can determine the version of the EXAScalerFilesystem Client module.

To check the EXAScaler filesystem Client version, check dmesg after you install the EXAScaler filesystem.



Note: The EXAScaler server version should be EXA-5.2.

This table provides a list of the client kernel module versions that have been tested with DDN AI200 and DDN AI400 systems:

Table 2. Tested Kernel Module Versions

DDN Client Version	Kernel Version	MLNX_OFED version
2.12.3_ddn28	4.15.0	MLNX_OFED 4.7
2.12.3_ddn29	4.15.0	MLNX_OFED 4.7
2.12.3_ddn39	4.15.0	MLNX_OFED 5.1
2.12.5_ddn4	5.4.0	MLNX_OFED 5.1
2.12.6_ddn19	5.4.0	MLNX_OFED 5.3

To verify the client version, run the following command:

```
$ sudo lctl get_param version
```

Sample output:

```
Lustre version: 2.12.3_ddn39
```

8.2. Checking the LNet Network Setup on a Client

You can check the LNet network setup on the client.

1. Run the following command.

```
$ sudo lnetctl net show:
```

2. Review the output, for example:

```
net:
- net type: lo
```

8.3. Checking the Health of the Peers

The following describes how to check the health of your interface.

An Lnet health value of 1000 is the best possible value that can be reported for a network interface. Anything less than 1000 indicates that the interface is running in a degraded mode and has encountered some errors.

1. Run the following command ;

```
$ sudo lnetctl net show -v 3 | grep health
```

2. Review the output, for example:

```
health stats:
health stats:
health value: 1000
health stats:
health value: 1000
health stats:
health value: 1000
health stats:
health value: 1000
health stats:
health value: 1000
health stats:
health value: 1000
health stats:
health value: 1000
health stats:
health value: 1000
health stats:
health value: 1000
```

8.4. Checking for Multi-Rail Support

You can verify whether multi-rail is supported.

1. Run the following command:

```
$ sudo lnetctl peer show | grep -i Multi-Rail:
```

2. Review the output, for example:

```
Multi-Rail: True
```


8.5. Checking GDS Peer Affinity

For peer affinity, you need to check whether the expected interfaces are being used for the associated GPUs.

The code snippet below is a description of a test that runs load on a specific GPU. The test validates whether the interface that is performing the send and receive is the interface that is the closest, and is correctly mapped, to the GPU. See [Resetting the nvidia-fs Statistics](#) and [Reviewing Peer Affinity Stats for a Kernel File System and Storage Drivers](#) for more information about the metrics that are used to check peer affinity.

You can run a `gdsio` test for the tools section and monitor the LNET stats. See the readme file for more information. In the `gdsio` test, a write test has been completed on GPU 0. The expected NIC interface for GPU 0 is `ib0` on the NVIDIA DGX-2™ platform. The `lnetctl net show` statistics were previously captured, and after the `gdsio` test, you can see that the RPC send and receive have happened over the `IB0`.

1. Run the `gdsio` test.
2. Review the output, for example:

```
$ sudo lustre_rmmmod
$ sudo mount -t lustre 192.168.1.61@o2ib,192.168.1.62@o2ib:/ai200 /mnt/ai200/
$ sudo lnetctl net show -v 3 | grep health
    health stats:
      health value: 0
    health stats:
      health value: 1000
    health stats:
      health value: 1000
    health stats:
      health value: 1000
    health stats:
      health value: 1000
    health stats:
      health value: 1000
    health stats:
      health value: 1000
    health stats:
      health value: 1000
    health stats:
      health value: 1000
    health stats:
      health value: 1000

$ sudo lnetctl net show -v 3 | grep -B 2 -i 'send_count\|rcv_count'
    status: up
    statistics:
      send_count: 0
      rcv_count: 0
--
    0: ib0
    statistics:
      send_count: 3
      rcv_count: 3
--
    0: ib2
    statistics:
      send_count: 3
      rcv_count: 3
--
    0: ib3
    statistics:
```

```

        send_count: 2
        recv_count: 2
--
        0: ib4
statistics:
        send_count: 13
        recv_count: 13
--
        0: ib5
statistics:
        send_count: 12
        recv_count: 12
--
        0: ib6
statistics:
        send_count: 12
        recv_count: 12
--
        0: ib7
statistics:
        send_count: 11
        recv_count: 11

$ echo 1 > /sys/module/nvidia_fs/parameters/peer_stats_enabled

$ /usr/local/cuda-x.y/tools/gdsio -f /mnt/ai200/test -d 0 -n 0 -w 1 -s 1G -i 4K -
x 0 -I 1
IoType: WRITE XferType: GPUD Threads: 1 DataSetSize: 1073741824/1073741824
IOSize: 4(KB),Throughput: 0.004727 GB/sec, Avg_Latency: 807.026154 usecs ops:
262144 total_time 211562847.000000 usecs

$ sudo lnetctl net show -v 3 | grep -B 2 -i 'send_count\|recv_count'

        status: up
statistics:
        send_count: 0
        recv_count: 0
--
        0: ib0
statistics:
        send_count: 262149
        recv_count: 524293
--
        0: ib2
statistics:
        send_count: 6
        recv_count: 6
--
        0: ib3
statistics:
        send_count: 6
        recv_count: 6
--
        0: ib4
statistics:
        send_count: 33
        recv_count: 33
--
        0: ib5
statistics:
        send_count: 32
        recv_count: 32
--
        0: ib6
statistics:
        send_count: 32
        recv_count: 32

```



```

    drop_count: 0
sent_stats:
  put: 119492
  get: 52129
  reply: 0
  ack: 0
  hello: 0
received_stats:
  put: 119492
  get: 0
  reply: 340225
  ack: 0
  hello: 0
dropped_stats:
  put: 0
  get: 0
  reply: 0
  ack: 0
  hello: 0
health stats:
  health value: 1000
  interrupts: 0
  dropped: 0
  aborted: 0
  no route: 0
  timeouts: 0
  error: 0
tunables:
  peer_timeout: 180
  peer_credits: 32
  peer_buffer_credits: 0
  credits: 256
  peercredits_hiw: 16
  map_on_demand: 1
  concurrent_sends: 64
  fmr_pool_size: 512
  fmr_flush_trigger: 384
  fmr_cache: 1
  ntx: 512
  conns_per_peer: 1
lnd tunables:
  dev cpt: 0
  tcp bonding: 0
CPT: "[0,1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19,20,21,22,23]"
- nid: 192.168.2.71@o2ib
  status: up
  interfaces:
    0: ib1
  statistics:
    send_count: 79
    rcv_count: 79
    drop_count: 0
sent_stats:
  put: 78
  get: 1
  reply: 0
  ack: 0
  hello: 0
received_stats:
  put: 78
  get: 0
  reply: 1
  ack: 0
  hello: 0
dropped_stats:
  put: 0
  get: 0

```

```

    reply: 0
    ack: 0
    hello: 0
health stats:
    health value: 979
    interrupts: 0
    dropped: 0
    aborted: 0
    no route: 0
    timeouts: 1
    error: 0
tunables:
    peer_timeout: 180
    peer_credits: 32
    peer_buffer_credits: 0
    credits: 256
    peercredits_hiw: 16
    map_on_demand: 1
    concurrent_sends: 64
    fmr_pool_size: 512
    fmr_flush_trigger: 384
    fmr_cache: 1
    ntx: 512
    conns_per_peer: 1
lnd tunables:
dev cpt: 0
tcp bonding: 0
CPT: "[0,1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19,20,21,22,23]"
- nid: 192.168.2.72@o2ib
  status: up
  interfaces:
    0: ib3
  statistics:
    send_count: 52154
    rcv_count: 52154
    drop_count: 0
  sent_stats:
    put: 25
    get: 52129
    reply: 0
    ack: 0
    hello: 0
  received_stats:
    put: 25
    get: 52129
    reply: 0
    ack: 0
    hello: 0
  dropped_stats:
    put: 0
    get: 0
    reply: 0
    ack: 0
    hello: 0
  health stats:
    health value: 66
    interrupts: 0
    dropped: 208
    aborted: 0
    no route: 0
    timeouts: 1735
    error: 0
  tunables:
    peer_timeout: 180
    peer_credits: 32
    peer_buffer_credits: 0
    credits: 256

```

```

peercredits_hiw: 16
map_on_demand: 1
concurrent_sends: 64
fmr_pool_size: 512
fmr_flush_trigger: 384
fmr_cache: 1
ntx: 512
conns_per_peer: 1
lnd tunables:
dev cpt: 0
tcp bonding: 0
CPT: "[0,1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19,20,21,22,23]"

```

If you see incrementing error stats, capture the net logging and provide this information for debugging:

```

$ lctl set_param debug=+net
# reproduce the problem
$ lctl dk > logfile.dk

```

8.7. Resolving LNet NIDs Health Degradation from Timeouts

With large machines, such as DGX™ that have multiple interfaces, if Linux routing is not correctly set up, there might be connection failures and other unexpected behavior.

Here is the typical network setting that is used to resolve local connection timeouts:

```
sysctl -w net.ipv4.conf.all.accept_local=1
```

There are also generic pointers for resolving LNet Network issues. Refer to [MR Cluster Setup](#) for more information.

8.8. Configuring LNet Networks with Multiple OSTs for Optimal Peer Selection

This section describes how to configure LNET networks that have multiple Object Storage Target (OSTs).

When there are multiple OSTs, and each OST is dual interface, to need to have one interface on each of the LNETs for which the client is configured.

For example, you have the following two LNet Subnets on the client side:

- ▶ o2ib
- ▶ o2ib1

The server has only one Lnet subnet, o2ib. In this situation, the routing is not optimal, because you are restricting the ib selection logic to a set of devices, which may not be closest to the GPU. There is no way to reach OST2 except over the LNet to which it is connected.

The traffic that goes to this OST will never be optimal, and this configuration might affect overall throughput and latency. If, however, you configure the server to use two networks, o2ib0 and o2ib1, then OST1 and OST2 can be reached over both networks. When the selection algorithm runs, it will determine that the best path is, for example, OST2 over o2ib1.

1. To configure the client-side LNET, run the following command:

```
$ sudo lnetctl net show
```

2. Review the output, for example:

```
net:
- net type: lo
  local NI(s):
  - nid: 0@lo
    status: up
- net type: o2ib
  local NI(s):
  - nid: 192.168.1.71@o2ib
    status: up
    interfaces:
      0: ib0
  - nid: 192.168.1.72@o2ib
    status: up
    interfaces:
      0: ib2
  - nid: 192.168.1.73@o2ib
    status: up
    interfaces:
      0: ib4
  - nid: 192.168.1.74@o2ib
    status: up
    interfaces:
      0: ib6
- net type: o2ib1
  local NI(s):
  - nid: 192.168.2.71@o2ib1
    status: up
    interfaces:
      0: ib1
  - nid: 192.168.2.72@o2ib1
    status: up
    interfaces:
      0: ib3
  - nid: 192.168.2.73@o2ib1
    status: up
    interfaces:
      0: ib5
  - nid: 192.168.2.74@o2ib1
    status: up
    interfaces:
      0: ib7
```

For an optimal configuration, the LNet peer should show two LNet subnets.

In this case, the primary nid is only one o2ib:

```
$ sudo lnetctl peer show
```

Sample output:

```
peer:
- primary nid: 192.168.1.62@o2ib
  Multi-Rail: True
  peer ni:
  - nid: 192.168.1.62@o2ib
    state: NA
  - nid: 192.168.2.62@o2ib1
```



```

state: NA
- primary nid: 192.168.1.61@o2ib
Multi-Rail: True
peer ni:
- nid: 192.168.1.61@o2ib
state: NA
- nid: 192.168.2.61@o2ib1
state: NA

```

From the server side, here is an example of sub-optimal LNet configuration:

```

[root@ai200-090a-vm01 ~]# lnetctl net show
net:
- net type: lo
  local NI(s):
  - nid: 0@lo
    status: up
- net type: o2ib (o2ib1 is not present)
  local NI(s):
  - nid: 192.168.1.62@o2ib
    status: up
    interfaces:
      0: ib0
  - nid: 192.168.2.62@o2ib
    status: up
    interfaces:
      0: ib1

```

Here is an example of an IB configuration for a non-optimal case, where a file is striped over two OSTs, and there are sequential reads:

```

$ ibdev2netdev -v

0000:b8:00.1 mlx5_13 (MT4123 - MCX653106A-ECAT) ConnectX-6 VPI adapter card, 100Gb/s
(HDR100, EDR IB and 100GbE), dual-port QSFP56
fw 20.26.4012 port 1
(ACTIVE) ==> ib4 (Up) (o2ib)

ib4: flags=4163<UP,BROADCAST,RUNNING,MULTICAST> mtu 2044
inet 192.168.1.73 netmask 255.255.255.0 broadcast 192.168.1.255

0000:bd:00.1 mlx5_15 (MT4123 - MCX653106A-ECAT) ConnectX-6 VPI adapter card, 100Gb/s
(HDR100, EDR IB and 100GbE), dual-port QSFP56
fw 20.26.4012 port 1
(ACTIVE) ==> ib5 (Up) (o2ib1)

ib5: flags=4163<UP,BROADCAST,RUNNING,MULTICAST> mtu 2044
inet 192.168.2.73 netmask 255.255.255.0 broadcast 192.168.2.255

$ cat /proc/driver/nvidia-fs/peer_distance | grep 0000:be:00.0 | grep network
0000:be:00.0 0000:58:00.1 138 0 network
0000:be:00.0 0000:58:00.0 138 0 network
0000:be:00.0 0000:86:00.1 134 0 network
0000:be:00.0 0000:35:00.0 138 0 network
0000:be:00.0 0000:5d:00.0 138 0 network
0000:be:00.0 0000:bd:00.0 3 0 network
0000:be:00.0 0000:b8:00.1 7 30210269 network (ib4) (chosen peer)
0000:be:00.0 0000:06:00.0 134 0 network
0000:be:00.0 0000:0c:00.1 134 0 network
0000:be:00.0 0000:e6:00.0 138 0 network
0000:be:00.0 0000:3a:00.1 138 0 network
0000:be:00.0 0000:e1:00.0 138 0 network
0000:be:00.0 0000:bd:00.1 3 4082933 network (ib5) (best peer)

```

```

0000:be:00.0    0000:e6:00.1    138    0    network
0000:be:00.0    0000:86:00.0    134    0    network
0000:be:00.0    0000:35:00.1    138    0    network
0000:be:00.0    0000:e1:00.1    138    0    network
0000:be:00.0    0000:0c:00.0    134    0    network
0000:be:00.0    0000:b8:00.0    7      0    network
0000:be:00.0    0000:5d:00.1    138    0    network
0000:be:00.0    0000:3a:00.0    138    0    network

```

Here is an example of an optimal LNet configuration:

```

[root@ai200-090a-vm00 ~]# lnetctl net show
net:
- net type: lo
  local NI(s):
  - nid: 0@lo
    status: up
- net type: o2ib
  local NI(s):
  - nid: 192.168.1.61@o2ib
    status: up
    interfaces:
      0: ib0
- net type: o2ib1
  local NI(s):
  - nid: 192.168.2.61@o2ib1
    status: up
    interfaces:
      0: ib1

```

Chapter 9. Understanding EXAScaler Filesystem Performance

Depending on the type of host channel adapter (HCA), commonly known as a NIC, there are mod parameters that can be tuned for LNet. The NICs that you select should be up and healthy.

To verify the health by mounting and running some basic tests, use `lnetctl health` statistics, and run the following command:

```
$ cat /etc/modprobe.d/lustre.conf
```

Review the output, for example:

```
options libcfs cpu_npartitions=24 cpu_pattern=""
options lnet networks="o2ib0(ib1,ib2,ib3,ib4,ib6,ib7,ib8,ib9)"

options ko2iblnd peer_credits=32 concurrent_sends=64 peer_credits_hiw=16
map_on_demand=0
```

9.1. osc Tuning Performance Parameters

The following is information about tuning filesystem parameters.



Note: To maximize the throughput, you can tune the following EXAScaler® filesystem client parameters, based on the network.

1. Run the following command:

```
$ lctl get_param osc.*.max* osc.*.checksums
```

2. Review the output, for example:

```
$ lctl get_param osc.*.max* osc.*.checksums
osc.ai400-OST0024-osc-ffff916f6533a000.max_pages_per_rpc=4096
osc.ai400-OST0024-osc-ffff916f6533a000.max_dirty_mb=512
osc.ai400-OST0024-osc-ffff916f6533a000.max_rpcs_in_flight=32
osc.ai400-OST0024-osc-ffff916f6533a000.checksums=0
```

To check llite parameters, run `$ lctl get_param llite.*.*`.

9.2. Miscellaneous Commands for osc, mdc, and stripesize

If the tuning parameters are set correctly, you can use these parameters to observe.

1. To get an overall EXAScaler filesystem client side statistics, run the following command:

```
$ lctl get_param osc.*.import
```



Note: The command includes `rpc` information.

2. Review the output, for example:

```
$ watch -d 'lctl get_param osc.*.import | grep -B 1 inflight'
  rpcs:
    inflight: 5
  rpcs:
    inflight: 33
```

3. To get the maximum number of pages that can be transferred per rpc in a EXAScaler filesystem client, run the following command:

```
$ lctl get_param osc.*.max_pages_per_rpc
```

4. To get the overall rpc statistics from a EXAScaler filesystem client, run the following command:

```
$ lctl set_param osc.*.rpc_stats=clear (to reset osc stats)
$ lctl get_param osc.*.rpc_stats
```

5. Review the output, for example:

```
osc.ai200-OST0000-osc-ffff8e0b47c73800.rpc_stats=
snapshot_time:      1589919461.185215594 (secs.nsecs)
read RPCs in flight: 0
write RPCs in flight: 0
pending write pages: 0
pending read pages: 0
```

	read				write			
pages per rpc	rpcs	%	cum %		rpcs	%	cum %	
1:	14222350	77	77		0	0	0	
2:	0	0	77		0	0	0	
4:	0	0	77		0	0	0	
8:	0	0	77		0	0	0	
16:	0	0	77		0	0	0	
32:	0	0	77		0	0	0	
64:	0	0	77		0	0	0	
128:	0	0	77		0	0	0	
256:	4130365	22	100		0	0	0	

	read				write			
rpcs in flight	rpcs	%	cum %		rpcs	%	cum %	
0:	0	0	0		0	0	0	
1:	3236263	17	17		0	0	0	
2:	117001	0	18		0	0	0	
3:	168119	0	19		0	0	0	
4:	153295	0	20		0	0	0	
5:	91598	0	20		0	0	0	
6:	42476	0	20		0	0	0	
7:	17578	0	20		0	0	0	

```

8:          9454  0 20 |          0  0  0
9:          7611  0 20 |          0  0  0
10:         7772  0 20 |          0  0  0
11:         8914  0 21 |          0  0  0
12:         9350  0 21 |          0  0  0
13:         8559  0 21 |          0  0  0
14:         8734  0 21 |          0  0  0
15:        10784  0 21 |          0  0  0
16:        11386  0 21 |          0  0  0
17:        13148  0 21 |          0  0  0
18:        15473  0 21 |          0  0  0
19:        17619  0 21 |          0  0  0
20:        18851  0 21 |          0  0  0
21:        21853  0 21 |          0  0  0
22:        21236  0 21 |          0  0  0
23:        21588  0 22 |          0  0  0
24:        23859  0 22 |          0  0  0
25:        24049  0 22 |          0  0  0
26:        26232  0 22 |          0  0  0
27:        29853  0 22 |          0  0  0
28:        31992  0 22 |          0  0  0
29:        43626  0 22 |          0  0  0
30:       116116  0 23 |          0  0  0
31:    14018326  76 100 |          0  0  0

```

To get statistics that are related to client metadata operations, run the following command:



Note: MetaDataClient (MDC) is the client side counterpart of MetaData Server (MDS).

```
$ lctl get_param mdc.*.md_stats
```

To get the stripe layout of the file on the EXAScaler filesystem, run the following command:

```
$ lfs getstripe /mnt/ai200
```

9.3. Getting the Number of Configured Object-Based Disks

This section describes how you can get the number of configured object-based disks.

1. Run the following command:

```
$ lctl get_param lov.*.target_obd
```

2. Review the output, for example:

```
0: ai200-OST0000_UUID ACTIVE
1: ai200-OST0001_UUID ACTIVE
```

9.4. Getting Additional Statistics related to the EXAScaler Filesystem

You can get additional statistics that are related to the EXAScaler Filesystem.

Refer to the [Lustre Monitoring and Statistics Guide](#) for more information.

9.5. Getting Metadata Statistics

Here is some information about how you can get metadata statistics.

1. Run the following command:

```
$ lctl get_param lmv.*.md_stats
```

2. Review the output, for example:

```
snapshot_time      1571271931.653827773 secs.nsecs
close              8 samples [reqs]
create             1 samples [reqs]
getattr           1 samples [reqs]
intent_lock       81 samples [reqs]
read_page         3 samples [reqs]
revalidate_lock   1 samples [reqs]
```

9.6. Checking for an Existing Mount

This section describes how you can check for an existing mount in the EXAScaler Filesystem.

1. Run the following command:

```
$ mount | grep lustre
```

2. Review the output, for example:

```
192.168.1.61@o2ib,192.168.1.62@o2ib1:/ai200 on /mnt/ai200 type lustre
(rw, flock, lazystatfs)
```

9.7. Unmounting an EXAScaler Filesystem Cluster

This section describes how to unmount an EXAScaler filesystem cluster.

Run the following command.

```
$ sudo umount /mnt/ai200
```

9.8. Getting a Summary of EXAScaler Filesystem Statistics

You can get a summary of statistics for the EXAScaler filesystem.

Refer to the [Lustre Monitoring and Statistics Guide](#) for more information about EXAScaler filesystem statistics.

9.9. Using GPUDirect Storage in Poll Mode

This section describes how to use GDS in Poll Mode with EXAScaler filesystem files that have a Stripe Count greater than 1.

Currently, if poll mode is enabled, `cuFileReads` or `cuFileWrites` might return bytes that are less than the bytes that were requested. This behavior is POSIX compliant and is observed with files that have a stripe count that is greater than the count in their layout. If behavior occurs, we recommend that the application checks for returned bytes and continues until all of the data is consumed. You can also set the corresponding `properties.poll_mode_max_size_kb`, (say 1024 (KB)) value to the lowest possible stripe size in the directory. This ensures that IO sizes that exceed this limit are not polled.

1. To check EXAScaler filesystem file layout, run the following command.

```
$ lfs getstripe <file-path>
```

2. Review the output, for example:

```
lfs getstripe /mnt/ai200/single_stripe/md1.0.0
/mnt/ai200/single_stripe/md1.0.0
lmm_stripe_count: 1
lmm_stripe_size: 1048576
lmm_pattern: raid0
lmm_layout_gen: 0
lmm_stripe_offset: 0
      objidx      objid      objid      group
        0         6146      0x1802         0
```

Chapter 10. Troubleshooting and FAQ for the WekaIO Filesystem

This section provides troubleshooting and FAQ information about the WekaIO file system.

10.1. Downloading the WekaIO Client Package

Here is some information about how to download the WekaIO client package.

Run the following command:

```
$ curl http://<IP of one of the WekaIO hosts' IB interface>:14000/dist/v1/install | sh
```

For example, `$ curl http://172.16.8.1:14000/dist/v1/install | sh`.

10.2. Determining Whether the WekaIO Version is Ready for GDS

This section describes how to determine whether the WekaIO version is ready for GDS. Currently, the only WekaIO FS version that supports GDS is * 3.6.2.5-rdma-beta:

1. Run the following command:

```
$ weka version
```

2. Review the output, for example:

```
* 3.6.2.5-rdma-beta
```

10.3. Mounting a WekaIO File System Cluster

Here is some information about how to mount a WekaIO file system cluster.

The WekaIO filesystem can take a parameter to reserve a fixed number of cores for the user space process.

1. To mount a server_ip 172.16.8.1 with two dedicated cores, run the following command:

```
$ mkdir -p /mnt/weka
$ sudo mount -t wekafs -o num_cores=2 -o
net=ib0,net=ib1,net=ib2,net=ib3,net=ib4,net=ib5,net=ib6,net=ib7
172.16.8.1/fs01 /mnt/weka
```

2. Review the output, for example:

```
Mounting 172.16.8.1/fs01 on /mnt/weka
Creating weka container
Starting container
Waiting for container to join cluster
Container "client" is ready (pid = 47740)
Calling the mount command
Mount completed successfully
```

10.4. Resolving a Failing Mount

This section describes how you can resolve a failing mount.

1. Before you use the IB interfaces in the mount options, verify that the interfaces are set up for net=<interface>:

```
$ sudo mount -t wekafs -o num_cores=2 -o
net=ib0,net=ib1,net=ib2,net=ib3,net=ib4,net=ib5,net=ib6,net=ib7
172.16.8.1/fs01 /mnt/weka
```

2. Review the output, for example:

```
Mounting 172.16.8.1/fs01 on /mnt/weka
Creating weka container
Starting container
Waiting for container to join cluster
error: Container "client" has run into an error: Resources
assignment failed: IB/MLNX network devices should have
pre-configured IPs and ib4 has none
```

3. Remove interfaces that do not have network connectivity from the mount options.

```
$ ibdev2netdev

mlx5_0 port 1 ==> ib0 (Up)
mlx5_1 port 1 ==> ib1 (Up)
mlx5_2 port 1 ==> ib2 (Up)
mlx5_3 port 1 ==> ib3 (Up)
mlx5_4 port 1 ==> ib4 (Down)
mlx5_5 port 1 ==> ib5 (Down)
mlx5_6 port 1 ==> ib6 (Up)
mlx5_7 port 1 ==> ib7 (Up)
mlx5_8 port 1 ==> ib8 (Up)
mlx5_9 port 1 ==> ib9 (Up)
```

10.5. Resolving 100% Usage for WekaIO for Two Cores

If you have two cores, and you are experiencing 100% CPU usage, here is some information about how to resolve this situation.

1. Run the following command.

```
$ top
```

2. Review the output, for example:

PID	USER	PR	NI	VIRT	RES	SHR	S	%CPU	%MEM	TIME+	COMMAND
54816	root	20	0	11.639g	1.452g	392440	R	94.4	0.1	781:06.06	wekanode
54825	root	20	0	11.639g	1.452g	392440	R	94.4	0.1	782:00.32	wekanode

When the `num_cores=2` parameter is specified, two cores are used for the user mode poll driver for WekaIO FE networking. This process improves the latency and performance. Refer to the [WekaIO documentation](#) for more information.

10.6. Checking for an Existing Mount in the Weka File System

This section describes how to check for an existing mount in the WekaIO file system.

1. Run the following command:

```
$ mount | grep wekafs
```

2. Review the output, for example:

```
172.16.8.1/fs01 on /mnt/weka type wekafs (
rw,relatime,writocache,inode_bits=auto,dentry_max_age_positive=1000,
dentry_max_age_negative=0)
```

10.7. Checking for a Summary of the WekaIO Filesystem Status

Here is some information about how you can check for a summary of the WekaIO file system status.

1. Run the following command:

```
$ weka status
```

2. Review the output, for example:

```
WekaIO v3.6.2.5-rdma-beta (CLI build 3.6.2.5-rdma-beta)
  cluster: Nvidia (e4a4e227-41d0-47e5-aa70-b50688b31f40)
  status: OK (12 backends UP, 72 drives UP)
  protection: 8+2
  hot spare: 2 failure domains (62.84 TiB)
  drive storage: 62.84 TiB total, 819.19 MiB unprovisioned
  cloud: connected
  license: Unlicensed

  io status: STARTED 1 day ago (1584 buckets UP, 228 io-nodes UP)
  link layer: InfiniBand
  clients: 1 connected
  reads: 61.54 GiB/s (63019 IO/s)
  writes: 0 B/s (0 IO/s)
  operations: 63019 ops/s
  alerts: 3 active alerts, use `Wekaalerts` to list them
```

10.8. Displaying the Summary of the WekaIO Filesystem Statistics

You can display a summary of the status of the WekaIO filesystem.

1. Run the following command.

```
$ cat /proc/wekafs/stat
```

2. Review the output, for example:

IO type:	UM Average	UM Longest	KM Average	KM Longest
IO count				
total:	812 us	563448 us	9398 ns	10125660 ns
718319292 (63260 IOPS, 0 MB/sec)				
lookup:	117 us	3105 us	6485 ns	436709 ns
4079 (12041)				
readdir:	0 us	0 us	0 ns	0 ns
0				
mknod:	231 us	453 us	3970 ns	6337 ns
96				
open:	0 us	0 us	0 ns	0 ns
0 (3232)				
release:	0 us	0 us	0 ns	0 ns
0 (2720)				
read:	0 us	0 us	0 ns	0 ns
0				
write:	18957 us	563448 us	495291 ns	920127 ns
983137 (983041)				
getattr:	10 us	10 us	6771 ns	6771 ns
1 (9271)				
setattr:	245 us	424 us	4991 ns	48222 ns
96				
rmdir:	0 us	0 us	0 ns	0 ns
0				
unlink:	0 us	0 us	0 ns	0 ns
0				
rename:	0 us	0 us	0 ns	0 ns
0				
symlink:	0 us	0 us	0 ns	0 ns
0				
readlink:	0 us	0 us	0 ns	0 ns
0				
hardlink:	0 us	0 us	0 ns	0 ns
0				
statfs:	4664 us	5072 us	38947 ns	59618 ns
7				
SG_release:	0 us	0 us	0 ns	0 ns
0				
SG_allocate:	1042 us	7118 us	2161 ns	110282 ns
983072				
falloc:	349 us	472 us	4184 ns	10239 ns
96				
atomic_open:	0 us	0 us	0 ns	0 ns
0				
flock:	0 us	0 us	0 ns	0 ns
0				
backcomm:	0 us	0 us	0 ns	0 ns
0				
getroot:	19701 us	19701 us	57853 ns	57853 ns
1				

trace:	0	0 us	0 us	0 ns	0 ns
jumbo alloc:	0	0 us	0 us	0 ns	0 ns
jumbo release:	0	0 us	0 us	0 ns	0 ns
jumbo write:	0	0 us	0 us	0 ns	0 ns
jumbo read:	0	0 us	0 us	0 ns	0 ns
keepalive:	184255	46 us	1639968 us	1462 ns	38996 ns
ioctl:	717328710	787 us	50631 us	8732 ns	10125660 ns
setxattr:	0	0 us	0 us	0 ns	0 ns
getxattr:	0	0 us	0 us	0 ns	0 ns
listxattr:	0	0 us	0 us	0 ns	0 ns
removexattr:	0	0 us	0 us	0 ns	0 ns
setfileaccess:	3072	130 us	3437 us	6440 ns	71036 ns
unmount:	0	0 us	0 us	0 ns	0 ns

10.9. Understanding Why WekaIO Writes Go Through POSIX

Here is some information to help you understand why, for GDS, WekaIO writes are going through POSIX.

For the WekaIO filesystem, GDS supports RDMA based reads and writes. You can use the `fs:weka:rdma_write_support` JSON property to enable writes on supported Weka filesystems. This option is disabled by default. If this option is set to false, writes will be internally staged through system memory, and the cuFile library will use `pwrite` POSIX calls internally for writes.

10.10. Checking for `nvidia-fs.ko` Support for Memory Peer Direct

Here is some information about how you can check for `nvidia-fs.ko` support for memory peer direct.

1. Run the following command:

```
$ lsmod | grep nvidia_fs | grep ib_core && echo "Ready for Memory Peer Direct"
```

2. Review the output, for example:

```
ib_core 319488 16
rdma_cm,ib_ipoib,mlx4_ib,ib_srp,iw_cm,nvidia_fs,ib_iser,ib_umad,
rdma_ucm,ib_uverbs,mlx5_ib,ib_cm,ib_ucm
"Ready for Memory Peer Direct"
```

10.11. Checking Memory Peer Direct Stats

Here is some information about how to check memory peer statistics.

1. Run the following script, which shows the counter for memroy peer direct statistics:

```
list=`ls /sys/kernel/mm/memory_peers/nvidia-fs/`. for stat in $list .
do echo "$stat value: " $(cat /sys/kernel/mm/memory_peers/nvidia-fs/$stat). done
```

2. Review the output.

```
num_alloc_mrs value: 1288
num_dealloc_mrs value: 1288
num_dereg_bytes value: 1350565888
num_dereg_pages value: 329728
num_free_callbacks value: 0
num_reg_bytes value: 1350565888
num_reg_pages value: 329728
version value: 1.0
```

10.12. Checking for Relevant nvidia-fs Statistics for the WekaIO Filesystem

This section describes how you can check for relevant `nvidia-fs` statistics for the WekaIO file system.



Note: Reads, Writes, Ops, and Error counters are not available through this interface for the WekaIO filesystem, so the value will be zero. See [Displaying the Summary of the WekaIO Filesystem Statistics](#) about using the Weka status for reads and writes.

1. Run the following command:

```
$ cat /proc/driver/nvidia-fs/stats | egrep -v 'Reads|Writes|Ops|Error'
```

2. Review the output, for example:

```
GDS Version: 1.0.0.80
NVFS statistics(ver: 4.0)
NVFS Driver(version: 2.7.49)

Active Shadow-Buffer (MB): 256
Active Process: 1
Mmap          : n=2088 ok=2088 err=0 munmap=1832
Bar1-map      : n=2088 ok=2088 err=0 free=1826 callbacks=6 active=256
GPU 0000:34:00.0  uuid:12a86a5e-3002-108f-ee49-4b51266cdc07 : Registered_MB=32
  Cache_MB=0 max_pinned_MB=1977
GPU 0000:e5:00.0  uuid:4c2c6b1c-27ac-8bed-8e88-9e59a5e348b5 : Registered_MB=32
  Cache_MB=0 max_pinned_MB=32
GPU 0000:b7:00.0  uuid:b224ba5e-96d2-f793-3dfd-9caf6d4c31d8 : Registered_MB=32
  Cache_MB=0 max_pinned_MB=32
GPU 0000:39:00.0  uuid:e8fac7f5-d85d-7353-8d76-330628508052 : Registered_MB=32
  Cache_MB=0 max_pinned_MB=32
GPU 0000:5c:00.0  uuid:2b13ed25-f0ab-aedb-1f5c-326745b85176 : Registered_MB=32
  Cache_MB=0 max_pinned_MB=32
GPU 0000:e0:00.0  uuid:df46743a-9b22-30ce-6ea0-62562efaf0a2 : Registered_MB=32
  Cache_MB=0 max_pinned_MB=32
GPU 0000:bc:00.0  uuid:c4136168-2a1d-1f3f-534c-7dd725fedbff : Registered_MB=32
  Cache_MB=0 max_pinned_MB=32
```

```
GPU 0000:57:00.0  uuid:54e472f2-e4ee-18dc-f2a1-3595fa8f3d33 : Registered_MB=32
Cache_MB=0 max_pinned_MB=32
```

10.13. Conducting a Basic WekaIO Filesystem Test

This section describes how to conduct a basic WekaIO file system test.

1. Run the following command:

```
$ /usr/local/cuda-x.y/tools/gdsio_verify -f /mnt/weka/gdstest/tests/reg1G
-n 1 -m 0 -s 1024 -o 0 -d 0 -t 0 -S -g 4K
```

2. Review the output, for example:

```
gpu index :0, file :/mnt/weka/gdstest/tests/reg1G, RING buffer size :0,
gpu buffer alignment :4096, gpu buffer offset :0, file offset :0,
io requested :1024, bufregister :false, sync :0, nr ios :1, fsync :0,
address = 0x564ffc5e76c0
Data Verification Success
```

10.14. Unmounting a WekaIO File System Cluster

This section describes how to unmount a WekaIO file system cluster.

1. Run the following command.

```
$ sudo umount /mnt/weka
```

2. Review the output, for example:

```
Unmounting /mnt/weka
Calling the umount command
umount successful, stopping and deleting client container
Umount completed successfully
```

10.15. Verify the Installed Libraries for the WekaIO Filesystem

Here is some information about verifying the installed libraries for the WekaIO filesystems.

Table 3. Verifying the Installed Libraries for WekaIO Filesystems

Task	Output
Check the WekaIO version.	<pre>\$ weka status WekaIO v3.6.2.5-rdma-beta (CLI build 3.6.2.5-rdma-beta)</pre>
Check whether GDS support for WekaFS is present.	<pre>\$ gdscheck -p [...] WekaFS: Supported</pre>

Task	Output
	Userspace RDMA: Supported [...]
Check for MLNX_OFED information.	Check for <code>ofed_info -s</code> Currently supported with: MLNX_OFED_LINUX-5.1-0.6.6.0 <code>\$ ofed_info -s</code> MLNX_OFED_LINUX-5.1-0.6.6.0:
Check for the <code>nvidia-fs.ko</code> driver.	<code>\$ lsmod grep nvidia_fs grep ib_core</code> && echo "Ready for Memory Peer Direct"
Check for <code>libibverbs.so</code>	<code>\$ dpkg -s libibverbs-dev</code> Package: libibverbs-dev Status: install ok installed Priority: optional Section: libdevel Installed-Size: 1151 Maintainer: Linux RDMA Mailing List <linux-rdma@vger.kernel.org> Architecture: amd64 Multi-Arch: same Source: rdma-core Version: 47mlnx1-1.47329

10.16. GDS Configuration File Changes to Support the WekaIO Filesystem

Here is some information about the GDS configuration file changes that are required to support the WekaIO filesystem.

1. By default, the configuration for Weka RDMA-based writes is disabled.

```
"fs": {
  "weka": {
    // enable/disable WekaFs rdma write
    "rdma_write_support" : false
  }
}
```

2. Change the configuration to add a new property, `rdma_dev_addr_list`.

```
"properties": {
  // allow compat mode,
  // this will enable use of cufile posix read/writes
  //"allow_compat_mode": true,

  "rdma_dev_addr_list": [
    "172.16.8.88" , "172.16.8.89",
    "172.16.8.90" , "172.16.8.91",
    "172.16.8.92" , "172.16.8.93",
    "172.16.8.94", "172.16.8.95"
  ]
}
```

10.17. Check for Relevant User-Space Statistics for the WekaIO Filesystem

This section describes how you can check for relevant user-space statistics for the WekaIO filesystem.

Issue the following command:

```
$ ./gds_stats -p <pid> -l 3 | grep GPU
```

Refer to [GDS User-Space RDMA Counters](#) for more information about statistics.

10.18. Check for WekaFS Support

Here is some information about how to check for WekaFS support.

If WekaFS support does not exist, the following issues are possible:

Table 4. Weka Filesystem Support Issues

Issue	Action
MLNX_OFED peer direct is not enabled.	<p>Check whether MLNX_OFED is installed (<code>ofed_info -s</code>).</p> <p>This issue can occur if the <code>nvidia-fs</code> Debian package was installed before MLNX_OFED was installed. When this issue occurs, uninstall and reinstall the <code>nvidia-fs</code> package.</p>
RDMA devices are not populated in the <code>/etc/cufile.json</code> file.	Add IP addresses to <code>properties.rdma_dev_addr_list</code> . Currently only IPv4 addresses are supported.
None of the configured RDMA devices are UP.	Check IB connectivity for the interfaces.

Chapter 11. Enabling IBM Spectrum Scale Support with GDS

GDS is supported as a technology preview in IBM Spectrum Scale 5.1.1.

After reviewing the NVIDIA GDS documentation, refer to the following link to enable GDS for IBM Spectrum Scale: www.ibm.com/support/pages/node/6444075

11.1. IBM Spectrum Scale Limitations with GDS

Refer to the following documentation for IBM Spectrum Scale Limitations with GDS:

<http://www.ibm.com/support/pages/node/6444075>

11.2. Checking nvidia-fs.ko Support for Mellanox PeerDirect

Use the following command to check support for memory peer direct.

```
$ cat /proc/driver/nvidia-fs/stats | grep -i "Mellanox PeerDirect Supported"
Mellanox PeerDirect Supported: True
```

In the above example, **False** means that MLNX_OFED was not installed with GPUDirect Storage support prior to installing nvidia-fs.

11.3. Verifying Installed Libraries for IBM Spectrum Scale

The following tasks, shown with sample output, can be performed to verify installed libraries for IBM Spectrum Scale:

- Check whether GDS support for IBM Spectrum Scale is present:

```
$ /usr/local/cuda-<x>.<y>/gdscheck.py -p
NVMe : Supported
```

```

NVMeOF           : Supported
SCSI             : Unsupported
ScaleFlux CSD   : Unsupported
NVMesh          : Unsupported
DDN EXAScaler   : Unsupported
IBM Spectrum Scale : Unsupported
NFS             : Unsupported
WekaFS          : Supported
UserSpace RDMA  : Supported
--Mellanox PeerDirect : Enabled
--rdma library   : Loaded (libcufile_rdma.so)
--rdma devices   : Configured
--rdma_device_status : Up: 1 Down: 0

```

- Check for MLNX_OFED information:

```

$ ofed_info -s
MLNX_OFED_LINUX-5.2.1.0.4.0

```

- Check for nvidia-fs.ko driver:

```

$ cat /proc/driver/nvidia-fs/stats
GDS Version: 1.0.0.43
NVFS statistics(ver: 4.0)
NVFS Driver(version: 2:7:46)
Mellanox PeerDirect Supported: True
IO stats: Disabled, peer IO stats: Disabled
Logging level: info

Active Shadow-Buffer (MiB): 0
Active Process: 0
Reads                    : err=0 io_state_err=0
Sparse Reads             : n=0 io=0 holes=0 pages=0
Writes                   : err=0 io_state_err=0 pg-cache=0 pg-cache-fail=0
  pg-cache-eio=0
Mmap                     : n=638 ok=638 err=0 munmap=638
Bar1-map                 : n=638 ok=638 err=0 free=638 callbacks=0
  active=0
Error                    : cpu-gpu-pages=0 sg-ext=0 dma-map=0 dma-ref=0
Ops                      : Read=0 Write=0
GPU 0000:43:00.0  uuid:3848a5e7-41d8-7965-3c44-beebfbf0ff7d : Registered_MiB=0
  Cache_MiB=0 max_pinned_MiB=138

```

- Check for libibverbs.so:

```

$ dpkg -s libibverbs-dev
Package: libibverbs-dev
Status: install ok installed
Priority: optional
Section: libdevel
Installed-Size: 1194
Maintainer: Linux RDMA Mailing List <linux-rdma@vger.kernel.org>
Architecture: amd64
Multi-Arch: same
Source: rdma-core
Version: 52mlnx1-1.52104

$ rpm -qi libibverbs
Name       : libibverbs
Version    : 52mlnx1
Release    : 1.53101
Architecture: x86_64
Install Date: Mon Apr 19 13:08:24 2021
Group      : System Environment/Libraries
Size       : 502145
License    : GPLv2 or BSD
Signature  : DSA/SHA1, Thu Apr  8 02:03:04 2021, Key ID c5ed83e26224c050
Source RPM : rdma-core-52mlnx1-1.53101.src.rpm
Build Date : Thu Apr  8 00:44:38 2021

```

```

Build Host   : c-135-161-1-004.mtl.labs.mlnx
Relocations : (not relocatable)
URL          : https://github.com/linux-rdma/rdma-core
Summary      : A library and drivers for direct userspace use of RDMA (InfiniBand/iWARP/RoCE) hardware
Description  :
libibverbs is a library that allows userspace processes to use RDMA
"verbs" as described in the InfiniBand Architecture Specification and
the RDMA Protocol Verbs Specification. This includes direct hardware
access from userspace to InfiniBand/iWARP adapters (kernel bypass) for
fast path operations.

Device-specific plug-in ibverbs userspace drivers are included:

- libmlx5: Mellanox ConnectX-4+ InfiniBand HCA

```

11.4. Checking PeerDirect Stats

You can check memory peer statistics by running the following script:

```
list=`ls /sys/kernel/mm/memory_peers/nvidia-fs/`; for stat in $list;do echo "$stat
value: " $(cat /sys/kernel/mm/memory_peers/nvidia-fs/$stat); done
```

Sample output:

```

num_alloc_mrs value: 1288
num_dealloc_mrs value: 1288
num_dereg_bytes value: 1350565888
num_dereg_pages value: 329728
num_free_callbacks value: 0
num_reg_bytes value: 1350565888
num_reg_pages value: 32972
version value: 1.0

```

11.5. Checking for Relevant nvidia-fs Stats with IBM Spectrum Scale

Use the following steps to check for relevant `nvidia-fs` statistics for the IBM Spectrum Scale file system.

1. Enable `nvidia-fs` statistics:

```
# echo 1 > /sys/module/nvidia_fs/parameters/rw_stats_enabled
```

2. `$ cat /proc/driver/nvidia-fs/stats`

3. Review the output:

```

root@e155j-hp325-c7-u41:/home/rladmin# cat /proc/driver/nvidia-fs/stats
GDS Version: 1.0.0.43
NVFS statistics(ver: 4.0)
NVFS Driver(version: 2:7:46)
Mellanox PeerDirect Supported: True
IO stats: Enabled, peer IO stats: Enabled
Logging level: info

Active Shadow-Buffer (MiB): 0
Active Process: 1
Reads                               : n=1469960 ok=1469960 err=0 readMiB=5742
  io_state_err=0
Reads                               : Bandwidth(MiB/s)=58 Avg-Latency(usec)=122
Sparse Reads                         : n=0 io=0 holes=0 pages=0

```

```

Writes                               : n=0 ok=0 err=0 writeMiB=0 io_state_err=0 pg-
cache=0 pg-cache-fail=0 pg-cache-eio=0
Writes                               : Bandwidth(MiB/s)=0 Avg-Latency(usec)=0
Mmap                                 : n=31 ok=31 err=0 munmap=29
Bar1-map                             : n=31 ok=31 err=0 free=23 callbacks=6 active=2
Error                                : cpu-gpu-pages=0 sg-ext=0 dma-map=0 dma-ref=0
Ops                                  : Read=0 Write=0
GPU 0000:43:00.0  uuid:5d9a801d-8312-b4ca-d9d3-b47c6bd34a9f : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=1 cross_root_port(%)=0

```

11.6. GDS User Space Stats for IBM Spectrum Scale for Each Process

To check GDS user space level stats, make sure the “cufile_stats” property in cufile.json is set to 3. Run the following command to check the user space stats for a specific process:

```

$ /usr/local/cuda-<x>.<y>/gds/tools/gds_stats -p <pid> -l 3
cuFile STATS VERSION : 4
GLOBAL STATS:
Total Files: 1
Total Read Errors : 0
Total Read Size (MiB): 7302
Read BandWidth (GiB/s): 0.691406
Avg Read Latency (us): 6486
Total Write Errors : 0
Total Write Size (MiB): 0
Write BandWidth (GiB/s): 0
Avg Write Latency (us): 0
READ-WRITE SIZE HISTOGRAM :
0-4(KiB): 0 0
4-8(KiB): 0 0
8-16(KiB): 0 0
16-32(KiB): 0 0
32-64(KiB): 0 0
64-128(KiB): 0 0
128-256(KiB): 0 0
256-512(KiB): 0 0
512-1024(KiB): 0 0
1024-2048(KiB): 0 0
2048-4096(KiB): 3651 0
4096-8192(KiB): 0 0
8192-16384(KiB): 0 0
16384-32768(KiB): 0 0
32768-65536(KiB): 0 0
65536-...(KiB): 0 0
PER_GPU STATS:
GPU_0 Read: bw=0.690716 util(%)=199 n=3651 posix=0 unalign=0 dr=0 r_sparse=0
r_inline=0 err=0 MiB=7302 Write: bw=0 util(%)=0 n=0 posix=0 unalign=0 dr=0 err=0
MiB=0 BufRegister: n=2 err=0 free=0 MiB=4
PER_GPU POOL BUFFER STATS:
PER_GPU POSIX POOL BUFFER STATS:

PER_GPU RDMA STATS:
GPU 0000:43:00.0 : mlx5_0(130:64):Reads: 3594 Writes: 0 mlx5_1(130:64):Reads:
3708 Writes: 0
RDMA MRSTATS:
peer name nr_mrs mr_size(MiB)
mlx5_0 1 2
mlx5_1 1 2

```

In the example above, 3954 MiB of IBM Spectrum Scale Read went through `m1x5_0` and 3708 MiB of IBM Spectrum Scale Read went through `m1x5_1`. The `RDMA_MRSTATS` value shows the number of RDMA memory registrations and size of those registrations.

11.7. GDS Configuration to Support IBM Spectrum Scale

1. Configure the DC key.

The DC key for the IBM Spectrum Scale client can be configured in the following ways:

- ▶ Set the environment variable `CUFILE_RDMA_DC_KEY`. This should be set to a 32-bit hex value. This can be set as shown in the following example.

```
export CUFILE_RDMA_DC_KEY = 0x11223344
```

- ▶ Set the property `rdma_dc_key` in `cufile.json`. This property is a 32-bit value and it can be set as shown in the following example.

```
"rdma_dc_key": "0xffeeddcc",
```

In case both the environment variable and the `cufile.json` have the property set, the environment variable `CUFILE_RDMA_DC_KEY` will take precedence over the `rdma_dc_key` property set in `cufile.json`.

In case none of the above is set, the default DC Key configured would be `0xffeeddcc`.

2. Configure the IP addresses in `cufile.json`.

The `>rdma_dev_addr_list` property should be set in `cufile.json` with the IP address of the RDMA devices to be used for IO.

```
"properties": {
  -----
  "rdma_dev_addr_list": [
    "172.16.8.88" , "172.16.8.89",
    "172.16.8.90" , "172.16.8.91",
    "172.16.8.92" , "172.16.8.93",
    "172.16.8.94", "172.16.8.95" ]
  }
  -----
}
```

3. Configure the `max_direct_io_size_kb` property in `cufile.json`.

Due to a IBM Spectrum Scale limitation the `max_direct_io_size_kb` property should be set to a value recommended by IBM Spectrum Scale. Please refer to the following documentation for the optimal configuration for this property.

<http://www.ibm.com/support/pages/node/6444075>

```
"properties": {
  -----
  "max_direct_io_size_kb" : 1024
  -----
}
```

4. Configure the `rdma_access_mask` property in `cufile.json`.

This property is a performance tunable. Refer to IBM Spectrum Scale documentation for optimal configuration of this property.

<http://www.ibm.com/support/pages/node/6444075>

```
"properties": {
  -----
  "rdma_access_mask": "0x1f",
  -----
}
```

Here is an explanation of what each bit of this flag denotes:

- ▶ Bit 0 - If set enables Local RDMA WRITE on the Memory Region
- ▶ Bit 1 - If set enables Remote RDMA WRITE on the Memory Region
- ▶ Bit 2 - If set enables Remote RDMA READ on the Memory Region
- ▶ Bit 3 - If set enables REMOTE RDMA Atomics on the Memory Region
- ▶ Bit 4 - If set enables Relaxed ordering on the Memory Region

All the remaining bits are reserved for future use.

11.8. Scenarios for Falling Back to Compat Mode

The following scenarios will cause the IBM Spectrum Scale IOs to go through compat mode, irrespective of the `allow_compat_mode` property's value in `cufile.json`. Refer to <http://www.ibm.com/support/pages/node/6444075> for details.

In the following scenarios, IBM Spectrum Scale IO would go through compat mode if the `allow_compat_mode` property is set to **true** in `cufile.json`.

- ▶ If `nvidia-fs` is not loaded.
- ▶ If IB NICs IP addresses are not set up in `cufile.json`.

11.9. GDS Limitations with IBM Spectrum Scale

GDS has a limit on the maximum number of allowed RDMA memory registration for a GPU buffer. The limit today is 16. Hence, the maximum size of memory that can be registered with RDMA per GPU buffer is $16 * \text{max_direct_to_size_kb}$ (set in `cufile.json`). Any GDS IO with IBM Spectrum Scale beyond this offset will go through bounce buffers and might have a performance impact.

Chapter 12. Setting Up and Troubleshooting VAST Data (NFSoRDMA+MultiPath)

This section provides information about how to set up and troubleshoot VAST data (NFSoRDMA+MultiPath).

12.1. Installing MLNX_OFED and VAST NFSoRDMA+Multipath Packages

This section provides information about system requirements and how to install MLNX_OFED and VAST NFSoRDMA+Multipath packages.

12.1.1. Client Software Requirements

Here is the information for the **minimum** client software requirements.

Table 5. Minimum Client Requirements

NFS Connection Type	Linux Kernel	MLNX_OFED
NFSoRDMA + Multipath	The following kernel versions are supported: <ul style="list-style-type: none">▶ 4.15▶ 4.18▶ 5.4	The following MLNX_OFED versions are supported: <ul style="list-style-type: none">▶ 4.6▶ 4.7▶ 5.0▶ 5.1▶ 5.3

For the most up to date supportability matrix and client configuration steps and package downloads, refer to: <https://support.vastdata.com/hc/en-us/articles/360016813140-NFSoRDMA-with-Multipath>.

MLNX_OFED must be installed for the VAST NFSoRDMA+Multipath package to function optimally. It is also important to download the correct VAST software packages to match your kernel+MLNX_OFED version combination. Refer to [Troubleshooting and FAQ for NVMe and NVMeOF](#) support for information about how to install MLNX_OFED with GDS support.

- ▶ To verify the current version of MLNX_OFED, issue the following command:

```
$ ofed_info -s
MLNX_OFED_LINUX-5.3-0.6.6.01:
```

- ▶ To verify the currently installed Linux kernel version, issue the following command:

```
$ uname -r -v
```

After you verify that your system has the correct combination of kernel and MLNX_OFED, you can install the VAST Multipath package.

12.1.2. Install the VAST Multipath Package

Here is the procedure to install the VAST Multipath package.

Although the VAST Multipath with NFSoRDMA package has been submitted upstream for inclusion in a future kernel release, it is currently only available as a download from: <https://support.vastdata.com/hc/en-us/articles/360016813140-NFSoRDMA-with-Multipath>.

Be sure to download the correct .deb file that is based on your kernel and MLNX_OFED version.

1. Install the VAST NFSoRDMA+Multipath package.

```
$ sudo apt-get install mlnx-nfsrdma-*.deb
```

2. Generate a new initramfs image.

```
$ sudo update-initramfs -u -k `uname -r`
```

3. Verify that the package is installed, and the version is the number that you expected.

```
$ dpkg -l | grep mlnx-nfsrdma
ii  mlnx-nfsrdma-dkms      5.3-OFED.5.1.0.6.6.0      all  DKMS support for NFS RDMA
    kernel module
```

4. Reboot the host and run the following commands to verify that the correct version is loaded.



Note: The versions shown by each command should match.

```
$ cat /sys/module/sunrpc/srcversion
4CC8389C7889F82F5A59269
$ modinfo sunrpc | grep srcversion
srcversion:      4CC8389C7889F82F5A59269
```

12.2. Set Up the Networking

This section provides information about how to set up client networking for VAST for GDS.

To ensure optimal GPU-to-storage performance while leveraging GDS, you need to configure VAST and client networking in a balanced manner.

12.2.1. VAST Network Configuration

Here is some information about the VAST network configuration.

VAST is a multi-node architecture. Each node has multiple high-speed (IB-HDR100 or 100GbE) interfaces, which can host-client-facing Virtual IPs. Refer to [VAST-Managing Virtual IP \(VIP\) Pools](#) for more information.

Here is the typical workflow:

1. Multiply the number of VAST-Nodes * 2 (one per Interface).
2. Create a VIP Pool with the resulting IP count.
3. Place the VAST-VIP Pool on the same IP-subnet as the client.

12.2.2. Client Network Configuration

The following is information about client network configuration.

Typically, GPU optimized clients (such as the NVIDIA DGX-2 and DGX-A100) are configured with multiple high speed network interface cards (NICs). In the following example, the system contains 8 separate NICs that were selected for optimal balance for NIC -->GPU and NIC -->CPU bandwidth.

```
$ sudo ibdev2netdev
mlx5_0 port 1 ==> ibp12s0 (Up)
mlx5_1 port 1 ==> ibp18s0 (Up)
mlx5_10 port 1 ==> ibp225s0f0 (Down)
mlx5_11 port 1 ==> ibp225s0f1 (Down)
mlx5_2 port 1 ==> ibp75s0 (Up)
mlx5_3 port 1 ==> ibp84s0 (Up)
mlx5_4 port 1 ==> ibp97s0f0 (Down)
mlx5_5 port 1 ==> ibp97s0f1 (Down)
mlx5_6 port 1 ==> ibp141s0 (Up)
mlx5_7 port 1 ==> ibp148s0 (Up)
mlx5_8 port 1 ==> ibp186s0 (Up)
mlx5_9 port 1 ==> ibp202s0 (Up)
```

Not all interfaces are connected, and this is to ensure optimal bandwidth.

When using the aforementioned VAST NFSoRDAM+Multipath package, it is recommended to assign static IP's to each interface on the same subnet, which should also match the subnet configured on the VAST VIP Pool. If using GDS with NVIDIA DGX-A100's, a simplistic netplan is all that is required, for example:

```
ibp12s0:
  addresses: [172.16.0.17/24]
  dhcp4: no
ibp141s0:
  addresses: [172.16.0.18/24]
  dhcp4: no
ibp148s0:
  addresses: [172.16.0.19/24]
  dhcp4: no
```

However, if you are using other systems, or non-GDS code, you need to apply the following code to ensure that the proper interfaces are used to traverse from Client-->VAST.



Note: See the `routes` section for each interface in the following sample.

```
$cat /etc/netplan/01-netcfg.yaml
network:
  version: 2
  renderer: networkd
  ethernets:
    enp226s0:
      dhcp4: yes
    ibp12s0:
      addresses: [172.16.0.25/24]
      dhcp6: no
      routes:
        - to: 172.16.0.0/24
          via: 172.16.0.25
          table: 101
      routing-policy:
        - from: 172.16.0.25
          table: 101
    ibp18s0:
      addresses: [172.16.0.26/24]
      dhcp4: no
      routes:
        - to: 172.16.0.0/24
          via: 172.16.0.26
          table: 102
      routing-policy:
        - from: 172.16.0.26
          table: 102
    ibp75s0:
      addresses: [172.16.0.27/24]
      dhcp4: no
      routes:
        - to: 172.16.0.0/24
          via: 172.16.0.27
          table: 103
      routing-policy:
        - from: 172.16.0.27
          table: 103
    ibp84s0:
      addresses: [172.16.0.28/24]
      dhcp4: no
      routes:
        - to: 172.16.0.0/24
          via: 172.16.0.28
          table: 104
      routing-policy:
        - from: 172.16.0.28
          table: 104
    ibp141s0:
      addresses: [172.16.0.29/24]
      dhcp4: no
      routes:
        - to: 172.16.0.0/24
          via: 172.16.0.29
          table: 105
      routing-policy:
        - from: 172.16.0.29
          table: 105
    ibp148s0:
      addresses: [172.16.0.30/24]
      dhcp4: no
      routes:
        - to: 172.16.0.0/24
          via: 172.16.0.30
          table: 106
      routing-policy:
        - from: 172.16.0.30
```

```

        table: 106
ibp186s0:
  addresses: [172.16.0.31/24]
  dhcp4: no
  routes:
    - to: 172.16.0.0/24
      via: 172.16.0.31
      table: 107
  routing-policy:
    - from: 172.16.0.31
      table: 107
ibp202s0:
  addresses: [172.16.0.32/24]
  dhcp4: no
  routes:
    - to: 172.16.0.0/24
      via: 172.16.0.32
      table: 108
  routing-policy:
    - from: 172.16.0.32
      table: 108

```

After making changes to the netplan, before issuing the following command, ensure that you have a IPMI/console connection to the client:

```
$ sudo netplan apply
```

12.2.3. Verify Network Connectivity

Here is some information about how you can verify network connectivity.

Once the proper netplan is applied, verify connectivity between all client interfaces and all VAST-VIPs with a ping loop:

```

# Replace with appropriate interface names
$ export IFACES="ibp12s0 ibp18s0 ibp75s0 ibp84s0 ibp141s0 ibp148s0 ibp186s0 ibp202s0"
# replace with appropriate VAST-VIPs
$ export VIPS=$(echo 172.16.0.{101..116})
$ echo "starting pingtest" > pingtest.log
$ for i in $IFACES;do for v in $VIPs; do echo $i >> pingtest.log; ping -c 1 $v -W 0.2 -I $i |
grep loss >> pingtest.log;done;done;
# Verify no failures:
$ grep '100%' pingtest.log

```

You should also verify that one of the following conditions are met:

- ▶ All client interfaces are directly cabled to the same IB switches as VAST.
- ▶ There are sufficient InterSwitch Links (ISLs) between client-switches, and switches to which VAST is connected.

To verify the current IB switch topology, issue the following command:

```

$ sudo ibnetdiscover
<output trimmed>

[37] "H-b8599f0300c3f4cb"[1] (b8599f0300c3f4cb) # "vastraplab-cn1 HCA-2" lid 55 2xHDR # <--
example of Vast-Node

[43] "S-b8599f0300e361f2"[43] # "MF0;RL-QM87-C20-U33:QM8700/U1" lid 1 4xHDR # <--
example of ISL

```

```
[67] "H-1c34da030073c27e" [1] (1c34da030073c27e) # "r1-dgxa-c21-u19 mlx5_9" lid 23 4xHDR # <--
example of client
```

12.3. Mount VAST NFS

This section describes how to mount VAST NFS.

To fully utilize available VAST VIPs, you must mount the filesystem by issuing the following command:

```
$ sudo mount -o proto=rdma,port=20049,vers=3 \
-o noidleprt,nconnect=40 \
-o localports=172.16.0.25-172.16.0.32 \
-o remoteports=172.16.0.101-172.16.0.140 \
172.16.0.101: /mnt/vast
```

The options are:

proto

RDMA must be specified.

port=20049

Must be specified, this is RDMA control port.

noidleprt

Do not disconnect idle connections. This is to detect and recover failing connections when there are no pending I/O's.

nconnect

Number of concurrent connections. Should be divisible evenly by the number of remoteports specified below for best balance.

localports

A list of IPv4 addresses for the local ports to bind.

Remoteports

A list of NFS server IPv4 ports to bind.

For both **localports** and **remoteports** you can specify an inclusive range with the -delimiter, for example, *FIRST-LAST*. Multiple ranges or individual IP addresses can be separated by ~ (a tilde)

12.4. Debugging and Monitoring

Here is some information about debugging and monitoring.

Typically, `mountstats` under `/proc` shows `xprt` statistics. However, instead of modifying it in a non-compatible way with the `nfsstat` utility, the VAST Multipath package extends `mountstats` with extra state reporting, to be exclusively accessed from `/sys/kernel/debug`.

The `stats` node was added for each RPC client, and the RPC client 0 shows the mount that is completed:

```
$ sudo cat /sys/kernel/debug/sunrpc/rpc_clnt/0/stats
```

The added information is multipath IP address information per `xprt` and `xprt` state in string format.

For example:

```
xprt: rdma 0 0 1 0 24 3 3 0 3 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 11 0 0 0
172.25.1.101 -> 172.25.1.1, state: CONNECTED BOUND
xprt: rdma 0 0 1 0 24 1 1 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 11 0 0 0
172.25.1.102 -> 172.25.1.2, state: CONNECTED BOUND
xprt: rdma 0 0 1 0 23 1 1 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 11 0 0 0
172.25.1.103 -> 172.25.1.3, state: CONNECTED BOUND
xprt: rdma 0 0 1 0 22 1 1 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 11 0 0 0
172.25.1.104 -> 172.25.1.4, state: CONNECTED BOUND
xprt: rdma 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
172.25.1.101 -> 172.25.1.5, state: BOUND
xprt: rdma 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
172.25.1.102 -> 172.25.1.6, state: BOUND
xprt: rdma 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
172.25.1.103 -> 172.25.1.7, state: BOUND
xprt: rdma 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
172.25.1.104 -> 172.25.1.8, state: BOUND
```

Chapter 13. Troubleshooting and FAQ for NVMe and NVMeOF Support

This section provides troubleshooting information for NVME and NVMeOF support.

13.1. MLNX_OFED Requirements and Installation

The following is information about the requirements to install MLNX_OFED.

- ▶ To enable GDS support for NVMe and NVMeOF, you need to install at least MLNX_OFED 5.3 or later.
- ▶ You must install MLNX_OFED with support for GDS.

After installation is complete, for the changes to take effect, update -initramfs and reboot. The Linux kernel version that was tested with MLNX_OFED 5.3-1.0.5.01 is 4.15.0-x and 5.4.0-x. Issue the following command:

```
$ sudo ./mlnxofedinstall --with-nvmf --with-nfsrdma --enable-gds --add-kernel-support
```



Note: With MLNX_OFED 5.3 onwards, the `--enable-gds` flag is no longer necessary.

```
$ sudo update-initramfs -u -k `uname -r`  
$ reboot
```

Here is the output:

```
$ /usr/local/cuda-x.y/gds/tools/gdscheck  
  
GDS release version : 1.0  
nvidia_fs version: 2.7 libcufile version: 2.4  
cuFile CONFIGURATION:  
NVMe      : Supported  
NVMeOF    : Supported
```

13.2. Determining Whether the NVMe device is Supported for GDS

This section describes how to determine whether an NVMe device is supported for GDS.

NVMe devices must be compatible with GDS, the device cannot have the block device integrity capability. For device integrity, the Linux block layer completes the metadata processing based on the payload in the host memory. This is a deviation from the standard GDS IO path and, as a result, cannot accommodate these devices. The cuFile file registration will fail when this type of underlying device is detected with appropriate error log in the `cufile.log` file.

```
$ cat /sys/block/devices/<nvme>/device/integrity_check
```

13.3. Check for the RAID Level

Here is some information about RAID support in GDS.

Currently GDS only supports RAID 0.

13.4. Mounting an EXT4 Filesystem for GDS

This section describes how to mount an EXT4 filesystem for GDS.

Currently EXT4 is the only block device based filesystem that GDS supports. Because of Direct IO semantics, the filesystem must be mounted with the journaling mode set to `data=ordered`. This has to be explicitly part of the mount options so that the library can recognize it:

```
$ sudo mount -o data=ordered /dev/nvme0n1 /mnt
```

If the EXT4 journaling mode is not in the expected mode, the `cuFileHandleRegister` will fail, and an appropriate error message will be logged in the log file. For instance, in the following case, `/mnt1` is mounted with `writeback`, and GDS returns an error:

```
$ mount | grep /mnt1
/dev/nvme0n1p2 on /mnt1 type ext4 (rw,relatime,data=writeback)

$ ./cufile_sample_001 /mnt1/foo 0
opening file /mnt1/foo
file register error:GPUDirect Storage not supported on current file
```

13.5. Check for an Existing Mount

This section describes how to check for an existing mount.

```
$ mount | grep ext4
/dev/sda2 on / type ext4 (rw,relatime,errors=remount-ro,data=ordered)
/dev/nvme1n1 on /mnt type ext4 (rw,relatime,data=ordered)
/dev/nvme0n1p2 on /mnt1 type ext4 (rw,relatime,data=writeback)
```

13.6. Check for IO Statistics with Block Device Mount

The following is a partial log that shows you how to obtain the I/O statistics:

```
$ sudo iotop
Actual DISK READ:      0.00 B/s | Actual DISK WRITE:      193.98 K/s
  TID  PRIO  USER      DISK READ  DISK WRITE  SWAPIN     IO>     COMMAND
  881  be/3  root       0.00 B/s   15.52 K/s   0.00 %    0.01 % [jbd2/sda2-8]
   1  be/4  root       0.00 B/s   0.00 B/s   0.00 %    0.00 % init splash
```

13.7. RAID Group Configuration for GPU Affinity

The following is information about RAID group configuration for GPU affinity.

Creating one RAID group from the available NVMe devices might not be optimal for GDS performance. You might need to create RAID groups that consist of devices that have a pci-affinity with the specified GPU. This is required to prevent and cross-node P2P traffic between the GPU and the NVMe devices.

If affinity is not enforced, GDS will use an internal mechanism of device bounce buffers to copy data from the NVMe devices to an intermediate device that is closest to the drives and copy the data back to the actual GPU. If NVLink is enabled, this will speed up these transfers.

13.8. Conduct a Basic EXT4 Filesystem Test

The following is information about how you can conduct a basic EXT4 filesystem test.

Issue the following command:

```
$ /usr/local/cuda-x.y/gds/tools/gdsio_verify -f /mnt/nvme/gdstest/tests/reg1G -n 1 -m 0 -s 1024 -o 0 -d 0 -t 0 -S -g 4K
```

Here is the output:

```
gpu index :0,file :/mnt/weka/gdstest/tests/reg1G, RING buffer size :0, gpu buffer
alignment :4096, gpu buffer offset :0, file offset :0, io_requested :1024,
bufregister :false, sync :0, nr ios :1,fsync :0,
address = 0x564ffc5e76c0
Data Verification Success
```

13.9. Unmount a EXT4 Filesystem

This section describes how to unmount an EXT4 filesystem.

Issue the following command:


```
$ sudo umount /mnt/
```

13.10. Udev Device Naming for a Block Device

This section describes the Udev device naming for a block device.

The library has a limitation when identifying the NVMe-based block devices in that it expects device names to have the `nvme` prefix as part of the naming convention.

Chapter 14. Displaying GDS NVIDIA FS Driver Statistics

GDS exposes the IO statistics information on the `procfs` filesystem.

1. Run the following command.

```
$ cat /proc/driver/nvidia-fs/stat
```

2. Review the output, for example:

```
GDS Version: 1.0.0.71
NVFS statistics(ver: 4.0)
NVFS Driver(version: 2:7:47)
Mellanox PeerDirect Supported: True
IO stats: Enabled, peer IO stats: Enabled
Logging level: info

Active Shadow-Buffer (MiB): 0
Active Process: 0
Reads                : n=0 ok=0 err=0 readMiB=0 io_state_err=0
Reads                : Bandwidth(MiB/s)=0 Avg-Latency(usec)=0
Sparse Reads : n=6 io=0 holes=0 pages=0
Writes               : n=0 ok=0 err=0 writeMiB=0 io_state_err=0
                   pg-cache=0 pg-cache-fail=0 pg-cache-eio=0
Writes               : Bandwidth(MiB/s)=0 Avg-Latency(usec)=0
Mmap : n=183 ok=183 err=0 munmap=183
Bar1-map             : n=183 ok=183 err=0 free=165 callbacks=18
                   active=0
Error                : cpu-gpu-pages=0 sg-ext=0 dma-map=0 dma-ref=0
Ops : Read=0 Write=0
GPU 0000:be:00.0  uuid:87e5c586-88ed-583b-df45-fcee0f1e7917 : Registered_MiB=0
Cache_MiB=0
                   max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:e7:00.0  uuid:029faa3b-cb0d-2718-259c-6dc650c636eb : Registered_MiB=0
Cache_MiB=0
                   max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:5e:00.0  uuid:39eeb04b-1c52-81cc-d76e-53d03eb6ed32 : Registered_MiB=0
Cache_MiB=0
                   max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:57:00.0  uuid:a99a7a93-7801-5711-258b-c6aca4fe6d85 : Registered_MiB=0
Cache_MiB=0
                   max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:39:00.0  uuid:d22b0bc4-cdb1-65ac-7495-3570e5860fda : Registered_MiB=0
Cache_MiB=0
                   max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:34:00.0  uuid:e11b33d9-60f7-a721-220a-d14e5b15a52c : Registered_MiB=0
Cache_MiB=0
                   max_pinned_MiB=128 cross_root_port(%)=0
GPU 0000:b7:00.0  uuid:e8630cd2-5cb7-cab7-ef2e-66c25507c119 : Registered_MiB=0
Cache_MiB=0
                   max_pinned_MiB=1 cross_root_port(%)=0
```

```
GPU 0000:e5:00.0  uuid:b3d46477-d54f-c23f-dc12-4eb5ea172af6 : Registered_MiB=0
Cache_MiB=0
    max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:e0:00.0  uuid:7a10c7bd-07e0-971b-a19c-61e7c185a82c : Registered_MiB=0
Cache_MiB=0
    max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:bc:00.0  uuid:bb96783c-5a46-233a-cbce-071aeb308083 : Registered_MiB=0
Cache_MiB=0
    max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:e2:00.0  uuid:b6565ee8-2100-7009-bcc6-a3809905620d : Registered_MiB=0
Cache_MiB=0
    max_pinned_MiB=2 cross_root_port(%)=0
GPU 0000:5c:00.0  uuid:5527d7fb-a560-ab42-d027-20aeb5512197 : Registered_MiB=0
Cache_MiB=0
    max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:59:00.0  uuid:bb734f6b-24ad-2f83-86c3-6ab179bce131 : Registered_MiB=0
Cache_MiB=0
    max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:3b:00.0  uuid:0ef0b9ee-bb8f-cdae-4535-c0d790b2c663 : Registered_MiB=0
Cache_MiB=0
    max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:b9:00.0  uuid:ad59f685-5836-c2ea-2c79-3c95bea23f0d : Registered_MiB=0
Cache_MiB=0
    max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:36:00.0  uuid:fda65234-707b-960a-d577-18c519301848 : Registered_MiB=0
Cache_MiB=0
    max_pinned_MiB=1 cross_root_port(%)=0
```

14.1. Understanding nvidia-fs Statistics

This section describes nvidia-fs statistics.

Table 6. NVIDIA-FS Statistics

Type	Statistics	Description
Reads	n	Total number of read requests.
	ok	Total number of successful read requests.
	err	Total number of read errors.
	Readmb (mb)	Total data read into the GPUs.
	io_state_err	Read errors that were seen. Some pages might have been in the page cache.
Reads	Bandwidth (MB/s)	Active Read Bandwidth when IO is in flight. This is the period from when IO was submitted to the GDS kernel driver until the IO completion was received by the GDS kernel driver.

Type	Statistics	Description
		There was no userspace involved.
	Avg-Latency (usec)	Active Read latency when IO is in flight. This is from the period from when IO was submitted to the GDS kernel driver until the IO completion is received by the GDS kernel driver. There was no userspace involved.
Sparse Reads	n	Total number of sparse read requests.
	holes	Total number of holes that were observed during reads.
	pages	Total number of pages that span the holes.
Writes	n	Total number of write requests.
	ok	Total number of successful write requests.
	err	Total number of write errors.
	Writemb (mb)	Total data that was written from the GPUs to the disk.
	io_state_err	Write errors that were seen. Some pages might have been in the page cache.
	pg-cache	Total number of write requests that were found in the page cache.
	pg-cache-fail	Total number of write requests that were found in the page cache but could not be flushed.
	pg-cache-eio	Total number of write requests that were found in the page-cache, but could not be flushed after multiple retries, and IO failed with EIO.

Type	Statistics	Description
Writes	Bandwidth (MB/s)	Active Write Bandwidth when IO is in flight. This is the period from when IO is submitted to the GDS kernel driver until the IO completion is received by the GDS kernel driver. There was no userspace involved.
	Avg-Latency (usec)	Active Write latency when IO is in flight. This is the period from when IO is submitted to the GDS kernel driver until the IO completion is received by the GDS kernel driver. There was no userspace involved.
Mmap	n	Total number of mmap system calls that were issued.
	ok	Total number of successful mmap system calls.
	err	Errors that were observed through the mmap system call.
	munmap	Total number of munmap that were issued.
Bar-map	n	Total number of times the GPU BAR memory was pinned.
	ok	Total number of times the successful GPU BAR memory was pinned.
	err	Total errors that were observed during the BAR1 pinning.
	free	Total number of times the BAR1 memory was unpinned.
	callbacks	Total number of times the NVIDIA kernel driver invoked callback to the GDS driver.

Type	Statistics	Description
		<p>This is invoked on the following instances:</p> <ul style="list-style-type: none"> ▶ When the process crashes or was abruptly killed. ▶ When <code>cudaFree</code> is invoked on memory, which is pinned through <code>cuFileBufRegister</code>, but <code>cuFileBufDeregister</code> is not invoked.
	<code>active</code>	<p>Active number of BAR1 memory that was pinned.</p> <p>(This value is the total number and not the total memory.)</p>
Error	<code>cpu-gpu-pages</code>	<p>Number of IO requests that had a mix of CPU-GPU pages when <code>nvfs_dma_map_sg_attrs</code> is invoked.</p>
	<code>sg-ext</code>	<p>Scatterlist that could not be expanded because the number of GPU pages is greater than <code>blk_nq_nr_phys_segments</code>.</p>
	<code>dma-map</code>	<p>A DMA map error.</p>
ops	Read	<p>Total number of Active Read IO in flight.</p>
	Write	<p>Total number of Active Write iO in flight.</p>

14.2. Analyze Statistics for each GPU

You can analyze the statistics for each GPU to better understand what is happening in that GPU.

Consider the following example output:

```
GPU 0000:5e:00:0  uid:dc87fe99-4d68-247b-b5d2-63f96d2adab1 : pinned_MB=0 cache_MB=0
max_pinned_MB=79
GPU 0000:b7:00:0  uid:b3a6a195-d08c-09d1-bf8f-a5423c277c04 : pinned_MB=0 cache_MB=0
max_pinned_MB=76
GPU 0000:e7:00:0  uid:7c432aed-a612-5b18-76e7-402bb48f21db : pinned_MB=0 cache_MB=0
max_pinned_MB=80
```

```
GPU 0000:57:00:0  uuid:aa871613-ee53-9a0c-a546-851d1afe4140 : pinned_MB=0 cache_MB=0
max_pinned_MB=80
```

In this sample output, `0000:5e:00:0`, is the PCI BDF of the GPU with the `Dc87fe99-4d68-247b-b5d2-63f96d2adab1` UUID. This is the same UUID that can be used to observe `nvidia-smi` statistics for this GPU.

Here is some additional information about the statistics:

- ▶ `pinned_MB` shows the active GPU memory that is pinned by using `nvidia_p2p_get_pages` from the GDS driver in MB across all active processes.
- ▶ `cache_MB` shows the active GPU memory that is pinned by using `nvidia_p2p_get_pages`, but this memory is used as the internal cache by GDS across all active processes.
- ▶ `max_pinned_MB` shows the max GPU memory that is pinned by GDS at any point in time on this GPU across multiple processes.

This value indicates that the max BAR size and administrator can be used for system sizing purposes.

14.3. Resetting the `nvidia-fs` Statistics

You can reset the `nvidia-fs` statistics.

Run the following command:

```
$ sudo bash
$ echo 1 >/proc/driver/nvidia-fs/stats
```

14.4. Checking Peer Affinity Stats for a Kernel Filesystem and Storage Drivers

This section describes how to review `nvidia-fs` PCI peer affinity statistics for a kernel file system and storage drivers.

The following `proc` files contain information about peer affinity DMA statistics via `nvidia-fs` callbacks:

- ▶ `nvidia-fs/stats`
- ▶ `nvidia-fs/peer_affinity`
- ▶ `nvidia-fs/peer_distance`

To enable the statistics, run the following command:

```
$ sudo bash
$ echo 1 > /sys/module/nvidia_fs/parameters/peer_stats_enabled
```

To view consolidated statistics as a regular user, run the following command:

```
$ cat /proc/driver/nvidia-fs/stats
```

Here is the sample output:

```

GDS Version: 1.0.0.71
NVFS statistics(ver: 4.0)
NVFS Driver(version: 2:7:47)
Mellanox PeerDirect Supported: True
IO stats: Enabled, peer IO stats: Enabled
Logging level: info

Active Shadow-Buffer (MiB): 0
Active Process: 0
Reads                                     : n=0 ok=0 err=0 readMiB=0 io_state_err=0
Reads                                     : Bandwidth(MiB/s)=0 Avg-Latency(usec)=0
Sparse Reads                             : n=6 io=0 holes=0 pages=0
Writes                                    : n=0 ok=0 err=0 writeMiB=0 io_state_err=0 pg-
cache=0 pg-cache-fail=0 pg-cache-eio=0
Writes                                    : Bandwidth(MiB/s)=0 Avg-Latency(usec)=0
Mmap                                       : n=183 ok=183 err=0 munmap=183
Barl-map                                  : n=183 ok=183 err=0 free=165 callbacks=18 active=0
Error                                     : cpu-gpu-pages=0 sg-ext=0 dma-map=0 dma-ref=0
Ops                                       : Read=0 Write=0
GPU 0000:be:00.0   uuid:87e5c586-88ed-583b-df45-fcee0f1e7917 : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:e7:00.0   uuid:029faa3b-cb0d-2718-259c-6dc650c636eb : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:5e:00.0   uuid:39eeb04b-1c52-81cc-d76e-53d03eb6ed32 : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:57:00.0   uuid:a99a7a93-7801-5711-258b-c6aca4fe6d85 : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:39:00.0   uuid:d22b0bc4-cdb1-65ac-7495-3570e5860fda : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:34:00.0   uuid:e11b33d9-60f7-a721-220a-d14e5b15a52c : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=128 cross_root_port(%)=0
GPU 0000:b7:00.0   uuid:e8630cd2-5cb7-cab7-ef2e-66c25507c119 : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:e5:00.0   uuid:b3d46477-d54f-c23f-dc12-4eb5ea172af6 : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:e0:00.0   uuid:7a10c7bd-07e0-971b-a19c-61e7c185a82c : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:bc:00.0   uuid:bb96783c-5a46-233a-cbce-071aeb308083 : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:e2:00.0   uuid:b6565ee8-2100-7009-bcc6-a3809905620d : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=2 cross_root_port(%)=0
GPU 0000:5c:00.0   uuid:5527d7fb-a560-ab42-d027-20aeb5512197 : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:59:00.0   uuid:bb734f6b-24ad-2f83-86c3-6ab179bce131 : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:3b:00.0   uuid:0ef0b9ee-bb8f-cdae-4535-c0d790b2c663 : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:b9:00.0   uuid:ad59f685-5836-c2ea-2c79-3c95bea23f0d : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=1 cross_root_port(%)=0
GPU 0000:36:00.0   uuid:fda65234-707b-960a-d577-18c519301848 : Registered_MiB=0
Cache_MiB=0 max_pinned_MiB=1 cross_root_port(%)=0

```

The `cross_root_port (%)` port is the percentage of total DMA traffic through `nvidia-fs` callbacks, and this value spans across PCIe root ports between GPU and its peers such as HCA.

- ▶ This can be a major reason for low throughput on certain platforms.
- ▶ This does not consider the DMA traffic that is initiated via `cudaMemcpyDeviceToDevice` or `cuMemcpyPeer` with the specified GPU.

Here are some examples:

Run the following command:

```
$ /usr/local/cuda-x.y/gds/samples /mnt/lustre/test 0
$ cat /proc/driver/nvidia-fs/stats
```

Here is the output:

```
GDS Version: 1.0.0.71
NVFS statistics(ver: 4.0)
NVFS Driver(version: 2:7:47)
Mellanox PeerDirect Supported: True
IO stats: Enabled, peer IO stats: Enabled
Logging level: info

Active Shadow-Buffer (MB): 0
Active Process: 0
Reads                : n=0 ok=0 err=0 readmb=0 io_state_err=0
Reads                : Bandwidth(MB/s)=0 Avg-Latency(usec)=0
Sparse Reads         : n=0 io=0 holes=0 pages=0
Writes               : n=1 ok=1 err=0 writemb=0 io_state_err=0 pg-cache=0
pg-cache-fail=0
pg-cache-eio=0
Writes               : Bandwidth(MB/s)=0 Avg-Latency(usec)=0
Mmap                 : n=1 ok=1 err=0 munmap=1
Bar1-map             : n=1 ok=1 err=0 free=1 callbacks=0 active=0
Error                : cpu-gpu-pages=0 sg-ext=0 dma-map=0
Ops                  : Read=0 Write=0
GPU 0000:34:00:0    uuid:98bb4b5c-4576-b996-3d84-4a5d778fa970 : pinned_MB=0 cache_MB=0
max_pinned_MB=0 cross_root_port(%)=100
```

Run the following command:

```
$ cat /proc/driver/nvidia-fs/peer_affinity
```

Here is the output:

```
GPU P2P DMA distribution based on pci-distance
(last column indicates p2p via root complex)

GPU :0000:b7:00:0 :0 0 0 0 0 0 0 0 0 0 0 0
GPU :0000:b9:00:0 :0 0 0 0 0 0 0 0 0 0 0 0
GPU :0000:bc:00:0 :0 0 0 0 0 0 0 0 0 0 0 0
GPU :0000:be:00:0 :0 0 0 0 0 0 0 0 0 0 0 0
GPU :0000:e0:00:0 :0 0 0 0 0 0 0 0 0 0 0 0
GPU :0000:e2:00:0 :0 0 0 0 0 0 0 0 0 0 0 0
GPU :0000:e5:00:0 :0 0 0 0 0 0 0 0 0 0 0 0
GPU :0000:e7:00:0 :0 0 0 0 0 0 0 0 0 0 0 0
GPU :0000:34:00:0 :0 0 0 0 0 0 0 0 0 0 0 2
GPU :0000:36:00:0 :0 0 0 0 0 0 0 0 0 0 0 0
GPU :0000:39:00:0 :0 0 0 0 0 0 0 0 0 0 0 0
GPU :0000:3b:00:0 :0 0 0 0 0 0 0 0 0 0 0 0
GPU :0000:57:00:0 :0 0 0 0 0 0 0 0 0 0 0 0
GPU :0000:59:00:0 :0 0 0 0 0 0 0 0 0 0 0 0
GPU :0000:5c:00:0 :0 0 0 0 0 0 0 0 0 0 0 0
GPU :0000:5e:00:0 :0 0 0 0 0 0 0 0 0 0 0 0
```

In the above example, there are DMA transactions between the GPU (34:00.0) and one of its peers. The peer device has the highest possible rank which indicates it is farthest away from the respective GPU pci-distance wise.

To check the percentage of traffic, check the `cross_root_port %` in `/proc/driver/nvidia-fs/stats`. In the third example above, this value is 100%, which means that the peer-to-peer-traffic is happening over QPI links.

14.6. Display the GPU-to-Peer Distance Table

The `peer_distance` table displays the device-wise IO distribution for each peer with its rank for the specified GPU, and it complements the rank-based stats.

The `peer_distance` table displays the device-wise IO distribution for each peer with its rank for the specified GPU. It complements the rank-based stats.

The ranking is done in the following order:

1. Primary priority given to p2p distance (upper 2 bytes).
2. Secondary priority is given to the device bandwidth (lower 2 bytes)

For peer paths that cross the root port, a fixed cost for p2p distance (127) is added. This is done to induce a preference for paths under one CPU root port relative to paths that cross the CPU root ports.

Issue the following command:

```
$ cat /proc/driver/nvidia-fs/peer_distance
```

Sample output:

gpu	class	peer	peerrank	p2pdist	np2p	link	gen
0000:af:00.0	network	0000:86:00.0	0x820088	0x82	0	0x8	0x3
0000:af:00.0	nvme	0000:18:00.0	0x820088	0x82	0	0x8	0x3
0000:af:00.0	network	0000:86:00.1	0x820088	0x82	0	0x8	0x3
0000:af:00.0	network	0000:19:00.1	0x820088	0x82	0	0x8	0x3
0000:af:00.0	nvme	0000:87:00.0	0x820088	0x82	0	0x8	0x3
0000:af:00.0	network	0000:19:00.0	0x820088	0x82	0	0x8	0x3
0000:3b:00.0	network	0000:86:00.0	0x820088	0x82	0	0x8	0x3
0000:3b:00.0	nvme	0000:18:00.0	0x820088	0x82	0	0x8	0x3
0000:3b:00.0	network	0000:86:00.1	0x820088	0x82	0	0x8	0x3
0000:3b:00.0	network	0000:19:00.1	0x820088	0x82	0	0x8	0x3
0000:3b:00.0	nvme	0000:87:00.0	0x820088	0x82	0	0x8	0x3
0000:3b:00.0	network	0000:19:00.0	0x820088	0x82	0	0x8	0x3
0000:5e:00.0	network	0000:86:00.0	0x820088	0x82	0	0x8	0x3
0000:5e:00.0	nvme	0000:18:00.0	0x820088	0x82	0	0x8	0x3
0000:5e:00.0	network	0000:86:00.1	0x820088	0x82	0	0x8	0x3
0000:5e:00.0	network	0000:19:00.1	0x820088	0x82	0	0x8	0x3
0000:5e:00.0	nvme	0000:87:00.0	0x820088	0x82	0	0x8	0x3

0000:5e:00.0 network	0000:19:00.0	0x820088	0x82	0	0x8	0x3
0000:d8:00.0 network	0000:86:00.0	0x820088	0x82	0	0x8	0x3
0000:d8:00.0 nvme	0000:18:00.0	0x820088	0x82	0	0x8	0x3
0000:d8:00.0 network	0000:86:00.1	0x820088	0x82	0	0x8	0x3
0000:d8:00.0 network	0000:19:00.1	0x820088	0x82	0	0x8	0x3
0000:d8:00.0 nvme	0000:87:00.0	0x820088	0x82	0	0x8	0x3
0000:d8:00.0 network	0000:19:00.0	0x820088	0x82	0	0x8	0x3

14.7. The GDSIO Tool

Here is some information about the GDSIO tool.

GDSIO is a synthetic IO benchmarking tool that uses `cufile` APIs for IO. The tool can be found in the `/usr/local/cuda-x.y/tools` directory. For more information about how to use this tool, run `$ /usr/local/cuda-x.y/tools/gdsio -h` or review the `gdsio` section in the `/usr/local/cuda-x.y/tools/README` file. In the examples below, the files are created on an `ext4` file system.

Issue the following command:

```
# ./gdsio -f /root/sg/test -d 0 -w 4 -s 1M -x 0 -i 4K:32K:1K -I 1
```

Here is the output:

```
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 671/1024(KiB)
IOSize: 4-32-1(KiB) Throughput: 0.044269 GiB/sec, Avg_Latency:
996.094925 usecs ops: 60 total_time 0.014455 secs
```

This command does a write IO (`-I 1`) on a file named `test` of size 1MiB (`-s 1M`) with an IO size that varies between 4KiB to 32 KiB in steps of 1KiB (`-i 4K:32K:1K`). The transfer is performed using GDS (`-x 0`) using 4 threads (`-w 4`) on GPU 0 (`-d 0`).

Here are some of additional features of the tool:

- Support for read/write at random offsets in a file.

The `gdsio` tool provides options to perform a read and write to a file at random offsets.

- Using `-I 2` and `-I 3` options does a file read and write operation at random offset respectively but the random offsets are always 4KiB aligned.

```
# ./gdsio -f /root/sg/test -d 0 -w 4 -s 1M -x 0 -i 4K:32K:1K -I 3
IoType: RANDWRITE XferType: GPUD Threads: 4 DataSetSize: 706/1024(KiB) IOSize:
4-32-1(KiB) Throughput: 0.079718 GiB/sec, Avg_Latency: 590.853274 usecs ops:
44 total_time 0.008446 secs
```

- To perform a random read and write at unaligned 4KiB offsets, the `-U` option can be used with `-I 0` or `-I 1` for read and write, respectively.

```
# ./gdsio -f /root/sg/test -d 0 -w 4 -s 1M -x 0 -i 4K:32K:1K -I 1 -U
IoType: RANDWRITE XferType: GPUD Threads: 4 DataSetSize: 825/1024(KiB) IOSize:
4-32-1(KiB) Throughput: 0.055666 GiB/sec, Avg_Latency: 919.112500 usecs ops:
49 total_time 0.014134 secs
```

- Random buffer fill for dedupe and compression.

Using the '-R' option fills the io size buffer (-i) with random data. This random data is then written to the file onto different file offsets.

```
# ./gdsio -f /root/sg/test -d 0 -w 4 -s 1M -x 0 -i 4K:32K:1K -I 1 -R
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 841/1024 (KiB) IOSize:
4-32-1 (KiB) Throughput: 0.059126 GiB/sec, Avg_Latency: 788.884580 usecs ops:
69 total_time 0.013565 secs
```

- Using the -F option will fill the entire file with random data.

```
# ./gdsio -f /root/sg/test -d 0 -w 4 -s 1M -x 0 -i 4K:32K:1K -I 1 -F
IoType: WRITE XferType: GPUD Threads: 4 DataSetSize: 922/1024 (KiB) IOSize:
4-32-1 (KiB) Throughput: 0.024376 GiB/sec, Avg_Latency: 1321.104532 usecs ops:
73 total_time 0.036072 secs
```

This is useful for file systems that use dedupe and compression algorithms to minimize disk access. Using random data increases the probability that these file systems will hit the backend disk more often.

- Variable block size.

To perform a read or a write on a file, you can specify the block size (-i), which says that IO would be performed in chunks of block sized lengths. To check the stats for what block sizes are used use the gds_stats tool. Ensure the the /etc/cufile.json file has cufile_stats is set to 3:

```
# ./gds_stats -p <pid of the gdsio process> -l 3
```

Sample output:

```
0-4 (KiB): 0 0
4-8 (KiB): 0 17205
8-16 (KiB): 0 45859
16-32 (KiB): 0 40125
32-64 (KiB): 0 0
64-128 (KiB): 0 0
128-256 (KiB): 0 0
256-512 (KiB): 0 0
512-1024 (KiB): 0 0
1024-2048 (KiB): 0 0
2048-4096 (KiB): 0 0
4096-8192 (KiB): 0 0
8192-16384 (KiB): 0 0
16384-32768 (KiB): 0 0
32768-65536 (KiB): 0 0
65536-... (KiB): 0 0
```

The highlighted counters show that, for the command above, the block sizes that are used for file IO are in the 4-32 KiB range.

- Verification mode usage and limitations.

To ensure data integrity, there is an option to perform IO in a Write and Read in verify mode using the -v option. Here is an example:

```
# ./gdsio -V -f /root/sg/test -d 0 -w 1 -s 2G -o 0 -x 0 -k 0 -i 4K:32K:1K -I 1
IoType: WRITE XferType: GPUD Threads: 1 DataSetSize: 2097144/2097152 (KiB) IOSize:
4-32-1 (KiB) Throughput: 0.074048 GiB/sec, Avg_Latency: 231.812570 usecs ops:
116513 total_time 27.009349 secs
Verifying data
IoType: READ XferType: GPUD Threads: 1 DataSetSize: 2097144/2097152 (KiB) IOSize:
4-32-1 (KiB) Throughput: 0.103465 GiB/sec, Avg_Latency: 165.900663 usecs ops:
116513 total_time 19.330184 secs
```

The command mentioned above will perform a write followed by a read verify test.

While using the verify mode, remember the following points:

- ▶ read test (-l 0) with verify option (-v) should be used with files written (-l 1) with the -v option
- ▶ read test (-l 2) with verify option (-v) should be used with files written (-l 3) with the -v option and using same random seed (-k) using same number of threads, offset, and data size
- ▶ write test (-l 1/3) with verify option (-v) will perform writes followed by read.
- ▶ Verify mode cannot be used in timed mode (-T option).

If Verify mode is used in a timed mode, it will be ignored.

- ▶ The configuration file

GDSIO has an option to configure the parameters that are needed to perform an IO in a configuration file and run the IO using those configurations. The configuration file gives the option of performing multiple jobs, where each job has some different configurations.

The configuration file has global parameters and job specific parameter support. For example, with a configuration file, you can configure each job to perform on a GPU and with a different number of threads. The global parameters, such as IO Size and transfer mode, remain the same for each job. For more information, refer to /usr/local/cuda-x.y/tools/README and /usr/local/cuda-x.y/tools/rw-sample.gdsio files. After configuring the parameters, to perform the IO operation using the configuration file, run the following command:

```
# ./gdsio <config file name>
```

See [Tabulated Fields](#) for a list of the tabulated fields.

14.8. Tabulated Fields

This section describes the tabulated fields after you run the #./gdsio <config file name> command.

Table 7. Tabulated Fields

Global Option	Description
xfer_type	GDSIO Transfer types: <ul style="list-style-type: none"> ▶ 0 : Storage->GPU ▶ 1 : Storage->CPU ▶ 2 : Storage->CPU->GPU ▶ 3 : Storage->CPU->GPU_ASYNC ▶ 4 : Storage->PAGE_CACHE->CPU->GPU ▶ 5 : Storage->GPU_ASYNC

Global Option	Description
rw	IO type, rw=read, rw=write, rw=randread, rw=randwrite
bs	block size, for example, bs=1M, for variable block size can specify range, for example, bs=1M:4M:1M, (1M : start block size, 4M : end block size, 1M :steps in which size is varied).
size	File-size, for example, size=2G.
runtime	Duration in seconds.
do_verify	Use 1 for enabling verification
skip_bufregister	Skip cufile buffer registration, ignored in cpu mode.
enable_nvlinks	Set up NVlinks. This field is recommended if p2p traffic is cross node.
random_seed	Use random seed, for example, 1234.
refill_buffer	Refill io buffer after every write.
fill_random	Fill request buffer with random data.
unaligned_random	Use random offsets which are not page-aligned.
start_offset	File offset to start read/write from.
Per-Job Options	Description
numa_node	NUMA node.
gpu_dev_id	GPU device index (check nvidia-smi).
num_threads	Number of IO Threads per job.
directory	Directory name where files are present. Each thread will work on a per file basis.
filename	Filename for single file mode, where threads share the same file. (Note: directory mode and filemode should not be used in a mixed manner across jobs).

14.9. GDSCHECK

This section describes the GDSCHECK tool.

The `/usr/local/cuda-x.y/tools/gdscheck.py` tool is used to perform a GDS platform check and has other options that can be found by using `-h` option.

```

$ ./gdscheck.py -h
usage: gdscheck.py [-h] [-p] [-f FILE] [-v] [-V]
GPUDirectStorage platform checker
optional arguments:
  -h, --help  show this help message and exit
  -p          gds platform check
  -f FILE    gds file check
  -v         gds version checks
  -V         gds fs checks

```

To perform a GDS platform check, issue the following command and expect the output in the following format:

```

# ./gdscheck.py -p
GDS release version: 1.0.0.78
nvidia_fs version: 2.7 libcufile version: 2.4
=====
ENVIRONMENT:
=====
DRIVER CONFIGURATION:
=====
NVMe                : Supported
NVMeOF              : Unsupported
SCSI                 : Unsupported
ScaleFlux CSD       : Unsupported
NVMesh              : Unsupported
DDN EXAScaler       : Supported
IBM Spectrum Scale  : Unsupported
NFS                  : Unsupported
WekaFS               : Unsupported
Userspace RDMA      : Unsupported
--Mellanox PeerDirect : Enabled
--rdma library       : Not Loaded (libcufile_rdma.so)
--rdma devices       : Not configured
--rdma_device_status : Up: 0 Down: 0
=====
CUFILE CONFIGURATION:
=====
properties.use_compat_mode : true
properties.gds_rdma_write_support : true
properties.use_poll_mode : false
properties.poll_mode_max_size_kb : 4
properties.max_batch_io_timeout_msecs : 5
properties.max_direct_io_size_kb : 16384
properties.max_device_cache_size_kb : 131072
properties.max_device_pinned_mem_size_kb : 33554432
properties.posix_pool_slab_size_kb : 4 1024 16384
properties.posix_pool_slab_count : 128 64 32
properties.rdma_peer_affinity_policy : RoundRobin
properties.rdma_dynamic_routing : 0
fs.generic.posix_unaligned_writes : false
fs.lustre.posix_gds_min_kb: 0
fs.weka.rdma_write_support: false
profile.nvtx : false
profile.cufile_stats : 0
miscellaneous.api_check_aggressive : false
=====
GPU INFO:
=====
GPU index 0 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS
GPU index 1 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS
GPU index 2 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS
GPU index 3 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS
GPU index 4 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS
GPU index 5 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS
GPU index 6 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS
GPU index 7 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS

```



```
GPU index 8 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS
GPU index 9 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS
GPU index 10 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS
GPU index 11 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS
GPU index 12 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS
GPU index 13 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS
GPU index 14 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS
GPU index 15 Tesla V100-SXM3-32GB bar:1 bar size (MiB):32768 supports GDS
=====
PLATFORM INFO:
=====
IOMMU: disabled
Platform verification succeeded
```

14.10. NFS Support with GPUDirect Storage

This section provides information about NFS support with GDS.

14.10.1. Install Linux NFS server with RDMA Support on MLNX_OFED 5.3 or Later

Here is some information about how to install a Linux NFS server with RDMA support on MLNX_OFED 5.3 or later.

To install a standard Linux kernel-based NFS server with RDMA support, complete the following steps:



Note: The server must have a Mellanox connect-X4/5 NIC with MLNX_OFED 5.3 or later installed.

1. Issue the following command:

```
$ ofed_info -s MLNX_OFED_LINUX-5.3-1.0.5.1:
```

2. Review the output to ensure that the server was installed.

```
$ sudo apt-get install nfs-kernel-server
$ mkfs.ext4 /dev/nvme0n1
$ mount -o data=ordered /dev/nvme0n1 /mnt/nvme
$ cat /etc/exports
/mnt/nvme *(rw,async,insecure,no_root_squash,no_subtree_check)
$ service nfs-kernel-server restart
$ modprobe rprdma
$ echo rdma 20049 > /proc/fs/nfsd/portlist
```

14.10.2. Install GPUDirect Storage Support for the NFS Client

Here is some information about installing GDS support for the NFS client.

To install a NFS client with GDS support complete the following steps:



Note: The client must have a Mellanox connect-X4/5 NIC with MLNX_OFED 5.3 or later installed.

1. Issue the following command:

```
$ ofed_info -s MLNX_OFED_LINUX-5.3-1.0.5.0:
```

2. Review the output to ensure that the support exists.

```
$ sudo apt-get install nfs-common
$ modprobe rprdma
$ mkdir -p /mnt/nfs_rdma_gds
$ sudo mount -v -o proto=rdma,port=20049,vers=3 172.16.0.101:/ /mnt/nfs_rdma_gds
To mount with nconnect using VAST nfs client package:
Eg: client IB interfaces 172.16.0.17 , 172.16.0.18, 172.16.0.19, 172.16.0.20,
172.16.0.21,172.16.0.22,172.16.0.23 172.16.0.24
$ sudo mount -v -o
proto=rdma,port=20049,vers=3,nconnect=20,localports=172.16.0.17-172.16.0.24,remoteports=172.16.0.17-172.16.0.24 /mnt/nfs_rdma_gds
```

14.11. NFS GPUDirect Storage Statistics and Debugging

Here is some information about NFS and GDS statistics and debugging.

NFS IO can be observed using regular Linux tools that are used for monitoring IO, such as iotop and nfsstat.

- ▶ To enable NFS RPC stats debugging, run the following command.

```
$ rpcdebug -v
```

- ▶ To observe GDS-related IO stats, run the following command.

```
$ cat /proc/driver/nvidia-fs/stats
```

- ▶ To determine GDS statistics per process, run the following command.

```
$ /usr/local/cuda-x.y/tools/gds_stats -p <PID> -l 3
```

14.12. GPUDirect Storage IO Behavior

This section provides information about IO behavior in GDS.

14.12.1. Read/Write Atomicity Consistency with GPUDirect Storage Direct IO

Here is some information about read/write atomicity consistency with GDS.

In GDS, the `max_direct_io_size_kb` property controls the IO unit size in which the limitation is issued to the underlying file system. By default, this value is 16MB. This implies that from a Linux VFS perspective, the atomicity of size is limited to the `max_direct_io_size_kb` size and not the original request size. This limitation exists in the standard GDS path and in compatible mode.

14.12.2. Write with File a Opened in O_APPEND Mode (cuFileWrite)

Here is some information about writing to a file that is opened in O_APPEND mode.

For a file that is opened in O_APPEND mode with concurrent writers, if the IO size that is used is larger than the `max_direct_io_size_kb` property, because of the write atomicity limitations, the file might have interleaved data from multiple writers. This cannot be prevented even if the underlying file-system has locking guarantees.

14.12.3. GPU to NIC Peer Affinity

Here is some information about GPU to NIC peer affinity.

The library maintains a peer affinity table that is a pci-distance-based ranking for a GPU and the available NICs in the platform for RDMA. Currently, the limitation in the ranking does not consider NUMA attributes for the NICs. For a NIC that does not share a common root port with a GPU, the P2P traffic might get routed cross socket over QPI links even if there is a NIC that resides on the same CPU socket as the GPU.

14.12.4. Compatible Mode with Unregistered Buffers

Here is some information about the compatible mode with unregistered buffers.

Currently in compatible mode, the IO path with non-registered buffers does not have optimal performance and does buffer allocation and deallocation in every `cuFileRead` or `cuFileWrite`.

14.12.5. Unaligned writes with Non-Registered Buffers

Here is some information about unaligned writes with non-registered buffers.

For unaligned writes, using unregistered buffers performance may not be optimal as compared to registered buffers.

14.12.6. Process Hang with NFS

Here is some information about process hangs with NFS.

A process hang is observed in NFS environments when the application crashes.

14.12.7. Tools Support Limitations for CUDA 9 and Earlier

Here is some information about the tool support issues with CUDA 9 and earlier.

The `gdsio` binary has been built against CUDA runtime 10.1 and has a dependency on the CUDA runtime environment to be equal to version 10.1 or later. Otherwise a driver dependency error will be reported by the tool.

14.13. GDS Statistics for Dynamic Routing

Dynamic Routing decisions are performed at I/O operation granularity. The GDS User-space Statistics contain a per-GPU counter to indicate the number of I/Os that have been routed using Dynamic Routing.

Table 8. cuFile Dynamic Routing Counter

Entry	Description
dr	Number of cuFileRead/cuFileWrite for which I/O was routed using Dynamic Routing for a given GPU.

There are existing counters in the PER_GPU POOL BUFFER STATS and PER_GPU POSIX POOL BUFFER STATS from which a user can infer the GPUs that are chosen by dynamic routing for use as the bounce buffers.

a) Platform has GPUs (0 and 1) not sharing the same PCIe host bridge as the NICs:

```
"rdma_dev_addr_list": [ "192.168.0.12", "192.168.1.12" ],
"rdma_dynamic_routing": true,
"rdma_dynamic_routing_order": [ "GPU_MEM_NVLINKS", "GPU_MEM", "SYS_MEM" ]

$ gds_stats -p <process id> -l 3
GPU 0 Read: bw=0 util(%)=0 n=0 posix=0 unalign=0 dr=0 r_sparse=0 r_inline=0 err=0
MiB=0 Write: bw=3.37598 util(%)=532 n=6629 posix=0 unalign=0 dr=6629 err=0 MiB=6629
BufRegister: n=4 err=0 free=0 MiB=4
GPU 1 Read: bw=0 util(%)=0 n=0 posix=0 unalign=0 dr=0 r_sparse=0 r_inline=0 err=0
MiB=0 Write: bw=3.29297 util(%)=523 n=6637 posix=0 unalign=0 dr=6637 err=0 MiB=6637
BufRegister: n=4 err=0 free=0 MiB=4

PER_GPU POOL BUFFER STATS:
GPU : 6 pool_size_MiB : 7 usage : 1/7 used_MiB : 1
GPU : 7 pool_size_MiB : 7 usage : 0/7 used_MiB : 0
GPU : 8 pool_size_MiB : 7 usage : 2/7 used_MiB : 2
GPU : 9 pool_size_MiB : 7 usage : 2/7 used_MiB : 2

PER_GPU POSIX POOL BUFFER STATS:

PER_GPU RDMA STATS:
GPU 0000:34:00.0 : mlx5_3(138:48):0 mlx5_6(265:48):0
GPU 0000:36:00.0 : mlx5_3(138:48):0 mlx5_6(265:48):0
GPU 0000:39:00.0 : mlx5_3(138:48):0 mlx5_6(265:48):0
GPU 0000:3b:00.0 : mlx5_3(138:48):0 mlx5_6(265:48):0
GPU 0000:57:00.0 : mlx5_3(7:48):0 mlx5_6(265:48):0
GPU 0000:59:00.0 : mlx5_3(7:48):0 mlx5_6(265:48):0
GPU 0000:5c:00.0 : mlx5_3(3:48):3318 mlx5_6(265:48):0
GPU 0000:5e:00.0 : mlx5_3(3:48):3318 mlx5_6(265:48):0
GPU 0000:b7:00.0 : mlx5_6(3:48):3316 mlx5_3(265:48):0
GPU 0000:b9:00.0 : mlx5_6(3:48):3317 mlx5_3(265:48):0
GPU 0000:bc:00.0 : mlx5_6(7:48):0 mlx5_3(265:48):0
GPU 0000:be:00.0 : mlx5_6(7:48):0 mlx5_3(265:48):0
GPU 0000:e0:00.0 : mlx5_6(138:48):0 mlx5_3(265:48):0
GPU 0000:e2:00.0 : mlx5_6(138:48):0 mlx5_3(265:48):0
GPU 0000:e5:00.0 : mlx5_6(138:48):0 mlx5_3(265:48):0
GPU 0000:e7:00.0 : mlx5_6(138:48):0 mlx5_3(265:48):0
```

b) Platform configuration that has no GPUs sharing the same PCIe host bridge as the NICs and no NVLinks between the GPUs. For such configurations, an admin can set a policy to use system memory other than the default P2P policy.

```
"rdma_dev_addr_list": [ "192.168.0.12", "192.168.1.12" ],
"rdma_dynamic_routing": true,
"rdma_dynamic_routing_order": [ "SYS_MEM" ]
PER_GPU STATS:
GPU 4 Read: bw=0 util(%)=0 n=0 posix=0 unalign=0 r_sparse=0 r_inline=0 err=0 MiB=0
Write: bw=1.11GiB util(%)=0 n=1023 posix=1023 unalign=1023 dr=1023 err=0 MiB=1023
BufRegister: n=0 err=0 free=0 MiB=0
GPU 8 Read: bw=0 util(%)=0 n=0 posix=0 unalign=0 r_sparse=0 r_inline=0 err=0 MiB=0
Write: bw=1.11GiB util(%)=0 n=1023 posix=1023 unalign=1023 dr=1023 err=0 MiB=1023
BufRegister: n=0 err=0 free=0 MiB=0
PER_GPU POSIX POOL BUFFER STATS:
GPU 4 4(KiB) :0/0 1024(KiB) :0/1 16384(KiB) :0/0
GPU 8 4(KiB) :0/0 1024(KiB) :1/1 16384(KiB) :0/0
```

14.13.1. Peer Affinity Dynamic Routing

Dynamic Routing decisions are performed at I/O operation granularity. The GDS User-space Statistics contain a per-GPU counter to indicate the number of I/Os that have been routed using Dynamic Routing.

Table 9. cuFile Dynamic Routing Counter

Entry	Description
dr	Number of cuFileRead/cuFileWrite for which I/O was routed using Dynamic Routing for a given GPU.

There are existing counters in the PER_GPU POOL BUFFER STATS and PER_GPU POSIX POOL BUFFER STATS from which a user can infer the GPUs that are chosen by dynamic routing for use as the bounce buffers.

```
// "rdma_dev_addr_list": [ "192.168.4.12", "192.168.5.12", "192.168.6.12",
"192.168.7.12" ],
cufile.log:
-----
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:133 Computing
GPU->NIC affinity table:
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:34:00.0 RDMA dev: mlx5_6 mlx5_8 mlx5_7 mlx5_9
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:36:00.0 RDMA dev: mlx5_6 mlx5_8 mlx5_7 mlx5_9
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:39:00.0 RDMA dev: mlx5_6 mlx5_8 mlx5_7 mlx5_9
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:3b:00.0 RDMA dev: mlx5_6 mlx5_8 mlx5_7 mlx5_9
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:57:00.0 RDMA dev: mlx5_6 mlx5_8 mlx5_7 mlx5_9
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:59:00.0 RDMA dev: mlx5_6 mlx5_8 mlx5_7 mlx5_9
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:5c:00.0 RDMA dev: mlx5_6 mlx5_8 mlx5_7 mlx5_9
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:5e:00.0 RDMA dev: mlx5_6 mlx5_8 mlx5_7 mlx5_9
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:b7:00.0 RDMA dev: mlx5_6
```

```

23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:b9:00.0 RDMA dev: mlx5_6
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:bc:00.0 RDMA dev: mlx5_7
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:be:00.0 RDMA dev: mlx5_7
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:e0:00.0 RDMA dev: mlx5_8
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:e2:00.0 RDMA dev: mlx5_8
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:e5:00.0 RDMA dev: mlx5_9
23-02-2021 10:17:49:641 [pid=22436 tid=22436] INFO curdma-ldbal:139 GPU:
0000:e7:00.0 RDMA dev: mlx5_9
    
```

A sample from `gds_stats` showing the GPU to NIC binding during a sample IO test:

```

PER_GPU RDMA STATS:
GPU 0000:34:00.0 : mlx5_6(265:48):0 mlx5_8(265:48):0 mlx5_7(265:48):0
mlx5_9(265:48):0
GPU 0000:36:00.0 : mlx5_6(265:48):0 mlx5_8(265:48):0 mlx5_7(265:48):0
mlx5_9(265:48):0
GPU 0000:39:00.0 : mlx5_6(265:48):0 mlx5_8(265:48):0 mlx5_7(265:48):0
mlx5_9(265:48):0
GPU 0000:3b:00.0 : mlx5_6(265:48):0 mlx5_8(265:48):0 mlx5_7(265:48):0
mlx5_9(265:48):0
GPU 0000:57:00.0 : mlx5_6(265:48):0 mlx5_8(265:48):0 mlx5_7(265:48):0
mlx5_9(265:48):0
GPU 0000:59:00.0 : mlx5_6(265:48):0 mlx5_8(265:48):0 mlx5_7(265:48):0
mlx5_9(265:48):0
GPU 0000:5c:00.0 : mlx5_6(265:48):0 mlx5_8(265:48):0 mlx5_7(265:48):0
mlx5_9(265:48):0
GPU 0000:5e:00.0 : mlx5_6(265:48):0 mlx5_8(265:48):0 mlx5_7(265:48):0
mlx5_9(265:48):0
GPU 0000:b7:00.0 : mlx5_6(3:48):22918 mlx5_7(7:48):0 mlx5_8(138:48):0
mlx5_9(138:48):0
GPU 0000:b9:00.0 : mlx5_6(3:48):22949 mlx5_7(7:48):0 mlx5_8(138:48):0
mlx5_9(138:48):0
GPU 0000:bc:00.0 : mlx5_7(3:48):22945 mlx5_6(7:48):0 mlx5_8(138:48):0
mlx5_9(138:48):0
GPU 0000:be:00.0 : mlx5_7(3:48):22942 mlx5_6(7:48):0 mlx5_8(138:48):0
mlx5_9(138:48):0
GPU 0000:e0:00.0 : mlx5_8(3:48):22937 mlx5_9(7:48):0 mlx5_6(138:48):0
mlx5_7(138:48):0
GPU 0000:e2:00.0 : mlx5_8(3:48):22930 mlx5_9(7:48):0 mlx5_6(138:48):0
mlx5_7(138:48):0
GPU 0000:e5:00.0 : mlx5_9(3:48):22922 mlx5_8(7:48):0 mlx5_6(138:48):0
mlx5_7(138:48):0
GPU 0000:e7:00.0 : mlx5_9(3:48):22920 mlx5_8(7:48):0 mlx5_6(138:48):0
mlx5_7(138:48):0
    
```

- For kernel-based DFS, DDN-Lustre and VAST-NFS, `nvidia-fs` driver provides a callback to determine the best NIC given a target GPU. The `nvidia-fs` `peer_affinity` can be used to track end-to-end IO affinity behavior.

For example, with a routing policy of `"GPU_MEM_NVLINK"`, one should not see cross-port traffic as shown in the statistics snippet below:

```

$ cat /proc/driver/nvidia-fs/peer_affinity
GPU P2P DMA distribution based on pci-distance

(last column indicates p2p via root complex)
GPU :0000:bc:00.0 :0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
GPU :0000:e0:00.0 :0 0 205305577 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0
GPU :0000:e5:00.0 :0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
    
```



```
22-02-2021 21:16:27:776 [pid=90794 tid=90794] INFO    cuffio-route:156 netdev:ib7
bdf:0000:bd:00.0 ip: 192.168.7.12 best gpus: 10 11 8 9
```

```
22-02-2021 21:16:27:776 [pid=90794 tid=90794] DEBUG  cuffio:1218 target gpu: 4 best
gpu: 4 selected based on dynamic routing
```

14.14. Installing and Uninstalling the Debian Package

This section provides information about how to install and uninstall the Debian packages.

The following packages are shipped as part of the Debian package:

1. `nvidia-fs_2.2_amd64.deb`
2. `gds_0.8.0_amd64.deb`
3. `gds-tools_0.8.0_amd64.deb`

Currently, NVIDIA only supports the Debian installation with Ubuntu 18.04 and 20.04. The first package, `nvidia-fs_2.2_amd64.deb`, can be installed or uninstalled without any dependencies. You must install the other three packages in the order as listed above and uninstalled in reverse order that is listed above.

For more information about how to install and uninstall the Debian package, see:

- ▶ [Install the Debian Package](#)
- ▶ [Uninstall the Debian Package](#)

14.14.1. Install the Debian Package

Here are the steps to install the Debian package.

Before you install the Debian package, complete the following tasks:

- ▶ Ensure that the NVIDIA driver is installed by using APT package manager.
- ▶ You installed the NVIDIA driver by using `NVIDIA-Linux-x86_64`.

The `<version>.run` file is not supported with the `nvidia-gds` package.

- ▶ Ensure that you download the correct GDS debian package based on your Ubuntu distribution and CUDA toolkit.

- ▶ For 20.04:

```
$ sudo dpkg -i gpudirect-storage-local-repo-ubuntu2004-cuda-
x.y-0.9.0_1.0-1_amd64.deb
```

- ▶ For 18.04:

```
$ sudo dpkg -i gpudirect-storage-local-repo-ubuntu1804-cuda-
x.y-0.9.0_1.0-1_amd64.deb
```

The following packages, which are shipped in the Debian package, will be uninstalled:

- ▶ `nvidia-fs_2.3_amd64.deb`

- ▶ gds_0.9.0_amd64.deb
- ▶ gds-tools_0.9.0_amd64.deb

1. Download the debian packages to local client.

```
$ sudo apt-key add /var/gpudirect-storage-local-repo-*/7fa2af80.pub
$ sudo apt-get update
```

2. Install all the GDS-related packages by running `nvidia-gds metapackage`.

If you installed version 0.8.0, run the following commands **before** you upgrade to version 0.9.0:

```
$ sudo dpkg --purge nvidia-fs
$ sudo dpkg --purge gds-tools
$ sudo dpkg --purge gds
```

3. To get the current NVIDIA driver version in the system:

```
$ NVIDIA_DRV_VERSION=$(cat /proc/driver/nvidia/version | grep Module | awk
'{print $8}' | cut -d '.' -f 1)
```

On DGX-based systems or systems with nvidia prebuilt kernels, run the following commands to install nvidia-gds with correct dependencies:

```
$ sudo apt install nvidia-gds nvidia-dkms-${NVIDIA_DRV_VERSION}-server
$ sudo modprobe nvidia_fs
```

For systems with the `nvidia-dkms-${NVIDIA_DRV_VERSION}` package installed:

```
$ sudo apt install nvidia-gds
$ sudo modprobe nvidia_fs
```

4. Verify the package installation.

```
$ dpkg -s nvidia-gds
Package: nvidia-gds
Status: install ok installed
Priority: optional
Section: multiverse/devel
Installed-Size: 7
Maintainer: cudatools <cudatools@nvidia.com>
Architecture: amd64
Source: gds-ubuntul804
Version: 0.9.0.15-1
Provides: gds
Depends: libcufv0, gds-tools, nvidia-fs
Description: Metapackage for GPU Direct Storage
GPU Direct Storage metapackage
```

5. To verify GDS install run `gdscheck`:

```
$ /usr/local/cuda-x.y/gds/tools/gdscheck.py -p
```

Here is the output:

```
GDS release version (beta): 0.9.0.15
nvidia_fs version: 2.3 libcufv version: 2.3
cuFile CONFIGURATION:
NVMe           : Supported
NVMeOF        : Unsupported
SCSI           : Unsupported
SCALEFLUX CSD : Unsupported
LUSTRE        : Unsupported
NFS           : Unsupported
WEKAFS        : Supported
USERSPACE RDMA : Supported
--MOFED peer direct : enabled
--rdma library      : Loaded (libcufv_rdma.so)
--rdma devices     : Configured
--rdma_device_status : Up: 1 Down: 0
```

```

properties.use_compat_mode : 1
properties.use_poll_mode : 0
properties.poll_mode_max_size_kb : 4
properties.max_batch_io_timeout_msecs : 5
properties.max_direct_io_size_kb : 16384
properties.max_device_cache_size_kb : 131072
properties.max_device_pinned_mem_size_kb : 33554432
properties.posix_pool_slab_size_kb : 4096 1048576 16777216
properties.posix_pool_slab_count : 128 64 32
properties.rdma_peer_affinity_policy : RoundRobin
fs.generic.posix_unaligned_writes : 0
fs.lustre.posix_gds_min_kb: 0
fs.weka.rdma_write_support: 0
profile.nvtx : 0
profile.cufile_stats : 3
miscellaneous.api_check_aggressive : 0
GPU INFO:
GPU index 0 Tesla T4 bar:1 bar size (MB):256 supports GDS
GPU index 1 Tesla T4 bar:1 bar size (MB):256 supports GDS
GPU index 2 Tesla T4 bar:1 bar size (MB):256 supports GDS
GPU index 3 Tesla T4 bar:1 bar size (MB):256 supports GDS
IOMMU : disabled
Platform verification succeeded

```

14.14.2. Uninstall the Debian Package

Here is the information about how to uninstall the Debian package.

Before you install GDS version 0.9, you need to uninstall GDS version 0.8 or earlier to uninstall GDS and remove the following packages:

- ▶ nvidia-fs_2.2_amd64.deb
- ▶ gds_0.8.0_amd64.deb
- ▶ gds-tools_0.8.0_amd64.deb

To uninstall the Debian package, run the following command:

```
$ sudo dpkg --purge nvidia-gds
```

Chapter 15. GDS Library Tracing

The GDS Library has USDT (static tracepoints), which can be used with Linux tools such as `ltrace`, `bcc/bpf`, `perf`. This section assumes familiarity with these tools.

The examples in this section show tracing by using the `bcc/bpf` tracing facility. GDS does not ship these tracing tools. Refer to [Installing BCC](#) for more information about installing `bcc/bpf` tools. Users must have root privileges to install.



Note: The user must also have `sudo` access to use these tools.

15.1. Example: Display Tracepoints

This example shows how you can display tracepoints.

1. To display tracepoints, run the following command:

```
# ./tplist -l /usr/local/gds/lib/libcufile.so
```

2. Review the output, for example:

```
/usr/local/cuda-x.y/lib/libcufile.so cufio:cufio_px_read
/usr/local/cuda-x.y/lib/libcufile.so cufio:cufio_rdma_read
/usr/local/cuda-x.y/lib/libcufile.so cufio:cufio_gds_read
/usr/local/cuda-x.y/lib/libcufile.so cufio:cufio_gds_read_async
/usr/local/cuda-x.y/lib/libcufile.so cufio:cufio_px_write
/usr/local/cuda-x.y/lib/libcufile.so cufio:cufio_gds_write
/usr/local/cuda-x.y/lib/libcufile.so cufio:cufio_gds_write_async
/usr/local/cuda-x.y/lib/libcufile.so cufio-internal:cufio-internal-write-bb
/usr/local/cuda-x.y/lib/libcufile.so cufio-internal:cufio-internal-read-bb
/usr/local/cuda-x.y/lib/libcufile.so cufio-internal:cufio-internal-bb-done
/usr/local/cuda-x.y/lib/libcufile.so cufio-internal:cufio-internal-io-done
/usr/local/cuda-x.y/lib/libcufile.so cufio-internal:cufio-internal-map
```

15.1.1. Example: Tracepoint Arguments

Here are examples of tracepoint arguments.

`cufio_px_read`

This tracepoint tracks POSIX IO reads and takes the following arguments:

- ▶ Arg1: File descriptor
- ▶ Arg 2: File offset
- ▶ Arg 3: Read size

- ▶ Arg 4: GPU Buffer offset
- ▶ Arg 5: Return value
- ▶ Arg 6: GPU ID for which IO is done

`cufile_rdma_read`

This tracepoint tracks IO reads for through WEKA filesystem and takes the following arguments:

- ▶ Arg1: File descriptor
- ▶ Arg2: File offset
- ▶ Arg3: Read size
- ▶ Arg4: GPU Buffer offset
- ▶ Arg5: Return value
- ▶ Arg6: GPU ID for which IO is done
- ▶ Arg7: Is the IO done to GPU Bounce buffer

`cufile_gds_read`

This tracepoint tracks IO reads going through the GDS kernel drive and takes the following arguments:

- ▶ Arg1: File descriptor
- ▶ Arg2: File offset
- ▶ Arg3: Read size
- ▶ Arg4: GPU Buffer offset
- ▶ Arg5: Return value
- ▶ Arg6: GPU ID for which IO is done
- ▶ Arg7: Is the IO done to GPU Bounce buffer

`cufile_gds_read_async`

This tracepoint tracks iO reads going through the GDS kernel driver and poll mode is set and takes the following arguments:

- ▶ Arg1: File descriptor
- ▶ Arg2: File offset
- ▶ Arg3: Read size
- ▶ Arg4: GPU Buffer offset
- ▶ Arg5: Return value
- ▶ Arg6: GPU ID for which IO is done
- ▶ Arg7: Is the IO done to GPU Bounce buffer

`cufio_px_write`

This tracepoint tracks POSIX IO writes and takes the following arguments:

- ▶ Arg1: File descriptor
- ▶ Arg 2: File offset
- ▶ Arg 3: Write size
- ▶ Arg 4: GPU Buffer offset
- ▶ Arg 5: Return value
- ▶ Arg 6: GPU ID for which IO is done

`cufio_gds_write`

This tracepoint tracks IO writes going through the GDS kernel driver and takes the following arguments:

- ▶ Arg1: File descriptor
- ▶ Arg2: File offset
- ▶ Arg3: Write size
- ▶ Arg4: GPU Buffer offset
- ▶ Arg5: Return value
- ▶ Arg6: GPU ID for which IO is done
- ▶ Arg7: Is the IO done to GPU Bounce buffer

`cufio_gds_write_async`

This tracepoint tracks IO writes going through the GDS kernel driver, and poll mode is set and takes the following arguments:

- ▶ Arg1: File descriptor
- ▶ Arg2: File offset
- ▶ Arg3: Write size
- ▶ Arg4: GPU Buffer offset
- ▶ Arg5: Return value
- ▶ Arg6: GPU ID for which IO is done
- ▶ Arg7: Is the IO done to GPU Bounce buffer

`cufio-internal-write-bb`

This tracepoint tracks IO writes going through internal GPU Bounce buffers and is specific to the EXAScaler[®] filesystem and block device-based filesystems. This tracepoint is in hot IO-path tracking in every IO and takes the following arguments:

- ▶ Arg1: Application GPU (GPU ID)
- ▶ Arg2: GPU Bounce buffer (GPU ID)
- ▶ Arg3: File descriptor
- ▶ Arg4: File offset
- ▶ Arg5: Write size
- ▶ Arg6: Application GPU Buffer offset
- ▶ Arg7: Size in bytes transferred from application GPU buffer to target GPU bounce buffer.
- ▶ Arg8: Total Size in bytes transferred so far through bounce buffer.
- ▶ Arg9: Pending IO count in this transaction

`cufio-internal-read-bb`

This tracepoint tracks IO reads going through internal GPU Bounce buffers and is specific to the EXAScaler[®] filesystem and block device-based filesystems. This tracepoint is in hot IO-path tracking every IO and takes the following arguments:

- ▶ Arg1: Application GPU (GPU ID)
- ▶ Arg2: GPU bounce buffer (GPU ID)
- ▶ Arg3: File descriptor
- ▶ Arg4: File offset
- ▶ Arg5: Read size
- ▶ Arg6: Application GPU Buffer offset
- ▶ Arg7: Size in bytes transferred from the GPU bounce buffer to application GPU buffer.
- ▶ Arg8: Total Size in bytes transferred so far through bounce buffer.
- ▶ Arg9: Pending IO count in this transaction.

`cufio-internal-bb-done`

This tracepoint tracks all IO going through bounce buffers and is invoked when IO is completed through bounce buffers. The tracepoint can be used to track all IO going through bounce buffers and takes the following arguments:

- ▶ Arg1: IO-type READ - 0, WRITE - 1
- ▶ Arg2: Application GPU (GPU ID)
- ▶ Arg3: GPU Bounce buffer (GPU ID)
- ▶ Arg4: File descriptor
- ▶ Arg5: File offset
- ▶ Arg6: Read/Write size
- ▶ Arg7: GPU buffer offset
- ▶ Arg8: IO is unaligned (1 - True, 0 - False)
- ▶ Arg9: Buffer is registered (1 - True, 0 - False)

cufile-internal-io-done

This tracepoint tracks all IO going through the GDS kernel driver. This tracepoint is invoked when the IO is completed and takes the following arguments:

- ▶ Arg1: IO-type READ - 0, WRITE - 1
- ▶ Arg2: GPU ID for which IO is done
- ▶ Arg3: File descriptor
- ▶ Arg4: File offset
- ▶ Arg5: Total bytes transferred

cufile-internal-map

This tracepoint tracks GPU buffer registration using `cuFileBufRegister` and takes the following arguments:

- ▶ Arg1: GPU ID
- ▶ Arg2: GPU Buffer size for which registration is done
- ▶ Arg3: `max_direct_io_size` that was used for this buffer.
The shadow memory size is set in the `/etc/cufile.json` file.
- ▶ Arg4: boolean value indicating whether buffer is pinned.
- ▶ Arg5: boolean value indicating whether this buffer is a GPU bounce buffer.
- ▶ Arg6: GPU offset.

The data type of each argument in these tracepoints can be found by running the following command:

```
# ./tplist -l /usr/local/cuda-x.y/lib/libcufile.so -vvv | grep cufile_px_read -A 7
cufile:cufile_px_read [sema 0x0]
```

Here is the output:

```
# ./tplist -l /usr/local/cuda-x.y/lib/libcufile.so -vvv | grep cufile_px_read -A 7
cufile:cufile_px_read [sema 0x0]
  location #1 7usr/local/cuda-x.y/lib/libcufile.so 0x16437c
    argument #1 4 signed  bytes @ dx
    argument #2 8 signed  bytes @ cx
    argument #3 8 unsigned bytes @ si
    argument #4 8 signed  bytes @ di
    argument #5 8 signed  bytes @ r8
    argument #6 4 signed  bytes @ ax
```

15.2. Example: Track the IO Activity of a Process that Issues cuFileRead/cuFileWrite

This example provides information about how you can track the IO activity of a process that issues the `cuFileRead` or the `cuFileWrite` API.

1. Run the following command.

```
# ./funccount u:/usr/local/cuda-x.y/lib/libcufio.so:cufio_* -i 1 -T -p 59467
Tracing 7 functions for "u:/usr/local/cuda-x.y/lib/libcufio.so:cufio_*"... Hit
Ctrl-C to end.
```

2. Review the output, for example:

```
cufio_gds_write          1891

16:21:13
FUNC                    COUNT
cufio_gds_write        1852

16:21:14
FUNC                    COUNT
cufio_gds_write        1865
^C
16:21:14
FUNC                    COUNT
cufio_gds_write        1138
Detaching...
```

15.3. Example: Display the IO Pattern of all the IOs that Go Through GDS

This example provides information about how you can display and understand the IO pattern of all IOs that go through GDS.

1. Run the following command:

```
# ./argdist -C 'u:/usr/local/cuda-x.y/lib/
libcufio.so:cufio_gds_read():size_t:arg3# Size Distribution'
```

2. Review the output, for example:

```
[16:38:22]
IO Size Distribution
COUNT    EVENT
4654      arg3 = 1048576
7480      arg3 = 131072
9029      arg3 = 65536
13561     arg3 = 8192
14200     arg3 = 4096
[16:38:23]
IO Size Distribution
COUNT    EVENT
4682      arg3 = 1048576
```



```

7459      arg3 = 131072
9049      arg3 = 65536
13556     arg3 = 8192
14085     arg3 = 4096
[16:38:24]
IO Size Distribution
COUNT   EVENT
4678     arg3 = 1048576
7416     arg3 = 131072
9018     arg3 = 65536
13536    arg3 = 8192
14082    arg3 = 4096

```

The 1M, 128K, 64K, 8K, and 4K IOs are all completing reads through GDS.

15.4. Understand the IO Pattern of a Process

You can review the output to understand the IO pattern of a process.

1. Run the following command.

```
# ./argdist -C 'u:/usr/local/cuda-x.y/lib/
libcufio.so:cufio_gds_read():size_t:arg3#IO
Size Distribution' -p 59702
```

2. Review the output.

```

[16:40:46]
IO Size Distribution
COUNT   EVENT
20774    arg3 = 4096
[16:40:47]
IO Size Distribution
COUNT   EVENT
20727    arg3 = 4096
[16:40:48]
IO Size Distribution
COUNT   EVENT
20713    arg3 = 4096

```

Process 59702 issues 4K IOs.

15.5. Understand the IO Pattern of a Process with the File Descriptor on Different GPUs

Explain the benefits of the task, the purpose of the task, who should perform the task, and when to perform the task in 50 words or fewer.

1. Run the following command.

```
# ./argdist -C
'u:/usr/local/cuda-x.y/lib/libcufio.so:cufio_gds_read():int,int,size:arg1,
arg6,arg3#IO Size Distribution arg1=fd, arg6=GPU# arg3=IOSize' -p `pgrep -n
gdsio`
```

- Review the output, for example:

```
[17:00:03]
u:/usr/local/cuda-x.y/lib/
libcufile.so:cufio_gds_read():int,int,size_t:arg1,arg6,arg3#IO Size Distribution
arg1=fd, arg6=GPU# arg3=IOSize
COUNT      EVENT
5482         arg1 = 87, arg6 = 2, arg3 = 131072
7361         arg1 = 88, arg6 = 1, arg3 = 65536
9797         arg1 = 89, arg6 = 0, arg3 = 8192
11145        arg1 = 74, arg6 = 3, arg3 = 4096
[17:00:04]
u:/usr/local/cuda-x.y/lib/
libcufile.so:cufio_gds_read():int,int,size_t:arg1,arg6,arg3#IO Size Distribution
arg1=fd, arg6=GPU# arg3=IOSize
COUNT      EVENT
5471         arg1 = 87, arg6 = 2, arg3 = 131072
7409         arg1 = 88, arg6 = 1, arg3 = 65536
9862         arg1 = 89, arg6 = 0, arg3 = 8192
11079        arg1 = 74, arg6 = 3, arg3 = 4096
[17:00:05]
u:/usr/local/cuda-x.y/lib/
libcufile.so:cufio_gds_read():int,int,size_t:arg1,arg6,arg3#IO Size Distribution
arg1=fd, arg6=GPU# arg3=IOSize
COUNT      EVENT
5490         arg1 = 87, arg6 = 2, arg3 = 131072
7402         arg1 = 88, arg6 = 1, arg3 = 65536
9827         arg1 = 89, arg6 = 0, arg3 = 8192
11131        arg1 = 74, arg6 = 3, arg3 = 4096
```

gdsio issues READS to 4 files with fd=87, 88,89, 74 to GPU 2, 1, 0, and 3 and with IO-SIZE of 128K, 64K, 8K, and 4K.

15.6. Determine the IOPS and Bandwidth for a Process in a GPU

You can determine the IOPS and bandwidth for each process in a GPU.

- Run the following command.

```
#!/argdist -C
'u:/usr/local/cuda-x.y/lib/libcufile.so:cufio_gds_read():int,int,size_t:arg1,
arg6,arg3:arg6==0||arg6==3#IO Size Distribution arg1=fd, arg6=GPU#
arg3=IOSize' -p `pgrep -n gdsio`
```

- Review the output.

```
[17:49:33]
u:/usr/local/cuda-x.y/lib/
libcufile.so:cufio_gds_read():int,int,size_t:arg1,arg6,arg3:arg6==0||arg6==3#IO
Size Distribution arg1=fd, arg6=GPU# arg3=IOSize
COUNT      EVENT
9826         arg1 = 89, arg6 = 0, arg3 = 8192
11168        arg1 = 86, arg6 = 3, arg3 = 4096
[17:49:34]
u:/usr/local/cuda-x.y/lib/
libcufile.so:cufio_gds_read():int,int,size_t:arg1,arg6,arg3:arg6==0||arg6==3#IO
Size Distribution arg1=fd, arg6=GPU# arg3=IOSize
COUNT      EVENT
9815         arg1 = 89, arg6 = 0, arg3 = 8192
11141        arg1 = 86, arg6 = 3, arg3 = 4096
[17:49:35]
```

```

u:/usr/local/cuda-x.y/lib/
libcufile.so:cufio_gds_read():int,int,size_t:arg1,arg6,arg3:arg6==0||arg6==3#IO
Size Distribution arg1=fd, arg6=GPU# arg3=IOSize
COUNT      EVENT
9914         arg1 = 89, arg6 = 0, arg3 = 8192
11194        arg1 = 86, arg6 = 3, arg3 = 4096

```

- ▶ gdsio is doing IO on all 4 GPUs, and the output is filtered for GPU 0 and GPU 3.
- ▶ Bandwidth per GPU is GPU 0 - 9826 IOPS of 8K block size, and the bandwidth = ~80MB/s .

15.7. Display the Frequency of Reads by Processes that Issue cuFileRead

You can display information about the frequency of reads by process that issue the cuFileRead API.

1. Run the following command.

```
#./argdist -C 'r:/usr/local/cuda-x.y/lib/libcufile.so:cuFileRead():u32:$PID'
```

2. Review the output, for example:

```

[17:58:01]
r:/usr/local/cuda-x.y/lib/libcufile.so:cuFileRead():u32:$PID
COUNT      EVENT
31191        $PID = 60492
31281        $PID = 60593
[17:58:02]
r:/usr/local/cuda-x.y/lib/libcufile.so:cuFileRead():u32:$PID
COUNT      EVENT
11741        $PID = 60669
30447        $PID = 60593
30670        $PID = 60492
[17:58:03]
r:/usr/local/cuda-x.y/lib/libcufile.so:cuFileRead():u32:$PID
COUNT      EVENT
29887        $PID = 60593
29974        $PID = 60669
30017        $PID = 60492
[17:58:04]
r:/usr/local/cuda-x.y/lib/libcufile.so:cuFileRead():u32:$PID
COUNT      EVENT
29972        $PID = 60593
30062        $PID = 60492
30068        $PID = 60669

```

15.8. Display the Frequency of Reads when cuFileRead Takes More than 0.1 ms

You can display the frequency of reads when the cuFileRead API takes more than 0.1 ms.

1. Run the following command.

```
#./argdist -C 'r:/usr/local/cuda-x.y/lib/libcufile.so:cuFileRead():u32:$PID:
$latency > 100000'
```

2. Review the output, for example:

```
[18:07:35]
```

```

r:/usr/local/cuda-x.y/lib/libcufile.so:cuFileRead():u32:$PID:$latency > 100000
COUNT      EVENT
17755       $PID = 60772
[18:07:36]
r:/usr/local/cuda-x.y/lib/libcufile.so:cuFileRead():u32:$PID:$latency > 100000
COUNT      EVENT
17884       $PID = 60772
[18:07:37]
r:/usr/local/cuda-x.y/lib/libcufile.so:cuFileRead():u32:$PID:$latency > 100000
COUNT      EVENT
17748       $PID = 60772
[18:07:38]
r:/usr/local/cuda-x.y/lib/libcufile.so:cuFileRead():u32:$PID:$latency > 100000
COUNT      EVENT
17898       $PID = 60772
[18:07:39]
r:/usr/local/cuda-x.y/lib/libcufile.so:cuFileRead():u32:$PID:$latency > 100000
COUNT      EVENT
17811       $PID = 60772

```

15.9. Displaying the Latency of cuFileRead for Each Process

You can display the latency of the the cuFileRead API for each process.

1. Run the following command.

```

#./funclatency /usr/local/cuda-x.y/lib/libcufile.so:cuFileRead -i 1 -T -u

```

2. Review the output, for example:

```

Tracing 1 functions for
"/usr/local/cuda-x.y/lib/libcufile.so:cuFileRead"... Hit Ctrl-C to end.

```

Here are two process with PID 60999 and PID 60894 that are issuing cuFileRead:

```

18:12:11
Function = cuFileRead [60999]
  usecs      : count      distribution
    0 -> 1      : 0          |
    2 -> 3      : 0          |
    4 -> 7      : 0          |
    8 -> 15     : 0          |
   16 -> 31     : 0          |
   32 -> 63     : 0          |
   64 -> 127    : 17973     |*****|
  128 -> 255    : 13383     |*****|
  256 -> 511    : 27        |
Function = cuFileRead [60894]
  usecs      : count      distribution
    0 -> 1      : 0          |
    2 -> 3      : 0          |
    4 -> 7      : 0          |
    8 -> 15     : 0          |
   16 -> 31     : 0          |
   32 -> 63     : 0          |
   64 -> 127    : 17990     |*****|
  128 -> 255    : 13329     |*****|
  256 -> 511    : 19        |
18:12:12
Function = cuFileRead [60999]
  usecs      : count      distribution
    0 -> 1      : 0          |
    2 -> 3      : 0          |

```

```

    4 -> 7      : 0      |
    8 -> 15     : 0      |
   16 -> 31    : 0      |
   32 -> 63    : 0      |
   64 -> 127   : 18209  |*****|
  128 -> 255   : 13047  |*****|
  256 -> 511   : 58      |
Function = cuFileRead [60894]
  usecs      : count   distribution
    0 -> 1    : 0      |
    2 -> 3    : 0      |
    4 -> 7    : 0      |
    8 -> 15   : 0      |
   16 -> 31   : 0      |
   32 -> 63   : 0      |
   64 -> 127  : 18199  |*****|
  128 -> 255  : 13015  |*****|
  256 -> 511  : 46     |
  512 -> 1023: 1      |

```

15.10. Example: Tracking the Processes that Issue cuFileBufRegister

This example provides information about how you can track processes that issue the `cuFileBufRegister` API.

1. Run the following command:

```
# ./trace 'u:/usr/local/cuda-x.y/lib/libcufio.so:cufio-internal-map "GPU
%d Size %d Bounce-Buffer %d",arg1,arg2,arg5'
```

2. Review the output, for example:

```

PID      TID      COMM      FUNC      -
62624    62624    gdsio_verify  cufio-internal-map GPU 0 Size 1048576 Bounce-
Buffer 1
62659    62726    fio        cufio-internal-map GPU 0 Size 8192 Bounce-Buffer
0
62659    62728    fio        cufio-internal-map GPU 2 Size 131072 Bounce-
Buffer 0
62659    62727    fio        cufio-internal-map GPU 1 Size 65536 Bounce-Buffer
0
62659    62725    fio        cufio-internal-map GPU 3 Size 4096 Bounce-Buffer
0

```

`gdsio_verify` issued an IO, but it did not register GPU memory using `cuFileBufRegister`. As a result, the GDS library pinned 1M of a bounce buffer on GPU 0. FIO, on the other hand, issued a `cuFileBufRegister` of 128K on GPU 2.


```

1013 1041 gdsio App-GPU 0 Bounce-Buffer GPU 0 Transfer Size 1048576 Unaligned 1
Registered 0
1013 1042 gdsio App-GPU 3 Bounce-Buffer GPU 3 Transfer Size 1048576 Unaligned 1
Registered 0
1013 1041 gdsio App-GPU 0 Bounce-Buffer GPU 0 Transfer Size 1048576 Unaligned 1
Registered 0
1013 1042 gdsio App-GPU 3 Bounce-Buffer GPU 3 Transfer Size 1048576 Unaligned 1
Registered 0

```

The `gdsio` app has 2 threads and both are doing unaligned IO on GPU 0 and GPU 3. Since the IO is unaligned, bounce buffers are also from the same application GPU.

15.13. Example: Tracing `cuFileRead` and `cuFileWrite` Failures, Print, Error Codes, and Time of Failure

This example shows you how to trace the `cuFileRead` and `cuFileWrite` failures, print, error codes, and time of failure.

1. Run the following command:

```

# ./trace 'r:/usr/local/cuda-x.y/lib/libcufile.so:cuFileRead ((int)retval < 0)
"cuFileRead failed: %d", retval' 'r:/usr/local/cuda-x.y/lib/
libcufile.so:cuFileWrite ((int)retval < 0)
"cuFileWrite failed: %d", retval' -T

```

2. Review the output, for example:

TIME	PID	TID	COMM	FUNC	-
23:22:16	4201	4229	gdsio	cuFileRead	cuFileRead failed: -5
23:22:42	4237	4265	gdsio	cuFileWrite	cuFileWrite failed: -5

In this example, two failures were observed with EIO (-5) as the return code with the timestamp.

15.14. Example: User-Space Statistics for Each GDS Process

This example provides information about the user-space statistics for each GDS process.

The `cuFile` library exports user-level statistics in the form of API level counters for each process. In addition to the regular GDS IO path, there are paths for user-space file-systems and IO compatibility modes that use POSIX read/writes, which do not go through the `nvidia-fs` driver. The user-level statistics are more useful in these scenarios.

There is a verbosity level for the counters which users can specify using JSON configuration file to enable and set the level. The following describes various verbosity levels.

Table 10. User-Space Statistics for Each GDS Process

Level	Description
Level 0	cuFile stats will be disabled.
Level 1	cuFile stats will report only Global Counters like overall throughput, average latency and error counts.
Level 2	With the Global Counters, an IO Size histogram will be reported for information on access patterns.
Level 3	At this level, per GPU counters are reported and also live usage of cuFile internal pool buffers.

Here is the JSON configuration key to enable GDS statistics by using the `/etc/cufile.json` file:

```
"profile": {
    // cufile stats level(0-3)
    "cufile_stats": 3
},
```

15.15. Example: Viewing GDS User-Level Statistics for a Process

This example provides information about how you can use the `gds_stats` tool to display user-level statistics for a process.

Prerequisite: Before you run the tool, ensure that the IO application is active, and the `gds_stats` has the same user permissions as the application.

The `gds_stats` tool can be used to read statistics that are exported by `libcufire.so`.

The output of the statistics is displayed in the standard output. If the user permissions are not the same, there might not be sufficient privilege to view the stats. A future version of `gds_stats` will integrate `nvidia-fs` kernel level statistics into this tool.

To use the tool, run the following command:

```
$ /usr/local/cuda-x.y/tools/gds_stats -p <pidof application> -l <stats_level(1-3)>
```

When specifying the statistics level, ensure that the corresponding level (`profile.cufile_stats`) is also enabled in the `/etc/cufile.json` file.

The GDS user level statistics are logged once to `cufile.log` file when the library is shut down, or the `cuFileDriverClose` API is run. To view statistics in the log file, set the log level to INFO.

15.16. Example: Displaying Sample User-Level Statistics for each GDS Process

This example shows you how to display sample user-level statistics for each GDS process.

1. Run the following command:

```
$ ./gds_stats -p 23198 -l 3
```

2. Review the output, for example:

```
cuFile STATS VERSION : 4
GLOBAL STATS:
Total Files: 1
Total Read Errors : 0
Total Read Size (MiB): 7302
Read BandWidth (GiB/s): 0.691406
Avg Read Latency (us): 6486
Total Write Errors : 0
Total Write Size (MiB): 0
Write BandWidth (GiB/s): 0
Avg Write Latency (us): 0
READ-WRITE SIZE HISTOGRAM :
0-4(KiB): 0 0
4-8(KiB): 0 0
8-16(KiB): 0 0
16-32(KiB): 0 0
32-64(KiB): 0 0
64-128(KiB): 0 0
128-256(KiB): 0 0
256-512(KiB): 0 0
512-1024(KiB): 0 0
1024-2048(KiB): 0 0
2048-4096(KiB): 3651 0
4096-8192(KiB): 0 0
8192-16384(KiB): 0 0
16384-32768(KiB): 0 0
32768-65536(KiB): 0 0
65536-...(KiB): 0 0
PER_GPU STATS:
GPU_0 Read: bw=0.690716 util(%)=199 n=3651 posix=0 unalign=0 dr=0 r_sparse=0
r_inline=0 err=0 MiB=7302 Write: bw=0 util(%)=0 n=0 posix=0 unalign=0 dr=0 err=0
MiB=0 BufRegister: n=2 err=0 free=0 MiB=4
PER_GPU POOL BUFFER STATS:
PER_GPU POSIX POOL BUFFER STATS:

PER_GPU RDMA STATS:
GPU_0000:43:00.0 : mlx5_0(130:64):Reads: 3594 Writes: 0 mlx5_1(130:64):Reads:
3708 Writes: 0
RDMA MRSTATS:
peer name nr_mrs mr_size(MiB)
mlx5_0 1 2
mlx5_1 1 2
```

Chapter 16. User-Space Counters in GPUDirect Storage

This section provides information about user-space counters in GDS.

Table 11. Global cuFile Counters

Counter Name	Description
Total Files	Total number of files registered successfully with <code>cuFileHandleRegister</code> . This is a cumulative counter. <code>cuFileHandleDeregister</code> does not change this counter.
Total Read Errors	Total number of <code>cuFileRead</code> errors.
Total Read Size	Total number of bytes read in MB using <code>cuFileRead</code> .
Read Bandwidth	Average overall read throughput in GiB/s over one second time period.
Avg Read Latency	Overall average read latency in microseconds over one second time period.
Total Write Errors	Total number of <code>cuFileWrite</code> errors.
Total Write Size	Total number of bytes written in MB using <code>cuFileWrite</code> .
Write Bandwidth	Overall average write throughput in GiB/s over one second time period.
Avg Write Latency	Overall average read latency in microseconds over one second time period.

Table 12. IO-Size Histogram

Counter Name	Description
Read	Distribution of number of cuFileRead requests based on IO size. Bin Size uses a 4K log scale.
Write	Distribution of number of cuFileWrite requests based on IO size. Bin Size uses a 4K log scale.

Table 13. Per-GPU Counters

Counter Name	Description
Read.bw/Write.bw	Average GPU read/write bandwidth in GiB/s per GPU.
Read.util/Write.util	Average per GPU read/write utilization in %. If A is the total length of time the resource was busy in a time interval T, then utilization is defined as A/T. Here the utilization is reported over one second period.
Read.n/Write.n	Number of cuFileRead/cuFileWrite requests per GPU.
Read.posix/Write.posix	Number of cuFileRead/cuFileWrite using POSIX read/write APIs per GPU.
Read.dr/Write.dr	Number of cuFileRead/cuFileWrites for a GPU have been issued using dynamic routing. If the routing policy uses SYS_MEM, GPU posix counters for read/writes will be incrementing in addition to the dr counter. Note: This counter does not tell which GPU was actually being used for routing the IO. For the latter information, one needs to observe the PER_GPU POOL BUFFER STATS/PER_GPU POSIX POOL BUFFER STATS.
Read.unalign/Write.unalign	Number of cuFileRead/cuFileWrite per GPU which have at least one IO parameter not 4K aligned. This can be either size, file offset or device pointer.
Read.error/Write.error	Number of cuFileRead/cuFileWrite errors per GPU.
Read.mb/Write.mb	Total number of bytes in MB read/written using cuFileRead/cuFileWrite per GPU.

Counter Name	Description
BufRegister.n	Total number of <code>cuFileBufRegister</code> calls per GPU.
BufRegister.err	Total number of errors per GPU seen with <code>cuFileBufRegister</code> .
BufRegister.free	Total number of <code>cuFileBufRegister</code> calls per GPU.
BufRegister.mb	Total number of bytes in MB currently registered per GPU.

Table 14. Bounce Buffer Counters Per GPU

Counter Name	Description
pool_size_mb	Total size of buffers allocated for per GPU bounce buffers in MB.
used_mb	Total size of buffers currently used per GPU for bounce buffer based IO.
usage	Fraction of bounce buffers used currently.

16.1. Distribution of IO Usage in Each GPU

Here is some information about how to display the distribution of IO usage in each GPU.

The `cuFile` library has a metric for IO utilization per GPU by application. This metric indicates the amount of time, in percentage, that the `cuFile` resource was busy in IO.

To run a single-threaded `gdsio` test, run the following command:

```
./gdsio -f /mnt/md1/test -d 0 -n 0 -w 1 -s 10G -i 4K -x 0 -I 1
```

Here is the sample output:

```
PER_GPU STATS
GPU_0 Read: bw=0 util(%)=0 n=0 posix=0 unalign=0 err=0 mb=0 Write: bw=0.154598
util(%)=89 n=510588 posix=0 unalign=0 err=0 mb=1994 BufRegister: n=1 err=0 free=0
mb=0
```

The `util` metric says that the application was completing IO on GPU 0 89% of the time.

To run a `gdsio` test using two-threads, run the following command:

```
./gdsio -f /mnt/md1/test -d 0 -n 0 -w 2 -s 10G -i 4K -x 0 -I 1
```

Here is the sample output:

```
PER_GPU STATS
GPU_0 Read: bw=0 util(%)=0 n=0 posix=0 unalign=0 err=0 mb=0 Write:
bw=0.164967 util(%)=186 n=140854 posix=0 unalign=0 err=0 mb=550 BufRegister: n=2
err=0 free=0 mb=0
```

Now the utilization is ~186%, which indicates the amount of parallelism in the way each GPU is used for IO.

16.2. User-space Statistics for Dynamic Routing

The `PER_GPU` section of `gds_stats` has a `dr` counter which indicates how many `cuFileRead/cuFileWrites` for a GPU have been issued using dynamic routing.

```
$ ./gds_stats -p <pidof application> -l 3

GPU 0 Read: bw=0 util(%)=0 n=0 posix=0 unalign=0 dr=0 r_sparse=0 r_inline=0
err=0 MiB=0 Write: bw=3.37598 util(%)=532 n=6629 posix=0 unalign=0 dr=6629 err=0
MiB=6629 BufRegister: n=4 err=0 free=0 MiB=4
GPU 1 Read: bw=0 util(%)=0 n=0 posix=0 unalign=0 dr=0 r_sparse=0 r_inline=0
err=0 MiB=0 Write: bw=3.29297 util(%)=523 n=6637 posix=0 unalign=0 dr=6637 err=0
MiB=6637 BufRegister: n=4 err=0 free=0 MiB=4
```

Chapter 17. User-Space RDMA Counters in GPUDirect Storage

This section provides information about user-space RDMA counters in GDS.

The library provides counters to monitor the RDMA traffic at a per-GPU level and requires that cuFile starts verbosity with a value of 3.

Table [14-1](#) provides the following information:

- ▶ Each column stores the total number of bytes that are sent/received between a GPU and a NIC.
- ▶ Each row shows the distribution of RDMA load with regards to a GPU across all NICs.
- ▶ Each row reflects the order of affinity that a GPU has with a NIC.

Ideally, all traffic should be routed through the NIC with the best affinity or is closest to the GPU as shown in *Example 1* in [cuFile RDMA IO Counters \(PER_GPU RDMA STATS\)](#).

In the annotation of each NIC entry in the table, the major number is the pci-distance in terms of the number of hops between the GPU and the NIC, and the minor number indicates the current bandwidth of the NIC (link_width multiplied by pci-generation). The NICs that the GPUs use for RDMA are loaded from the `rdma_dev_addr_list` `cufile.json` property:

```
"rdma_dev_addr_list": [  
  "172.172.1.240",  
  "172.172.1.241",  
  "172.172.1.242",  
  "172.172.1.243",  
  "172.172.1.244",  
  "172.172.1.245",  
  "172.172.1.246",  
  "172.172.1.247" ],
```

Each IP address corresponds to an IB device that appear as column entries in the RDMA counter table.

17.1. cuFile RDMA IO Counters (PER_GPU RDMA STATS)

Here is some information about cuFile RDMA IO counters.

Table 15. cuFile RDMA IO Counters (PER_GPU RDMA STATS)

Entry	Description
GPU	Bus device function
NIC	+) Bus device function +) Device Attributes ++) pci-distance between GPU and NIC ++) device bandwidth indicator +) Send/Receive bytes

Table 16. Example 1

GPU 0000:34:	mlx5_3 (3:48):6	mlx5_5 (7:48):0	mlx5_15 (138:48):	mlx5_15 (138:48):	mlx5_17 (138:48):	mlx5_9 (138:48):	mlx5_13 (138:48):	mlx5_7 (138:12):	:0
GPU 0000:36:	mlx5_3 (3:48):6	mlx5_5 (7:48):1	mlx5_15 (138:48):	mlx5_19 (138:48):	mlx5_17 (138:48):	mlx5_9 (138:48):	mlx5_13 (138:48):	mlx5_7 (138:12):	:0
GPU 0000:3b:	mlx5_5 (3:48):5	mlx5_3 (7:48):0	mlx5_15 (138:48):	mlx5_19 (138:48):	mlx5_17 (138:48):	mlx5_9 (138:48):	mlx5_13 (138:48):	mlx5_7 (138:12):	:0
GPU 0000:57:	mlx5_7 (3:12):4	mlx5_9 (7:48):0	mlx5_15 (138:48):	mlx5_19 (138:48):	mlx5_5 (138:48):	mlx5_17 (138:48):	mlx5_13 (138:48):	mlx5_3 (138:48):	:0
GPU 0000:59:	mlx5_7 (3:12):4	mlx5_9 (7:48):1	mlx5_15 (138:48):	mlx5_19 (138:48):	mlx5_5 (138:48):	mlx5_17 (138:48):	mlx5_13 (138:48):	mlx5_3 (138:48):	:0
GPU 0000:5c:	mlx5_9 (3:48):4	mlx5_7 (7:12):0	mlx5_15 (138:48):	mlx5_19 (138:48):	mlx5_5 (138:48):	mlx5_17 (138:48):	mlx5_13 (138:48):	mlx5_3 (138:48):	:0
GPU 0000:5e:	mlx5_9 (3:48):4	mlx5_7 (7:12):0	mlx5_15 (138:48):	mlx5_19 (138:48):	mlx5_5 (138:48):	mlx5_17 (138:48):	mlx5_13 (138:48):	mlx5_3 (138:48):	:0

17.2. cuFile RDMA Memory Registration Counters (RDMA MRSTATS)

Here is some information about cuFile RDMA memory registration counters.

Table 17. cuFile RDMA IO Counters (PER_GPU RDMA STATS)

Entry	Description
peer name	System name of the NIC.
nr_mrs	Count of active memory registration per NIC.

Entry	Description
mr_size(mb)	Total size

Table 18. Example 2

peer name	nr_ms	mr_size (mb)
mlx5_3	128	128
mlx5_5	128	128
mlx5_11	0	0
mlx5_1	0	0
mlx5_15	128	128
mlx5_19	128	128
mlx5_17	128	128
mlx5_9	128	128
mlx5_13	128	128
mlx5_7	128	128

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