



Program Listing for File application.hpp

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or agreed to in writing, software * distributed under the License is distributed on an
"AS IS" BASIS, * WITHOUT WARRANTIES OR CONDITIONS OF ANY KIND, either
express or implied. * See the License for the specific language governing
permissions and * limitations under the License. */ #ifndef
HOLOSCAN_CORE_APPLICATION_HPP #define HOLOSCAN_CORE_APPLICATION_HPP
#include <iostream> // for std::cout #include <memory> // for std::shared_ptr
#include <set> // for std::set #include <string> // for std::string #include <type_traits>
// for std::enable_if_t, std::is_constructible #include <utility> // for std::pair #include
<vector> // for std::vector #include "./fragment.hpp" #include "./app_driver.hpp"
#include "./app_worker.hpp" #include "./cli_parser.hpp" namespace holoscan {
template <typename AppT, typename... ArgsT> std::shared_ptr<AppT>
make_application(ArgsT&&... args) { return std::make_shared<AppT>
(std::forward<ArgsT>(args)...); } class Application : public Fragment { public: explicit
Application(const std::vector<std::string>& argv = {}); ~Application() override =
default; template <typename FragmentT = Fragment, typename StringT, typename...
ArgsT, typename = std::enable_if_t<std::is_constructible_v<std::string, StringT>>>
std::shared_ptr<Fragment> make_fragment(StringT name, ArgsT&&... args) { auto
fragment = std::make_shared<FragmentT>(std::forward<ArgsT>(args)...); fragment-
>name(name); fragment->application(this); // Set the fragment config to the
application config. fragment->config(config_); return fragment; } template
<typename FragmentT, typename... ArgsT> std::shared_ptr<FragmentT>
make_fragment(ArgsT&&... args) { auto fragment = std::make_shared<FragmentT>
(std::forward<ArgsT>(args)...); fragment->application(this); // Set the fragment config
to the application config. fragment->config(config_); return fragment; } std::string&
description(); Application& description(const std::string& desc) &; Application&&
description(const std::string& desc) &&; std::string& version(); Application&
version(const std::string& version) &; Application&& version(const std::string&
version) &&; std::vector<std::string>& argv(); CLIOptions& options();
```

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FragmentGraph& fragment_graph(); virtual void add_fragment(const
std::shared_ptr<Fragment>& frag); // Inherit Fragment's add_flow methods (for
Operator) in addition to the overloads below using Fragment::add_flow; virtual void
add_flow(const std::shared_ptr<Fragment>& upstream_frag, const
std::shared_ptr<Fragment>& downstream_frag, std::set<std::pair<std::string,
std::string>> port_pairs); void compose_graph() override; void run() override;
std::future<void> run_async() override; protected: friend class AppDriver; friend
class AppWorker; AppDriver& driver(); AppWorker& worker(); void
process_arguments(); static expected<SchedulerType, ErrorCode>
get_distributed_app_scheduler_env(); static expected<bool, ErrorCode>
get_stop_on_deadlock_env(); static expected<int64_t, ErrorCode>
get_stop_on_deadlock_timeout_env(); static expected<int64_t, ErrorCode>
get_max_duration_ms_env(); static expected<double, ErrorCode>
get_check_recession_period_ms_env(); static void
set_scheduler_for_fragments(std::vector<FragmentNodeType>& target_fragments);
std::string app_description_{}; std::string app_version_{"0.0.0"}; CLIParser
cli_parser_; std::vector<std::string> argv_; std::unique_ptr<FragmentGraph>
fragment_graph_; std::shared_ptr<AppDriver> app_driver_;
std::shared_ptr<AppWorker> app_worker_; private: void set_ucx_env(); }; } //
namespace holoscan #endif/* HOLOSCAN_CORE_APPLICATION_HPP */

```

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