



Program Listing for File entity.hpp

[Return to documentation for file \(include/holoscan/core/gxf/entity.hpp\)](#)

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or agreed to in writing, software * distributed under the License is distributed on an
"AS IS" BASIS, * WITHOUT WARRANTIES OR CONDITIONS OF ANY KIND, either
express or implied. * See the License for the specific language governing
permissions and * limitations under the License. */ #ifndef
HOLOSCAN_CORE_GXF_ENTITY_HPP #define HOLOSCAN_CORE_GXF_ENTITY_HPP
#include <memory> // Entity definition // Since it has code that causes a warning as an
error, we disable it here. #pragma GCC diagnostic push #pragma GCC diagnostic
ignored "-Wmissing-field-initializers" #include "gxf/core/entity.hpp" #pragma GCC
diagnostic pop #include "gxf/multimedia/video.hpp" #include "gxf/std/tensor.hpp"
#include "holoscan/core/gxf/gxf_utils.hpp" #include "holoscan/core/type_traits.hpp"
// Forward declaration namespace holoscan { class ExecutionContext; } namespace
holoscan::gxf { class Entity : public nvidia::gxf::Entity { public: Entity() = default;
explicit Entity(const nvidia::gxf::Entity& other) : nvidia::gxf::Entity(other) {} explicit
Entity(nvidia::gxf::Entity&& other) : nvidia::gxf::Entity(other) {} // Creates a new entity
static Entity New(ExecutionContext* context); operator bool() const { return
!is_null(); } // Gets a component by type. Asserts if no such component. template
<typename DataT, typename = std::enable_if_t<!holoscan::is_vector_v<DataT> &&
holoscan::is_one_of_v<DataT, holoscan::Tensor>>> std::shared_ptr<DataT>
get(const char* name = nullptr, bool log_errors = true) const { // We should use
nullptr as a default name because In GXF, 'nullptr' should be used with //
GxfComponentFind() if we want to get the first component of the given type. // Try to get
nvidia::gxf::Tensor from GXF Entity. gxf_tid_t tid; auto tid_result =
GxfComponentTypeId(context(), nvidia::TypeNameAsString<nvidia::gxf::Tensor>(),
&tid); if (tid_result != GXF_SUCCESS) { if (log_errors) { HOLOSCAN_LOG_ERROR(
"Unable to get component type id from 'nvidia::gxf::Tensor' (error code: {})",
tid_result); } return nullptr; } gxf_uid_t cid; auto cid_result =
GxfComponentFind(context(), eid(), tid, name, nullptr, &cid); if (cid_result !=
GXF_SUCCESS) { if (log_errors) { HOLOSCAN_LOG_ERROR("Unable to find component
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from the name '{} (error code: {})", name == nullptr ? "" : name, cid_result); } return
nullptr; } // Create a holoscan::Tensor object from the newly constructed GXF Tensor
object. (~680 ns) auto handle =
nvidia::gxf::Handle<nvidia::gxf::Tensor>::Create(context(), cid); auto maybe_dl_ctx =
(*handle->get()).toDLManagedTensorContext(); if (!maybe_dl_ctx) {
HOLOSCAN_LOG_ERROR( "Failed to get std::shared_ptr<DLManagedTensorContext>
from nvidia::gxf::Tensor"); return nullptr; } std::shared_ptr<Tensor> tensor =
std::make_shared<Tensor>(maybe_dl_ctx.value()); return tensor; } // Adds a
component with given type template <typename DataT, typename =
std::enable_if_t<!holoscan::is_vector_v<DataT> && holoscan::is_one_of_v<DataT,
holoscan::Tensor>>> void add(std::shared_ptr<DataT>& data, const char* name =
nullptr) { gxf_tid_t tid; HOLOSCAN_GXF_CALL_FATAL(
GxfComponentTypeId(context(), nvidia::TypenameAsString<nvidia::gxf::Tensor>(),
&tid)); gxf_uid_t cid; HOLOSCAN_GXF_CALL_FATAL(GxfComponentAdd(context(),
eid(), tid, name, &cid)); auto handle =
nvidia::gxf::Handle<nvidia::gxf::Tensor>::Create(context(), cid); nvidia::gxf::Tensor*
tensor_ptr = handle->get(); // Copy the member data
(std::shared_ptr<DLManagedTensorCtx>) from the Tensor to the // nvidia::gxf::Tensor
*tensor_ptr = nvidia::gxf::Tensor(data->dl_ctx()); } }; // Modified version of the Tensor
version of gxf::Entity::get // Retrieves a VideoBuffer instead // TODO: Support
gxf::VideoBuffer natively in Holoscan nvidia::gxf::Handle<nvidia::gxf::VideoBuffer>
getvideobuffer(Entity entity, const char* name = nullptr); } // namespace
holoscan::gxf #endif/* HOLOSCAN_CORE_GXF_ENTITY_HPP */

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