



Program Listing for File `flow_graph.hpp`

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or agreed to in writing, software * distributed under the License is distributed on an
"AS IS" BASIS, * WITHOUT WARRANTIES OR CONDITIONS OF ANY KIND, either
express or implied. * See the License for the specific language governing
permissions and * limitations under the License. */ #ifndef
HOLOSCAN_CORE_GRAPHS_FLOW_GRAPH_HPP #define
HOLOSCAN_CORE_GRAPHS_FLOW_GRAPH_HPP #include <functional> #include
<list> #include <memory> #include <set> #include <string> #include
<unordered_map> #include <vector> #include "../graph.hpp" namespace holoscan {
// Forward declarations template <typename NodeT, typename EdgeDataElementT>
class FlowGraph; // Graph type aliases // for operator graph using OperatorFlowGraph
= FlowGraph<OperatorNodeType, OperatorEdgeDataElementType>; // for fragment
graph using FragmentFlowGraph = FlowGraph<FragmentNodeType,
FragmentEdgeDataElementType>; template <typename NodeT =
OperatorNodeType, typename EdgeDataElementT =
OperatorEdgeDataElementType> class FlowGraph : public Graph<NodeT,
EdgeDataElementT> { public: using NodeType = NodeT; using NodePredicate =
std::function<bool(const NodeType&)>; using EdgeDataElementType =
EdgeDataElementT; using EdgeDataType = std::shared_ptr<EdgeDataElementType>;
using Graph<NodeT, EdgeDataElementT>::Graph; ~FlowGraph() override = default;
void add_node(const NodeType& node) override; void add_flow(const NodeType&
node_u, const NodeType& node_v, const EdgeDataType& port_map) override;
std::optional<EdgeDataType> get_port_map(const NodeType& node_u, const
NodeType& node_v) override; bool is_root(const NodeType& node) override; bool
is_user_defined_root(const NodeType& node) { return get_nodes().empty() ? false :
get_nodes()[0] == node; } bool is_leaf(const NodeType& node) override;
std::vector<NodeType> has_cycle() override; std::vector<NodeType>
get_root_nodes() override; std::vector<NodeType> get_nodes() override;
std::vector<NodeType> get_next_nodes(const NodeType& node) override;
```

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std::vector<NodeType> get_previous_nodes(const NodeType& node) override;
NodeType find_node(const NodePredicate& pred) override; NodeType
find_node(const NodeType& node) override; NodeType find_node(std::string name)
override; private: std::unordered_map<NodeType, std::unordered_map<NodeType,
EdgeDataType>> succ_; std::unordered_map<NodeType,
std::unordered_map<NodeType, EdgeDataType>> pred_; std::list<NodeType>
ordered_nodes_; std::unordered_map<std::string, NodeType> name_map_; }; } //
namespace holoscan #endif/* HOLOSCAN_CORE_GRAPHS_FLOW_GRAPH_HPP */
```

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