



Program Listing for File graph.hpp

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or agreed to in writing, software * distributed under the License is distributed on an
"AS IS" BASIS, * WITHOUT WARRANTIES OR CONDITIONS OF ANY KIND, either
express or implied. * See the License for the specific language governing
permissions and * limitations under the License. */ #ifndef
HOLOSCAN_CORE_GRAPH_HPP #define HOLOSCAN_CORE_GRAPH_HPP #include
<functional> #include <iostream> #include <memory> #include <optional> #include
<set> #include <string> #include <unordered_map> #include <vector> #include
"./common.hpp" namespace holoscan { // Forward declarations class Operator; //
Graph type aliases // for operator graph using OperatorNodeType =
std::shared_ptr<Operator>; using OperatorEdgeDataElementType =
std::unordered_map<std::string, std::set<std::string, std::less<>>>; using
OperatorGraph = Graph<OperatorNodeType, OperatorEdgeDataElementType>; //
for fragment graph using FragmentNodeType = std::shared_ptr<Fragment>; using
FragmentEdgeDataElementType = std::unordered_map<std::string,
std::set<std::string, std::less<>>>; using FragmentGraph =
Graph<FragmentNodeType, FragmentEdgeDataElementType>; template <typename
NodeT = OperatorNodeType, typename EdgeDataElementT =
OperatorEdgeDataElementType> class Graph { public: using NodeType = NodeT;
using NodePredicate = std::function<bool(const NodeT&)>; using
EdgeDataElementType = EdgeDataElementT; using EdgeDataType =
std::shared_ptr<EdgeDataElementT>; Graph() = default; virtual ~Graph() = default;
virtual void add_node(const NodeT& node) = 0; virtual void add_flow(const
NodeType& node_u, const NodeType& node_v, const EdgeDataType& port_map) =
0; virtual std::optional<EdgeDataType> get_port_map(const NodeType& node_u,
const NodeType& node_v) = 0; virtual bool is_empty() { return !find_node([](const
NodeType&) { return true; }); } virtual bool is_root(const NodeType& node) = 0;
virtual bool is_user_defined_root(const NodeType& node) = 0; virtual bool
is_leaf(const NodeType& node) = 0; virtual std::vector<NodeType> has_cycle() = 0;
```

```
virtual std::vector<NodeType> get_root_nodes() = 0; virtual std::vector<NodeType>
get_nodes() = 0; virtual std::vector<NodeType> get_next_nodes(const NodeType&
node) = 0; virtual NodeType find_node(const NodePredicate& pred) = 0; virtual
NodeType find_node(const NodeType& node) = 0; virtual NodeType
find_node(std::string name) = 0; virtual std::vector<NodeType>
get_previous_nodes(const NodeType& node) = 0; virtual void context(void* context)
{ context_ = context; } virtual void* context() { return context_; } protected: void*
context_ = nullptr; }; } // namespace holoscan #endif/*
HOLOSCAN_CORE_GRAPH_HPP */
```

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