

Holoscan and GXF

Table of contents

Design differences		
Current limitations	 	

Design differences

There are 2 main elements at the core of Holoscan and GXF designs:

- 1. How to define and execute application graphs
- 2. How to define nodes' functionality

How Holoscan SDK interfaces with GXF on those topics varies as Holoscan SDK evolves, as described below:

Holoscan SDK v0.2

Holoscan SDK was tightly coupled with GXF's existing interface:

- GXF application graphs are defined in YAML configuration files. GXE (Graph Execution Engine) is used to execute AI application graphs. Its inputs are the YAML configuration file, and a list of GXF Extensions to load as plugins (manifest yaml file). This design allows entities to be swapped or updated without needing to recompile an application.
- 2. Components are made available by registering them within a **GXF extension**, each of which maps to a shared library and header(s).

Those concepts are illustrated in the <u>GXF by example</u> section.

The only additions that Holoscan provided on top of GXF were:

- domain specific reference applications
- new extensions
- CMake configurations for building extensions and applications

Holoscan SDK v0.3

The Holoscan SDK shifted to provide a more developer-friendly interface with C++:

1. GXF application graphs, memory allocation, scheduling, and message routing can be defined using a C++ API, with the ability to read parameters and required GXF

extension names from a YAML configuration file. The backend used is still GXF as Holoscan uses the GXF C API, but this bypasses GXE and the full YAML definition.

2. The C++ **Operator** class was added to wrap and expose GXF extensions to that new application interface (See <u>dev guide</u>).

Holoscan SDK v0.4

The Holoscan SDK added Python wrapping and native operators to further increase ease of use:

- 1. The C++ API is also wrapped in Python. GXF is still used as the backend.
- 2. The Operator class supports **native operators**, i.e. operators that do not require to implement and register a GXF Extension. An important feature is the ability to support messaging between native and GXF operators without any performance loss (i.e. zero-copy communication of tensors).

Holoscan SDK v0.5

- 1. The built-in Holoscan GXF extensions are loaded automatically and don't need to be listed in the YAML configuration file of Holoscan applications. This allows Holoscan applications to be defined without requiring a YAML configuration file.
- 2. No significant changes to build operators. However, most built-in operators were switched to native implementations, with the ability to <u>convert native operators to</u> <u>GXF codelets</u> for GXF application developers.

Holoscan SDK v1.0

1. The remaining GXF-based DemosiacOp operator was switched to a native implementation. Now all operators provided by the SDK are native operators.

Current limitations

Here is a list of GXF capabilities not yet available in the Holoscan SDK which are planned to be supported in future releases:

• Job Statistics

The GXF capabilities below are not available in the Holoscan SDK either. There is no plan to support them at this time:

- Graph Composer
- Behavior Trees
- Epoch Scheduler
- Target Time Scheduling Term
- Multi-Message Available Scheduling Term
- Expiring Message Available Scheduling Term

© Copyright 2022-2024, NVIDIA.. PDF Generated on 06/06/2024