

Custom YOLO Model in the DeepStream YOLO App

Application Note



Document History

Doc_Number

Version	Date	Authors	Description of Change
1.0	July 23, 2019	cshah, jachs	Initial release

How to Use the Custom YOLO Model

The objectDetector_Yolo sample application provides a working example of the open source YOLO models: YOLOv2, YOLOv3, tiny YOLOv2, and tiny YOLOv3. You can find more information about the models at https://pireddie.com/darknet/yolo/. The sample also illustrates NVIDIA® TensorRTTM INT8 calibration (yolov3-calibration.table.trt5.1).

To set up the sample

Compile the open source model and run the DeepStream app as explained by the README in objectDetector_volo. This is a sanity check that you are able to run the open source YOLO model with the sample app.

To use the custom YOLOv3 and tiny YOLOv3 models

- 1. Open nvdsinfer_custom_impl_Yolo/nvdsparsebbox_Yolo.cpp.
- 2. Change the value of the NUM_CLASSES_YOLO constant to reflect the number of classes in your model. For example, if your model uses 80 classes:

static const int NUM_CLASSES_YOLO = 80;

The default values in the file are from:

<u>https://pjreddie.com/media/files/papers/YOLOv3.pdf</u> <u>https://raw.githubusercontent.com/pjreddie/darknet/master/cfg/yolov3.cfg</u> <u>https://raw.githubusercontent.com/pjreddie/darknet/master/cfg/yolov3-tiny.cfg</u>

 Replace the model parameters with your new model parameters in NvDsInferParseCustomYoloV3() (if you are using the YOLOV3) or NvDsInferParseCustomYoloV3Tiny() (if you are using tiny YOLOV3). Taking YOLOV3 as an example:

```
extern "C" bool NvDsInferParseCustomYoloV3(
    std::vector<NvDsInferLayerInfo> const& outputLayersInfo,
    NvDsInferNetworkInfo const& networkInfo,
    NvDsInferParseDetectionParams const& detectionParams,
    std::vector<NvDsInferParseObjectInfo>& objectList)
{
```

4. Replace the model parameters in NvDsInferParseYoloV3() with your new model parameters. These model parameters are shared between YOLOV3 and tiny YOLOV3.

```
static bool NvDsInferParseYoloV3()
{
    ## Bounding box overlap Threshold
    const float kNMS_THRESH = 0.5f;
    const float kPROB_THRESH = 0.7f;
    ## Predicted boxes
    const uint kNUM_BBOXES = 3;
}
```

To use custom models of YOLOv2 and YOLOv2-tiny

- 1. Open nvdsinfer_custom_impl_Yolo/nvdsparsebbox_Yolo.cpp.
- 2. Change the value of the NUM_CLASSES_YOLO constant to reflect the number of classes in your model. For example, if your model uses 80 classes:

```
static const int NUM_CLASSES_YOLO = 80;
```

The default values in the file are from:

https://raw.githubusercontent.com/pjreddie/darknet/master/cfg/yolov2.cfg https://raw.githubusercontent.com/pjreddie/darknet/master/cfg/yolov2-tiny.cfg

3. Change the model parameters for NvDsInferParseCustomYoloV2() (if you are using YOLOV2) or NvDsInferParseCustomYoloV2Tiny() (if you are using tiny YOLOV2). Taking YOLOV2 as an example:

```
# specify NMS and confidence threshold
static const float kNMS_THRESH = 0.3f;
static const float kPROB_THRESH = 0.6f;
```

Note: The built-in example ships with the TensorRT INT8 calibration file yolov3calibration.table.trt5.1. The example runs at INT8 precision for best performance. To compare the performance to the built-in example, generate a new INT8 calibration file for your model.

You can run the sample with another type of precision but it will be slower. If you run with FP16 or FP32 precision, change the network-mode parameter in the configuration file (config_infer_primary_yolo*.txt.

```
## 0=FP32, 1=INT8, 2=FP16 mode
network-mode=1 <== Change to 0 or 2</pre>
```

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