Custom YOLO Model in the DeepStream YOLO App

Application Note

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Document History

Doc_Number

Version	Date	Authors	Description of Change
1.0	August 6, 2019	cshah, jachs	Initial release

How to Use the Custom YOLO Model

The `objectDetector_Yolo` sample application provides a working example of the open source YOLO models: YOLOv2, YOLOv3, tiny YOLOv2, and tiny YOLOv3. You can find more information about the models at https://pjreddie.com/darknet/yolo/. The sample also illustrates NVIDIA® TensorRT™ INT8 calibration (`yolov3-calibration.table.trt5.1`).

To set up the sample

Compile the open source model and run the DeepStream app as explained by the README in `objectDetector_Yolo`. This is a sanity check that you are able to run the open source YOLO model with the sample app.

To use the custom YOLOv3 and tiny YOLOv3 models

1. Open `nvdsinfer_custom_impl_Yolo/nvdsparsebbox_Yolo.cpp`.
2. Change the value of the `NUM_CLASSES_YOLO` constant to reflect the number of classes in your model. For example, if your model uses 80 classes:

   ```
   static const int NUM_CLASSES_YOLO = 80;
   ```

   The default values in the file are from:

   https://pjreddie.com/media/files/papers/YOLOv3.pdf
   https://raw.githubusercontent.com/pjreddie/darknet/master/cfg/yolov3.cfg
   https://raw.githubusercontent.com/pjreddie/darknet/master/cfg/yolov3-tiny.cfg
3. Replace the model parameters with your new model parameters in `NvDsInferParseCustomYoloV3()` (if you are using the YOLOv3) or `NvDsInferParseCustomYoloV3Tiny()` (if you are using tiny YOLOv3). Taking YOLOv3 as an example:

   ```
   extern "C" bool NvDsInferParseCustomYoloV3(
           std::vector<NvDsInferLayerInfo> const& outputLayersInfo,
           NvDsInferNetworkInfo const& networkInfo,
           NvDsInferParseDetectionParams const& detectionParams,
           std::vector<NvDsInferParseObjectInfo>& objectList)
   {
   ```

```
  . . .
    ## 9 clusters from COCO dataset
    const std::vector<float> kANCHORS =
            {10.0, 13.0, 16.0, 30.0, 33.0, 23.0, 30.0, 61.0, 62.0,
            45.0, 59.0, 119.0, 116.0, 90.0, 156.0, 198.0, 373.0, 326.0};

    ## Specifies which of the 9 anchors above to use
    static const std::vector<std::vector<int>> kMASKS = {
            {6, 7, 8},
            {3, 4, 5},
            {0, 1, 2}};
}
```

4. Replace the model parameters in `NvDsInferParseYoloV3()` with your new model parameters. These model parameters are shared between YOLOv3 and tiny YOLOv3.

```
static bool NvDsInferParseYoloV3()
{
    ## Bounding box overlap Threshold
    const float kNMS_THRESH = 0.5f;
    const float kPROB_THRESH = 0.7f;

    ## Predicted boxes
    const uint kNUM_BBOXES = 3;
}
```

To use custom models of YOLOv2 and YOLOv2-tiny

1. Open `nvdsinfer_custom_impl_Yolo/nvdsparsebbox_Yolo.cpp`.
2. Change the value of the `NUM_CLASSES_YOLO` constant to reflect the number of classes in your model. For example, if your model uses 80 classes:

```
static const int NUM_CLASSES_YOLO = 80;
```

   The default values in the file are from:

   https://raw.githubusercontent.com/pjreddie/darknet/master/cfg/yolov2.cfg
   https://raw.githubusercontent.com/pjreddie/darknet/master/cfg/yolov2-tiny.cfg

3. Change the model parameters for `NvDsInferParseCustomYoloV2()` (if you are using YOLOv2) or `NvDsInferParseCustomYoloV2Tiny()` (if you are using tiny YOLOv2). Taking YOLOv2 as an example:

```
# specify NMS and confidence threshold
static const float kNMS_THRESH = 0.3f;
static const float kPROB_THRESH = 0.6f;
```

```
# specify anchors and in NvDsInferParseYoloV2, kANCHORS = {[anchors] in
yolov2.cfg} * stride
static const std::vector<float> kANCHORS = {
         18.3273602, 21.6763191, 59.9827194, 66.0009613,
         106.829758, 175.178879, 252.250244, 112.888962,
         312.656647, 293.384949 };
# Predicted boxes in NvDsInferParseYoloV2
const uint kNUM_BBOXES = 5;
```

Note: The built-in example ships with the TensorRT INT8 calibration file `yolov3-calibration.table.trt5.1`. The example runs at INT8 precision for best performance. To compare the performance to the built-in example, generate a new INT8 calibration file for your model.

You can run the sample with another type of precision but it will be slower. If you run with FP16 or FP32 precision, change the `network-mode` parameter in the configuration file `(config_infer_primary_yolo*.txt`.

```
## 0=FP32, 1=INT8, 2=FP16 mode
network-mode=1 <== Change to 0 or 2
```

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